

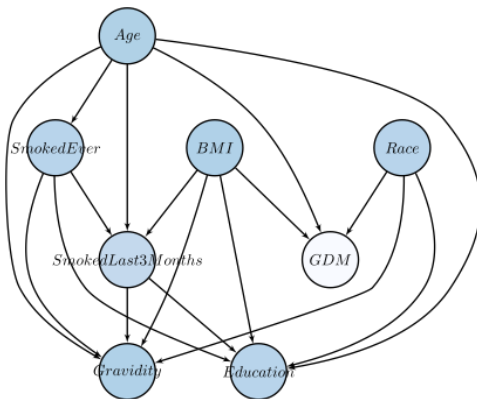
# Normalizing flows

**Materials adapted from:**

- Normalizing Flows and Invertible Neural Networks, ECCV 2020 Tutorial
- Nordic Probabilistic AI School (ProbAI) 2022.

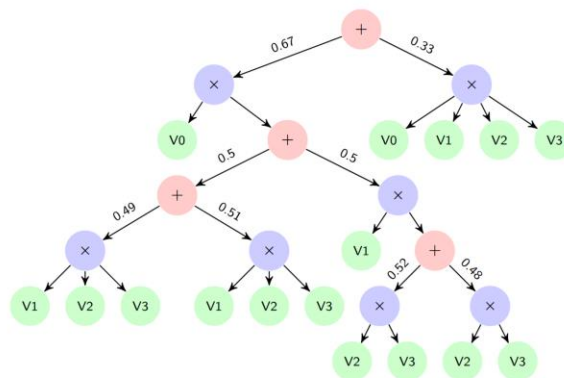
# Joint distributions

PGMs



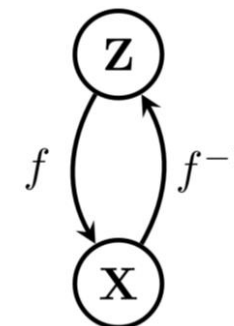
Explainable

PCs



Tractable

Normalizing flows



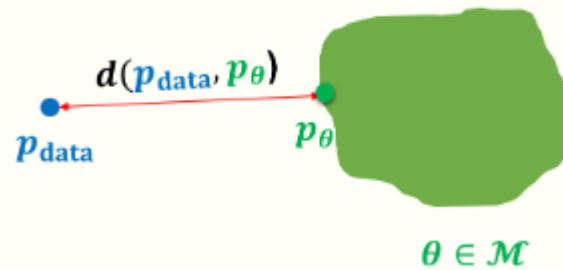
Expressive

# Learning Probability Distributions

The curse of dimensionality & continuous spaces



$$\mathbf{x}^{(j)} \sim p_{\text{data}} \\ j = 1, 2, \dots, |\mathcal{D}|$$



- Typical image resolution – 700 x 1400
- Each pixel has 3 channels - RGB
- Each channel can take values 0-255

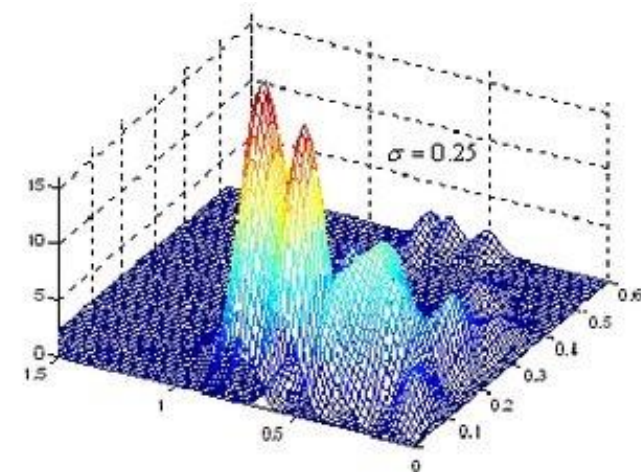
**How many possible images?**

$$256^{700 \times 1400 \times 3} \approx 10^{800000}$$

What if the data was continuous ?

- Infinite no. of values
- Complex shapes for probability densities

**We have only a limited amount of data to fit the model**



# Give up ?

Not yet. Look at these images .. Can you say which of them are real ?

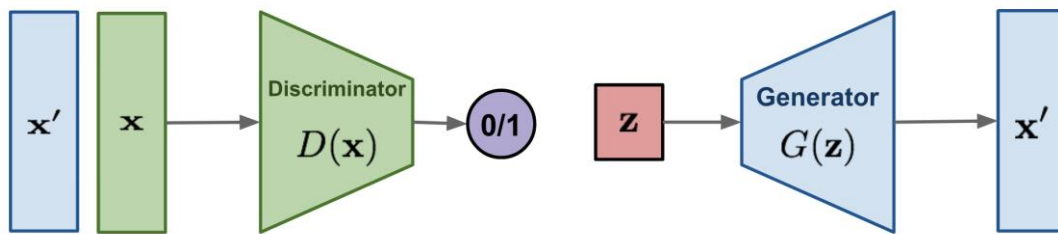


All of them are generated by a model. **None of these people exist in real life !**

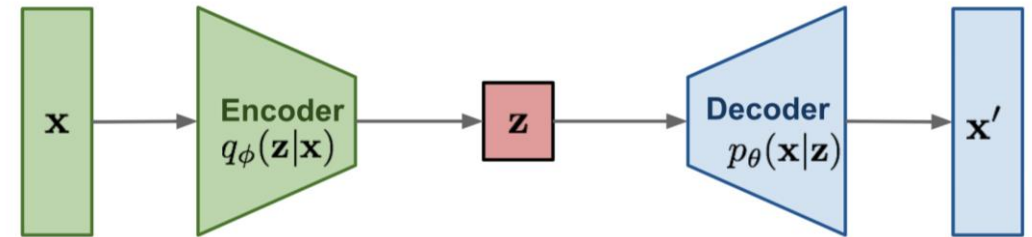
# Deep Generative Models

Using **deep neural networks** to learn **probability** distributions

- Deep latent variable models
  - Assume a simple distribution over low dimensional latent factors of variation
  - Map to data space using neural networks



**Generative Adversarial Networks (GANs)**



**Variational Auto Encoders (VAEs)**

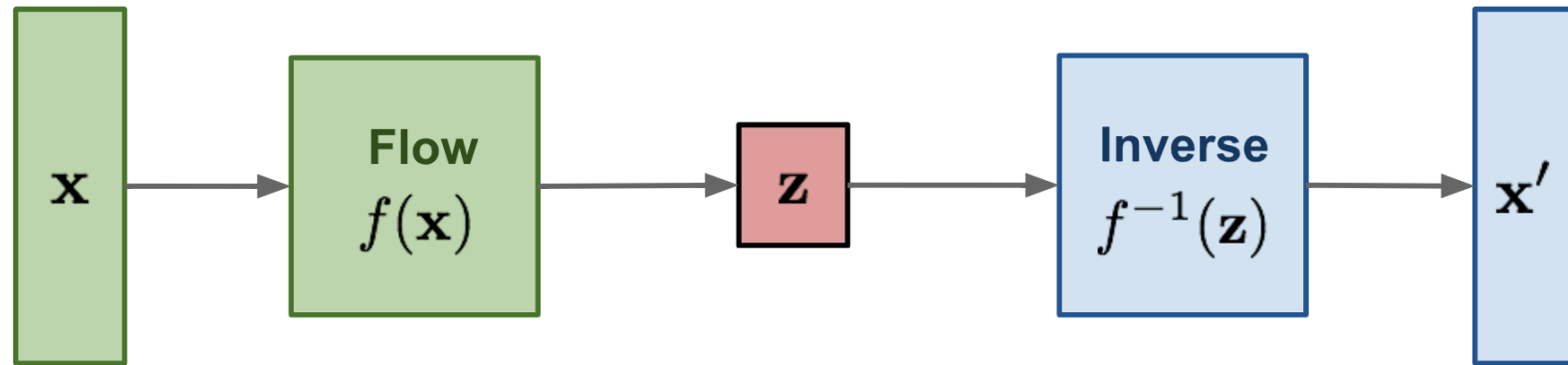
**Expressive** models, can generate high quality samples

But **cannot** perform exact **inference** over the modeled probability distribution

# Normalizing flows

A new class of **deep generative** model

- Utilizes invertible transformations



Why are they exciting?

- **Expressive** models utilizing flexible neural networks
- Can perform **exact likelihood evaluation**

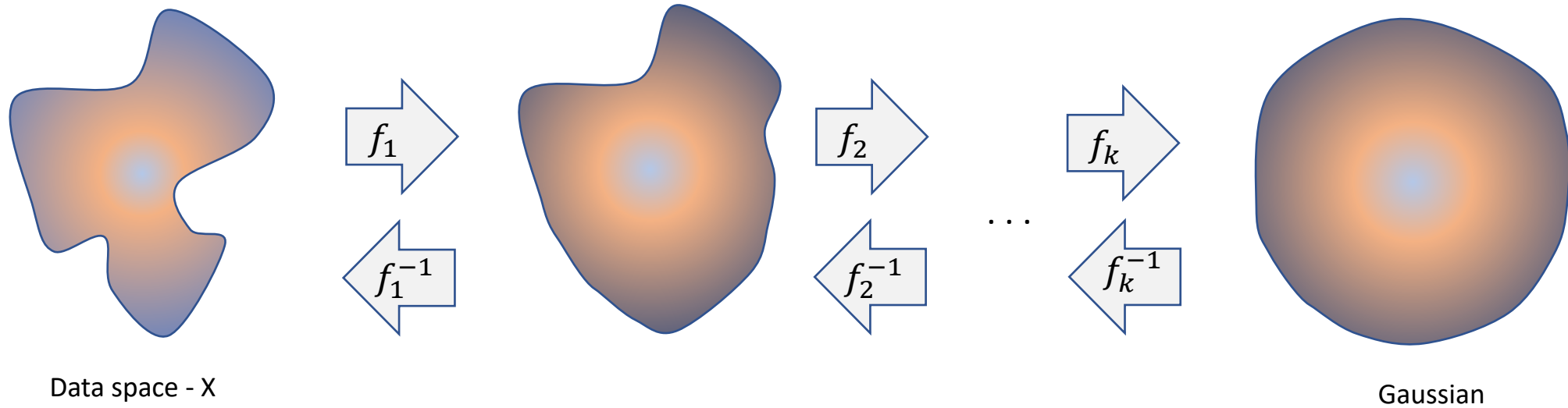


# Some cool results using normalizing flows



Almost as **good** as GANs / VAEs but better **tractability**

# Normalizing Flows: Overview



Model **complex** probability distributions by

- flowing a simple distribution through a sequence of **invertible transformations**

Components

- Simple base distribution – typically a gaussian
- **Invertible** Transformation – parameterized using neural networks



# Normalizing Flows: Formulation

**Change of variables:** Linking the probability densities in the two spaces

$$p_X(x) = \underbrace{p_Z(f(x))}_{\text{Density in the gaussian space}} \underbrace{|\det(J_f(x))|}_{\text{Volume correction term}}, \text{ where } J_f(x) = \frac{\partial f(x)}{\partial x}$$

## Properties

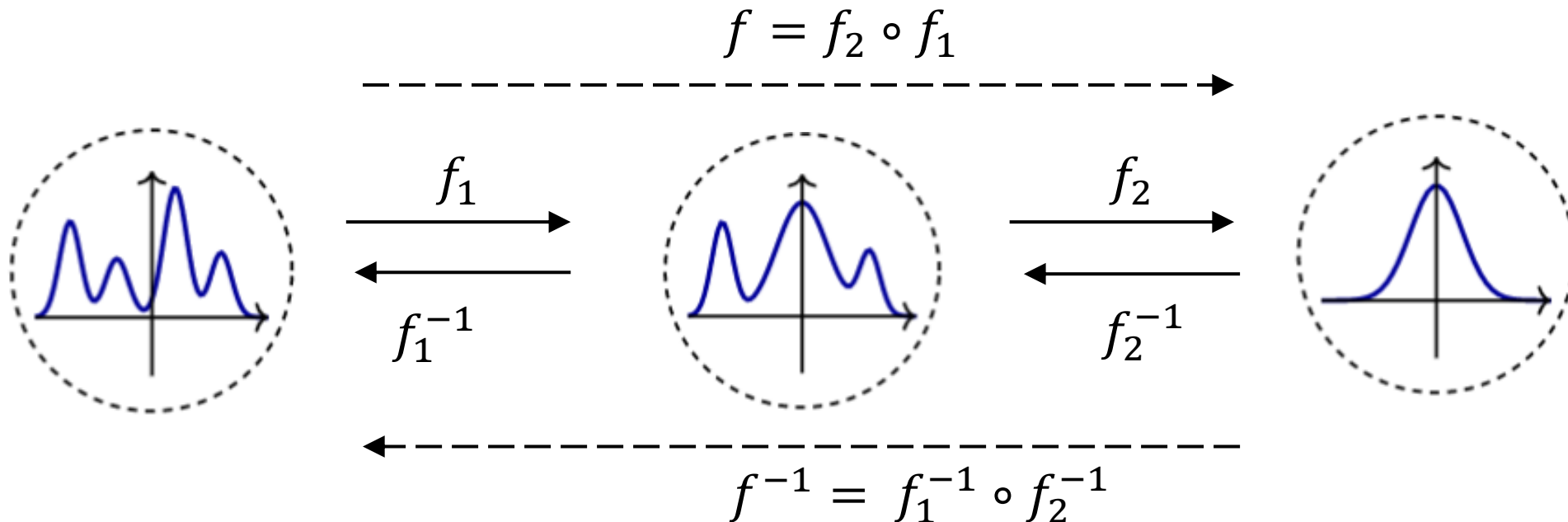
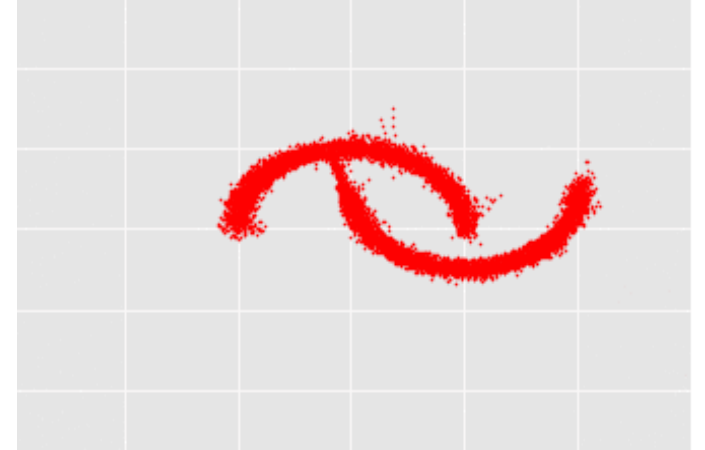
A flow  $f$  is a parametric function which is

- Invertible
- Differentiable
- Has efficiently computable Jacobian determinant

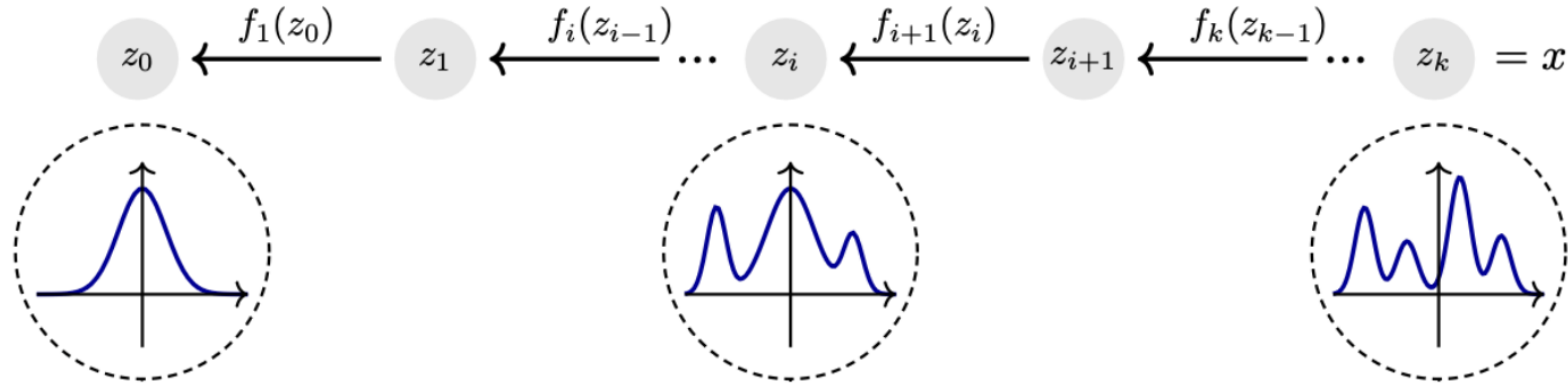
Designing such functions is the core research problem in the field of flows

# Why are they called **normalizing flows** ?

- Composing transformations
  - Invertible differentiable functions are closed under composition
- Can slowly 'flow' a complex distribution step by step into a normal



# How do you train them?



We can compute likelihood exactly

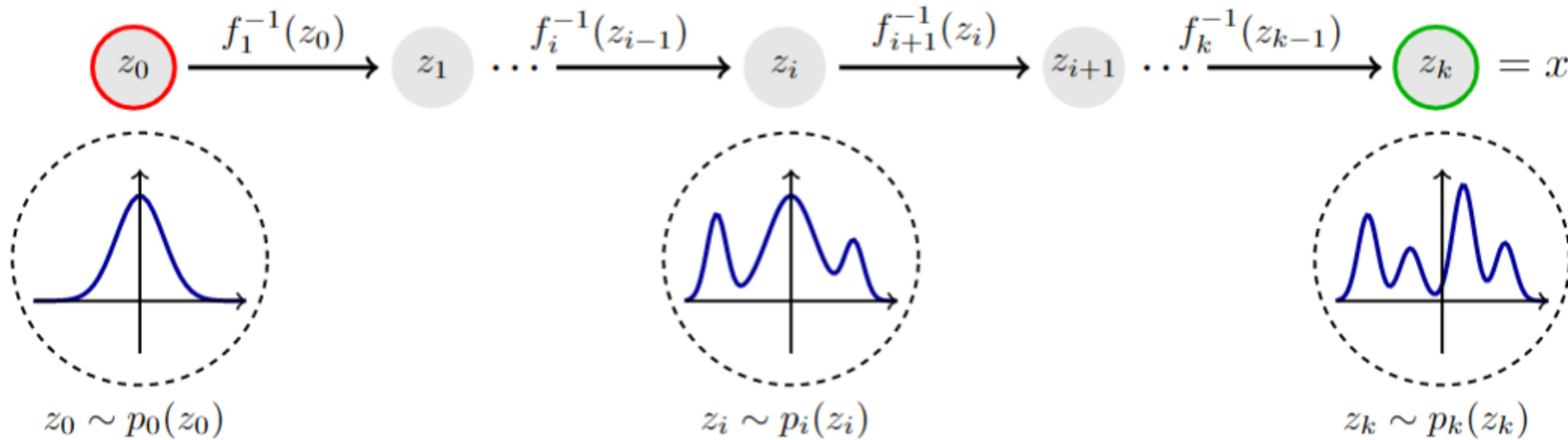
$$\begin{aligned} p_X(x) &= p_Z(f(x)) |\det(J_f(x))| &= p_Z(f_1 \circ f_2 \circ \dots \circ f_k(x)) |\det(J_{f_1 \circ f_2 \circ \dots \circ f_k}(x))| \\ &= p_Z(f_1 \circ f_2 \circ \dots \circ f_k(x)) \prod_i |\det(J_{f_i})| \end{aligned}$$

Maximize the log-likelihood of the data points w.r.t to the parameters of the flow

$$\arg \max_{\theta} \sum_m \log p_X(x_m) = \arg \max_{\theta} \sum_m \log p_Z(f_{\theta}(x_m)) + \sum_m \sum_i \log |\det(J_{f_{\theta_i}})|$$

$f$  is differentiable, solve using **gradient descent**

# Tractable for what ?



- **Sampling**
  - Sample from gaussian and apply inverse transform
- **Density estimation**
  - Use change of variables formula to compute  $p_X(x)$  exactly.

✓ Evidential	✗ Marginal	✗ Conditional	✗ MAP
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# Parameterizing flow transformations

## Linear Flows

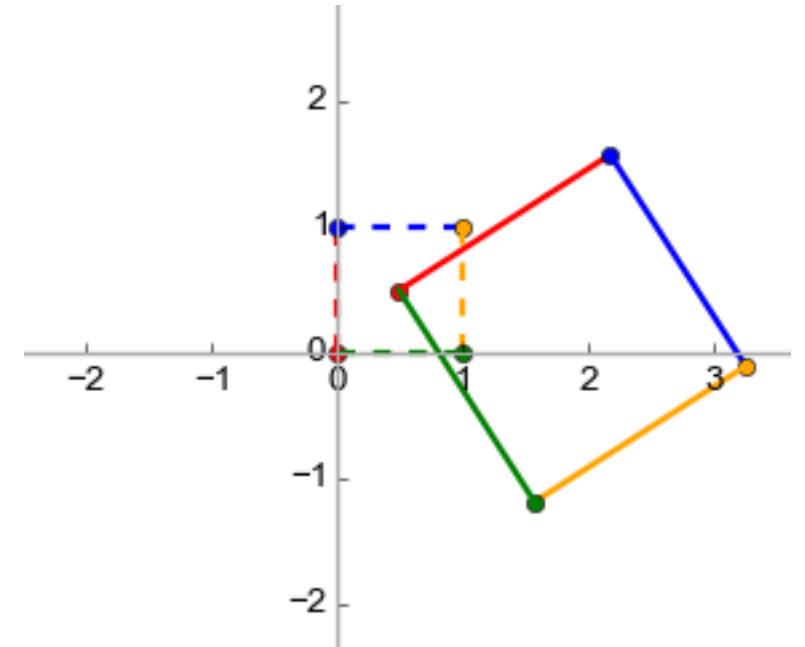
We can define a flow using a linear transformation if the matrix is invertible

$$f(\mathbf{x}) = A\mathbf{x} + b$$

- **Inverse:**  $f^{-1}(\mathbf{z}) = A^{-1}(\mathbf{z} - b)$
- **Jacobian** is same as  $A$ . Thus,  $\det J_f = \det A$

### Caveats

- Will have to ensure invertibility during learning
- Affine gaussians are gaussians! Not quite **expressive**.
- Determinant computation is expensive  $O(d^3)$





# Coupling Flows

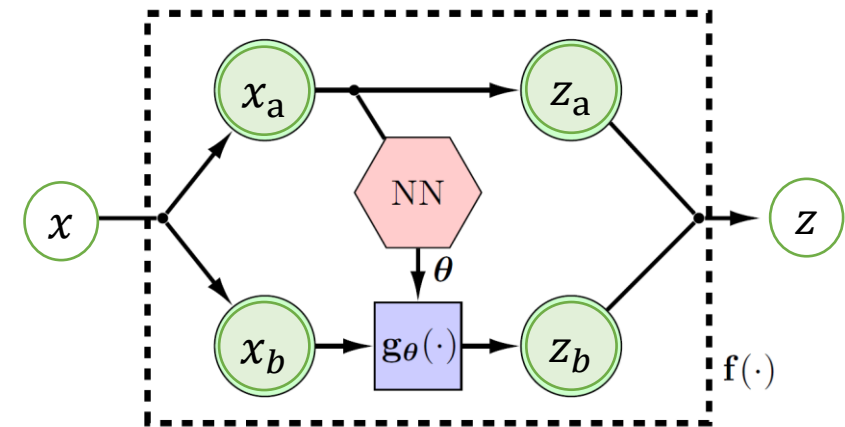
A general approach to building more **expressive** Non-linear flows

Partition the input into two disjoint sets  $\mathbf{x} = (\mathbf{x}_A, \mathbf{x}_B)$

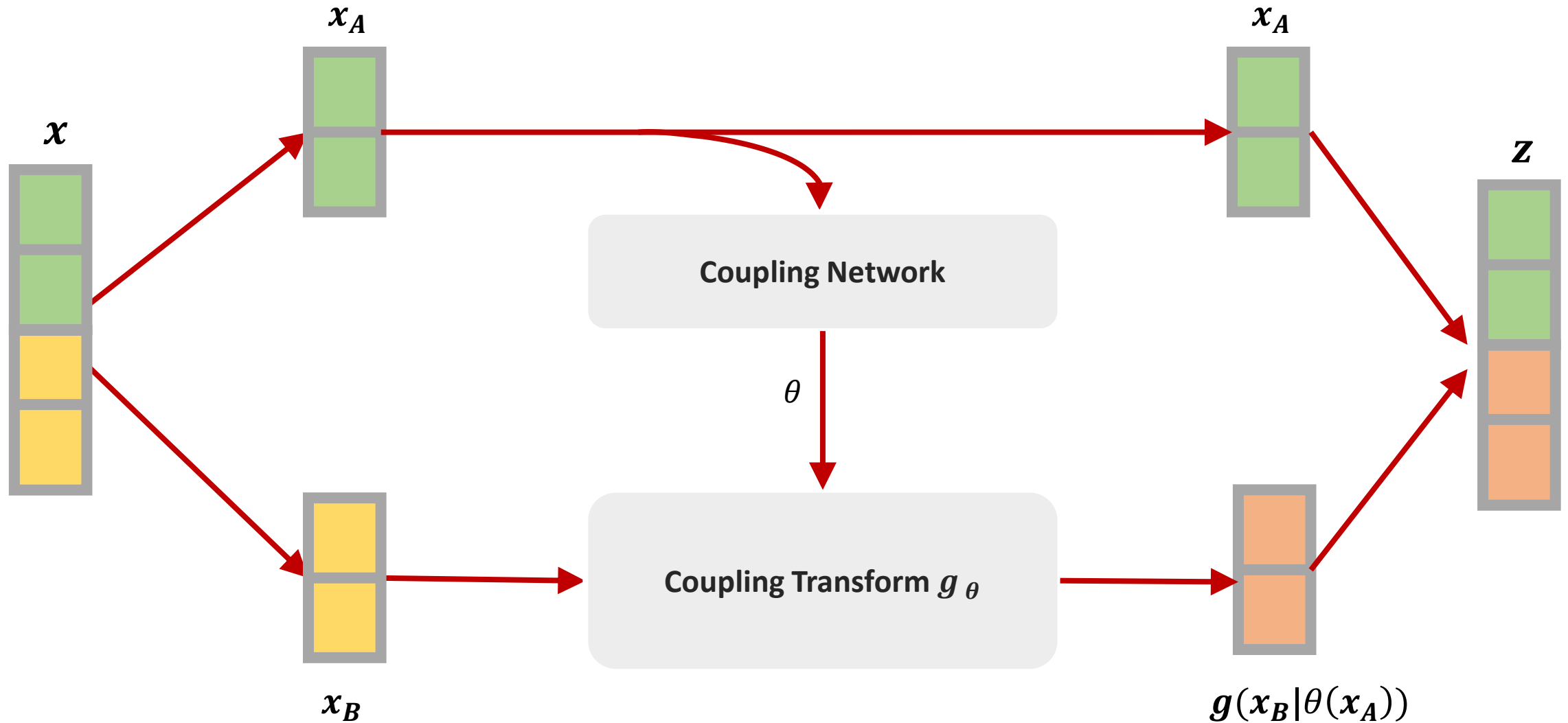
Define  $f(\mathbf{x}) = (\mathbf{x}_A, g(\mathbf{x}_B | \theta(\mathbf{x}_A)))$

$g$  is an invertible transformation whose parameters depend on  $\mathbf{x}_A$

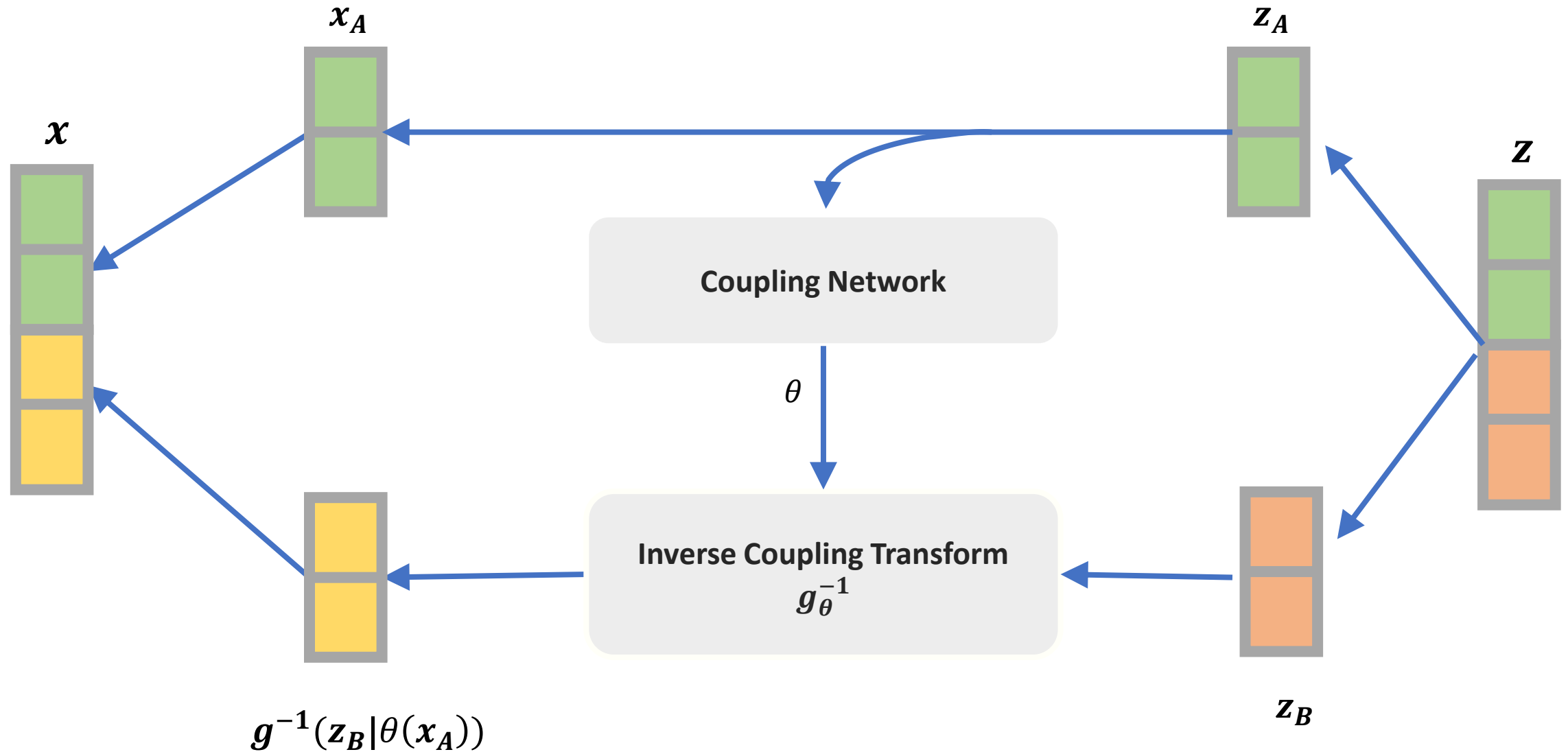
- Will use this as a case study demonstrate the key properties
  - invertibility
  - efficiently Jacobian determinant
- Also implement in hands on part



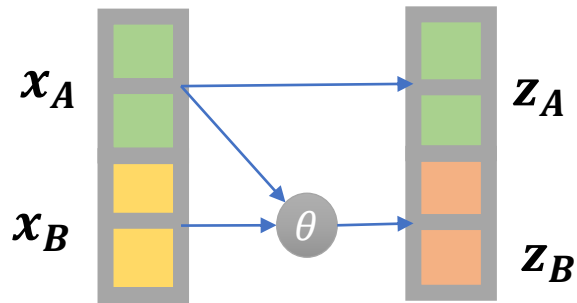
# Coupling Flow: The **forward** transformation



# Coupling Flow: The **inverse** transformation



# Coupling Flow: **Jacobian**



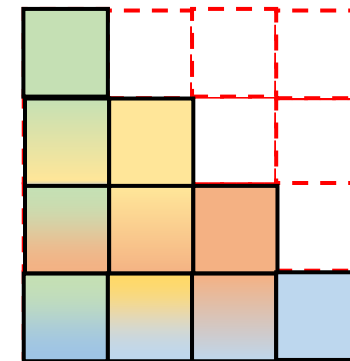
$$J_f(\mathbf{x}) = \begin{bmatrix} \frac{\partial z_A}{\partial x_A} & \frac{\partial z_A}{\partial x_B} \\ \frac{\partial z_B}{\partial x_A} & \frac{\partial z_B}{\partial x_B} \end{bmatrix} = \begin{bmatrix} \mathbb{I} & 0 \\ \boxed{\frac{\partial g(x_B | \theta(x_A))}{\partial x_A}} & J_g \end{bmatrix}$$

We don't need this for determinant!

$\theta$  can be an arbitrarily complex (non-invertible) model like a neural network

Block diagonal jacobian, determinant computation is efficient

$O(d)$



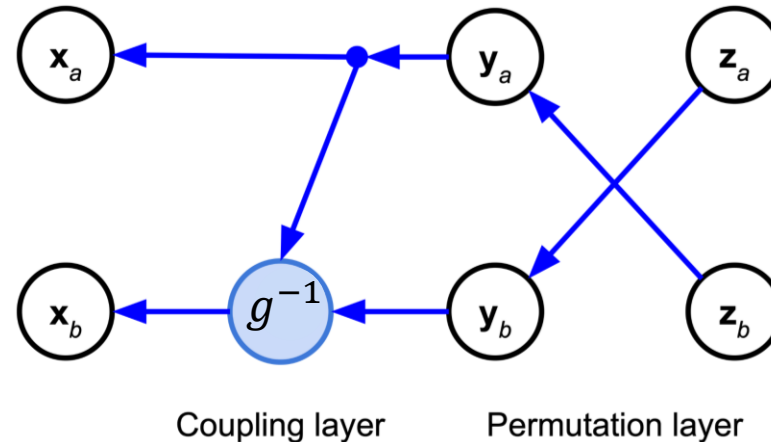
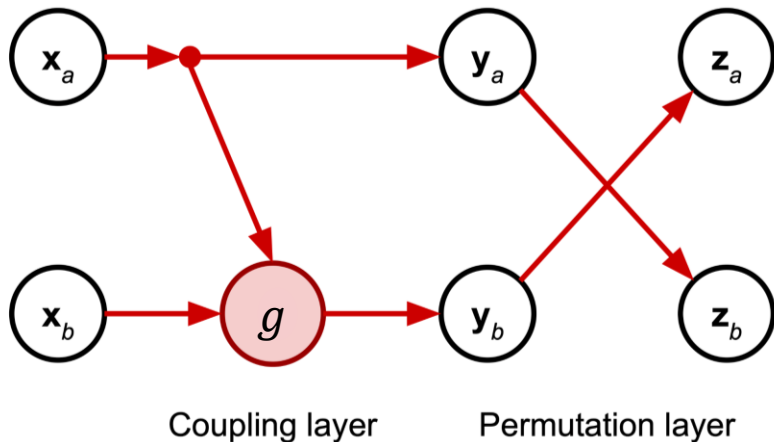
# Coupling Transforms

Just Compose ?

Needs permutations between flow layers to utilize the entire space

- Permutation is an invertible linear operation
  - Has unit determinant

$$\underbrace{\begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}}_{\mathbf{P}^T \text{ matrix}} \cdot \underbrace{\begin{bmatrix} 4 & 6 & 8 & 1 \\ 5 & 3 & 1 & 0 \\ 7 & 21 & 0 & 9 \\ 3 & -4 & 1 & 3 \end{bmatrix}}_{\mathbf{A} \text{ matrix}} = \underbrace{\begin{bmatrix} 3 & -4 & 1 & 3 \\ 4 & 6 & 8 & 1 \\ 5 & 3 & 1 & 0 \\ 7 & 21 & 0 & 9 \end{bmatrix}}_{\mathbf{P}^T \cdot \mathbf{A} \text{ matrix}}$$





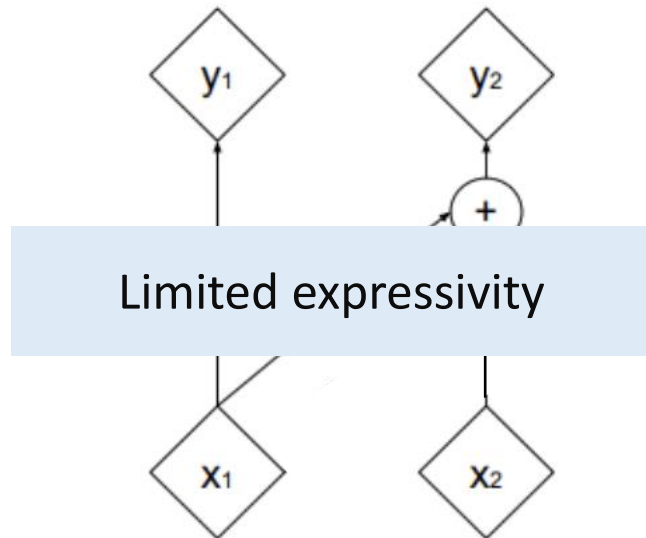
# Coupling Transforms

Defining Coupling transforms  $g$  ..

**Simple** invertible transformations suffice

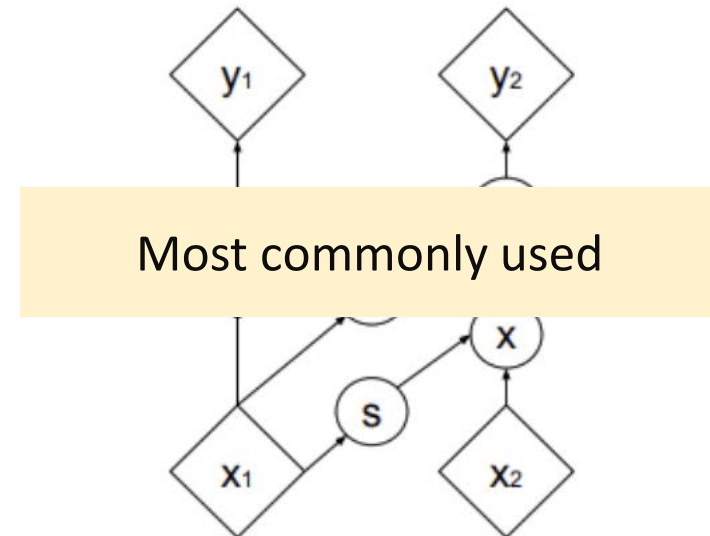
- **Additive** [NICE-Dinh et al., 2014]

- $g(x|t) = x + t$
- $g^{-1}(z|t) = z - t$



- **Affine** [RealNVP-Dinh et al., 2017]

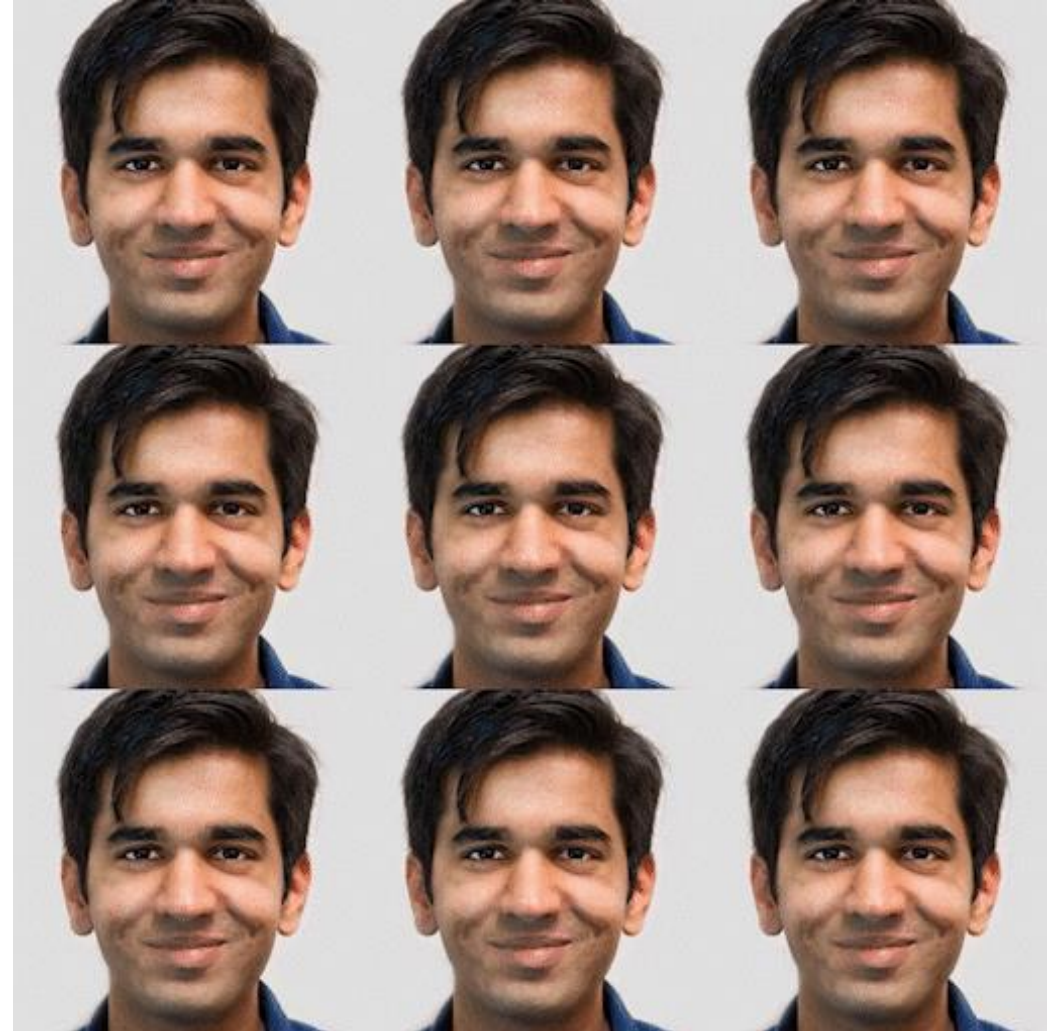
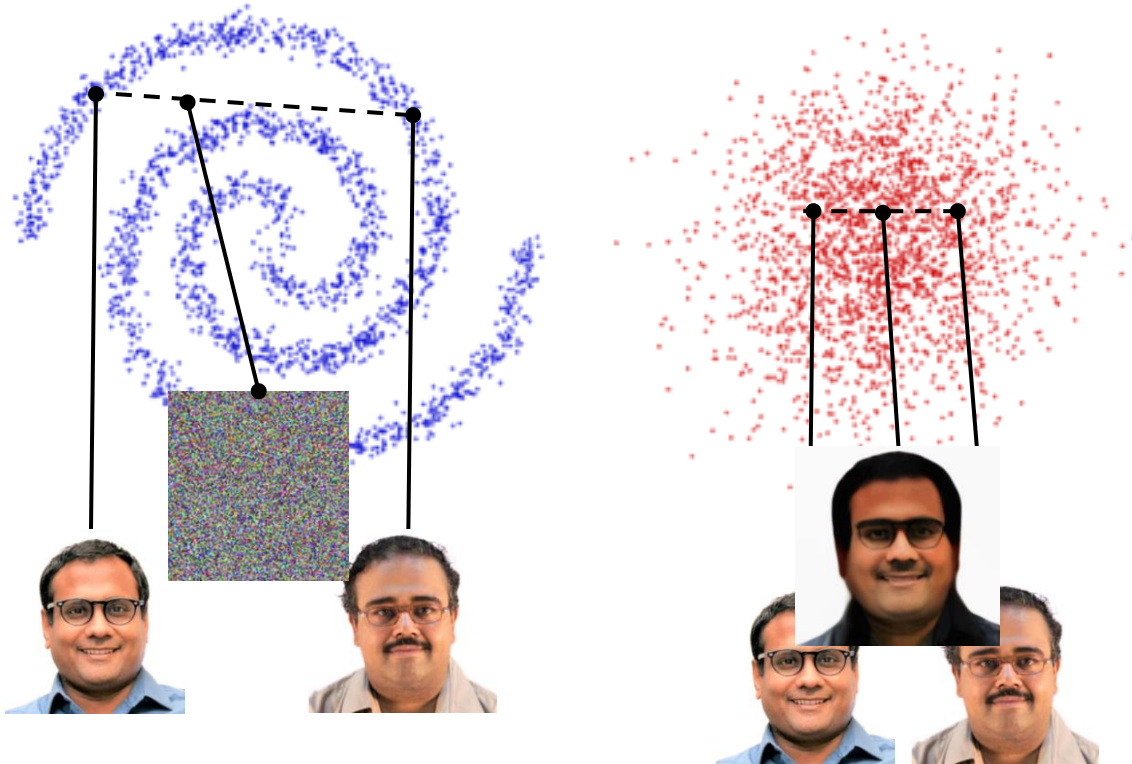
- $g(x|s, t) = \exp(s) \odot x + t$
- $g^{-1}(z|s, t) = \exp(s)^{-1} \odot (z - t)$



Can have more complex coupling transform formulations .. MLP, splines, etc. [Kingma et al., 2016, Huang et al., 2018; de Cao et al., 2019; Durkan et al., 2019]

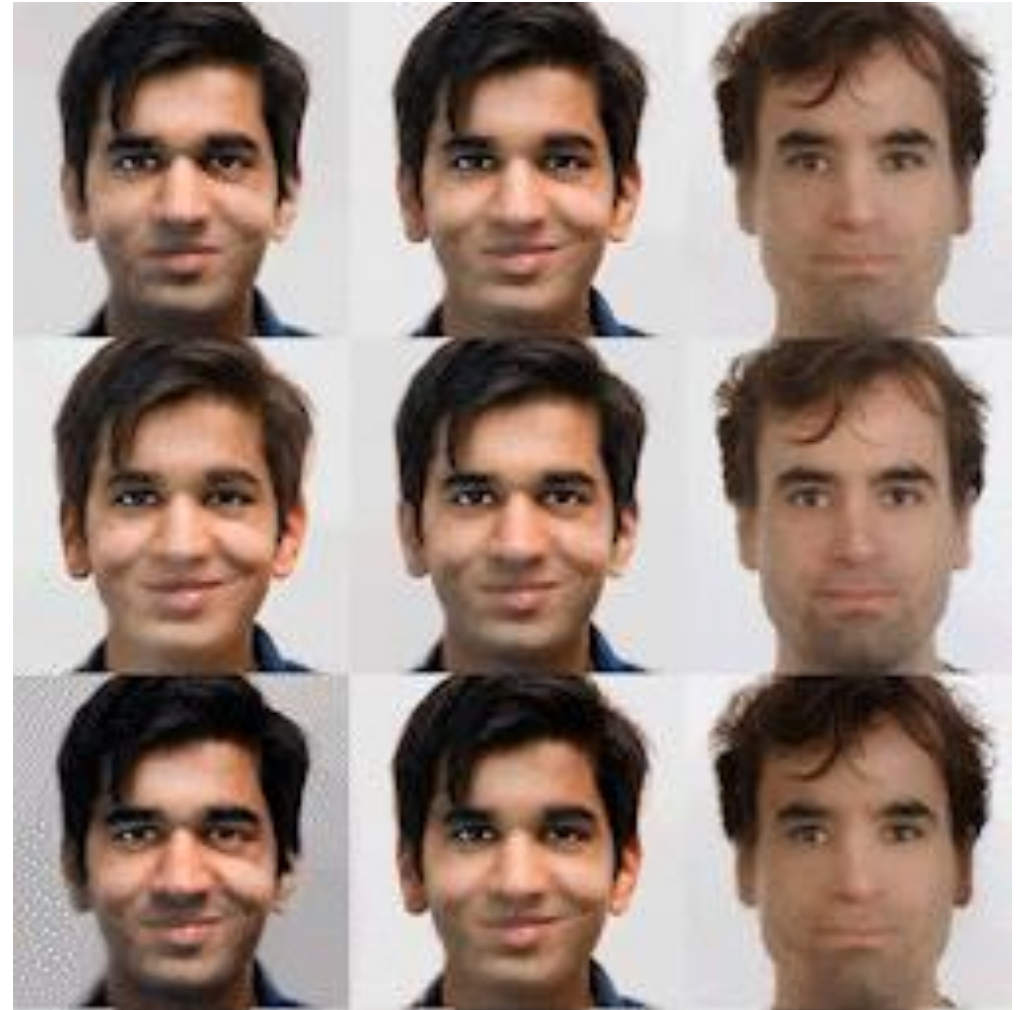
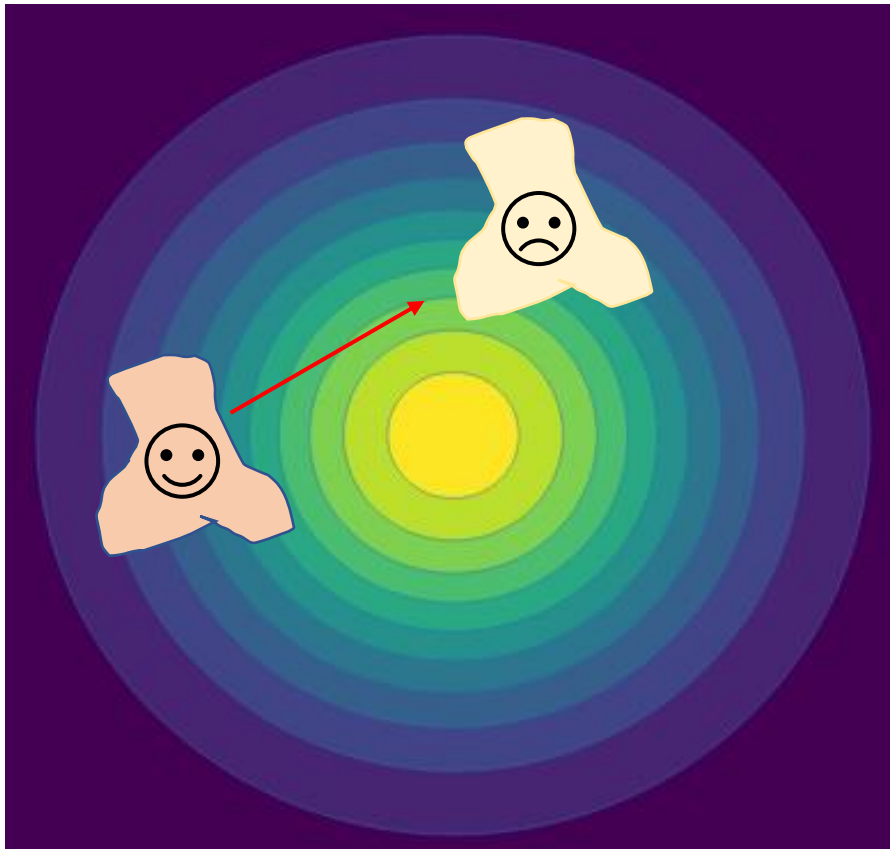
# Utilizing the **latent space** of the flow

Can Interpolate between points in the latent space



# Utilizing the **latent space** of the flow

Manipulate semantic features by moving in certain directions of the latent space



# Normalizing Flows

## Hands-On Demo

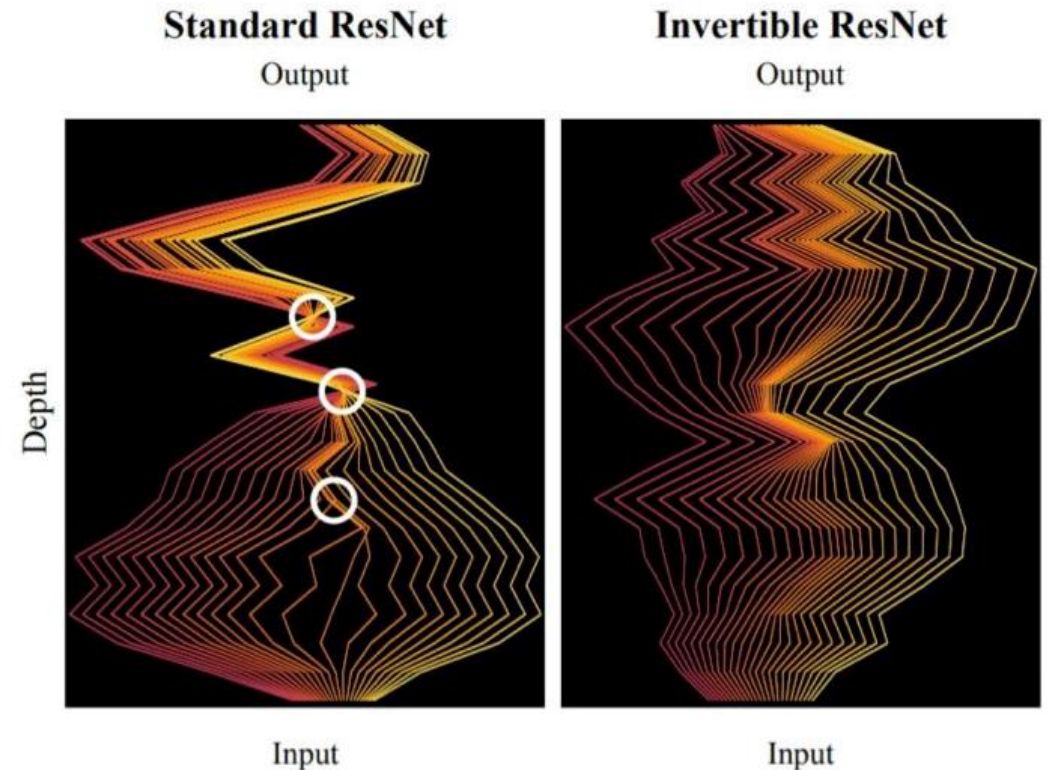
<https://bit.ly/tpm-day2-flows>





# Conclusion

- Other approaches
  - Discrete time invertible transforms
    - Contractive Flows [Behrmann et al. 2019, Perugachi-Diaz et. Al 2020, Chen et al.]
  - Continuous time invertible transforms
    - Neural ODE flows [Grathwohl et al. 2018]
- Limitations and takeaways
  - Tractability compared to PCs
  - Dimensionality preserving
  - Topological restrictions of diffeomorphisms





# Some Resources on Flows

## Review Paper

Papamakarios, G., Nalisnick, E., Rezende, D. J., Mohamed, S., & Lakshminarayanan, B. (2021). **Normalizing flows for probabilistic modeling and inference**. *The Journal of Machine Learning Research*,

## Tutorial

Normalizing Flows and Invertible Neural Networks in Computer Vision, CVPR 2021 by Marcus A. Brubaker, Ullrich Köthe

## Github Repo

[janosh / awesome-normalizing-flows](#) Public

# Thank You!