

# Locally Differentially Private Distributed Deep Learning via Knowledge Distillation (2022)

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## Contributions

1. A fully trusted aggregator barely exists
  2. Less efficient and not scalable
  3. At least two non-colluding honest data users might not be practical
- A novel, effective and efficient privacy-preserving distributed deep learning framework using LDP and Knowledge-Distillation.
  - An active sampling approach to efficiently reduce the total number of queries from the data user to each data owners, so that to reduce the total cost of privacy budget.

## Method

- Each data owner perturbs the query data's soft label (using LDP techniques)
- LDP -> piecewise Mechanism

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**Algorithm 2:** Piecewise Mechanism for One-Dimensional Numerical Data (PM-ONE) 13

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**Input:** tuple  $z_i \in [-1, 1]$ ; privacy budget  $\epsilon$ .

**Output:** perturbed tuple  $z'_i \in [-\Delta, \Delta]$ .

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1  $\Delta \leftarrow \frac{e^{\epsilon/2} + 1}{e^{\epsilon/2} - 1}$ ;  
2  $L(z_i) \leftarrow \frac{\Delta + 1}{2} \cdot z_i - \frac{\Delta - 1}{2}$ ;  
3  $R(z_i) \leftarrow L(z_i) + \Delta - 1$ ;  
4 Sample value  $v$  uniformly at random from  $[0, 1]$ ;  
5 if  $v < \frac{e^{\epsilon/2}}{e^{\epsilon/2} + 1}$  then  
6   | Sample  $z'_i$  uniformly at random from  
   |  $[L(z_i), R(z_i)]$ ;  
7 else  
8   | Sample  $z'_i$  uniformly at random from  
   |  $[-\Delta, L(z_i)] \cup [R(z_i), \Delta]$ ;  
9 return  $z'_i$ .
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**Algorithm 3:** Piecewise Mechanism for Multidimensional Numerical Data (PM) [13]
 

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**Input:** tuple  $z \in [-1, 1]^k$ ; privacy budget  $\epsilon$ .  
**Output:** perturbed tuple  $z' \in [-k \cdot \Delta, k \cdot \Delta]^k$ .  
 1  $z' \leftarrow \langle 0, 0, \dots, 0 \rangle$ ;  
 2  $m \leftarrow \max\{1, \min\{k, \lfloor \frac{\epsilon}{2.5} \rfloor\}\}$ ;  
 3 Sample  $m$  values uniformly without replacement from  $\{1, 2, \dots, k\}$ ;  
 4 **for** each sampled attribute  $j$  **do**  
 5    $z'_j = \frac{k}{m} \cdot \text{PM-ONE}(z_j, \frac{\epsilon}{m})$ ;  
 6 **return**  $z'$ .

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- Knowledge Distillation -> Active query sampling

- 1) Select an initial subset of  $S$  unlabeled public data  $X^Q$  uniformly at random from  $X^P$ . Update  $X^P \leftarrow X^P - X^Q$ .
- 2) Use  $X^Q$  to query the teacher models, and use the distilled knowledge to train the student initial student model  $M_S$ .
- 3) For each available public data  $x_i \in X_P$ , evaluate it on the student model  $M_S$ . Let  $P_{ij}$  denote the probability of  $x_i$  belonging to class  $j \in \{1, 2, \dots, k\}$  predicted by  $M_S$ . Let  $P_i = \{P_{i1}, P_{i2}, \dots, P_{ik}\}$ , and suppose  $\sum_{l=1}^k P_{il} = 1$ . Let  $P_i^*$  be the largest value (posterior probability) in  $P_i$ . Then, repeat the procedure below for  $S$  times to select  $S$  query samples:

$$\begin{aligned}
 x_i &\leftarrow X^P \\
 P_i &\leftarrow M_S(x_i) \\
 X^Q &\leftarrow X^Q \cup \underset{x_i}{\operatorname{argmin}} \frac{1}{m-1} \sum_{l=1}^k (P_i^* - P_{il}) \\
 X^P &\leftarrow X^P - X^Q
 \end{aligned} \tag{5}$$

Then, use  $X^Q$  to query the teacher models, and use the distilled knowledge to train the student initial student model  $M_S$ .

- 4) Repeat 3), until the student model meet the performance requirement or no more public data available (i.e.,  $X_P = \emptyset$ ).

## Experimental

- CIFAR-10/MNIST/Fashion-MNIST with LDP -> Piecewise mechanism /Duchi's mechanism /Laplace mechanism
- LDP-DL -> (SOTA) DP-SGD/PATE/DP-FL

Datasets	CIFAR10 [16]		MNIST [17]		FashionMNIST [18]	
Approaches	Accuracy	Privacy Budget	Accuracy	Privacy Budget	Accuracy	Privacy Budget
LDP-DL	77.5%	5	98.1%	5	83.4%	5
	79.7%	8	98.8%	8	85.7%	8
DP-SGD [15]	73.0%	8	97.00%	8	-	-
PATE [10]	73.6%	5	97.7%	5	81.5%	5
	76.0%	8	98.2%	8	84.7%	8
DP-FL [12]	75.9%	5	96.4%	5	82.6%	5
	78.7%	8	97.2%	8	83.6%	8

TABLE 1: In Comparison with Existing Approaches.