

MLE of Location Parameter of a Cauchy Distribution by Using Different Algorithms

HW 3 of STAT 5361 Statistical Computing

*Biju Wang*¹

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¹bijuwang@uconn.edu

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Chapter 1

Proofs and Loglikelihood Function Plot against θ

1.1 Proofs

The likelihood function is

$$L(\theta) = \prod_{i=1}^n \frac{1}{\pi[1 + (X_i - \theta)^2]}$$

Hence, the log likelihood function is

$$l(\theta) = \log L(\theta) = \log \prod_{i=1}^n \frac{1}{\pi[1 + (X_i - \theta)^2]} = -n \log \pi - \sum_{i=1}^n \log[1 + (\theta - X_i)^2] \quad (1.1)$$

Further

$$l'(\theta) = - \sum_{i=1}^n \frac{d}{d\theta} \log[1 + (\theta - X_i)^2] = -2 \sum_{i=1}^n \frac{\theta - X_i}{1 + (\theta - X_i)^2} \quad (1.2)$$

Compute the second derivative according to $l'(\theta)$

$$l''(\theta) = -2 \sum_{i=1}^n \frac{d}{d\theta} \frac{\theta - X_i}{1 + (\theta - X_i)^2} = -2 \sum_{i=1}^n \frac{1 - (\theta - X_i)^2}{[1 + (\theta - X_i)^2]^2} \quad (1.3)$$

Therefore, the Fisher information is

$$\begin{aligned} I_n(\theta) &= -E_X[l''(\theta)] \\ &= 2nE_X \left[\frac{1 - (\theta - X)^2}{[1 + (\theta - X)^2]^2} \right] \\ &= 2n \int_{-\infty}^{\infty} \frac{1 - (x - \theta)^2}{[1 + (x - \theta)^2]^2} \frac{1}{\pi[1 + (x - \theta)^2]} dx \\ &= \frac{2n}{\pi} \int_{-\infty}^{\infty} \frac{1 - x^2}{(1 + x^2)^2} \frac{1}{1 + x^2} dx = \frac{2n}{\pi} \int_{-\infty}^{\infty} \left(\frac{x}{1 + x^2} \right)' \frac{1}{1 + x^2} dx = \frac{2n}{\pi} \left[\frac{x}{(1 + x^2)^2} \right]_{-\infty}^{\infty} + \int_{-\infty}^{\infty} \frac{2x^2}{(1 + x^2)^3} dx \\ &= \frac{4n}{\pi} \int_{-\infty}^{\infty} \frac{x^2}{(1 + x^2)^3} dx = \frac{4n}{\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{\tan^2 \alpha}{(1 + \tan^2 \alpha)^3} \sec^2 \alpha d\alpha = \frac{4n}{\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{1 - \cos 4\alpha}{8} d\alpha = \frac{4n}{\pi} \cdot \frac{\pi}{8} \\ &= \frac{n}{2} \end{aligned} \quad (1.4)$$

1.2 Loglikelihood Function Plot against θ

The following plot is the curve of log likelihood function

```
set.seed(20180909)
sample <- rcauchy(10, 5)
```

Chapter 2

Newton-Raphson Method

Chapter 3

Fixed-Point Iterations

Chapter 4

Fisher Scoring Method and Newton-Raphson Method

Chapter 5

Comments