1. Determine the coefficients of FIR filter using rectangular window with following

$$H_{d}(e^{jw}) = \begin{bmatrix} e^{-j3w} & -\pi/4 \le w \le +\pi/4 \\ 0 & \pi/4 \le w \le \pi \end{bmatrix}$$

Length of the filter is 7.

Ans1. Taking, I.F.T of 
$$H_d(e^{jw})$$
,  $h_d(n) = \frac{1}{2 \prod} \int_{-\Pi}^{\Pi} \left[ H_d(e^{j\omega}) \cdot e^{j\omega n} \right] d\omega$ 

$$h_d(n) = \frac{\sin \frac{\pi (n-3)}{4}}{\pi (n-3)}$$

Considering a rectangular window,

Response of filter is  $h(n)=h_d(n).w(n)$ .

To determine the coefficients, find the value of  $h_d(n)$  for n in the range 0 to 6. (As  $w_r(n)$  is 1 ). The values are 0.075, 0.159, 0.225, 0.25, 0.25, 0.159, 0.075.

2. Let  $h_d[n]$ ,  $-\infty < n < \infty$ , denotes the impulse response samples of a zero-phase filter with frequency response  $H_d(exp\{j\omega\})$ . It is known that the frequency response  $H_t(exp\{j\omega\})$  of the zero-phase FIR filter  $h_t[n]$ ,  $-M \le n \le M$ , obtained by multiplying  $h_d[n]$  with a rectangular window  $w_R[n]$ ,  $-M \le n \le M$ , has the least integral-squared error  $\Phi_R$  defined in the following equation.

$$\Phi_R = \sum_{n=-\infty}^{\infty} |h_t[n] - h_d[n]^2$$

Let  $\Phi$ \_Hann denote the integral-squared error if a length 2M+1 Hann window is used to develop FIR filter. Determine an expression for the excess error

$$\Phi$$
\_excess =  $\Phi$ \_R -  $\Phi$ \_Hann

Ans2.

$$\Phi_R = \frac{1}{2\pi} \int_{-\pi}^{\pi} \left| H_t(e^{j\omega}) - H_d(e^{j\omega}) \right|^2 d\omega, \text{ where } H_t(e^{j\omega}) = \sum_{n=-M}^{M} h_t[n] e^{-j\omega n}.$$

Using Parseval's relation, we can write  $\Phi_R = \sum_{n=-\infty}^{\infty} |h_t[n] - h_d[n]^2$ 

$$= \sum_{n=-M}^{M} |h_t[n] - h_d[n]^2 + \sum_{n=-\infty}^{-M-1} h_d^2[n] + \sum_{n=M+1}^{\infty} h_d^2[n].$$

Now, 
$$\Phi_{Haan} = \sum_{n=-\infty}^{\infty} |h_d[n] \cdot w_{Hann}[n] - h_d[n]^2$$

$$= \sum_{n=-M}^{M} \left| h_d \left[ n \left( \frac{1}{2} + \frac{1}{2} \cos \left( \frac{2\pi n}{2M+1} \right) \right) - h_d \left[ n \right]^2 + \sum_{n=-\infty}^{-M-1} h_d^2 \left[ n \right] + \sum_{n=-M+1}^{\infty} h_d^2 \left[ n \right] \right] \right|$$

Hence,  $\Phi_{Excess} = \Phi_R - \Phi_{Haan}$ 

$$= \sum_{n=-M}^{M} |h_d[n] \cdot w_R[n] - h_d[n]^2 - \sum_{n=-M}^{M} |h_d[n] \cdot \left(\frac{1}{2} + \frac{1}{2}\cos\left(\frac{2\pi n}{2M+1}\right)\right) - h_d[n]^2$$

$$= -\sum_{n=-M}^{M} \left|\frac{h_d[n]}{2}\cos\left(\frac{2\pi n}{2M+1}\right) - \frac{h_d[n]}{2}\right|^2 = \frac{1}{2}(1+2M)\cos\left(\frac{2\pi M}{2M+1}\right) - 1^2.$$

3. Repeat above problem if a Hamming window is used instead. Ans3.

$$\Phi_R = \sum_{n=-\infty}^{\infty} |h_t[n] - h_d[n]^2 \text{ and } \Phi_{Hamm} = \sum_{n=-\infty}^{\infty} |h_d[n] \cdot w_{Hamm}[n] - h_d[n]^2.$$

Therefore, 
$$\Phi_{Excess} = \Phi_R - \Phi_{Hamm} = -\sum_{n=-M}^{M} \left| h_d \left[ n \left( 0.46 \cos \left( \frac{2\pi n}{2M+1} \right) - 0.46 \right) \right|^2 \right|$$

$$= -\sum_{n=-M}^{M} \left| 0.46h_d[n] \left( \cos \left( \frac{2\pi n}{2M+1} \right) - 1 \right) \right|^2 = 0.46(2M+1) \left| \cos \left( \frac{2\pi M}{2M+1} \right) - 1 \right|^2.$$

4. Determine the coefficients {h(n)} of a linear-phase FIR filter of length M =15 which has a symmetric unit sample response and a frequency response that satisfies the condition

$$H_r\left(\frac{2\pi k}{15}\right) = \begin{cases} 1, & k = 0, 1, 2, 3\\ 0, & k = 4, 5, 6, 7 \end{cases}$$

Ans4.

$$M = 15.H_r(\frac{2\pi k}{15}) = \begin{cases} 1, & k = 0, 1, 2, 3\\ 0, & k = 4, 5, 6, 7 \end{cases}$$

$$H_r(w) = h(\frac{M-1}{2}) + 2\sum_{n=0}^{\frac{M-3}{2}} h(n)cosw(\frac{M-1}{2} - n)$$

$$h(n) = h(M-1-n)$$

$$h(n) = h(14-n)$$

$$H_r(w) = h(7) + 2\sum_{n=0}^{6} h(n)cosw(7-n)$$

Solving the above eqn yields,

$$h(n) = \{0.3189, 0.0341, -0.1079, -0.0365, 0.0667, 0.0412, -0.0498, 0.4667, 0.4667, -0.0498, 0.0412, 0.0667, -0.0365, -0.1079, 0.0341, 0.3189\}$$

 Design a 5-tap FIR band reject filter with a lower cutoff frequency of 2,000 Hz, an upper cutoff frequency of 2,400 Hz, and a sampling rate of 8,000 Hz using the Hamming window method. Determine the transfer function.
 Ans5.

2N+1=5 which leads that N=2, h(n) is given by

$$h(n) = \begin{cases} \frac{\pi - \omega_H + \omega_L}{\pi}, & n = 0\\ \frac{-\sin(\omega_H n)}{\pi n} + \frac{\sin(\omega_L n)}{\pi n} & n \neq 0 \end{cases}$$

Then the five samples of h(n) shifted by 2 is equal to

$$h(2) = 0.9,$$
  
 $h(1) = h(3) = 0.01558$   
 $h(0) = h(4) = 0.09355$ 

For Hamming window with M = 5

$$w(n) = 0.54 - 0.46\cos\left(\frac{n\pi}{2}\right)$$

and for n = 0, 1, 2, 3, 4

$$W_{ham}(2) = 1,$$
  
 $W_{ham}(1) = W_{ham}(3) = 0.54,$   
 $W_{ham}(0) = W_{ham}(4) = 0.08,$ 

Then the windowed impulse response coefficients are

$$h_w(2) = 0.9,$$
  
 $h_w(1) = h_w(3) = 0.00841$   
 $h_w(0) = h_w(4) = 0.00748$ 

Convert to z-domain

$$H(z) = 0.00748 + 0.00841z^{-1} + 0.9z^{-2} + 0.00841z^{-3} + 0.00748z^{-4}$$

6. What are the filter coefficients for a 3-tap FIR low pass filter with a cutoff frequency of 800 Hz and a sampling rate of 8,000 Hz using Hamming window? Also determine the transfer function and difference equation of the designed FIR system. Ans6.

$$\omega_c = 2\pi f_c T_s = 2\pi \times 800/8000 = 0.2\pi$$

The coefficients of the lowpass filter

$$h(0) = 0.2, h(-1) = h(1) = 0.1871$$

For Hamming window with M = 3

$$w(n) = 0.54 + 0.46\cos(n\pi)$$

and for n = 0.1, 2

$$W_{ham}(0) = 1$$
,  $W_{ham}(1) = W_{ham}(2) = 0.08$ 

Then the windowed impulse response coefficients are

$$h_w(0) = 0.2, h_w(1) = h_w(2) = 0.01497$$

convert to z-domain

$$H(z) = 0.01497 + 0.2z^{-1} + 0.1497z^{-2}$$

Then the difference equation is

$$y(n) = 0.01497x(n) + 0.2x(n-1) + 0.01497x(n-2)$$

- 7. A Hilbert Transform is a filter with frequency response H<sub>d</sub>(w)=-j sign(w)
  - A] Roughly plot the magnitude and phase plot of the filter.
  - B] Determine  $h_d(n)$ .

Ans7.

The converse 
$$H_{3}(\omega) = -3$$
 sign  $(\omega)$ 

$$H_{3}(\omega) = \pm 4 \omega$$

$$= \pm \frac{1}{2} \text{ if } \omega \lambda 0$$

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- 8. A Digital Filter is defined by the difference equation y[n] = 0.99\*y[n-1] + x[n].
  - A] Determine the filter transfer function.
  - B] What is filter impulse function?
  - C] Is it LPF or HPF? (hint: check pole-zero plot)

