

Reminders: HW 2 due Friday
Comments on Project proposals:

How to deal with outliers

Density level sets

Metric measure spaces/ Wasserstein distance

Distance to measure.

$$d_{\Gamma}(P\mathcal{H}(R(x)), P\mathcal{H}(R(Y))) \leq d_Y(x, Y) \rightarrow \text{⑧}$$



Problem: because sampling single point can drastically change $P\mathcal{H}$.

Common Setup: $X \sim M + N(0, I)$ has tails

$$X \stackrel{\text{ind}}{\sim} M + \underbrace{N(0, I)}_{\text{IR}^d} \rightarrow \text{some probability of sampling outlier}$$

What we often want is to capture topology of dense subsets, ignore outliers.

E.g. Carlsson & de Silva's idea of using
knn-based Persistence filter.

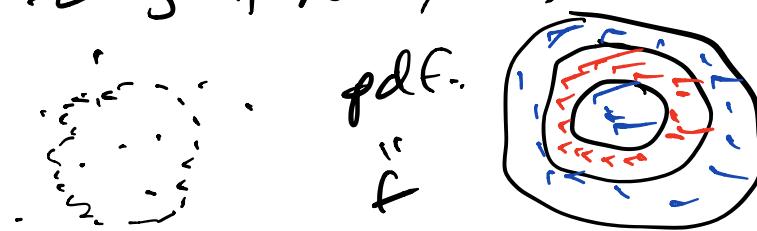
→ what is κ ? what is threshold for cut?

one solution for low dimensions:

don't do R_{pts} . Do density level sets

$$x \stackrel{\text{use}}{\sim} s + N(0, \tau^2)$$

$$\mathcal{E}((a, r_0))$$



$\text{PH}(\tilde{f})$: will have
robust fl.
feature

if we have ground truth, this is straightforward.
problem: we need to estimate pdf f from
samples. Convergence is exponential in dimension
i.e. $x \subseteq \mathbb{R}^d$ need $O(\frac{1}{\epsilon}^d)$ samples for
 $\Omega(\epsilon)$ accurate estimation of f .

in low dimensions ($d=2, 3$) this is tractable.

can adapt stability results from levelset persistence
 $d_I(\text{PH}(f), \text{PH}(g)) = \|f - g\|_\infty$

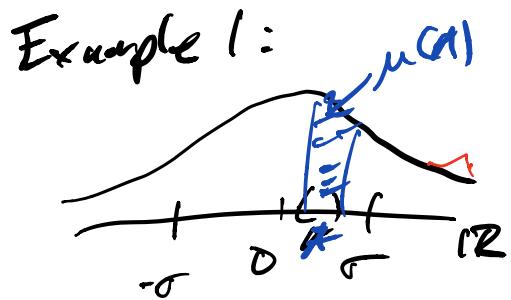
so if f is pdf, $g \in \tilde{f}$ and estimator converges
uniformly as $n \rightarrow \infty$, then barcodes converge.

* assume Euclidean.

In higher dimensions ($d \geq 4$) need something else.
 Metric measure spaces are good definition to work with.

Def: A metric measure space is a triple
 (X, d, μ) where (X, d) is metric space
 μ is a measure in sense of prob. measure.

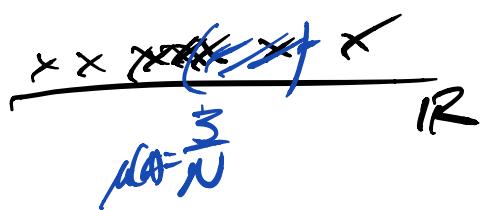
μ is a measure in sense of prob. measure.
 mass of Borel subset $A \subseteq X$ is $\mu(A)$
 and $A \cap B = \emptyset \Rightarrow \underbrace{\mu(A \cup B) = \mu(A) + \mu(B)}$
 (Countably) additive



$$\text{pdf } N(0, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-x^2/2\sigma^2}$$

$$\mu_f(A) = \int_A f(x) dx$$

Example 2: $X \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$, N samples



empirical measure:

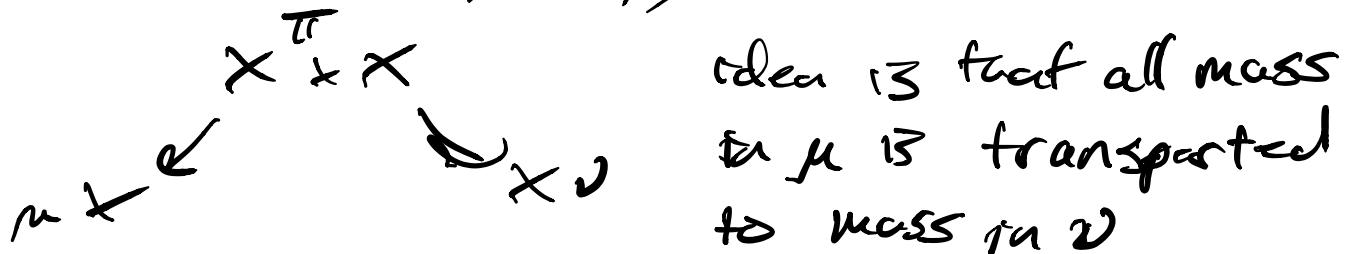
$$\mu_x(A) = \frac{1}{N} |\{x_i \in A\}|$$

$$= \frac{1}{N} \sum_{x \in A} \delta_x(\gamma) dy$$

in what sense are measures close? & dirac delta
 i.e. we might expect $\mu_x \rightarrow \mu_f$ if $x \leftarrow$
 $N \rightarrow \infty$.

Note: positive measures have $\mu(A) \geq 0 \forall A$
 probability measures have $\mu(X) = 1$
 $\mu(\mathbb{R}^n)$

Transport plan: let μ, ν be measures on X ,
 $\mu(X) = \nu(X)$ (same mass). A transport plan
 b/w μ and ν is a measure π on $X \times X$
 s.t. $\pi(A \times X) = \mu(A)$, $\pi(X \times B) = \nu(B)$



Example:

μ	$\begin{array}{ c c c }\hline & & & \\ \hline 0 & & & 1 \\ \hline \end{array}$	ν	π	$x(\cdot) = \frac{1}{3}$
ν	$\begin{array}{ c c c }\hline & & & \\ \hline 0 & & & 1 \\ \hline \end{array}$		$\begin{array}{ c c c }\hline & & & \\ \hline 0 & \vdots & \vdots & 1 \\ \hline \end{array}$	

for discrete setting, can encode in a
 Assignment matrix i.e. $C = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix} \stackrel{\frac{1}{3}}{=} \frac{1}{3} \delta_x$

Sum rows: projection onto μ

Sum cols: projection onto ν

There are many possible transport plans e.g.

$$\begin{bmatrix} \frac{1}{3} & \frac{1}{3} & 0 \\ 0 & \frac{1}{3} & \frac{1}{3} \end{bmatrix} \text{ also valid}$$

k transport plans: $\sum_{i=1}^k w_i C_i \quad \sum_{i=1}^k w_i = 1, w_i \geq 0$

is also a transport plan.

$$c_i \geq 0$$

The p^{th} order cost of a transport plan π

$$\text{B } C_p(\pi) = \left(\int_{x,y} d(x,y)^p d\pi(x,y) \right)^{1/p}$$
$$\leq d(x,y) d\pi(x,y)$$

Note: $C_1(\pi)$ is "Earth mover's cost": ie sum of cost to move 1 unit of mass 1-unit of distance

Let $\Pi(\mu, \nu)$ denote set of all transport plans
btw μ and ν .

Def: the p^{th} order Wasserstein distance
btw. μ and ν is

$$W_p(\mu, \nu) : \min_{\pi \in \Pi(\mu, \nu)} C_p(\pi)$$

If measures have finite p^{th} moments, $W_p(\mu, \nu) < \infty$

Comment 1: There is a generalization of
Wasserstein distance to barcodes. W_∞ is
bottleneck distance.

Comment 2: There is a notion of Gromov -
Wasserstein distance,

Comment 3: Finding π which minimizes C_p
is subject of optimal transport. Important
in applications. eg: supply logistics.

Distance to measure (DTM)

Let μ be a prob. measure on (X, d) and $m \in (0, 1]$ be mass parameter.

define distance $d_{\mu, m}$ to measure μ as

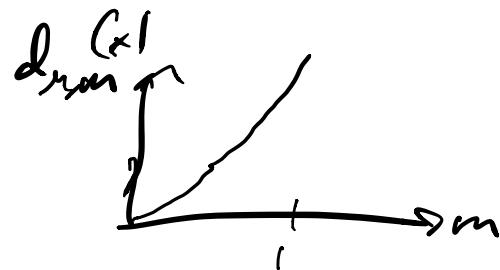
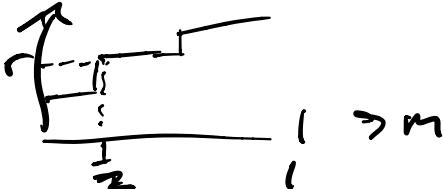
$$d_{\mu, m} : x \in X \mapsto \sqrt{\frac{1}{m} \int_0^m \delta_{\mu, r}(x)^2 dr}$$

$$\text{where } \delta_{\mu, m} : x \mapsto \inf_{r \geq 0} \left\{ \mu(\overline{B}(x; r) > m) \right\}$$



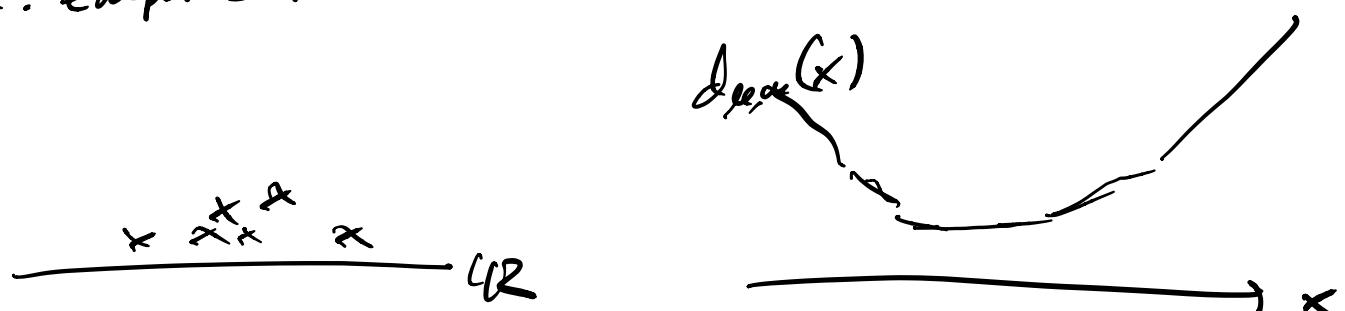
$$\delta_{\mu, \frac{1}{2}-\epsilon}(x) = \frac{1}{d}$$

$$\delta_{\mu, m}(x)$$



Fix m

μ : empirical measure



{ points w/ small $d_{\mu, m}$ are "more important" than points w/ large DTM.

• m is a parameter that can be tuned
 $m \rightarrow 0$ distance to closest point
 $m \rightarrow 1$ smoother, may lose structure

Idea: Create sub-levelset filtration w/
 $d_{\mu, m}$.

Bachet et al 2016 (Oudot Ch. 5.6)
 Then 3.1:

$$d_g(\text{PH}(d_{\mu, m}), \text{PH}(d_{\nu, m})) = \frac{1}{\sqrt{m}} W_2(\mu, \nu)$$


Proof: ...

A measure ν is a submeasure of μ if
 $\nu(B) \leq \mu(B) \forall B$. Let $\text{Sub}_m(\mu)$ be
 submeasures w/ mass m .

Prop: Let μ be a prob. measure on X , and
 $m \in (0, 1]$. Then

$$\underline{d}_{\mu, m}(x) = \min_{\nu \in \text{Sub}_m(\mu)} \frac{1}{\sqrt{m}} W_2(\mu \delta_x, \nu)$$

↑ mass on
conc. at x .

Pf: ν is measure of mass $m \Rightarrow$ Transport
 plan betw. ν and $\mu \delta_x$

$$W_2(\mu \delta_x, \nu)^2 = \int_X d_x(y, x)^2 d\nu(y)$$

Let $d_x : X \rightarrow \mathbb{R} : d_x(y) = d(x, y)$

Let $\nu_x : \mathcal{V}_x(\mathbb{I}) : \nu(d_x^{-1}(\mathbb{I})) \forall \mathbb{I} \subseteq \mathbb{R}$

Let $F_\nu(y) = \nu([0, y]) : F_\nu^{-1} : m \mapsto \inf \{t \in \mathbb{R} \mid F_\nu(t) > m\}$

$\Rightarrow F_{d_x}^{-1}(m) = S_{\nu, m}(x)$

$\inf \{t \in \mathbb{R} \mid \nu_x([0, t]) > m\}$

$\inf \{t \in \mathbb{R} \mid \nu(\{y \mid d(x, y) < t\}) > m\}$

$\inf \{r \mid \mu(\overline{B}(x; r)) > m\}$

$S_{\nu, m}(x)$

$$\int_X \frac{d_x(y, x)^2}{T} d\nu(y) = \int_{\mathbb{R}^+} t^2 d\nu_x(t) =$$
$$= \int_0^m F_{d_x}^{-1}(l)^2 dl$$

ν submeasure of $\mu \Rightarrow \underline{F}_{d_x}(x) \leq \overline{F}_{d_x}(x) \forall x \in X$

$$\Rightarrow F_{d_x}^{-1}(l) \geq \underline{F}_{d_x}^{-1}(l)$$

$$\exists \mu_x(m \delta_x; v) \sum_l^m (\underline{F}_{d_x}(l))^2 dl = \int_0^m \delta_{x, l}(x)^2 dl$$

" $m \delta_{x, l}(x)^2$

Inequality is tight for set of submeasures

$$R_{\mu, m}(x) \leq \text{Sub}_{\alpha}(\mu)$$

$$\left\{ D \mid \text{supp}(D) \subseteq \overline{B}(x, \delta_{\mu, m}(x)) \right\},$$
$$\nu(B(x, \delta_{\mu, m}(x))) = \underline{\mu}(B(x, \delta_{\mu, m}(x)))$$

Existence of such a measure

$\mu_{x, m} = \mu(B(x, \delta_{\mu, m}(x))),$ rescale mass
on $\partial B(x, \delta_{\mu, m}(x))$ if too much mass

$$\Rightarrow W_2(m\delta_x, \mu_{x, m})^2 = \int d\mu_{x, m}(x)^2$$

$$\lim_{m \rightarrow \infty} W_2(m\delta_x, \mu_{x, m}) = d_{\mu, \mu}(x) \quad \square$$

Thm: Let μ, ν be prob. measures on (X, d) ,
 $m \in [0, 1]$ mass param. Then

$$\|d\mu_m - d\nu_m\|_\infty \equiv \lim_{m \rightarrow \infty} W_2(\mu, \nu)$$

$$\text{Pf. } \sqrt{m} d_{\mu, \mu}(x) = W_2(m\delta_x, \mu_{x, m})$$

Let π be OT plan μ to ν

$$\int_{X \times X} d_x(x, y)^2 d\pi(x, y) = W_2(\mu, \nu)^2$$

Consider submeas $\mu_{x, m}$. $\exists \tilde{\pi}$ submeas. of π
that transports $\mu_{x, m}$ to $\tilde{\nu}$ submeas of ν

$$\Rightarrow W_2(\mu_{x,m}, \tilde{\nu}) \leq W_2(\mu, \nu)$$

again, $\sqrt{m} d_{\nu,m}(x) \leq W_2(m\delta_x, \tilde{\nu}) \Rightarrow$

$$\sqrt{m} d_{\nu,m}(x) \leq W_2(m\delta_x, \tilde{\nu}) \quad (\leq) \rightarrow \text{ineq.}$$

$$\begin{aligned} \sqrt{m} d_{\nu,m}(x) &= W_2(m\delta_x, \tilde{\nu}) \\ &\leq W_2(m\delta_x, \mu_{x,m}) + \\ &\quad W_2(\tilde{\nu}, \mu_{x,m}) \end{aligned}$$

$$\leq \sqrt{m} d_{\mu,m}(x) + W_2(\nu, \mu)$$

Similarly,

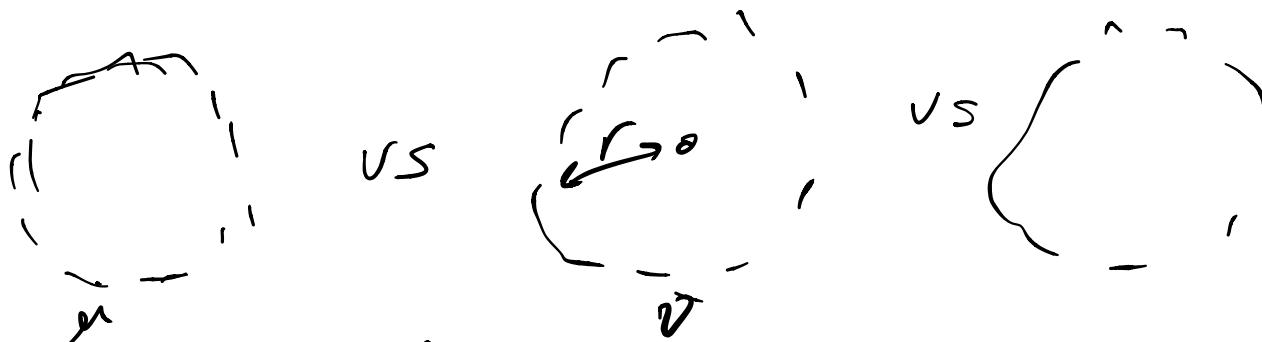
$$\sqrt{m} d_{\mu,m} \leq \sqrt{m} d_{\nu,m}(x) + W_2(\nu, \mu)$$

$$\Rightarrow \|d_{\mu,m} - d_{\nu,m}\|_{\infty} \leq W_2(\mu, \nu)$$

Now, can apply levelset stability result.

$$d_B(\text{PH}(d_{\mu,m}), \text{PH}(d_{\nu,m})) \leq \|d_{\mu,m} - d_{\nu,m}\|_{\infty} \leq W_2(\mu, \nu)$$

□.



outliers don't change measure much.

measure assigned to outlier is $\frac{1}{N}$

$$W_2(\mu, \nu) \sim \frac{1}{N} r$$

Problem: this function is defined on
all of \mathbb{R}^d . Want simplicial construction.

End of Ch 5.6.