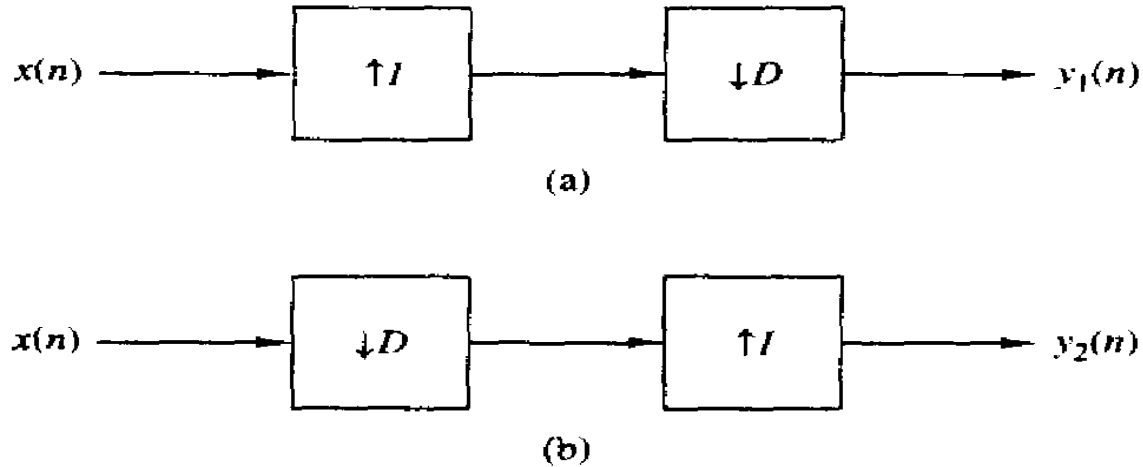


# DSP Tutorial-5

# Discussion

Q1) Considering the two different ways of cascading a decimator with an interpolator shown in figure.



- a) If  $D = I$ , show that output of the two configuration are different i.e. the systems are not identical.
- b) Show that the two systems are identical if and only if  $D$  and  $I$  are relatively prime number.

Ans-a)

$$x(n) = \{x_0, x_1, x_2, \dots\}$$

$D = I = 2$ . Decimation first

$$z_2(n) = \{x_0, x_2, x_4, \dots\}$$

$$y_2(n) = \{x_0, 0, x_2, 0, x_4, 0, \dots\}$$

Interpolation first

$$z_1(n) = \{x_0, 0, x_1, 0, x_2, 0, \dots\}$$

$$y_1(n) = \{x_0, x_1, x_2, \dots\}$$

$$\text{so } y_2(n) \neq y_1(n)$$

(b) suppose  $D = dk$  and  $I = ik$  and  $d, i$  are relatively prime.

$$x(n) = \{x_0, x_1, x_2, \dots\}$$

Decimation first

$$z_2(n) = \{x_0, x_{dk}, x_{2dk}, \dots\}$$

$$y_2(n) = \left\{ x_0, \underbrace{0, \dots, 0}_{ik-1}, x_{dk}, \underbrace{0, \dots, 0}_{ik-1}, x_{2dk}, \dots \right\}$$

Interpolation first

$$z_1(n) = \left\{ x_0, \underbrace{0, \dots, 0}_{ik-1}, x_1, \underbrace{0, \dots, 0}_{ik-1}, x_2, \underbrace{0, \dots, 0}_{ik-1}, \dots \right\}$$

$$y_1(n) = \left\{ x_0, \underbrace{0, \dots, 0}_{d-1}, x_d, \underbrace{0, \dots, 0}_{d-1}, \dots \right\}$$

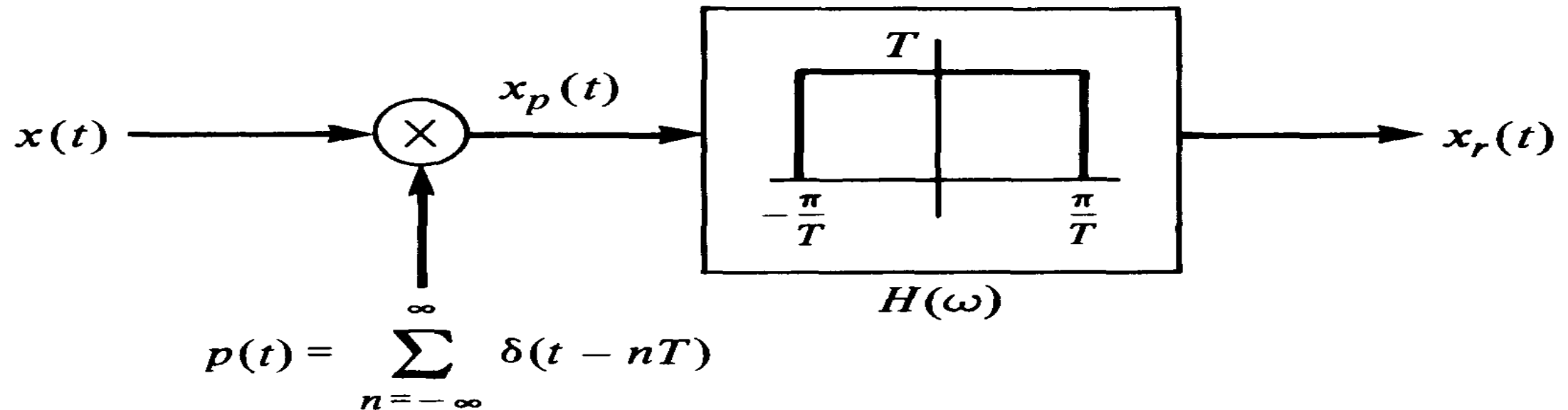
Thus  $y_2(n) = y_1(n)$  iff  $d = dk$  or  $k = 1$  which means that  $D$  and  $I$  are relatively prime.

Q.2. Consider the following system. The sampling period  $T = 1\text{ms}$  and  $x(t) = \cos(2\pi f_0 t + \theta)$ . Determine  $x_r(t)$  for each of the following:

a)  $f_0 = 250\text{Hz}$ ,  $\theta = \pi/4$

b)  $f_0 = 750\text{Hz}$ ,  $\theta = \pi/2$

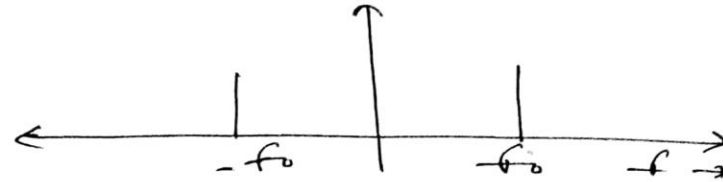
c)  $f_0 = 500\text{Hz}$ ,  $\theta = \pi/2$



Ans-

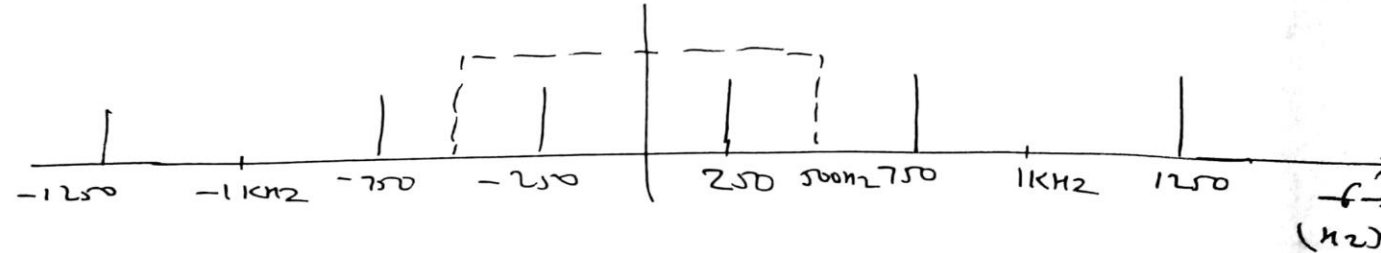
$$\rightarrow x(t) = \cos(2\pi f_0 t + \theta)$$

$$\Rightarrow x(t) = \frac{\delta(t - f_0) + \delta(t + f_0)}{2}$$



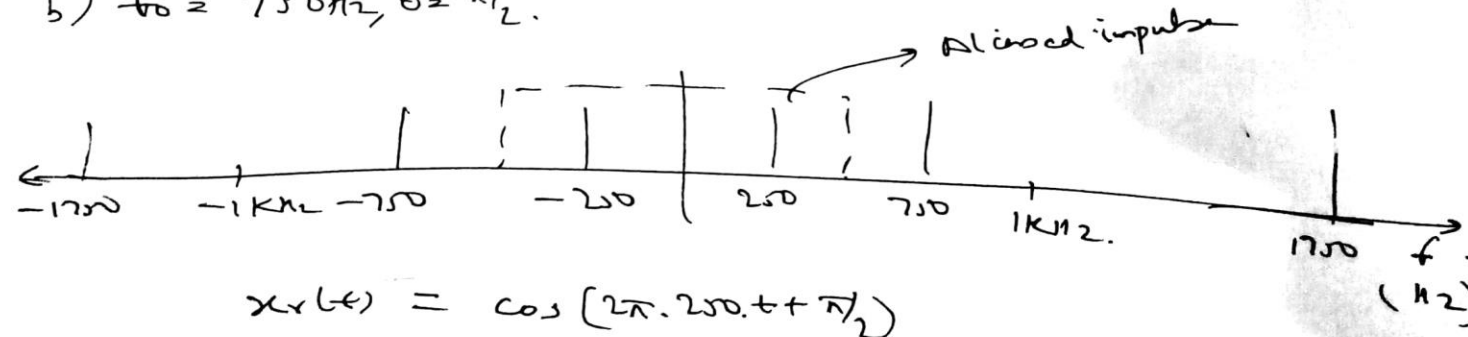
a)  $f_0 = 250 \text{ Hz}$ ,  $\theta = \pi/4$ ,  $T = 1 \text{ ms} \Rightarrow f_s = 1 \text{ kHz}$ .

$$x_p(f) =$$



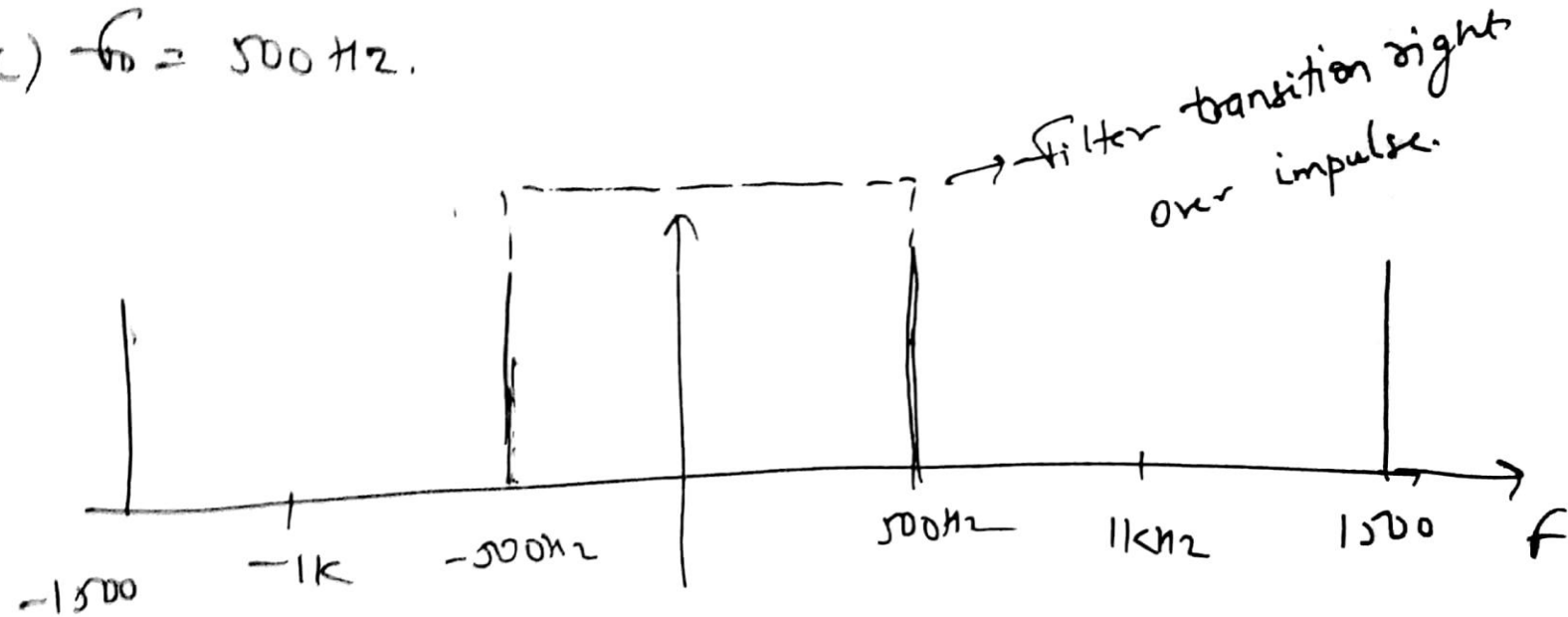
$$\Rightarrow x_r(t) = \cos(2\pi \cdot 250 t + \pi/4)$$

b)  $f_0 = 750 \text{ Hz}$ ,  $\theta = \pi/2$ .



$$x_r(t) = \cos(2\pi \cdot 250 t + \pi/2)$$

c)  $f_0 = 500 \text{ Hz}$ .

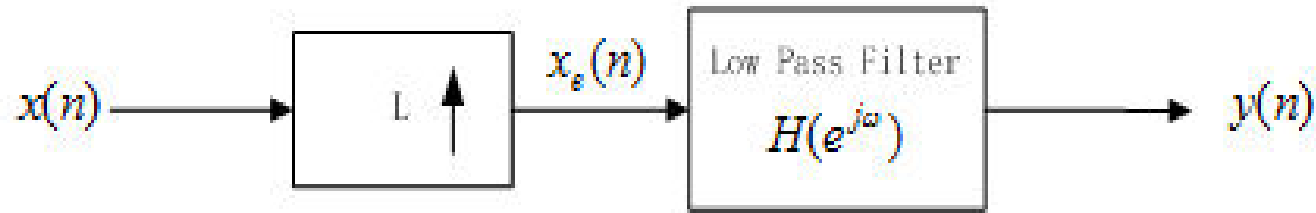


$x_r(t) = 0$  [As filter transition is over frequency response of  $x(t)$ ].

# Question

10 min

Q1)The system diagram is as follows.

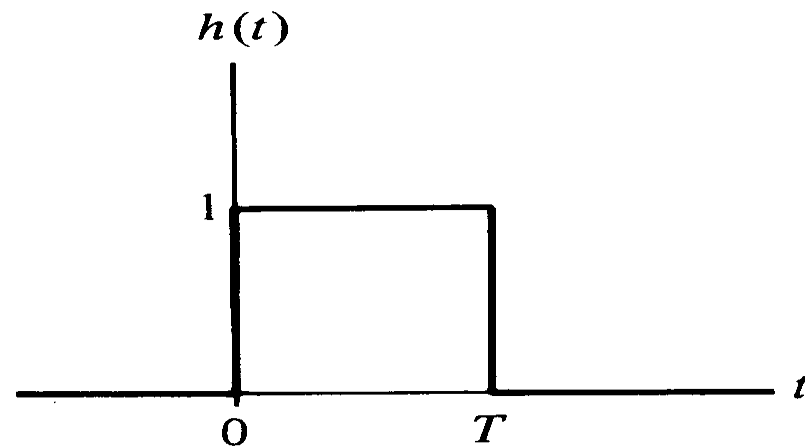
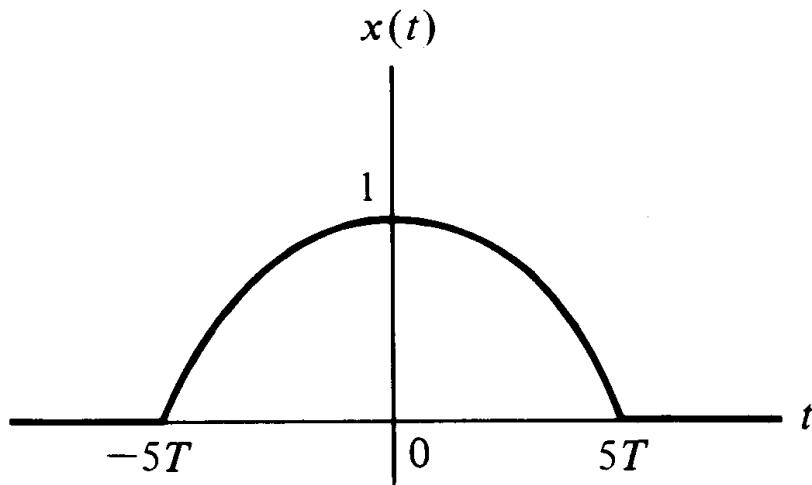
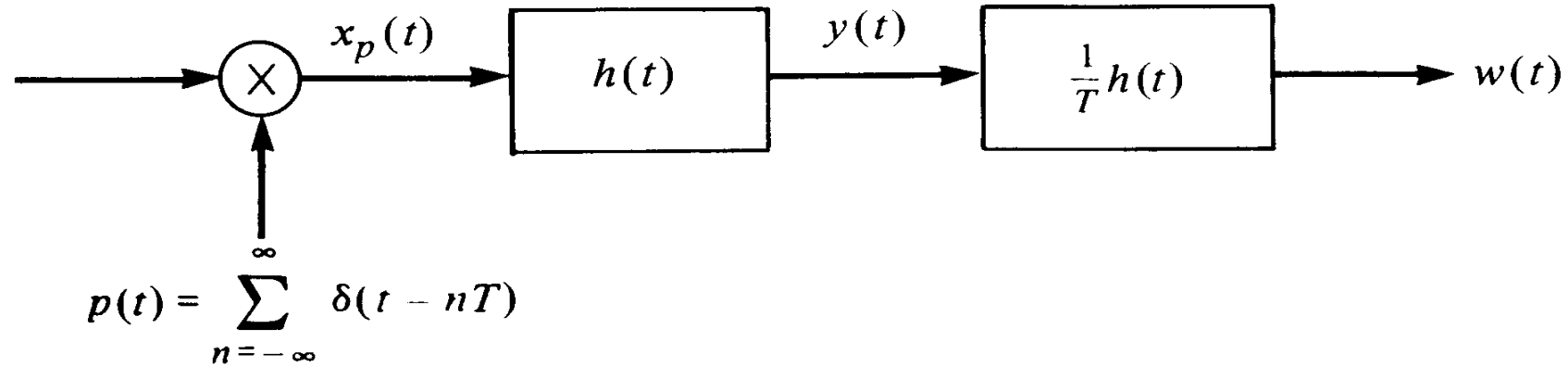


In order to get rid of aliasing, what is the cut-off frequency of the low pass filter? Explain your answer



10 min

Q.2. Consider the following system given in the figure where input is  $x(t)$ . Here,  $p(t)$  is an impulse train. Sketch  $x_p(t)$ ,  $y(t)$  and  $w(t)$ .



**Q3) Consider the signal  $x(n) = a^n u(n)$ ,  $|a| < 1$ .**

**(a) Determine the spectrum  $X(\omega)$ .**

**(b) The signal  $x(n)$  is applied to a decimator that reduces the rate by a factor of 2. Determine the output spectrum.**

**(c) Show that the spectrum in part (b) is simply the Fourier transform of  $x(2n)$ .**

Ans 1)

Let  $X(e^{j\omega}), X_e(e^{j\omega}), Y(e^{j\omega})$  is the DTFT of  $x(n), x_e(n), y(n)$ .

Then  $X(e^{j\omega})$  has a period of  $2\pi$ .

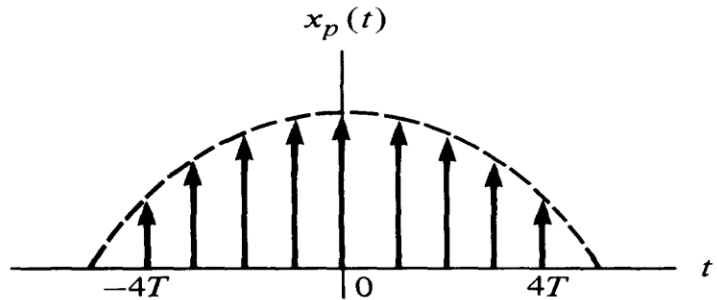
After the up sampling, all the original information of  $x(n)$  will be contained in the interval  $[-\pi/L, \pi/L]$ .

New aliases occur in the interval of  $[-\pi, -\pi/L], [\pi/L, \pi]$  which need to be filtered out.

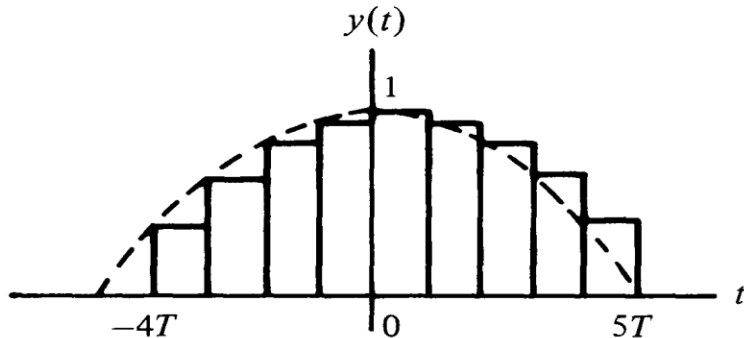
Thus, the cut-off frequency of the LP filter is  $\pi/L$ .

Ans 2)

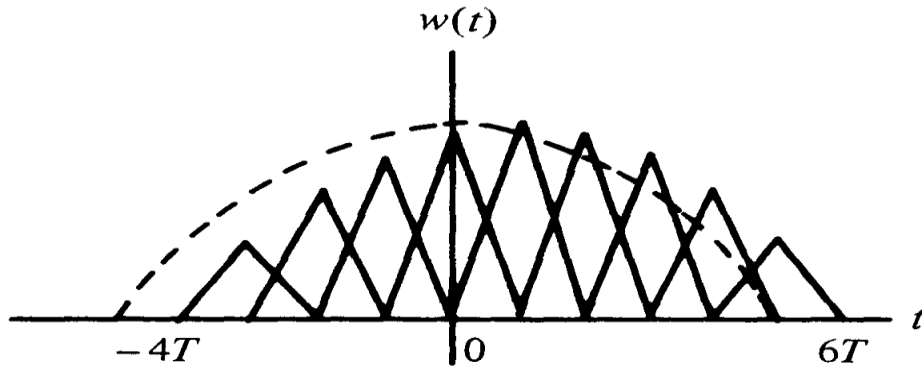
The signal  $x_p(t)$  can be drawn as,



Now,  $y(t) = x_p(t) * h(t)$ . Hence, we can draw  $y(t)$  as,

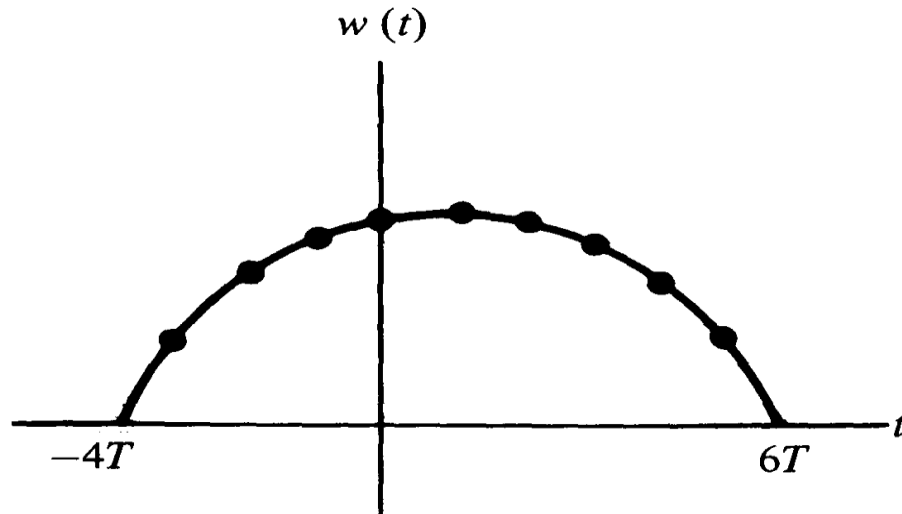


We know, the convolution of two rectangular signals is a triangular signal. The signal  $y(t)$  contains rectangular patches of similar width. Also, the system  $1/T \cdot h(t)$  is also a rectangular signal in time. Hence, the output  $w(t)$  can be drawn as



Hence, the output  $w(t)$  would contain superimposed triangular impulses.

We note that this superposition is actually linear interpolation between samples of  $x(t)$ . Therefore our final output signal  $w(t)$  would be linear interpolation of  $x_p(t)$ , shifted by  $T$ .



Ans 3)

(a)  $X(w) = \frac{1}{(1 - ae^{-jw})}$

(b) After decimation  $Y(w') = \frac{1}{2}X\left(\frac{w'}{2}\right) = \frac{1}{2(1 - ae^{-\frac{jw'}{2}})}$

(c)

$$\begin{aligned}\text{DTFT } \{x(2n)\} &= \sum_n x(2n)e^{-jw2n} \\ &= \sum_n x(2n)e^{-jw'n} \\ &= Y(w')\end{aligned}$$