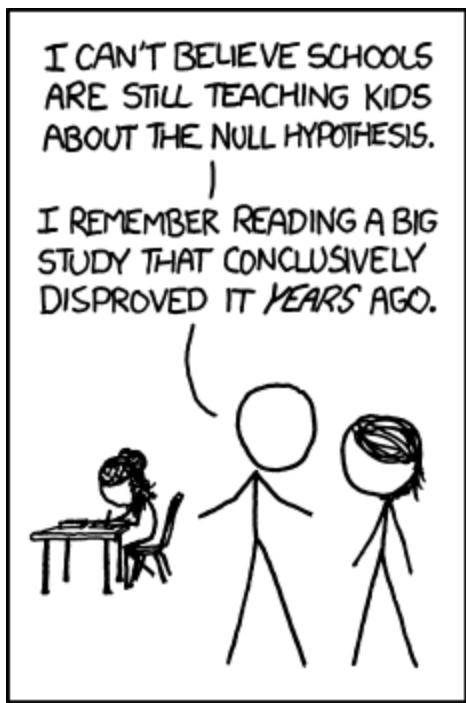


# Chapter 2: Probability for Statistical Computing

We will **briefly** review some definitions and concepts in probability and statistics that will be helpful for the remainder of the class.

Just like we reviewed computational tools (**R** and packages), we will now do the same for probability and statistics.

**Note:** This is not meant to be comprehensive. I am assuming you already know this and maybe have forgotten a few things.



i.e. you may need to look some  
things up on your own.

<https://xkcd.com/892/>

Alternative text: “Hell, my eighth grade science class managed to conclusively reject it just based on a classroom experiment. It’s pretty sad to hear about million-dollar research teams who can’t even manage that.”

# 1 Random Variables and Probability

**Definition 1.1** A random variable is a function that maps sets of all possible outcomes of an experiment (sample space  $\Omega$ ) to  $\mathbb{R}$

"real numbers"

$(-\infty, \infty)$

**Example 1.1**

experiment: Toss 2 dice.

$$\Omega = \{(i, j) : i=1, \dots, 6; j=1, \dots, 6\}$$

r.v.  $X = \text{sum of the dice.}$

**Example 1.2**

experiment: Randomly select 25 deer & test for CWD

r.v.  $X_i : \{0 \text{ or } 1\} \text{ observe } X_1, \dots, X_{25} \quad \Omega = \{+, - \text{ CWD}\}$

r.v.  $P = \frac{\sum_{i=1}^{25} X_i}{25} \text{ is also a r.v.!}$

**Example 1.3**

experiment: Deck of cards, draw one card

r.v.  $X : 1 \text{ if clubs, } 0 \text{ otherwise.} \quad \Omega = \{\text{values of all 52 cards in a deck}\}$

$\subseteq \{\text{AC, 2C, 3C, ..., KC,}$

$\text{AS, 2S, ..., KS,}$

$\text{AD, 2D, ..., KD,}$

$\text{AH, 2H, ..., RH}\}$

Ex. 1.4  
Today's temp =  $X_i$   
high

Types of random variables -

**Discrete** take values in a countable set.

Ex. 1.1

$X_i$  from Ex 1.2,  $X$  from Ex 1.3

**Continuous** take values in an uncountable set (like  $\mathbb{R}$ )

Ex 1.4  $X_i \in \mathbb{R}$

$p$  from Ex 1.2,  $p \in [0, 1]$

## 1.1 Distribution and Density Functions

**Definition 1.2** The probability mass function (pmf) of a random variable  $X$  is  $f_X$  defined by

Notation: sometimes when the r.v. is obvious I will omit the subscript and write  $f(x)$ .

$$f_X(x) = P(X = x) \quad \text{for any } x \in \mathbb{R}$$

where  $P(\cdot)$  denotes the probability of its argument.

There are a few requirements of a valid pmf

1.  $f(x) \geq 0$  for all  $x \in \mathbb{R}$ .

2.  $\sum_x f(x) = 1$

Not a requirement 3. We call  $\mathcal{X} = \{x : f(x) > 0\}$  the "support" of  $X$ .

**Example 1.4** Let  $\Omega$  = all possible values of a roll of a single die =  $\{1, \dots, 6\}$  and  $X$  be the outcome of a single roll of one die  $\in \{1, \dots, 6\}$ .

Fair die  
 $f(1) = P(X=1) = \frac{1}{6}$   
 $\vdots$   
 $f(6) = \frac{1}{6}$

$$\sum_{x \in \mathcal{X}} f(x) = \sum_{x=1}^6 \frac{1}{6} = 1 \quad \checkmark \text{ valid pmf.}$$

A pmf is defined for **discrete variables**, but what about **continuous**? Continuous variables do not have positive probability **mass** at any single point.

**Definition 1.3** The probability density function (pdf) of a random variable  $X$  is  $f_X$  defined by

$A \subset \mathbb{R}$

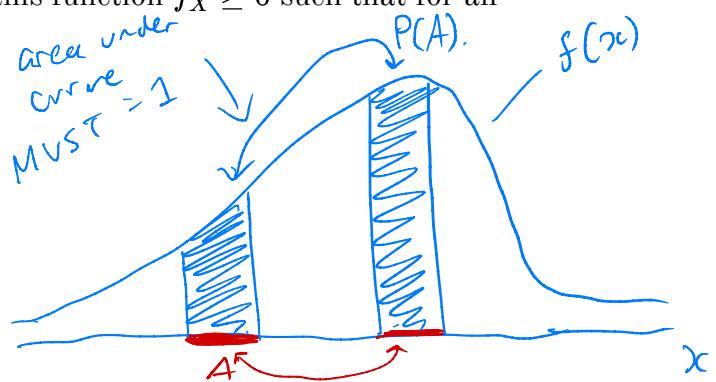
$$P(X \in A) = \int_{x \in A} f_X(x) dx.$$

$X$  is a continuous random variable if there exists this function  $f_X \geq 0$  such that for all  $x \in \mathbb{R}$ , this probability exists.

For  $f_X$  to be a valid pdf,

1.  $f(x) \geq 0 \quad \forall x \in \mathbb{R}$

2.  $\int_{-\infty}^{\infty} f(x) dx = 1$



Again  $\mathcal{X} = \{x : f(x) > 0\}$  is the "support" of  $X$

pmfs

There are many named pdfs and pmfs that you have seen in other class, e.g.

Bernoulli, Poisson, Gamma, Normal, Beta, exponential, hypergeometric.

**Example 1.5** Let

$$f(x) = \begin{cases} c(4x - 2x^2) & 0 < x < 2 \\ 0 & \text{otherwise} \end{cases}$$

support

Find  $c$  and then find  $P(X > 1)$

↳ such that  $f(x)$  is a valid pdf.

$$\int_0^2 c(4x - 2x^2) dx = c \left[ 2x^2 - \frac{2x^3}{3} \right]_0^2 = c \left[ \frac{8}{3} \right] \Rightarrow c = \frac{3}{8}$$

"normalizing constant"

$$P(X > 1) = \int_1^\infty f(x) dx = \int_1^2 \frac{3}{8} (4x - 2x^2) dx = \frac{3}{8} \left[ 2x^2 - \frac{2x^3}{3} \right]_1^2 = \frac{1}{2}$$

**Definition 1.4** The cumulative distribution function (cdf) for a random variable  $X$  is  $F_X$  defined by

cdf function of  $x \in \mathbb{R}$

$$F_X(x) = P(X \leq x), \quad x \in \mathbb{R}.$$

↳ same def'n for both cts and discrete r.v.'s

The cdf has the following properties

1.  $F_X$  is non-decreasing
2.  $F_X$  is right-continuous
3.  $\lim_{x \rightarrow -\infty} F_X(x) = 0$     $\lim_{x \rightarrow \infty} F_X(x) = 1$

A random variable  $X$  is *continuous* if  $F_X$  is a continuous function and *discrete* if  $F_X$  is a step function.

**Example 1.6** Find the cdf for the previous example.

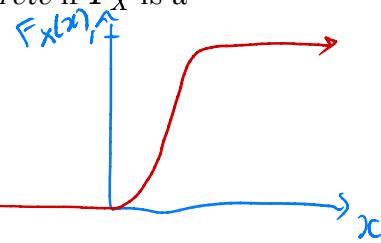
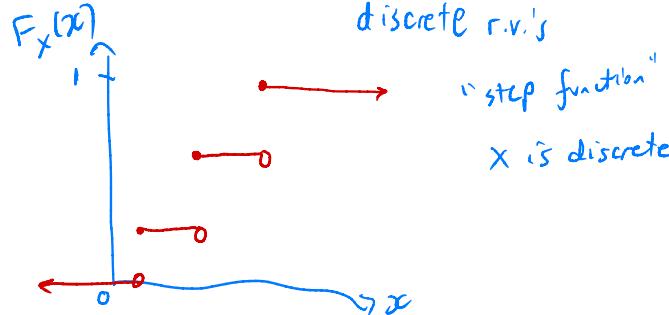
$$F_X(x) = P(X \leq x)$$

$$\text{for } x \in (0, 2), \quad P(X \leq x) = \int_0^x \frac{3}{8} (4y - 2y^2) dy = \left[ \frac{3}{8} \left( 2y^2 - \frac{2y^3}{3} \right) \right]_0^x$$

$$\text{So, } F_X(x) = \begin{cases} 0 & x \leq 0 \\ \frac{3}{4} x^2 \left(1 - \frac{x}{3}\right) & x \in (0, 2) \\ 1 & x \geq 2 \end{cases} = \frac{3}{4} x^2 \left(1 - \frac{x}{3}\right)$$

Note  $f(x) = F'(x) = \frac{dF(x)}{dx}$  in the continuous case.

pdf derivative  
of cdf

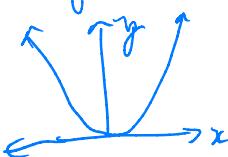


due to the Fundamental Thm of Calculus.

Recall an indicator function is defined as

$$1_{\{A\}} = \begin{cases} 1 & \text{if } A \text{ is true} \\ 0 & \text{otherwise} \end{cases}.$$

**Example 1.7**  $y = x^2$



**Example 1.8** If  $X \sim N(0, 1)$ , the pdf is  $f(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$  for  $-\infty < x < \infty$ .

If  $f(x) = \frac{c}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) 1_{\{x>0\}}$ , what is  $c$ ?

We have symmetry of  $N(0, 1)$  around 0.

$$\Rightarrow \int_0^\infty \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx = \frac{1}{2}$$

$$1 = c \int_0^\infty \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx = \frac{c}{2} \Rightarrow c = 2.$$

## 1.2 Two Continuous Random Variables

**Definition 1.5** The joint pdf of the continuous vector  $(X, Y)$  is defined as

$$P((X, Y) \in A) = \iint_A f_{X,Y}(x, y) dxdy$$

for any set  $A \subset \mathbb{R}^2$ .

Joint pdfs have the following properties

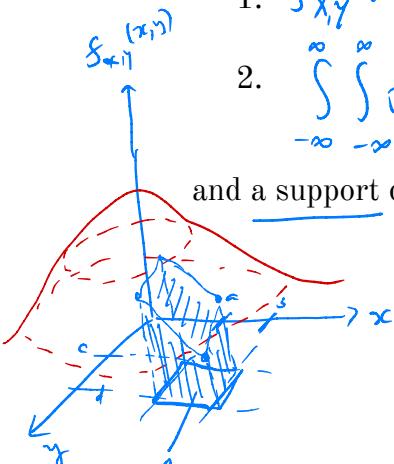
$$1. f_{X,Y}(x, y) \geq 0 \quad \forall x, y \in \mathbb{R}^2$$

$$2. \iint_{-\infty}^{\infty} \iint_{-\infty}^{\infty} f_{X,Y}(x, y) dxdy = 1$$

and a support defined to be  $\{(x, y) : f_{X,Y}(x, y) > 0\} = \mathcal{X}$

Note: We can also have jointly discrete r.v.'s w/ corresponding joint pmfs where

$$\sum \sum f_{X,Y}(x, y) = 1.$$

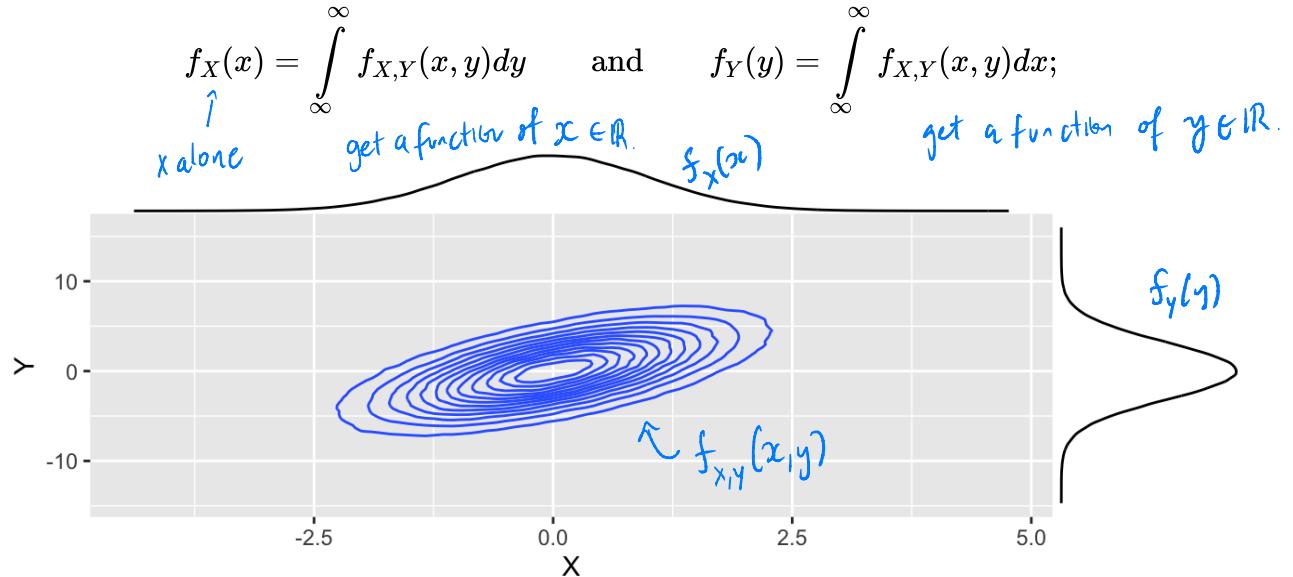


example A could be rectangle

$$x \in [a, b] \\ y \in [c, d]$$

## Example 1.9

The *marginal densities* of  $X$  and  $Y$  are given by



**Example 1.10** (From Devore (2008) Example 5.3, pg. 187) A bank operates both a drive-up facility and a walk-up window. On a randomly selected day, let  $X$  be the proportion of time that the drive-up facility is in use and  $Y$  is the proportion of time that the walk-up window is in use.

The set of possible values for  $(X, Y)$  is the square  $D = \{(x, y) : 0 \leq x \leq 1, 0 \leq y \leq 1\}$ . Suppose the joint pdf is given by

$$f_{X,Y}(x, y) = \begin{cases} \frac{6}{5}(x + y^2) & x \in [0, 1], y \in [0, 1] \\ 0 & \text{otherwise} \end{cases}$$

support  
 $\{(x, y) : 0 \leq x \leq 1, 0 \leq y \leq 1, \text{ not both } x, y = 0\}$

Evaluate the probability that both the drive-up and the walk-up windows are used a quarter of the time or less.

$$\begin{aligned}
 P(0 \leq x \leq \frac{1}{4}, 0 \leq y \leq \frac{1}{4}) &= \int_0^{1/4} \int_0^{1/4} \frac{6}{5}(x + y^2) dx dy \\
 &= \int_0^{1/4} \int_0^{1/4} \left[ \frac{x^2}{2} + xy^2 \right]_0^{1/4} dy \\
 &= \int_0^{1/4} \frac{6}{5} \left( \frac{1}{32} + \frac{y^2}{4} \right) dy \\
 &= \left[ \frac{6}{5} \left( \frac{y^2}{32} + \frac{y^3}{12} \right) \right]_0^{1/4} = \frac{6}{5} \left( \frac{1}{32} \cdot \frac{1}{4} + \frac{1}{12} \left( \frac{1}{4} \right)^3 \right) = \frac{7}{640} \\
 &= 0.0109
 \end{aligned}$$

Find the marginal densities for  $X$  and  $Y$ .

$$f_X(x) = \int_0^1 \frac{6}{5} (x+y^2) dy = \frac{6}{5} \left[ xy + \frac{y^3}{3} \right]_{y=0}^1 = \begin{cases} \frac{6}{5} \left( x + \frac{1}{3} \right) & \text{for } x \in [0, 1] \\ 0 & \text{o.w.} \end{cases}$$

$$f_Y(y)$$



Leave up to you.

~~X~~ Compute the probability that the drive-up facility is used a quarter of the time or less.

$$\begin{aligned} P(X \leq \frac{1}{4}) &= \int_0^{1/4} f_X(x) dx = \int_0^{1/4} \frac{6}{5} \left( x + \frac{1}{3} \right) dx \\ &= \frac{6}{5} \left[ \frac{x^2}{2} + \frac{x}{3} \right]_0^{1/4} \\ &= \frac{11}{80} = 0.1375 \end{aligned}$$

## 2 Expected Value and Variance

**Definition 2.1** The *expected value* (average or mean) of a random variable  $X$  with pdf or pmf  $f_X$  is defined as

$$E[X] = \begin{cases} \sum_{x \in \mathcal{X}} x f_X(x_i) & X \text{ is discrete} \\ \int_{\mathcal{X}} x f_X(x) dx & X \text{ is continuous.} \end{cases}$$

Where  $\mathcal{X} = \{x : f_X(x) > 0\}$  is the support of  $X$ .

This is a weighted average of all possible values  $\mathcal{X}$  by the probability distribution.

**Example 2.1** Let  $X \sim \text{Bernoulli}(p)$ . Find  $E[X]$ .

$$X = \begin{cases} 1 & \text{w.p. } p \\ 0 & \text{o.w.} \end{cases} \Rightarrow f(x) = \begin{cases} p & \text{when } x=1 \\ 1-p & \text{when } x=0 \end{cases} \quad \text{or} \quad f(x) = p^x (1-p)^{1-x} \text{ for } x \in \{0, 1\}$$

support is  
X is the r.v., pmf is  $f(x)$ ,  $\{0, 1\}$ ,  
parameter is  $p$ .

$$E[X] = \sum_{x \in \{0, 1\}} x f(x) = 0(1-p) + 1(p) = p.$$

**Example 2.2** Let  $X \sim \text{Exp}(\lambda)$ . Find  $E[X]$ .

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0. \end{cases}$$

integration by parts

$$E[X] = \int_0^\infty x \lambda e^{-\lambda x} dx = \dots = \frac{1}{\lambda}$$

HW 1

**Definition 2.2** Let  $g(X)$  be a function of a continuous random variable  $X$  with pdf  $f_X$ .

Then,

$$E[g(X)] = \int_{x \in \mathcal{X}} g(x) f_X(x) dx.$$

sometimes this is hard to compute analytically  
 $\Rightarrow$  we will need stat computing to estimate

**Definition 2.3** The *variance* (a measure of spread) is defined as

$$\begin{aligned} \text{Var}[X] &= E[(X - E[X])^2] \\ &= E[X^2] - (E[X])^2 \quad \text{computational formula} \\ &\quad \text{if } g(x) = x^2 \end{aligned}$$

(Ch. 5)

**Example 2.3** Let  $X$  be the number of cylinders in a car engine. The following is the pmf function for the size of car engines.

x	4.0	6.0	8.0
f	0.5	0.3	0.2

i.e.  $P(X=4) = 0.5$ , etc.

Who might care about this?

Find

$$E[X] = \sum_{x \in X} x f(x) = 4 \cdot 0.5 + 6 \cdot 0.3 + 8 \cdot 0.2 = 5.4$$

$$Var[X] = E(X^2) - (E[X])^2$$

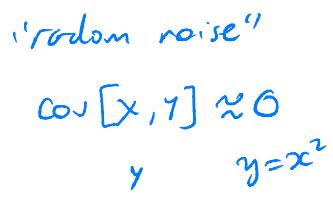
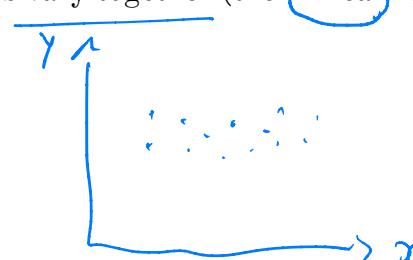
$$E(X^2) = \sum_{x \in X} x^2 f(x) = 4^2(0.5) + 6^2(0.3) + 8^2(0.2) = 31.6$$

$$\Rightarrow Var[X] = 31.6 - (5.4)^2 = 2.44 \quad \text{easier to interpret is } \sqrt{Var[X]} = 1.56$$

Covariance measures how two random variables vary together (their linear relationship).



$$\text{Cov}(X, Y) > 0$$



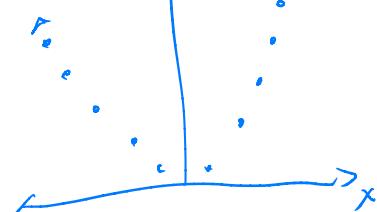
**Definition 2.4** The covariance of  $X$  and  $Y$  is defined by

$$\begin{aligned} \text{Cov}[X, Y] &= E[(X - E[X])(Y - E[Y])] \\ &= E[XY] - E[X]E[Y] \end{aligned}$$

and the correlation of  $X$  and  $Y$  is defined as

↑ Computational form

$$\rho(X, Y) = \frac{\text{Cov}[X, Y]}{\sqrt{Var[X]Var[Y]}}. \quad \rho \in [-1, 1]$$



Two variables  $X$  and  $Y$  are uncorrelated if  $\rho(X, Y) = 0$ .

# 3 Independence and Conditional Probability

In classical probability, the *conditional probability* of an event  $A$  given that event  $B$  has occurred is

$$P(A|B) = \frac{P(A \cap B)}{P(B)}. \quad \text{Handwritten note: } P(A|B)P(B) = P(A \cap B)$$

**Definition 3.1** Two events  $A$  and  $B$  are *independent* if  $P(A|B) = P(A)$ . The converse is also true, so

$$A \text{ and } B \text{ are independent} \Leftrightarrow P(A|B) = P(A) \Leftrightarrow P(A \cap B) = P(A)P(B)$$

**Theorem 3.1 (Bayes' Theorem)** Let  $A$  and  $B$  be events. Then,

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{P(B|A)P(A)}{P(B)}$$

## 3.1 Random variables

The same ideas hold for random variables. If  $X$  and  $Y$  have joint pdf  $f_{X,Y}(x,y)$ , then the conditional density of  $X$  given  $Y = y$  is

$$f_{X|Y=y}(x) = \frac{f_{X,Y}(x,y)}{f_Y(y)}.$$

Thus, two random variables  $X$  and  $Y$  are independent if and only if

$$f_{X,Y}(x,y) = f_X(x)f_Y(y).$$

Also, if  $X$  and  $Y$  are independent, then

$$f_{X|Y=y}(x) = \frac{f_{X,Y}(x,y)}{f_Y(y)} \stackrel{\text{indep.}}{\downarrow} = \frac{f_X(x)f_Y(y)}{f_Y(y)} = f_X(x).$$

## 4 Properties of Expected Value and Variance

Suppose that  $X$  and  $Y$  are random variables, and  $a$  and  $b$  are constants. Then the following hold:

$$1. E[aX + b] = a E[X] + b$$

$$2. E[X + Y] = E[X] + E[Y]$$

$$3. \text{If } X \text{ and } Y \text{ are independent, then } E[XY] = E[X]E[Y] \leftarrow \begin{matrix} \text{only true with} \\ \text{independence.} \end{matrix}$$

$$4. Var[b] = 0$$

$$5. Var[aX + b] = a^2 Var[X]$$

$$6. \text{If } X \text{ and } Y \text{ are independent, } Var[X + Y] = \underline{Var[X] + Var[Y]}$$

# 5 Random Samples

**Definition 5.1** Random variables  $\{X_1, \dots, X_n\}$  are defined as a *random sample* from  $f_X$  if  $X_1, \dots, X_n \stackrel{iid}{\sim} f_X$ .  
 independent and identically distributed.

**Example 5.1**

$X_1, \dots, X_n \stackrel{iid}{\sim} N(0, \sigma^2)$  vs.  
 random sample

$X_1 \sim N(\mu_1, \sigma^2)$   
 $X_2 \sim N(\mu_2, \sigma^2)$

not a random sample

(unless indep +  $\mu_1 = \mu_2$ ).

These may be  
 independent, but  
 not identically  
 distributed.

**Theorem 5.1** If  $X_1, \dots, X_n \stackrel{iid}{\sim} f_X$ , then

$$f(x_1, \dots, x_n) = \prod_{i=1}^n f_X(x_i).$$

$\uparrow$   
 joint pdf       $\uparrow$  product of  
 marginals, easier to deal with.

**Example 5.2** Let  $X_1, \dots, X_n$  be iid. Derive the expected value and variance of the sample

$$\text{mean } \bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i. \quad \begin{matrix} \text{property 1} \\ \downarrow \end{matrix} \quad \begin{matrix} \text{property 2} \\ \downarrow \end{matrix} \quad \begin{matrix} \text{v}_1, \dots, \text{v}_n \text{ iid } E\text{v}_1 = \dots = E\text{v}_n \\ \downarrow \end{matrix}$$

$$E(\bar{X}_n) \stackrel{\substack{\text{def'n of} \\ \text{mean}}}{=} E\left(\frac{1}{n} \sum_{i=1}^n X_i\right) = \frac{1}{n} E\left(\sum_{i=1}^n X_i\right) = \frac{1}{n} \sum_{i=1}^n E X_i = \frac{1}{n} \sum_{i=1}^n E X_i = \frac{1}{n} n E X_i = E X_i$$

$$\text{Var}\left(\frac{1}{n} \sum_{i=1}^n X_i\right) = \frac{1}{n^2} \text{Var}\left(\sum_{i=1}^n X_i\right) = \frac{1}{n^2} \sum_{i=1}^n \text{Var} X_i = \frac{1}{n^2} \cdot n \text{Var} X_i = \frac{1}{n} \text{Var} X_i$$

$\uparrow$   
 property 5       $\uparrow$   
 $X_i$  independent  
 + property 6       $\uparrow$   
 $X_i \text{ iid} \Rightarrow \text{Var} X_1 = \dots = \text{Var} X_n$

# 6 R Tips

From here on in the course we will be dealing with a lot of **randomness**. In other words, running our code will return a **random** result.

But what about reproducibility??

When we generate “random” numbers in R, we are actually generating numbers that *look* random, but are pseudo-random (not really random). The vast majority of computer languages operate this way.

This means all is not lost for reproducibility!

`set.seed(400)`

set the starting point.

Before running our code, we can fix the starting point (**seed**) of the pseudorandom number generator so that we can reproduce results.

Speaking of generating numbers, we can generate numbers (also evaluate densities, distribution functions, and quantile functions) from named distributions in R.

