

Robust covariance estimation for partially observed functional data

2021-06-24

1. Partially observed case

Table 1: 4 FPCs from 30 repetitions

| Type | Method | PVE | Reconstruction | Completion | Eigenfunction |
|------------------|---------------------|------|----------------|----------------|---------------|
| Not contaminated | Yao | 1.00 | 2.17 (9.93) | 9.26 (44.28) | 0.05 (0.03) |
| | Kraus | 0.99 | | 0.29 (0.26) | 0.06 (0.03) |
| | Huber | 0.86 | 0.08 (0.03) | 0.27 (0.12) | 0.06 (0.07) |
| | Boente | 1.00 | 26.35 (133.16) | 76.37 (369.40) | 0.12 (0.02) |
| | M-est | 0.95 | 0.08 (0.06) | 0.26 (0.19) | 0.13 (0.09) |
| | M-est-noise | 0.95 | 0.04 (0.02) | 0.14 (0.08) | |
| | M-est(smooth) | 0.99 | 0.38 (0.83) | 1.14 (2.47) | 0.08 (0.04) |
| | M-est(smooth)-noise | 0.99 | 0.04 (0.01) | 0.10 (0.04) | |
| Contaminated | Yao | 0.82 | 42.53 (102.54) | 62.78 (145.71) | 1.70 (0.17) |
| | Kraus | 0.65 | | 2.72 (0.68) | 1.82 (0.08) |
| | Huber | 0.87 | 0.09 (0.03) | 0.33 (0.11) | 0.06 (0.05) |
| | Boente | 1.00 | 21.79 (68.31) | 59.95 (180.04) | 1.42 (0.33) |
| | M-est | 0.68 | 0.17 (0.11) | 0.49 (0.43) | 0.21 (0.13) |
| | M-est-noise | 0.71 | 0.10 (0.04) | 0.26 (0.11) | |
| | M-est(smooth) | 0.99 | 3.72 (4.80) | 11.87 (14.63) | 0.09 (0.06) |
| | M-est(smooth)-noise | 0.99 | 0.06 (0.02) | 0.20 (0.08) | |