- Giving spin to the ball
 - o 2 Wheels and Spinning Head
 - o 3 Wheels
 - o 4 Wheels
 - 2 Tension Belt with spinning head
 - Small Ledges with Friction pad
- Giving speed to the ball
 - 2 Wheels and Spinning Head
 - o 3 Wheels
 - o 4 Wheels
 - o 2 Tension Belt with spinning head
 - Throwing with propeller/paddle
 - Hammer
- Giving pitch angle to the launching mechanism
 - Gear
 - o Single worm gear
 - o Bevel Gear
 - Four bar
 - Rope-Controlled Head Pulley
- Giving yaw angle to the launching mechanism
 - o Gear
 - Gear from base
 - Single worm gear
 - Bevel Gear
 - Four bar
 - Dual slider Crank
- Accepting frequency information from the user
 - Integrated Controller
 - Remote Controller
 - Mobile Application
 - Wired Remote Controller
- Accepting trajectory information from the user
 - Integrated Controller
 - o Remote Controller
 - Mobile Application
 - Wired Remote Controller
- Accepting numerical information from the user
 - Potentiometer with Buttons
 - Encoder with Buttons
 - Touchscreen
 - o Buttons
- Allowing user to position the device
 - Clamps
 - Magnets

- Suction Cups
- o Rail System
- o Wheels
- Controlling the spin of the ball
 - Servo
 - Stepper
 - o DC
 - o BLDC
- Controlling the speed of the ball
 - o DC
 - o BLDC
- Controlling the yaw angle
 - o DC
 - o BLDC
- Controlling the pitch angle
 - o Servo
 - Stepper
- · Controlling the ball feed for storage
 - Servo
 - o Stepper
- Controlling the ball feed for launching
 - o Stepper
- Controlling the ball feed for launching
 - Stepper
- Catching the balls
 - Net
 - o Spherical Wall
 - o Wiper
- Storing the balls
 - Box
 - o Tunnel Closed Tube
 - Groove
 - Gravity Funnel
- Transferring balls to launch
 - Slider Crank
 - Maltese Wheel
 - Rotating Pusher
 - Gravity
- Giving the balls desired frequency
 - Slider Crank
 - Maltese wheel
 - Rotating pusher
 - Lid mechanism
 - Hinge mechanism

- o Rotating hole
- Transferring the balls from storage
 - o Maltese wheel
 - o Spiral Lift
 - o Translating Box
 - o Belt mechanism