

Outline

- Introduction
- Random variable, atom, and event
- Joint distribution
- Conditional probability
- Bayes theorem
- Independence
- Expectation
- Continuous random variables

(Based on David MacKay, David Blei,
<https://www.cs.princeton.edu/courses/archive/spring12/cos424/pdf/lecture02.pdf>)

Introduction

Consider the “card problem”

- There are three cards:
 - Red/Red
 - Red/Blue
 - Blue/Blue
- I go through the following process
 - ① Close my eyes and pick a card
 - ② Pick a side at random
 - ③ Show you that side
- I show you Red. What's the probability the other side is Red too?

Random variable, atom, and event

- In Algebra a variable, x , is an unknown value
 - E.g. $2x = 4$
 - It can take at most one value at a time
- A **random variable** represents simultaneously a set of values
- Necessary in contexts where we *cannot* determine a unique value
 - Of course, theoretically, it also corresponds to one value...
 - But we can only determine its distribution
 - E.g. $p(5 < X < 10) = 0.5$
- It can be a single value, a vector, a matrix...

Random variable, atom, and event

- Random variables take on values in a sample space
- They can be discrete or continuous
- For example:
 - Coin flip: $\{H, T\}$
 - Height: Positive values $(0, \infty)$
 - Temperature: real values $(-\infty, \infty)$
 - Number of words in a document: Positive integers $\{1, 2, \dots, \infty\}$
- We call the values of random variables *atoms*

Random variable, atom, and event

- A *discrete probability distribution* assigns probability to every atom in the sample space
- For example, if X is an (unfair) coin, then
 - $p(X = H) = 0.7$
 - $p(X = T) = 0.3$
- The sum of probabilities of *any* distribution is 1

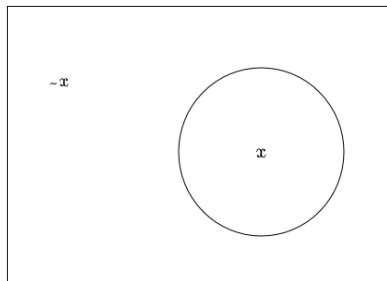
$$\sum_x p(X = x) = 1$$

- And all probabilities have to be greater or equal to 0
- Probabilities of disjunctions are sums over part of the space.
E.g., the probability that a die is bigger than 3:

$$p(X > 3) = p(X = 4) + p(X = 5) + p(X = 6)$$

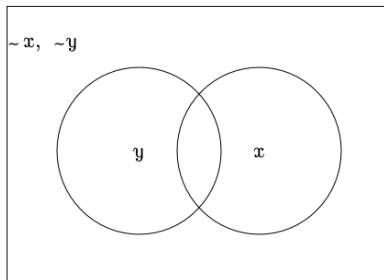
Random variable, atom, and event

- The figure below is helpful to understand these concepts well



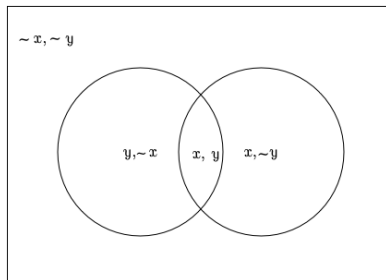
- An *atom* is a point in the box. All atoms together form the *sample space*
- An *event* is a subset of atoms. Two events in the picture are x and $\sim x$
- The probability of an event is the sum of the probabilities of its atoms

- In practice, we need to consider many variables at the same time
- An event would then combine atoms from multiple variables



- The **joint distribution** is a distribution over the configuration of all the random variables in the ensemble
 - For the figure, the function $p(X, Y)$ gives the probability of all possible combinations of X and Y
 - Notice that $X \in \{x, \sim x\}$ and $Y \in \{y, \sim y\}$
 - Therefore $X, Y \in \{(x, y), (x, \sim y), (\sim x, y), (\sim x, \sim y)\}$

Joint distribution



- Some useful properties:

- Union: $p(X \cup Y) = p(X) + p(Y) - p(X, Y)$

- **Marginalization:** $p(X) = \sum_Y p(X, Y)$

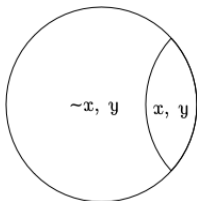
This property is referred to as the **sum rule of probability!**

Joint distribution

- We can make a joint distribution of *two consecutive events*
- With the cards example:
 - $X = \text{first draw} \in \{\text{Red/Blue}, \text{Red/Red}, \text{Blue/Blue}\}$
 - $Y = \text{second draw} \in \{\text{Red/Blue}, \text{Red/Red}, \text{Blue/Blue}\}$
- $X, Y \in \{(\text{Red/Blue}, \text{Red/Blue}), (\text{Red/Blue}, \text{Red/Red}), (\text{Red/Blue}, \text{Blue/Blue}), (\text{Red/Blue}, \text{Red/Red}), (\text{Red/Red}, \text{Red/Red}), (\text{Red/Red}, \text{Blue/Blue}), (\text{Red/Blue}, \text{Blue/Blue}), (\text{Blue/Blue}, \text{Blue/Blue})\}$
- How to calculate the joint distribution, $p(X, Y)$?

Conditional probability

- What about when we have observed one event, but want to know the probability of another one?
- The **conditional probability** of X given Y is the probability of event X when event Y is known



- So, we only concentrate on the subset of events where the specific value of Y occurs
- In the above figure, we focus on when $Y = y$

$$p(X|Y = y) = \frac{p(X, Y = y)}{p(Y = y)}$$

Conditional probability

- We can now solve the card problem
- Let's have two events, X_1 for observed side of the card, and X_2 for the side we want to guess
- We need to calculate $p(X_2 = \text{Red} | X_1 = \text{Red})$

$$p(X_1 = \text{Red}) = \frac{1}{2}$$

$$p(X_1 = \text{Red}, X_2 = \text{Red}) = \frac{1}{3}$$

therefore

$$p(X_2 = \text{Red} | X_1 = \text{Red}) = \frac{p(X_2 = \text{Red}, X_1 = \text{Red})}{p(X_1 = \text{Red})} = \frac{1/3}{1/2} = \frac{2}{3}$$

The chain rule (or product rule)

- Consider the conditional probability rule

$$p(X|Y) = \frac{p(X, Y)}{p(Y)}$$

- It allows us to derive the chain rule, which defines the joint distribution as a product of conditionals:

$$\begin{aligned} p(X, Y) &= p(X, Y) \frac{p(Y)}{p(Y)} \\ &= p(X|Y) p(Y) \end{aligned}$$

- In general, for any set of variables

$$p(X_1, X_2, \dots, X_N) = \prod_{n=1}^N p(X_n | X_1, X_2, \dots, X_{n-1})$$

- For example:

$$p(X, Y, Z) = p(X) p(Y|X) p(Z|Y, X)$$

Bayes theorem

- Using the chain rule, we can trivially say:

$$p(X|Y) p(Y) = p(Y|X) p(X)$$

which means that [**Bayes theorem**]:

$$p(X|Y) = \frac{p(Y|X) p(X)}{p(Y)}$$

- The Bayes theorem is an important foundation for Bayesian statistics, and particularly for Probabilistic Graphical Models!

Playtime!

- Open “1.Probability_Review.ipynb” in Jupyter
- Do Part 1, estimated duration 20 min

Independence

- Random variables are *independent* if knowing about X tells us nothing about Y

$$p(Y|X) = p(Y)$$

- This means that their joint distribution is

$$p(X, Y) = p(X)p(Y)$$

- Why?
- A couple of examples:
 - Two persons, A, and B, start their trip in different parts of town. The transport mode for A is X and for B, it is Y . Are these two choices independent?
 - It's a rainy day. Two accidents happen on different roads of the city, far from each other. Are these two, independent events?

Independence

- Are these independent?
 - the speeds in adjacent road sections
 - the flow of pedestrians and the flow of cars in the same road
 - whether it is raining and the number of taxi cabs
 - whether it is raining and the amount of time it takes me to hail a cab
 - the departure time and arrival time of a trip

Independence

- Example: two coins, C_1, C_2 with $p(H|C_1) = 0.5, p(H|C_2) = 0.3$
 - ① Suppose that I randomly choose a number $Z \in \{1, 2\}$, and take coin C_Z
 - ② I flip it twice, with results (X_1, X_2)

Are X_1 and X_2 independent? What about if I know Z ?

Conditional independence

- X and Y are *conditionally independent* given Z

$$p(X|Y, Z) = p(X|Z)$$

- So, we can say that

$$X \perp\!\!\!\perp Y|Z \implies p(X, Y|Z) = p(X|Z)p(Y|Z)$$

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- *If we know Z , then knowing about Y tells us nothing about X*

Playtime!

- Open “1.Probability_Review.ipynb” in Jupyter
- Do Part 2, estimated duration 30 min

Expectation

- The *expected value* of a random variable is the probability-weighted average of all possible values
- In other words, it is the *mean* of the distribution of this random variable

$$\mathbb{E}[X] = \sum_x x p(X = x)$$

- More generically (remember the $f(x)$ can be itself a random variable)

$$\mathbb{E}[f(X)] = \sum_x f(x) p(X = x)$$

Playtime!

- Open “1.Probability_Review.ipynb” in Jupyter
- Do Part 3, estimated duration 10 min

Continuous random variables

- We've only used discrete random variables so far (e.g., dice, cards)
- Random variables can be continuous
- We need a density function $p(x)$, which integrates to one.

$$\int_{-\infty}^{\infty} p(x) dx = 1$$

- Probabilities are integrals over $p(x)$
- An *event* is thus defined by an interval of possible values of the random variable

$$P(a \leq X \leq b) = \int_a^b p(x) dx$$

- Notice that we use X , x , P , and p !...

Some distributions - Gaussian

- By far, the most common one...
- Two parameters:
 - Mean, μ
 - Standard deviation, σ (or, variance, σ^2)

- $p(x)$ is defined as

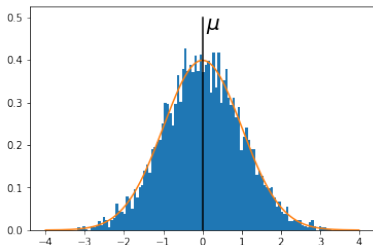
$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

- Often represented as:

$$p(x) \sim \mathcal{N}(\mu, \sigma^2)$$

Some distributions - Gaussian

- Support is $] - \infty, \infty[$
- Symmetrical



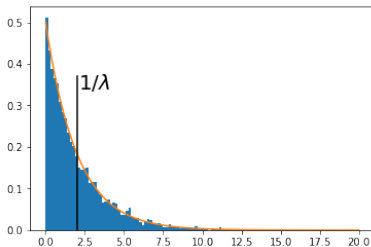
- The Central limit theorem (CLT) establishes that *the distribution of the sampling means approaches a normal distribution as the sample size gets larger, no matter what the shape of the population distribution.*

Some distributions - Exponential

- Exponential distribution, with *rate* λ

$$p(x) = \lambda e^{-\lambda x}$$

- Support is $[0, \infty[$

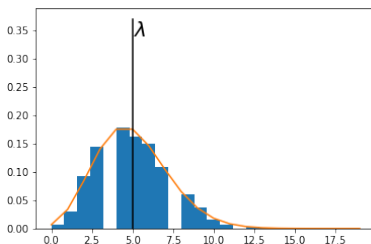


Some distributions - Poisson

- Poisson distribution, with *rate* λ

$$p(k) = \frac{\lambda^k e^{-\lambda}}{k!}$$

- for $k = 0, 1, 2, \dots$
- Pretty common in transportation (e.g. arrival rates)



1

¹In fact, this distribution relates to a discrete random variable, so we include it to emphasize that not only continuous variables can be parameterized as a probability distribution.

Independent and identically distributed random variables (iid)

- Independent
- Identically distributed

Independent and identically distributed random variables (iid)

- Independent
- Identically distributed

If we repeatedly flip the same coin N times and record the outcome, then X_1, \dots, X_N are **iid**

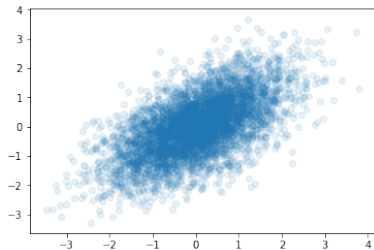
- The iid assumption can be extremely useful in data analysis

Multivariate distributions

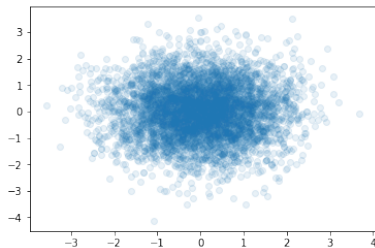
- So far, we've been working with single variable distributions
- Multivariate means it's the same as above, but with more variables at the same time!
- In practice, joint distribution of variables that share a common structure
- In some cases (e.g. Poisson), it is not a trivial problem
- In others (e.g. Gaussian), it is well studied, and extensively applied

$$p(\mathbf{x}) = \frac{1}{\sqrt{2\pi}|\Sigma|} e^{-\frac{1}{2}(\mathbf{x}-\mu)^T \Sigma^{-1}(\mathbf{x}-\mu)}$$

- Bivariate Gaussian



$$\Sigma = \begin{bmatrix} 1 & 0.6 \\ 0.6 & 1 \end{bmatrix}$$



$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Playtime!

- Open “2. Probability_Review.ipynb”
- Do part 1. Est. time is 15 min

A note on notation

- So far we have been using a rather standard statistics notation
 - X is a random variable and x is atom/event
 - We write e.g. $p(X = x)$
- In the machine learning literature, this notation is typically simplified
 - Lowercase letters, such as x , represent random variables
 - We simply write $p(x)$. Everything else should be clear from the context!
- This allows us to have
 - Bold letters denote vectors (e.g. \mathbf{x} , where the i^{th} element is referred as x_i)
 - Matrices are represented by bold uppercase letters such as \mathbf{X}
 - Roman letters, such as N , denote constants
- This is the notation that we will adopt from now on!

The likelihood function

- Imagine you have the data. For example:
 - N readings of traffic counts at a certain time, each one called x_i , $i = 1 \dots N$
- You assume it follows some parametric distribution (e.g. Gaussian)
- How do you determine its parameters, Θ ?

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- The likelihood function, $L(\Theta)$, should be:

$$L(\Theta) = \prod_i^N p(x_i | \Theta)$$

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- Notice that this is the joint distribution of all **independent** data points!

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- In the case of the Gaussian, we should have $\Theta = \{\mu, \sigma\}$
- The likelihood function, $L(\Theta)$, would be

$$L(\Theta) = \prod_i^N \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}$$

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- If you actually *had* the true parameters, the likelihood function would have the maximum value, right?
- So, this becomes an optimization problem:
 - Find the values of Θ that maximize the function $L(\Theta)$

The log-likelihood function

- For practical reasons, we apply a logarithmic transformation to the likelihood function
 - Less prone to numeric error (numerical stability)
 - Computationally faster

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- In the case of the Gaussian distribution, the log likelihood becomes:

$$-\frac{N}{2}(\log(2\pi) + \log(\sigma^2)) - \frac{1}{2\sigma^2} \sum_i (x_i - \mu)^2$$

Maximum likelihood estimate (MLE)

- The maximum likelihood estimate is the value of the parameter that maximizes the log likelihood (equivalently, the likelihood)
- In the case of the Gaussian, the MLE corresponds to:

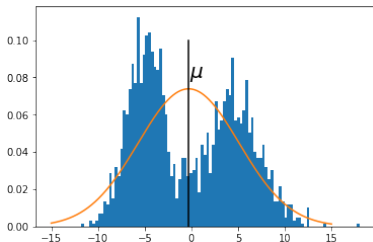
$$\hat{\mu} = \frac{\sum_{i=1}^N x_i}{N}, \quad \text{i.e. the *sample mean*}$$

$$\hat{\sigma}^2 = \frac{\sum_{i=1}^N (x_i - \hat{\mu})^2}{N}, \quad \text{i.e. the *sample variance*}$$

Maximum likelihood estimate (MLE)

DISCLAIMER:

- The fact that you get a MLE doesn't mean you found a good model!



- You need to know your data...

Playtime!

- Open “2. Probability_Review.ipynb”
- Do part 2. Est. time is 30 min