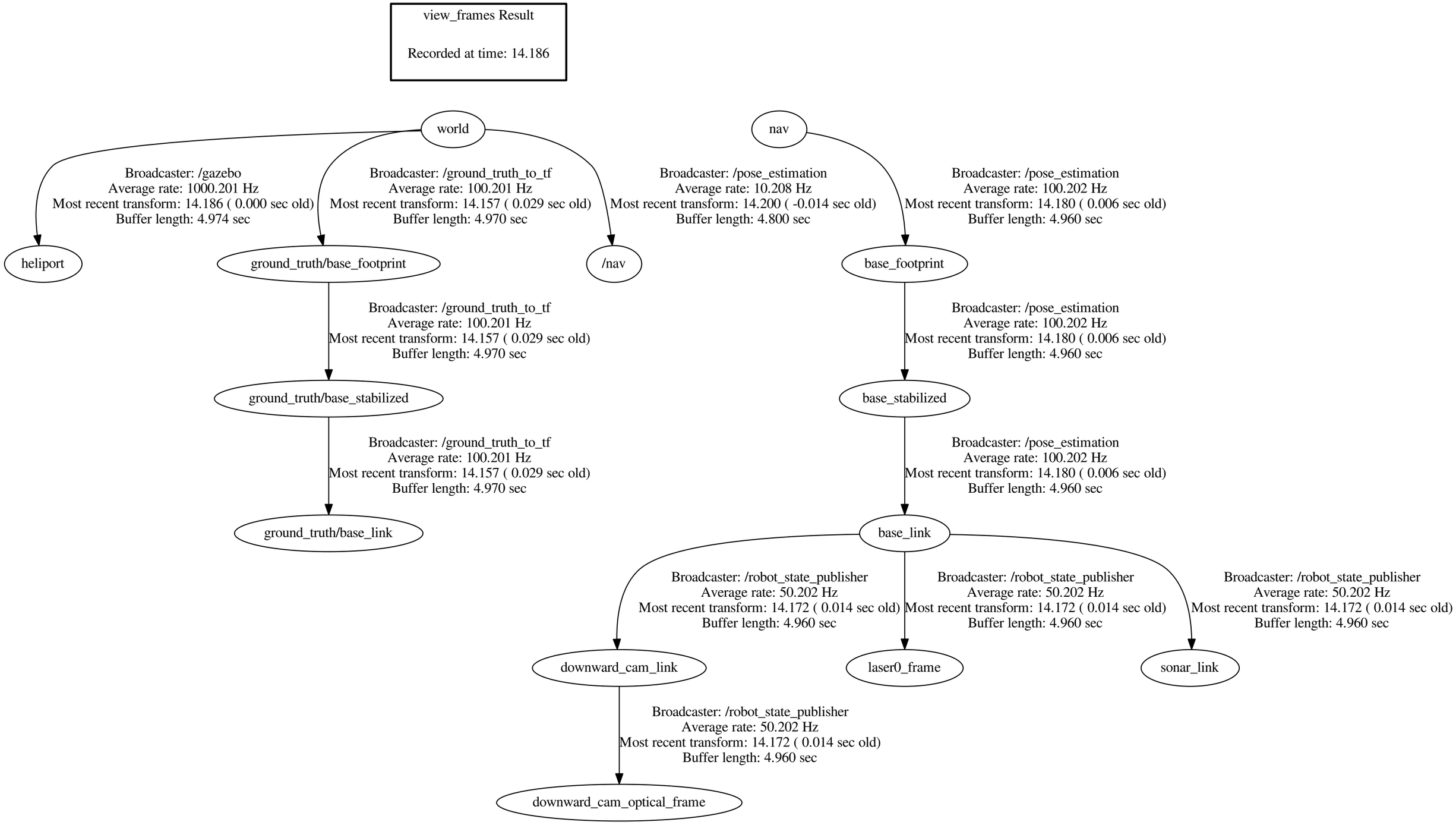
view_frames Result
Recorded at time: 14.186
world
Broadcaster: /gazebo
Average rate: 1000.201 Hz
Most recent transform: 14.186 (0.000 sec old)
Buffer length: 4.974 sec
Broadcaster: /ground_truth_to_tf
Average rate: 100.201 Hz
Most recent transform: 14.157 (0.029 sec old)
Buffer length: 4.970 sec
Broadcaster: /pose_estimation
Average rate: 10.208 Hz
Most recent transform: 14.200 (-0.014 sec old)
Buffer length: 4.800 sec
nav
Broadcaster: /pose_estimation
Average rate: 100.202 Hz
Most recent transform: 14.180 (0.006 sec old)
Buffer length: 4.960 sec
heliport
ground_truth/base_footprint
/nav
base_footprint
Broadcaster: /ground_truth_to_tf
Average rate: 100.201 Hz
Most recent transform: 14.157 (0.029 sec old)
Buffer length: 4.970 sec
Broadcaster: /pose_estimation
Average rate: 100.202 Hz
Most recent transform: 14.180 (0.006 sec old)
Buffer length: 4.960 sec
ground_truth/base_stabilized
base_stabilized
Broadcaster: /ground_truth_to_tf
Average rate: 100.201 Hz
Most recent transform: 14.157 (0.029 sec old)
Buffer length: 4.970 sec
Broadcaster: /pose_estimation
Average rate: 100.202 Hz
Most recent transform: 14.180 (0.006 sec old)
Buffer length: 4.960 sec
ground_truth/base_link
base_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 14.172 (0.014 sec old)
Buffer length: 4.960 sec
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 14.172 (0.014 sec old)
Buffer length: 4.960 sec
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 14.172 (0.014 sec old)
Buffer length: 4.960 sec
downward_cam_link
laser0_frame
sonar_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 14.172 (0.014 sec old)
Buffer length: 4.960 sec
downward_cam_optical_frame