

Outline:

Graph

Clustering

Dendrograms

Union-find algorithm

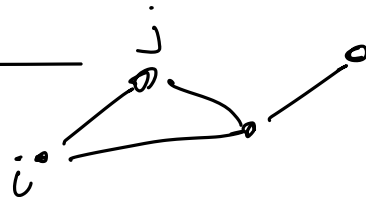
Spectral Clustering.

Graph:  $G(V, E)$

$$|V| = N, |E| = M$$

$$E \subseteq V \times V$$

$$e = (i, j) \quad i, j \in V$$



directed edges

$$i \rightarrow j \neq i \leftarrow j$$



undirected graph

$$(i, j) \sim (j, i)$$

Examples:

Social Networks (vertices: individuals  
edge: friend relation)

Self-loop  
 $(i, i)$

transportation networks (vertices: cities,  
edges: roads)

food webs (species, who eats who)

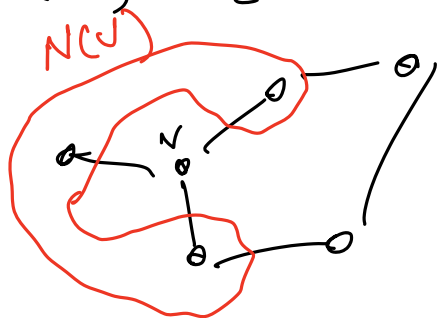
generally, edges encode relationship b/w. entities.

Nearest neighbors graph: edge if two points are  
within some distance from each other.

Assumptions today: undirected, unweighted graphs

$$V = \{1, \dots, N\}$$

Def. the neighborhood of a vertex  $v \in V$  is the set  $N(v) = \{w \in V \mid (v, w) \in E\}$



Def. a path from  $i \in V$  to  $j \in V$  is a sequence of edges  $(i, k_0), (k_0, k_1), \dots, (k_{p-1}, k_p), (k_p, j)$

$i$  and  $j$  are in the same connected component if  $\exists$  a path between  $i$  and  $j$ .

Prop: path connectedness is an equivalence relation.  $i \sim j$  if  $\exists$  path  $i \rightarrow j$   
identity, symmetry, reflexivity.

$i \sim j, j \sim k \Rightarrow i \sim k$  through concatenation of paths.

Equivalence class is a connected component.

Clustering: there are many ways to define this,  
and many algs. (ref. on difficulty in clustering  
Kleinberg)

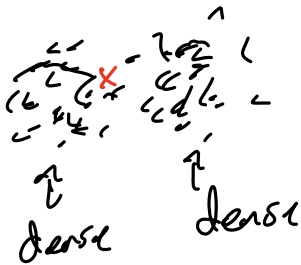
K-means, DBSCAN, ...

we'll focus on notion that is topologically  
meaningful: single linkage clustering.

Examples:



"easy to cluster"

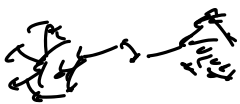


"harder to cluster"

---

idea of single-linkage clustering:

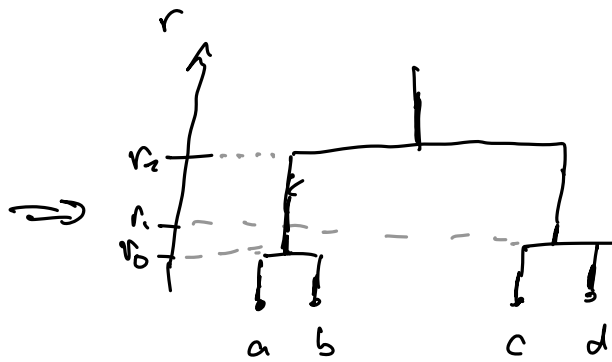
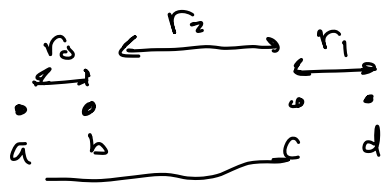
we form a graph that connects points that  
are near each other. the two clusters  
merge if there is a single link btw them.



we identify connected components  
of nbhd graph.

we run into a problem: how to choose nbhd  
parameter? in practice: use all nbhd parameters.

produce what is called a dendrogram, this  
shows how clusters merge.  $\rightarrow$  tree



$$r_0 < r_1 < r_2$$

edge  $(a, c)$  at param  $r_0 + r_2$   
but already in same cluster

Single linkage: single edge merges clusters

average linkage: merge at avg. distance

complete linkage: need to add all edges btw. clusters to merge.

Union-find / Disjoint set data structure

can use to compute dendrogram.

Disjoint set data structure:

two operations:

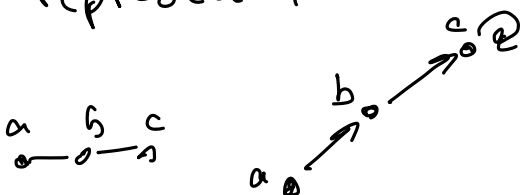
find (find connected component)

union/merge (merge two connected components)

idea: every cluster has a representative point

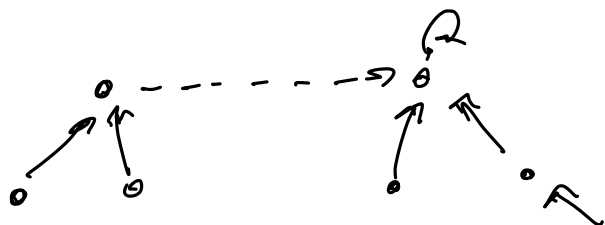
every vertex has a parent in same cluster

representative point is its own parent.

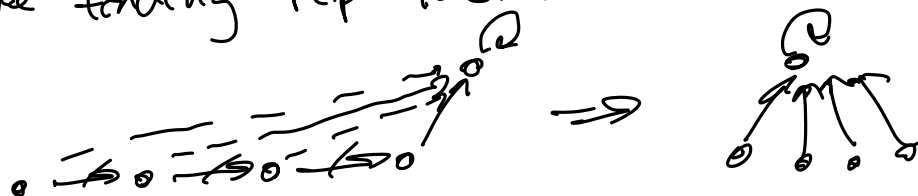


c is the representative point

To merge two clusters, simply find the representative for each cluster, and then make the parent of the rep for smaller cluster the rep for larger cluster.



idea (important for performance) "data compression"  
make finding rep faster each time.



how to represent on computer:

1st data structure:  $N$  points Array

"parent" array of length  $N$

$\text{parent}[i] : i \rightarrow j$

$\text{parent}[i] = i$  if  $i$  rep of cluster.

to form dendrogram every time we add an edge to nbhd graph  $(i, j)$  try merging clusters that contain  $i$  and  $j$ .

if  $\text{rep}(i) = \text{rep}(j)$  then already same cluster.

if  $\text{rep}(i) \neq \text{rep}(j)$  then merge two components

dendrogram just needs to remember which components merged, and which edge caused this to happen, so we can look up parameter value.

analysis:  $\Theta(M \alpha(N))$  time  
inverse ackerman function

---

Spectral Clustering:

recall incidence matrix:  $B \in \mathbb{R}^{N \times M}$

$$\left. \begin{array}{l} B[i, k] = -1 \\ B[j, k] = +1 \end{array} \right\} e_k = (i, j)$$
$$B[\cdot, k] = 0 \text{ otherwise.}$$

we define graph Laplacian  $L = BB^T$ ,  $L \in \mathbb{R}^{N \times N}$

Exercise:  $L = D - A$ ,  $D$  is degree matrix,  $A$  adjacency matrix

Prop:  $L$  satisfies the following properties:

- 1)  $x^T L x = \sum_{(i,j) \in E} (x_i - x_j)^2$
- 2)  $L$  is symmetric, positive semi-definite
- 3) The null eigenspace of  $L$  is spanned by indicator vectors on CC.

$$\text{Pf: } 1: x^T L x = (x^T B) (B^T x) = (B^T x)^T (B^T x)$$

$$\left. \begin{aligned} B[i, k] &= -1 \\ B[j, k] &= +1 \\ B[:, k] &= 0 \end{aligned} \right\} e_k = (i, j)$$

$$B^T[k] = x_j - x_i$$

$$(B^T x)^T (B^T x) = \sum_{(i,j) \in E} (x_j - x_i)^2$$

2) symmetry obvious. Positive semi-definite:

$$x^T L x \geq 0 \quad \forall x \quad \text{implied by (1)}$$

3) we can verify this let  $\mathbb{1}_C$  be an indicator on  $C$ .

$$\mathbb{1}_C[i] = \begin{cases} 1 & \text{if } i \in C \\ 0 & \text{if } i \notin C \end{cases}$$

$$x_i - x_j = 0 = (-1) \quad \text{if } i, j \in C \leftarrow$$

$$x_i - x_j = 0 = 0 - 0 \quad \text{if } i, j \notin C \leftarrow$$

no other edges.

$$\mathbb{1}_C^T L \mathbb{1}_C = 0 \quad \forall \text{ indicators on } C. \quad \square$$

What abl. weak connectors? e.g. SBM.



want to partition  $V$  into  $S \subseteq V$   $\bar{S} \subseteq V$   
 $S \cup \bar{S} = V, S \cap \bar{S} = \emptyset$

minimize quantity

$$h_G(S) = \frac{|E(S, \bar{S})|}{\min(|S|, |\bar{S}|)}$$

Cheeger inequality:

$$2h_G \leq \lambda_1 \leq \frac{h_G^2}{2} \quad (\lambda_1 = \text{smallest non-zero eigenvalue of } L)$$

idea to use eigenvector  $v_1$  for an embedding  
and do clustering in embedded space.