

In[1]:= (\*第一问\*)

```
vx0 = v0 Cos[θ0 / 180 * Pi];
vy0 = v0 Sin[θ0 / 180 * Pi];
S = (2 vx0 vy0) / g;
H = vy0^2 / (2 g);
T = (2 vy0) / g;
sol = DSolve[{x''[t] == -b x'[t] / m, y''[t] == -b y'[t] / m - g, x[0] == 0,
y[0] == 0, x'[0] == vx0, y'[0] == vy0}, {x[t], y[t]}, t] // ExpandAll;
x[t_] = x[t] /. sol[[1, 1]];
tx = Flatten[Simplify[Solve[x[t] == x, t, Reals],
b > 0 && v0 > 0 && m > 0 && 0 < θ0 < 90 && x > 0 && m v0 Cos[(π θ0) / 180] > b x]];
yx[x_] = y[t] /. sol[[1, 2]] /. tx
```

Out[9]=

$$\frac{g m^2}{b^2} - \frac{g m^2 \operatorname{Log}\left[\frac{m v_0 \cos\left[\frac{\pi \theta_0}{180}\right]}{-b x + m v_0 \cos\left[\frac{\pi \theta_0}{180}\right]}\right]}{b^2} - \frac{g m \left(-b x + m v_0 \cos\left[\frac{\pi \theta_0}{180}\right]\right) \operatorname{Sec}\left[\frac{\pi \theta_0}{180}\right]}{b^2 v_0} + \frac{m v_0 \sin\left[\frac{\pi \theta_0}{180}\right]}{b} - \frac{\left(-b x + m v_0 \cos\left[\frac{\pi \theta_0}{180}\right]\right) \operatorname{Tan}\left[\frac{\pi \theta_0}{180}\right]}{b}$$

In[26]:= (\*第二问\*)

(\*变量定义\*)

`m = 0.14 ;`

`v0 = 45;`

`θ0 = 60;`

`b = 0.033;`

`g = 9.81;`

`vx0 = vx0 // N;`

|数值运算

`vy0 = vy0 // N;`

|数值运算

`S = S // N;`

|数值运算

`H = H // N;`

|数值运算

`T = T // N;`

|数值运算

`pathWithoutAirResistance =`

`Plot[vy0 / vx0 x - 1 / 2 g / vx0^2 x^2, {x, 0, S}, PlotRange -> {0, H}];`

|绘图

|绘制范围

`yt[t_] = y[t] /. sol[[1, 2]];`

`tmax = t /. FindRoot[yt[t], {t, T}];`

|求根

`tab = Table[`

|表格

`Show[`

|显示

`pathWithoutAirResistance,`

`Graphics[{AbsolutePointSize[7], Red, Point[{x[(tmax / 32) i], yt[(tmax / 32) i]}]}],`

|绝对点大小

|红色 |点

`ParametricPlot[{x[t], yt[t]}, {t, 0, (tmax / 32) i + 0.0001},`

|绘制参数图

`PlotStyle -> {Blue, Dashing[{0.02, 0.02}]}, PlotRange ->`

|蓝色

|虚线线段配置

|绘制范围

`{{-0.01, S}, {-0.01, 1.02 H}}, ImageSize -> 500, LabelStyle -> {FontSize -> 20},`

|图像尺寸

|标签样式

|字体大小

`AxesLabel -> {"x(m)", "y(m)", AspectRatio -> Automatic}], {i, 0, 32}];`

|坐标轴标签

|宽高比

|自动

`ListAnimate[`

|列表帧动画

`tab]`

Out[40]=

