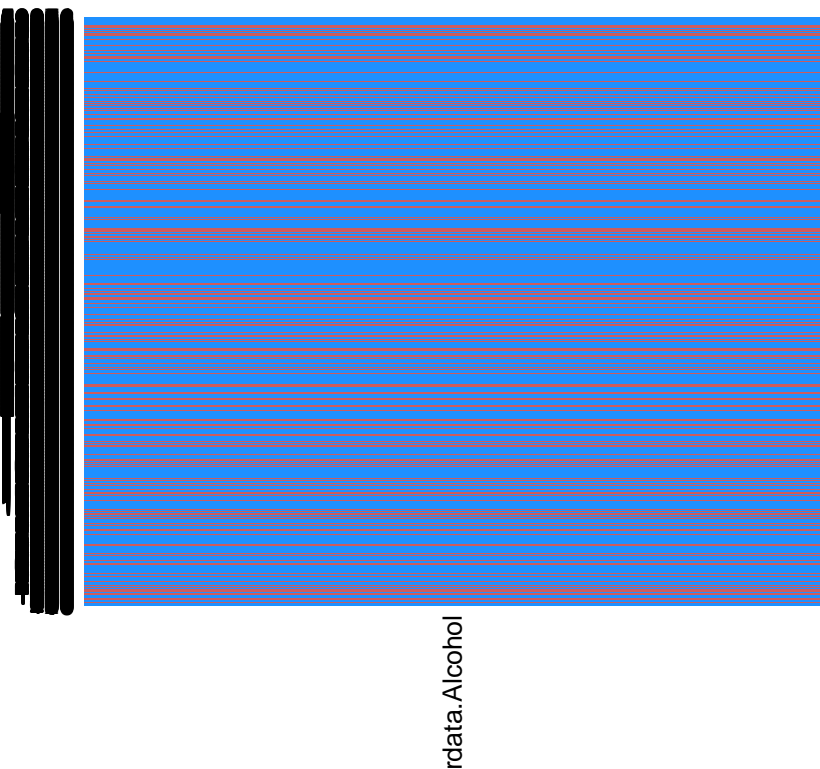


Missingness Map



Missing (25%)
Observed (75%)