

Aizzo

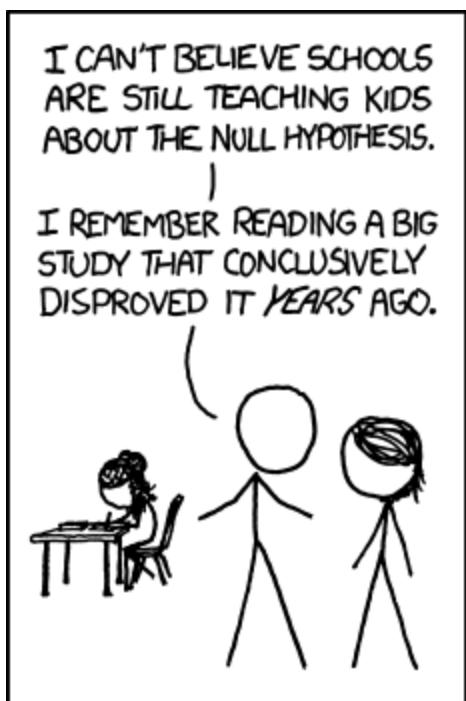
## Chapter 2: Probability for Statistical Computing

just like we did  
for R

We will **briefly** review some definitions and concepts in probability and statistics that will be helpful for the remainder of the class.

Just like we reviewed computational tools (**R** and packages), we will now do the same for probability and statistics.

**Note:** This is not meant to be comprehensive. I am assuming you already know this and maybe have forgotten a few things.



i.e. you may need to do some refreshing outside  
of class as well.

<https://xkcd.com/892/>

Alternative text: "Hell, my eighth grade science class managed to conclusively reject it just based on a classroom experiment. It's pretty sad to hear about million-dollar research teams who can't even manage that."

# 1 Random Variables and Probability

**Definition 1.1** A *random variable* is a function that maps sets of all possible outcomes of an experiment (sample space  $\Omega$ ) to  $\mathbb{R}$ .

↪ real number line.

**Example 1.1**

Toss 2 dice

$X = \text{sum of the dice}$

r.v.

**Example 1.2**

Randomly select 25 deer & test for CWD (chronic wasting disease)

Sample  $\{+, -\}$  (CWD test)

$X \sim \{0, 1\}$  observe  $X_1, \dots, X_{25}$  ← each a r.v.

Note  $P = \frac{\sum_{i=1}^{25} X_i}{25}$  is also a r.v.!

**Example 1.3**

Today's high temperature =  $X_i$

Types of random variables –

**Discrete** take values in a countable set.

Ex. 1.1 and  $X_i$  from Ex 1.2

**Continuous** take values in an uncountable set (like  $\mathbb{R}$ )

↪ real numbers  $(-\infty, \infty)$

Ex. 1.3  $X_i \in \mathbb{R}$

$P$  from ex. 1.2,  $p \in [0, 1]$ .

## 1.1 Distribution and Density Functions

**Definition 1.2** The probability mass function (pmf) of a random variable  $X$  is  $f_X$  defined by

only defined for discrete r.v.'s

$$f_X(x) = P(X = x)$$

sometimes when the r.v. is obvious we'll omit the subscript, just write  $f(x)$ .

where  $P(\cdot)$  denotes the probability of its argument.

There are a few requirements of a valid pmf

$$1. f(x) \geq 0 \text{ for all } x$$

$$2. \sum_x f(x) = 1$$

Not a requirement 3. We call  $\mathcal{X} = \{x : f(x) > 0\}$  the "support" of  $X$ .  
fair

**Example 1.4** Let  $\Omega$  = all possible values of a roll of a single die =  $\{1, \dots, 6\}$  and  $X$  be the outcome of a single roll of one die  $\in \{1, \dots, 6\}$ .

$$f(1) = P(X=1) = \frac{1}{6}$$

$$\vdots$$

$$f(6) = \frac{1}{6}$$

$$1. f(x) \geq 0 \forall x.$$

$$2. \sum_{x \in \mathcal{X}} f(x) = \sum_{i=1}^6 \frac{1}{6} = 1$$

✓ valid pmf.

support  $\mathcal{X} = \{1, 2, \dots, 6\}$ .

A pmf is defined for **discrete variables**, but what about **continuous**? Continuous variables do not have positive probability mass at any single point.

**Definition 1.3** The probability density function (pdf) of a random variable  $X$  is  $f_X$  defined by

$$P(X \in A) = \int_{x \in A} f_X(x) dx.$$

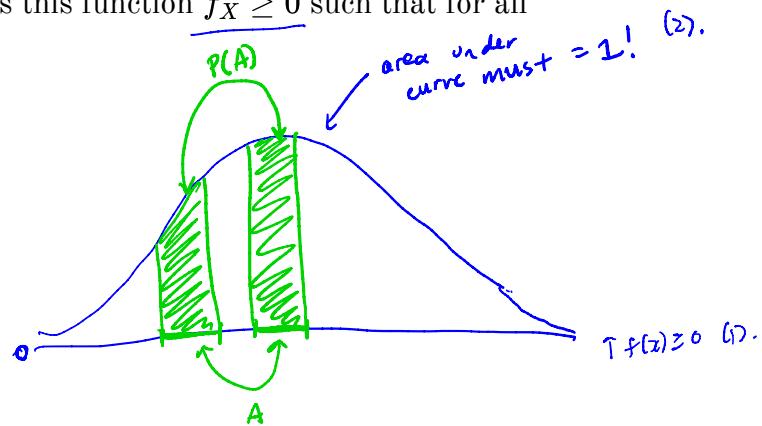
$X$  is a continuous random variable if there exists this function  $f_X \geq 0$  such that for all  $x \in \mathbb{R}$ , this probability exists.

For  $f_X$  to be a valid pdf,

$$1. f(x) \geq 0 \forall x$$

$$2. \int_{\mathbb{R}} f(x) dx = 1$$

Again  $\mathcal{X} = \{x : f(x) > 0\}$   
is the "support" of  $X$ .



There are many named pdfs and cdfs that you have seen in other class, e.g.

Gamma, Poisson, Normal, Uniform, student t, snedecor's F,  $\chi^2$ , binomial, exponential, Beta, hypergeometric...

**Example 1.5** Let

$$f(x) = \begin{cases} c(4x - 2x^2) & \text{shape} \\ 0 & 0 < x < 2 \\ \text{otherwise} & \end{cases}$$

*to make f a valid pdf*

\* The support  $(0, 2)$ .

Find  $c$  and then find  $P(X > 1)$

$$1 = \int_0^2 c(4x - 2x^2) dx = c \left[ 2x^2 - \frac{2x^3}{3} \right]_0^2 = c \left[ \frac{8}{3} \right] \Rightarrow c = \frac{3}{8} \quad \text{"normalizing constant"}$$

$$P(X > 1) = \int_1^\infty f(x) dx = \int_1^2 \frac{3}{8}(4x - 2x^2) dx = \frac{3}{8} \left[ 2x^2 - \frac{2x^3}{3} \right]_1^2 = \frac{1}{2}$$

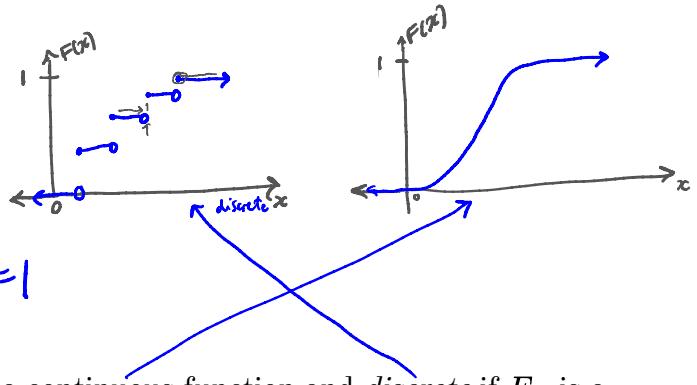
**Definition 1.4** The *cumulative distribution function (cdf)* for a random variable  $X$  is  $F_X$  defined by

$$F_X(x) = P(X \leq x), \quad x \in \mathbb{R}.$$

↓ for both cts and discrete.

The cdf has the following properties

1.  $F_X$  is non decreasing
2.  $F_X$  is right-continuous
3.  $\lim_{x \rightarrow -\infty} F_X(x) = 0$  and  $\lim_{x \rightarrow \infty} F_X(x) = 1$



A random variable  $X$  is *continuous* if  $F_X$  is a continuous function and *discrete* if  $F_X$  is a step function.

**Example 1.6** Find the cdf for the previous example.

$$F(x) = P(X \leq x) = \begin{cases} 0 & x \leq 0 \\ \frac{3}{4}x^2 \left(1 - \frac{x}{3}\right) & x \in (0, 2) \\ 1 & x \geq 2 \end{cases}$$

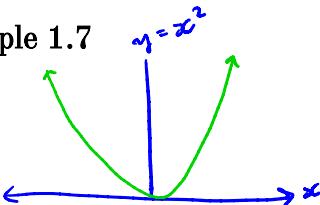
$$\begin{aligned} \text{For } x \in (0, 2), P(X \leq x) &= \int_0^x \frac{3}{8}(4y - 2y^2) dy \\ &= \frac{3}{8} \left[ 2y^2 - \frac{2y^3}{3} \right]_0^x \\ &= \frac{3}{4}x^2 \left(1 - \frac{x}{3}\right) \end{aligned}$$

Note  $f(x) = F'(x) = \frac{dF(x)}{dx}$  in the continuous case.  
*derivative of cdf wrt x = pdf.*

Recall an indicator function is defined as

$$1_{\{A\}} = \begin{cases} 1 & \text{if } A \text{ is true} \\ 0 & \text{otherwise} \end{cases} . \quad 1_A(x) = \begin{cases} 1 & \text{if } x \in A \\ 0 & \text{otherwise} \end{cases}$$

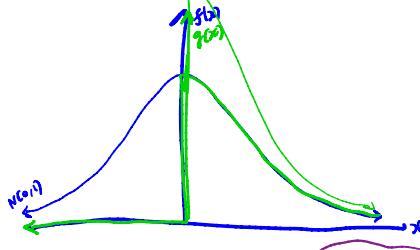
**Example 1.7**



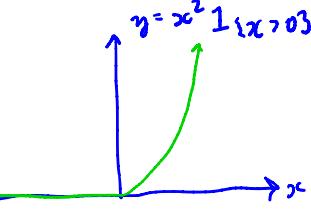
**Example 1.8** If  $X \sim N(0, 1)$ , the pdf is  $f(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$  for  $-\infty < x < \infty$ .

If  $g(x) = \frac{c}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) 1_{\{x>0\}}$ , what is  $c$ ? *in order for g to be a valid pdf?*

$$= c \cdot 1_{\{x>0\}} f(x).$$



$$\text{Need: } 1 = \int_{-\infty}^{\infty} g(x) dx = \left[ \int_0^{\infty} \frac{c}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx \right]$$



We know by symmetry of  $N(0, 1)$  around 0,

$$c \int_0^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx = \frac{c}{2}$$

$$\Rightarrow \text{need } c = 2.$$

## 1.2 Two Continuous Random Variables

**Definition 1.5** The joint pdf of the continuous vector  $(X, Y)$  is defined as

$$P((X, Y) \in A) = \iint_A f_{X,Y}(x, y) dxdy$$

for any set  $A \subset \mathbb{R}^2$ .

Joint pdfs have the following properties

$$1. f_{X,Y}(x, y) \geq 0 \quad \forall x, y \in \mathbb{R}^2$$

$$2. \iint_{-\infty}^{\infty} f_{X,Y}(x, y) dx = 1$$

and a support defined to be  $\{(x, y) : f_{X,Y}(x, y) > 0\}$ . *"X"*

Note: can also have joint discrete r.v.'s where

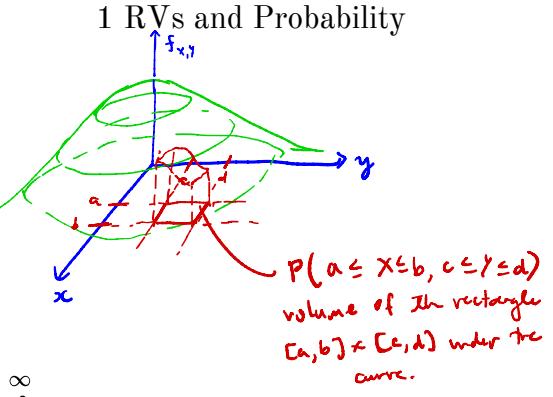
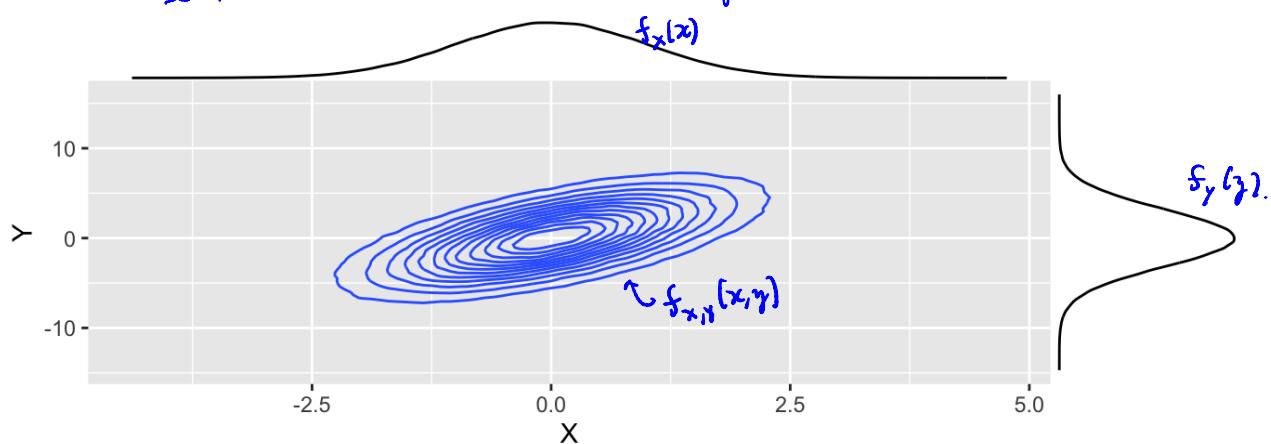
$$\sum_x \sum_y f(x, y) = 1.$$

**Example 1.9**

$$P(a \leq X \leq b, c \leq Y \leq d) = \int_a^b \int_c^d f_{X,Y}(x,y) dy dx$$

The *marginal densities* of  $X$  and  $Y$  are given by

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy \quad \text{and} \quad f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx;$$



**Example 1.10** (From Devore (2008) Example 5.3, pg. 187) A bank operates both a drive-up facility and a walk-up window. On a randomly selected day, let  $X$  be the proportion of time that the drive-up facility is in use and  $Y$  is the proportion of time that the walk-up window is in use.

The set of possible values for  $(X, Y)$  is the square  $D = \{(x, y) : 0 \leq x \leq 1, 0 \leq y \leq 1\}$ . Suppose the joint pdf is given by

$$f_{X,Y}(x,y) = \begin{cases} \frac{6}{5}(x+y^2) & x \in [0,1], y \in [0,1] \\ 0 & \text{otherwise} \end{cases}$$

NOTE:  
 $\int_0^1 \int_0^1 \frac{6}{5}(x+y^2) dx dy = 1$   
 valid joint pdf

Evaluate the probability that both the drive-up and the walk-up windows are used a quarter of the time or less.

$$\begin{aligned} P(0 \leq X \leq \frac{1}{4}, 0 \leq Y \leq \frac{1}{4}) &= \int_0^{\frac{1}{4}} \int_0^{\frac{1}{4}} \frac{6}{5}(x+y^2) dx dy \\ &= \int_0^{\frac{1}{4}} \frac{6}{5} \left[ \frac{x^2}{2} + xy^2 \right]_{x=0}^{x=\frac{1}{4}} dy \\ &= \int_0^{\frac{1}{4}} \frac{6}{5} \left( \frac{1}{32} + \frac{y^2}{4} \right) dy \\ &= \left. \frac{6}{5} \left( \frac{y}{32} + \frac{y^3}{12} \right) \right|_0^{\frac{1}{4}} = \frac{6}{5} \left( \frac{1}{32} \cdot \frac{1}{4} + \frac{1}{12} \left( \frac{1}{4} \right)^3 \right) = \frac{7}{640} = 0.0109 \end{aligned}$$

Find the marginal densities for  $X$  and  $Y$ .

$$f_X(x) = \int_0^1 \frac{6}{5} (x+y^2) dy = \frac{6}{5} \left[ xy + \frac{y^3}{3} \right]_{y=0}^1 = \begin{cases} \frac{6}{5} \left( x + \frac{1}{3} \right) & x \in [0, 1] \\ 0 & \text{o.w.} \end{cases}$$

$$f_Y(y) = \int_0^1 \frac{6}{5} (x+y^2) dx = \frac{6}{5} \left[ \frac{x^2}{2} + xy^2 \right]_{x=0}^1 = \begin{cases} \frac{6}{5} \left( \frac{1}{2} + y^2 \right) & y \in [0, 1] \\ 0 & \text{o.w.} \end{cases}$$

Compute the probability that the drive-up facility is used a quarter of the time or less.

$$\begin{aligned} P(X \leq \frac{1}{4}) &= \int_0^{\frac{1}{4}} f_X(x) dx = \int_0^{\frac{1}{4}} \frac{6}{5} \left( x + \frac{1}{3} \right) dx = \frac{6}{5} \left[ \frac{x^2}{2} + \frac{1}{3}x \right]_0^{\frac{1}{4}} = \frac{6}{5} \left[ \frac{1}{4} \cdot \frac{1}{2} + \frac{1}{3} \cdot \frac{1}{4} \right] \\ &= \frac{11}{80} = 0.1375. \end{aligned}$$

## 2 Expected Value and Variance

**Definition 2.1** The *expected value* (average or mean) of a random variable  $X$  with pdf or pmf  $f_X$  is defined as

$$E[X] = \begin{cases} \sum_{x \in \mathcal{X}} x f_X(x_i) & X \text{ is discrete } (f_X \text{ is pmf}) \\ \int_{x \in \mathcal{X}} x f_X(x) dx & X \text{ is continuous. } (f_X \text{ is pdf}) \end{cases}$$

Where  $\mathcal{X} = \{x : f_X(x) > 0\}$  is the support of  $X$ .

This is a weighted average of all possible values  $\mathcal{X}$  by the probability distribution.

**Example 2.1** Let  $X \sim \text{Bernoulli}(p)$ . Find  $E[X]$ .

$$\Rightarrow X = \begin{cases} 1 & \text{p.r.} \\ 0 & \text{o.w.} \end{cases} \Rightarrow f(x) = \begin{cases} p & x=1 \\ 1-p & x=0 \\ 0 & \text{o.w.} \end{cases} \text{ or } f(x) = p^x (1-p)^{1-x} \text{ for } x \in \{0, 1\}.$$

p(X=x)  
// pmf  
p parameter  
support

$$E[X] = \sum_{x \in \{0, 1\}} x f(x) = \sum_{x \in \{0, 1\}} x \cdot p^x (1-p)^{1-x} = 0 \cdot (1-p) + 1 \cdot p = p$$

**Example 2.2** Let  $X \sim \text{Exp}(\lambda)$ . Find  $E[X]$ .

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & \text{o.w.} \end{cases}$$

$$E[X] = \int_0^\infty x \lambda e^{-\lambda x} dx$$

integration by parts  
(H.W 3)

$$\int u dv = uv - \int v du$$

↑  
pick u and dv

**Definition 2.2** Let  $g(X)$  be a function of a continuous random variable  $X$  with pdf  $f_X$ .

Then,

$$* E[g(X)] = \int_{x \in \mathcal{X}} g(x) f_X(x) dx.$$

Sometimes this is hard to compute by hand!  
 $\Rightarrow$  will need stat computing to estimate this value.  
(ch. 5).

**Definition 2.3** The *variance* (a measure of spread) is defined as

$$\begin{aligned} \text{Var}[X] &= E[(X - E[X])^2] \leftarrow \text{defn} \\ &= E[X^2] - (E[X])^2 \leftarrow \text{computational def'n} \end{aligned}$$

**Example 2.3** Let  $X$  be the number of cylinders in a car engine. The following is the pmf function for the size of car engines.

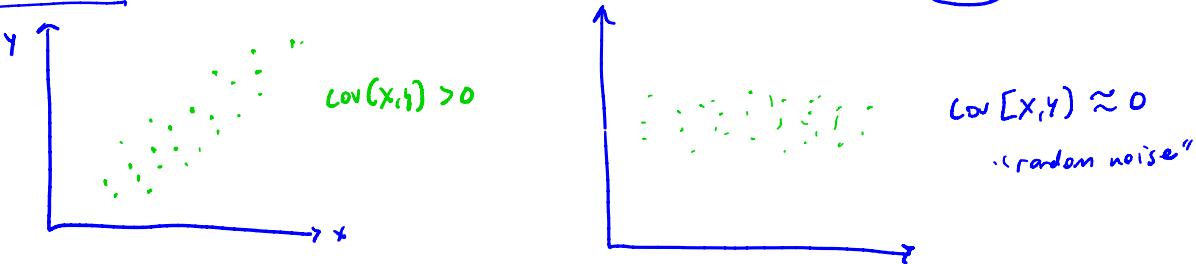
x	4.0	6.0	8.0
f	0.5	0.3	0.2

Find

$$E[X] = \sum_x x f(x) = 4(0.5) + 6(0.3) + 8(0.2) = 5.4$$

$$\begin{aligned} Var[X] &= E(X^2) - (EX)^2 \\ E(X^2) &= \sum_x x^2 f(x) = 4^2(0.5) + 6^2(0.3) + 8^2(0.2) = 31.6 \\ \Rightarrow Var[X] &= 31.6 - (5.4)^2 = 2.44 \quad \text{easier to interpret: } sd = \sqrt{Var[X]} = 1.56 \end{aligned}$$

Covariance measures how two random variables vary together (their linear relationship).



**Definition 2.4** The covariance of  $X$  and  $Y$  is defined by

$$\begin{aligned} Cov[X, Y] &= E[(X - E[X])(Y - E[Y])] \\ &= E[XY] - E[X]E[Y] \end{aligned}$$

Note: for 2 r.v.'s  
 $E[g(x,y)] = \iint g(x,y) f_{x,y}(x,y) dx dy$   
 computational definition

and the correlation of  $X$  and  $Y$  is defined as

$$\rho(X, Y) = \frac{Cov[X, Y]}{\sqrt{Var[X]Var[Y]}}.$$

Two variables  $X$  and  $Y$  are uncorrelated if  $\rho(X, Y) = 0$ .

no linear relationship.

# 3 Independence and Conditional Probability

In classical probability, the *conditional probability* of an event  $A$  given that event  $B$  has occurred is

$$P(A|B) = \frac{P(A \cap B)}{P(B)}. \quad \xrightarrow{\text{defn}} P(A|B) P(B) = P(A \cap B).$$

*"given"*       *$A$  "and"  $B$*

**Definition 3.1** Two events  $A$  and  $B$  are *independent* if  $P(A|B) = P(A)$ . The converse is also true, so

$$A \text{ and } B \text{ are independent} \Leftrightarrow P(A|B) = P(A) \Leftrightarrow P(A \cap B) \stackrel{\text{defn}}{=} P(A|B)P(B) = P(A)P(B) \text{ independent.}$$

**Theorem 3.1 (Bayes' Theorem)** Let  $A$  and  $B$  be events. Then,

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{P(B|A)P(A)}{P(B)}$$

*Bayes' thm.*

## 3.1 Random variables

The same ideas hold for random variables. If  $X$  and  $Y$  have joint pdf  $f_{X,Y}(x,y)$ , then the conditional density of  $X$  given  $Y = y$  is

$$f_{X|Y=y}(x) = \frac{f_{X,Y}(x,y)}{f_Y(y)}.$$

*joint pdf*  
*"and"*  
*marginal pdf*  
 *$y = y$ .*

Thus, two random variables  $X$  and  $Y$  are independent if and only if

$$f_{X,Y}(x,y) = f_X(x)f_Y(y).$$

*joint pdf*      *product of marginal pdfs.*

Also, if  $X$  and  $Y$  are independent, then

$$f_{X|Y=y}(x) = \frac{f_{X,Y}(x,y)}{f_Y(y)} = \frac{f_X(x)f_Y(y)}{f_Y(y)} = f_X(x)$$

*conditional pdf*      *defn*      *indep.*      *marginal pdf of  $X$ .*  
*of conditional pdf*      *of  $X \& Y$*

## 4 Properties of Expected Value and Variance

Suppose that  $X$  and  $Y$  are random variables, and  $a$  and  $b$  are constants. Then the following hold:

$$1. E[aX + b] = aE\cancel{X} + b$$

$$2. E[X + Y] = E\cancel{X} + E\cancel{Y}$$

$$3. \text{ If } X \text{ and } Y \text{ are } \underline{\text{independent}}, \text{ then } E[XY] = E\cancel{X} E\cancel{Y}$$

$$4. Var[b] = 0$$

$$5. Var[aX + b] = a^2 Var\cancel{X}$$

$$6. \text{ If } X \text{ and } Y \text{ are } \underline{\text{independent}}, Var[X + Y] = Var\cancel{X} + Var\cancel{Y}$$

# 5 Random Samples

**Definition 5.1** Random variables  $\{X_1, \dots, X_n\}$  are defined as a random sample from  $f_X$  if  $X_1, \dots, X_n \stackrel{iid}{\sim} f_X$ . "independent and identically distributed"

**Example 5.1**

$$X_1, \dots, X_n \stackrel{iid}{\sim} N(0, \sigma^2)$$

vs.

$$\left. \begin{array}{l} X_1 \sim N(\mu_1, \sigma^2) \\ X_2 \sim N(\mu_2, \sigma^2) \end{array} \right\} \begin{array}{l} \text{may be independent,} \\ \text{but if } \mu_1 \neq \mu_2 \\ \text{they are NOT identically} \\ \text{distributed.} \end{array}$$

**Theorem 5.1** If  $X_1, \dots, X_n \stackrel{iid}{\sim} f_X$ , then

$$f(x_1, \dots, x_n) = \prod_{i=1}^n f_X(x_i).$$

joint dsn      product marginals  
 ↑  
 some marginal distribution  
 for each  $X_i$

**Example 5.2** Let  $X_1, \dots, X_n$  be iid. Derive the expected value and variance of the sample

$$\text{mean } \bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i.$$

in terms of  $E X_i$  and  $\text{Var } X_i$

$$E(\bar{X}_n) = E\left(\frac{1}{n} \sum_{i=1}^n X_i\right) = \frac{1}{n} E\left(\sum_{i=1}^n X_i\right) \stackrel{\substack{\text{iid} \\ \text{prop. 1}}}{=} \frac{1}{n} \sum_{i=1}^n E X_i = \frac{1}{n} \sum_{i=1}^n E X_i = \frac{1}{n} \cdot n \cdot E X_i = E X_i$$

$$\text{Var}(\bar{X}_n) = \text{Var}\left(\frac{1}{n} \sum_{i=1}^n X_i\right) = \frac{1}{n^2} \text{Var}\left(\sum_{i=1}^n X_i\right) \stackrel{\substack{\text{indep} \\ \text{prop. 5}}}{=} \frac{1}{n^2} \sum_{i=1}^n \text{Var } X_i = \frac{1}{n^2} \sum_{i=1}^n \text{Var } X_i = \frac{1}{n^2} \cdot n \cdot \text{Var } X_i = \frac{\text{Var } X_i}{n}$$

# 6 R Tips

From here on in the course we will be dealing with a lot of **randomness**. In other words, running our code will return a **random** result.

But what about reproducibility?? *pseudorandom*

When we generate “random” numbers in R, we are actually generating numbers that *look* random, but are *pseudo-random* (not really random). The vast majority of computer languages operate this way.

This means all is not lost for reproducibility!

*set starting place for our pseudorandom number generator*  
`set.seed(400)`

Before running our code, we can fix the starting point (**seed**) of the pseudorandom number generator so that we can reproduce results.

Speaking of generating numbers, we can generate numbers (also evaluate densities, distribution functions, and quantile functions) from named distributions in R.

