< STAT-5361 > HW#3-Exercises

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Contents

(a) Proof

$$f(x;\theta) = \frac{1}{\pi[1 + (x - \theta)^2]}, x \in R, \theta \in R.$$

Because $x_1, ..., x_n$ is an i.i.d. sample and $l(\theta)$ the log-likelihood function of θ based on the sample. Therefore,

$$l(\theta) = \ln(\prod_{i=1}^{n} f(x_i; \theta))$$

$$= \ln(\prod_{i=1}^{n} \frac{1}{\pi[1 + (x_i - \theta)^2]})$$

$$= \sum_{i=1}^{n} \ln(\frac{1}{\pi[1 + (x_i - \theta)^2]})$$

$$= \sum_{i=1}^{n} \ln(\frac{1}{\pi}) + \sum_{i=1}^{n} \ln(\frac{1}{1 + (x_i - \theta)^2})$$

$$= -n \ln \pi - \sum_{i=1}^{n} \ln[1 + (\theta - x_i)^2]$$

And,

$$l'(\theta) = \frac{\partial}{\partial \theta} \left(-n \ln \pi - \sum_{i=1}^{n} \ln[1 + (\theta - x_i)^2]\right)$$
$$= -\frac{\partial}{\partial \theta} \left(\sum_{i=1}^{n} \ln[1 + (\theta - x_i)^2]\right)$$
$$= -\left(\sum_{i=1}^{n} \frac{2(\theta - x_i)}{1 + (\theta - x_i)^2}\right)$$
$$= -2\sum_{i=1}^{n} \frac{\theta - x_i}{1 + (\theta - x_i)^2}$$

$$l''(\theta) = \frac{\partial}{\partial \theta} \left(-2 \sum_{i=1}^{n} \frac{\theta - x_i}{1 + (\theta - x_i)^2} \right)$$

$$= -2 \sum_{i=1}^{n} \left(\frac{1}{1 + (\theta - x_i)^2} - \frac{2(\theta - x_i)^2}{(1 + (\theta - x_i)^2)^2} \right)$$

$$= -2 \sum_{i=1}^{n} \left(\frac{1 + (\theta - x_i)^2}{(1 + (\theta - x_i)^2)^2} - \frac{2(\theta - x_i)^2}{(1 + (\theta - x_i)^2)^2} \right)$$

$$= -2 \sum_{i=1}^{n} \frac{1 - (\theta - x_i)^2}{[1 + (\theta - x_i)^2]^2}$$

As for $I(\theta)$,

$$I_n(\theta) = n \int \frac{f'(x)^2}{f(x)} dx$$

$$I(\theta) = n \int \frac{(f'(x))^2}{f(x)} dx$$

$$= n \int_{-\infty}^{\infty} \frac{-(\frac{2\pi x}{(\pi(1+x^2))^2})^2}{\frac{1}{\pi(1+x^2)}} dx = n \int_{-\infty}^{\infty} \frac{4\pi^2 x^2}{(\pi(1+x^2))^3} dx$$

$$= \frac{4n}{\pi} \int_{-\infty}^{\infty} \frac{x^2}{(1+x^2)^3} dx = \frac{4n}{\pi} \int_{-\infty}^{\infty} \frac{x^2}{1+x^2} \frac{1}{(1+x^2)^2} dx$$

$$= \frac{4n}{\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{\arctan^2(\theta)}{1+\arctan^2(\theta)} \frac{1+\arctan^2(\theta)}{(1+\arctan^2(\theta))^2} d\theta$$

$$= \frac{4n}{\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \sin^2(\theta) \cos^2(\theta) d\theta = \frac{4n}{\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{\sin^2(2\theta)}{4} d\theta$$

$$= \frac{n}{\pi} (\frac{\pi}{2}) = \frac{n}{2}$$

(b) Graph the log-likelihood function

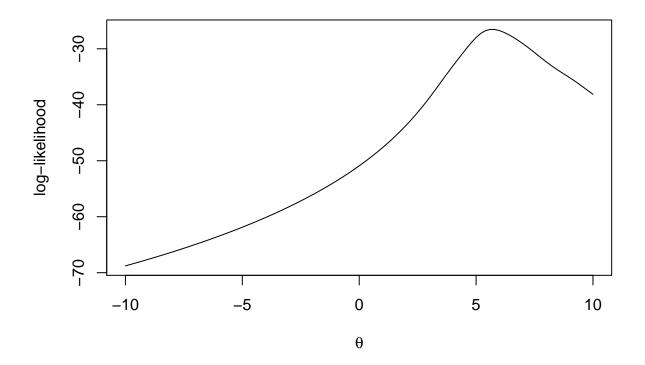
```
set.seed(20180909)
n = 10

data <- rcauchy(n,5,1)
in_value = seq(-10, 20, by=0.5);

m <- length(in_value)
y <- c()

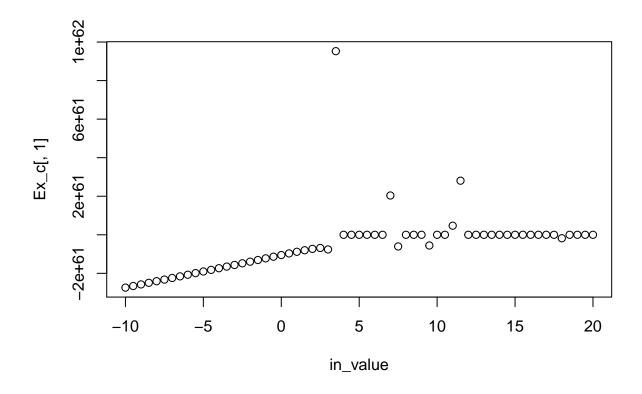
Log_like=function(theta)
{
    Hee= -(length(data)*log(pi) + sum(log(1+(theta-data)^2))) #-log
    return(Hee)
}

curve(sapply(x,Log_like),-10,10,xlab=expression(theta), ylab='log-likelihood')</pre>
```



(C)

```
set.seed(20180909)
n = 10
data <- rcauchy(n,5,1)</pre>
in_value = seq(-10, 20, by=0.5);
m <- length(in_value)</pre>
first_deri=function(theta){
  first_deri=-2*sum((theta-data)/(1+(theta-data)^2))
  return(first_deri)
second_deri=function(theta){
  second_deri=-2*sum((1-(theta-data)^2)/(1+(theta-data)^2)^2)
  return(second_deri)
}
Newton = function(in_value,max, tol=1e-10){
  curr=in_value
  for(i in 1:max)
    update=curr-first_deri(curr)/second_deri(curr)
    if(abs(update-curr)<tol) break</pre>
    curr=update
  }
  return(c(curr,i))
}
iii=length(in_value)
Ex_c=matrix(0,iii,2)
for(i in 1:iii){
Ex_c[i,]=Newton(in_value[i], 200)
}
 plot(in_value,Ex_c[,1])
```



(d)

```
set.seed(20180909)
  n = 10
  data <- rcauchy(n,5,1)
  in_value = seq(-10, 20, by=0.5);
 m <- length(in_value)</pre>
 first_deri=function(theta){
    first_deri=-2*sum((theta-data)/(1+(theta-data)^2))
    return(first_deri)
  }
 fixed_point=function(in_value,alpha, max=1000, tol=1e-10 ){
   curr=in value
  for(i in 1: max)
    update=curr + (alpha*first_deri(curr))
     if (abs(update-curr)<tol) break</pre>
     curr=update
return(c(curr,i))
}
alpha_1 <- alpha_0.64 <- alpha_0.25 <- matrix(0,length(in_value),2)
for(i in 1:length(in_value))
  alpha_1[i,]=fixed_point(in_value[i],1,1000)
  alpha_0.64[i,]=fixed_point(in_value[i],0.64,1000)
  alpha_0.25[i,]=fixed_point(in_value[i],0.25,1000)
}
alpha_1[,1]
## [1] 4.087057 9.547862 4.087057 6.486114 9.547862 4.087057 6.486114
## [8] 6.486114 9.547862 4.087057 4.087057 6.486114 9.547862 9.547862
## [15] 6.486114 4.087057 6.486114 6.486114 4.087057 9.547862 4.087057
## [22] 4.087057 4.087057 9.547862 6.486114 6.486114 6.486114 9.547862
## [29] 9.547862 9.547862 9.547862 6.486114 4.087057 4.087057 4.087057
## [36] 4.087057 4.087057 4.087057 6.486114 6.486114 6.486114 6.486114
## [43] 6.486114 6.486114 4.087057 9.547862 9.547862 9.547862 9.547862
```

```
## [50] 4.087057 4.087057 4.087057 6.486114 6.486114 6.486114 9.547862 ## [57] 9.547862 4.087057 6.486114 6.486114 4.087057
```

alpha_0.64[,1]

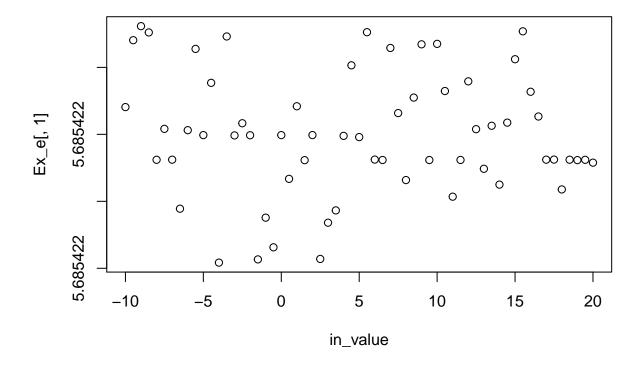
```
## [1] 5.529107 7.706106 5.127538 4.951869 6.725152 5.197111 7.075917 ## [8] 5.964188 5.182739 4.957631 5.173272 7.716718 5.540465 5.199886 ## [15] 4.951297 7.557473 7.608167 5.157557 5.181790 5.443351 7.564154 ## [22] 7.183275 7.398215 6.609417 5.290579 7.154975 5.240143 5.549859 ## [29] 4.951676 7.161017 4.993766 5.286890 6.371987 6.900178 7.181054 ## [36] 7.203470 5.187023 5.222680 5.059510 5.045353 7.383910 7.715984 ## [43] 7.607361 6.868118 7.572404 5.053074 4.975029 5.570223 6.865950 ## [50] 6.966023 5.031455 5.238599 7.125650 7.319846 5.173538 5.354787 ## [57] 7.156821 5.294795 7.372832 5.256387 5.266334
```

alpha_0.25[,1]

```
## [1] 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 ## [8] 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 ## [15] 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 ## [29] 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422 5.685422
```

(e)

```
set.seed(20180909)
n = 10
data <- rcauchy(n,5,1)</pre>
in_value = seq(-10, 20, by=0.5);
m <- length(in_value)</pre>
first_deri=function(theta){
  first_deri=-2*sum((theta-data)/(1+(theta-data)^2))
  return(first_deri)
}
Newton = function(in_value,max, tol=1e-10){
  curr=in_value
  for(i in 1:max)
    update=curr+2*first_deri(curr)/10
    if(abs(update-curr)<tol) break</pre>
    curr=update
  }
 return(c(curr,i))
}
iii=length(in_value)
Ex_e=matrix(0,iii,2)
for(i in 1:iii){
  Ex_e[i,]=Newton(in_value[i], 200)
}
plot(in_value,Ex_e[,1])
```



(f) We have performed 3 iterations of the Fisher scoring method, then the Newton-Raphson method for refinement. Under Fisher scoring together with Newton method, the convergence points of MLE are less affected by choice of initial point. The number of iterations is not significantly different from the results of Newton-Raphson method alone. All iterations are similar in terms of the speed. Under those testing conditions, however, we can say that the Fisher Scoring with Newton method is the most stable algorithm for global maximization overall