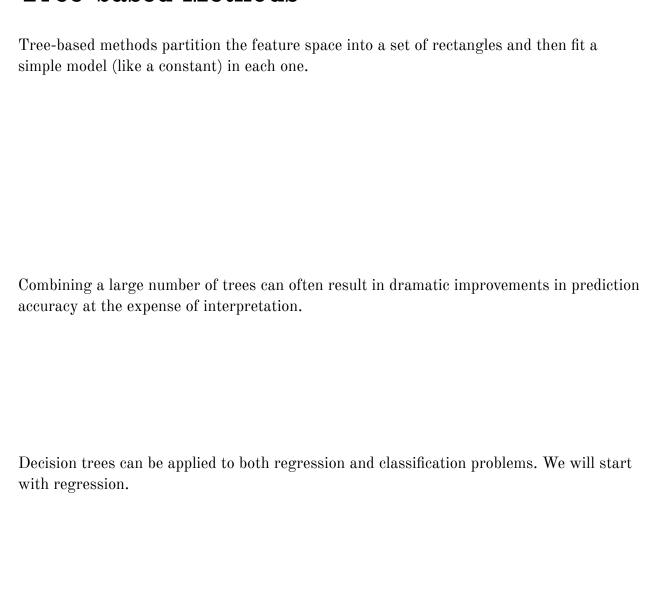
### **Tree-based Methods**



## 1 Decision Trees

Let's consider a regression problem with continuous response $Y$ and inputs $X_1$ and $X_2$ , each taking values in the unit interval.
In each partition, we can model $Y$ with a different constant. However, there is a problem:
To simplify, we restrict attention to binary partitions.
The result is a partition into five regions $R_1, \ldots, R_5$ . The corresponding regression mode predicts $Y$ with a constant $c_m$ in region $R_m$ :

#### 1.1 Regression Trees

How should we grow a regression tree? Our data consists of p inputs for i = 1, ..., n. We need an automatic way to decide which variables to split on and where to split them.

Suppose we have a partition into M regions and we model the response as a constant in each region.

Finding the best binary partition in terms of minimum sums of squares is generally computationally infeasible.

1 Decision Trees

The process described above may produce good predictions on the training set, but is likely to overfit the data.

A smaller tree, with less splits might lead to lower variance and better interpretation at the cost of a little bias.

A strategy is to grow a very large tree  $T_0$  and then  $\mathit{prune}$  it back to obtain a  $\mathit{subtree}$ .

#### 1.2 Classification Trees

If	the	target is a	classification	outcome t	taking valu	ies $1, 2, \ldots,$	K, the on	ly changes	needed
in	the	tree algori	thm are the o	eriteria for	splitting,	pruning, and	$d c_m$ .		

 $c_m$ :

Node impurity (Splitting):

Pruning:

# 2 Bagging

2 Dagging
Decision trees suffer from high variance.
Bootstrap aggregation or bagging is a general-purpose procedure for reducing the variance of a statistical learning method, particularly useful for trees.
So a natural way to reduce the variance is to take many training sets from the population, build a separate prediction model using each training set, and average the resulting predictions.
Of course, this is not practical because we generally do not have access to multiple training sets.

While bagging can improve predictions for many regression methods, it's particularly useful for decision trees.

These trees are grown deep and not pruned.

How can bagging be extended to a classification problem?

#### 2.1 Out-of-Bag Error

There is a very straightforward way to estimate the test error of a bagged model.

8 2 Bagging

### 2.2 Interpretation

### 3 Random Forests

${\it Random\ forests}$ provide an improvement over bagged trees by a small tweak that decorrelates the trees.
As with bagged trees, we build a number of decision trees on bootstrapped training samples.
In other words, in building a random forest, at each split in the tree, the algorithm is not allowed to consider a majority of the predictors.
The main difference between bagging and random forests is the choice of predictor subset size $m$ .

### 4 Boosting

The basic idea of *boosting* is to take a simple (and poorly performing form of) predictor and by sequentially modifying/perturbing it and re-weighting (or modifying) the training data set, to creep toward an effective predictor.

Consider a 2-class 0-1 loss classification problem. We'll suppose that output y takes values in  $\mathcal{G} = \{-1, 1\}$ . The AdaBoost.M1 algorithm is built on some base classifier form.

- 1. Initialize the weights on the training data.
- 2. Fit a  $\mathcal{G}$ -valued predictor/classifier  $\hat{f}_1$  to the training data to optimize the 0-1 loss.
- 3. Set new weights on the training data.
- 4. For m = 2, ..., M,

5. Output an updated classifier based on "weighted voting".

Why might this work?