

HW2

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Abstract

I create several functions by Newton-Raphson Method, Fixed-point Iteration, Fisher scoring, Gauss-Newton Approach and so on to calculate the required theta and other data asked. Many of them contains stopping or updating rule to get the most ideal value I need.

1(a)

$$l(\theta) \tag{1}$$

$$= \ln \prod_{i=1}^n \frac{1}{\pi[1 + (x - \theta)^2]} \tag{2}$$

$$= \sum_{i=1}^n \ln \frac{1}{\pi[1 + (x - \theta)^2]} \tag{3}$$

$$= \sum_{i=1}^n \left[\ln \frac{1}{\pi} + \ln \frac{1}{1 + (x - \theta)^2} \right] \tag{4}$$

$$= -n \ln \pi - \sum_{i=1}^n \ln[1 + (x - \theta)^2] \tag{5}$$

$$\tag{6}$$

$$l'(\theta) \tag{7}$$

$$= 0 - \sum_{i=1}^n \frac{2(\theta - x_i)}{1 + (\theta - x_i)^2} \tag{8}$$

$$= -2 \sum_{i=1}^n \frac{\theta - x_i}{1 + (\theta - x_i)^2} \tag{9}$$

$$\tag{10}$$

$$l''(\theta) \tag{11}$$

$$= -2 \sum_{i=1}^n \frac{1 + (\theta - x_i)^2 - 2(\theta - x_i)(\theta - x_i)}{[1 + (\theta - x_i)^2]^2} \tag{12}$$

$$= -2 \sum_{i=1}^n \frac{1 - (\theta - x_i)^2}{[1 + (\theta - x_i)^2]^2} \tag{13}$$

$$\tag{14}$$

$$I(\theta) \tag{15}$$

$$= n \int \frac{\{p'(x)\}^2}{p(x)} dx \tag{16}$$

$$= n \int \frac{4(x-\theta)^2}{\pi[1+(x-\theta)^2]^4} * \pi[1+(x-\theta)^2] dx \tag{17}$$

$$= \frac{4n}{\pi} \int_{-\infty}^{\infty} \frac{(x-\theta)^2}{[1+(x-\theta)^2]^3} dx \tag{18}$$

$$= \frac{4n}{\pi} \int_{-\infty}^{\infty} \frac{x^2}{(1+x^2)^3} dx \tag{19}$$

$$= \frac{4n}{\pi} \int_{-\infty}^{\infty} [(\frac{1}{(1+x^2)^2} - \frac{1}{(1+x^2)^3})] dx \tag{20}$$

$$= \frac{4n}{\pi} (\int_{-\infty}^{\infty} \frac{1}{(1+x^2)^2} dx - \int_{-\infty}^{\infty} \frac{1}{(1+x^2)^3} dx) \tag{21}$$

$$= \frac{4n}{\pi} [\int_{-\infty}^{\infty} \frac{1}{(1+x^2)^2} dx - (\frac{x}{4(x^2+1)^2}|_{-\infty}^{\infty} + \frac{3}{4} \int_{-\infty}^{\infty} \frac{dx}{(x^2+1)^2})] \tag{22}$$

$$= \frac{4n}{\pi} (\int_{-\infty}^{\infty} \frac{1}{4(1+x^2)^2} dx - \frac{x}{4(x^2+1)^2}|_{-\infty}^{\infty}) \tag{23}$$

$$= \frac{4n}{\pi} [\frac{1}{4} (\frac{x}{2(x^2+1)})|_{-\infty}^{\infty} + \frac{1}{2} \int_{-\infty}^{\infty} \frac{1}{1+x^2} dx) - \frac{x}{4(x^2+1)^2}|_{-\infty}^{\infty}] \tag{24}$$

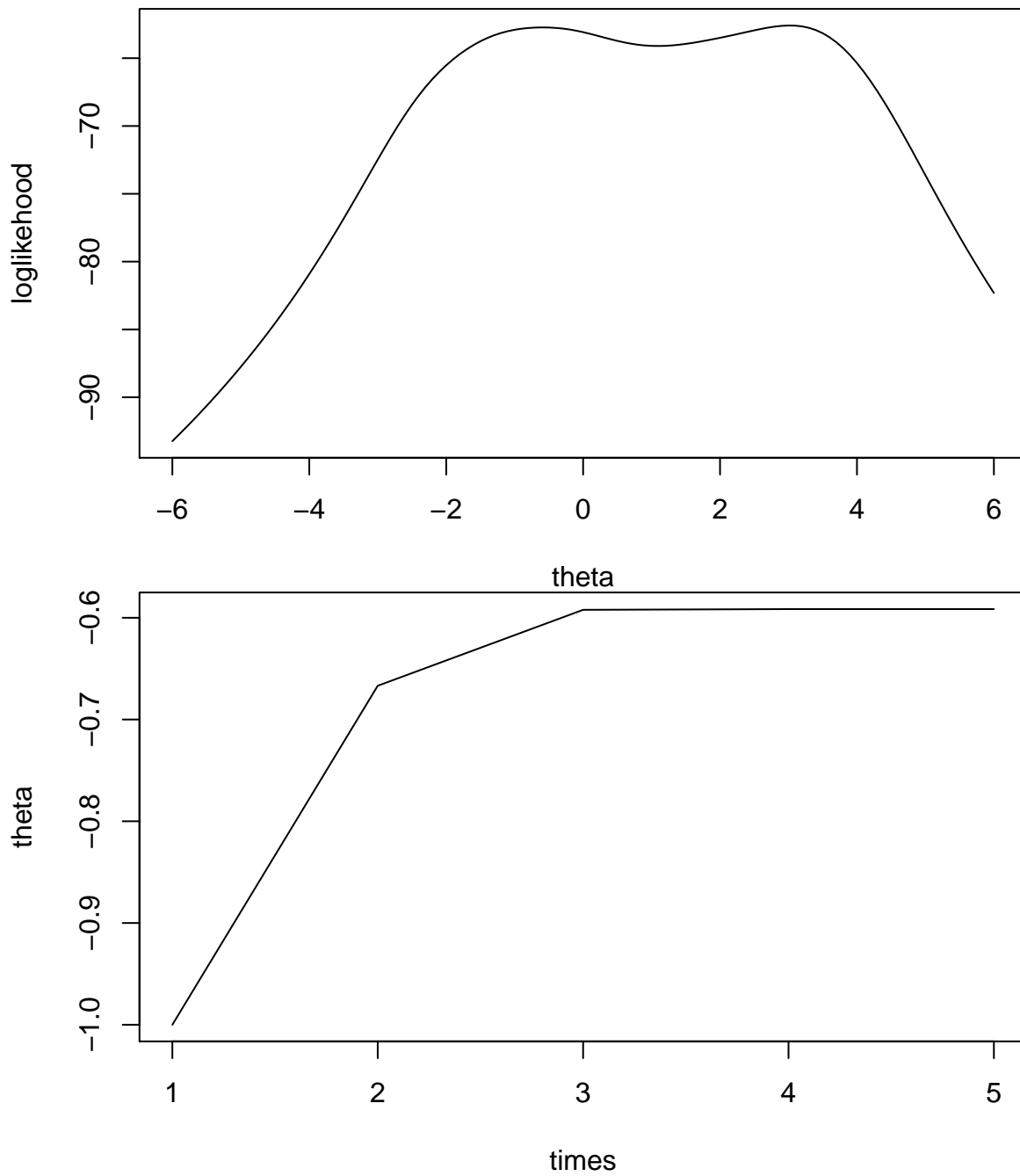
$$= \frac{4n}{\pi} (\frac{x(x^2-1)}{8(x^2+1)^2}|_{-\infty}^{\infty} + \frac{1}{8} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{\sec^2 t}{1+\tan^2 t} dt) \tag{25}$$

$$= \frac{4n}{\pi} (0 + \frac{\pi}{8}) \tag{26}$$

$$= \frac{n}{2} \tag{27}$$

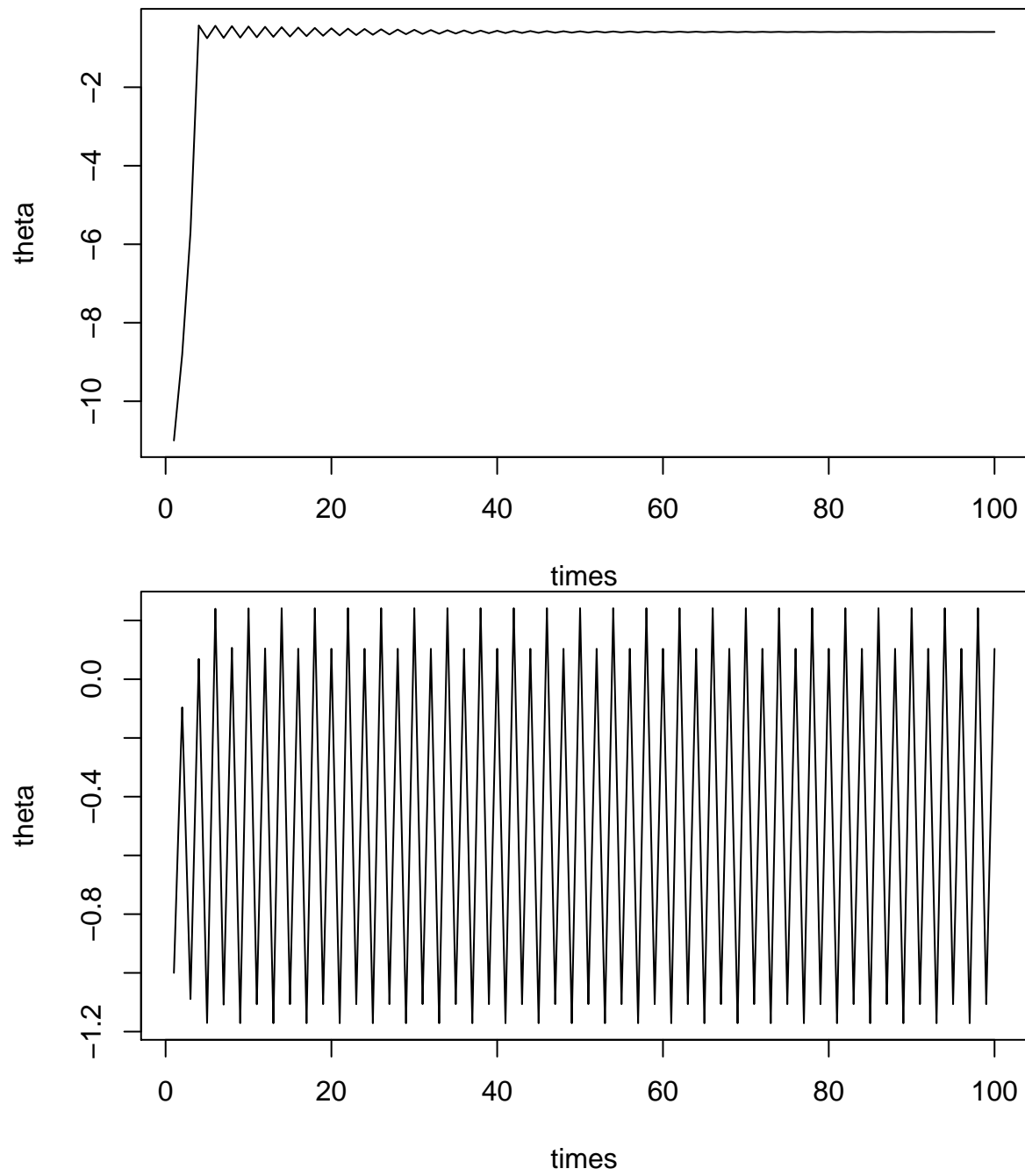
$$\tag{28}$$

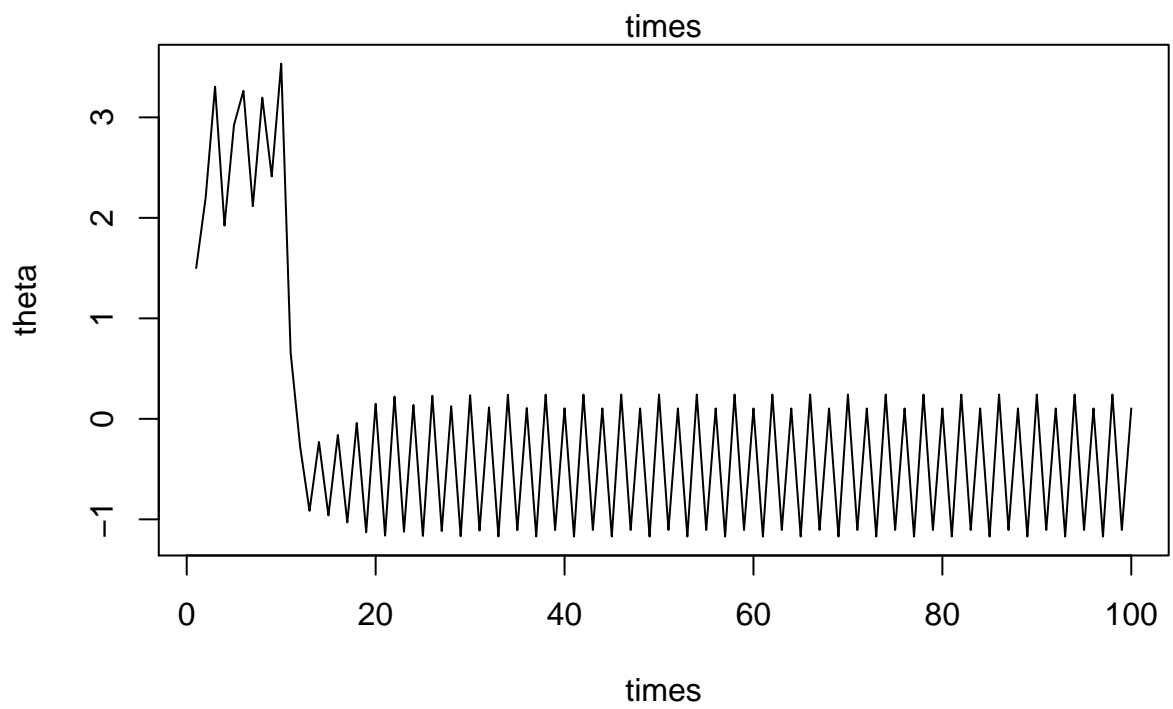
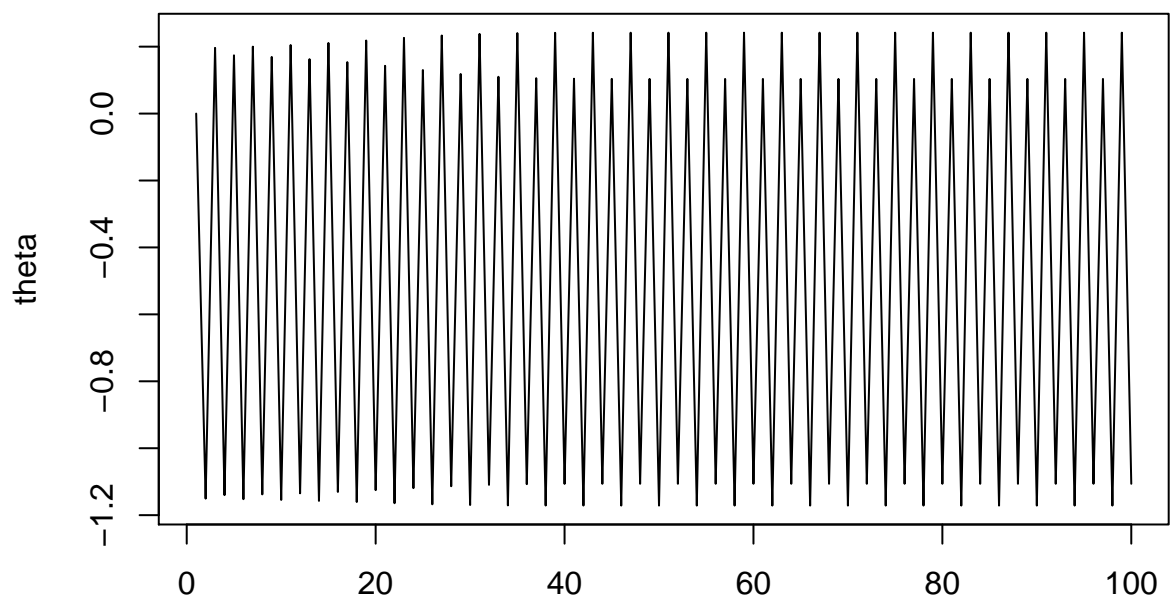
1(b)

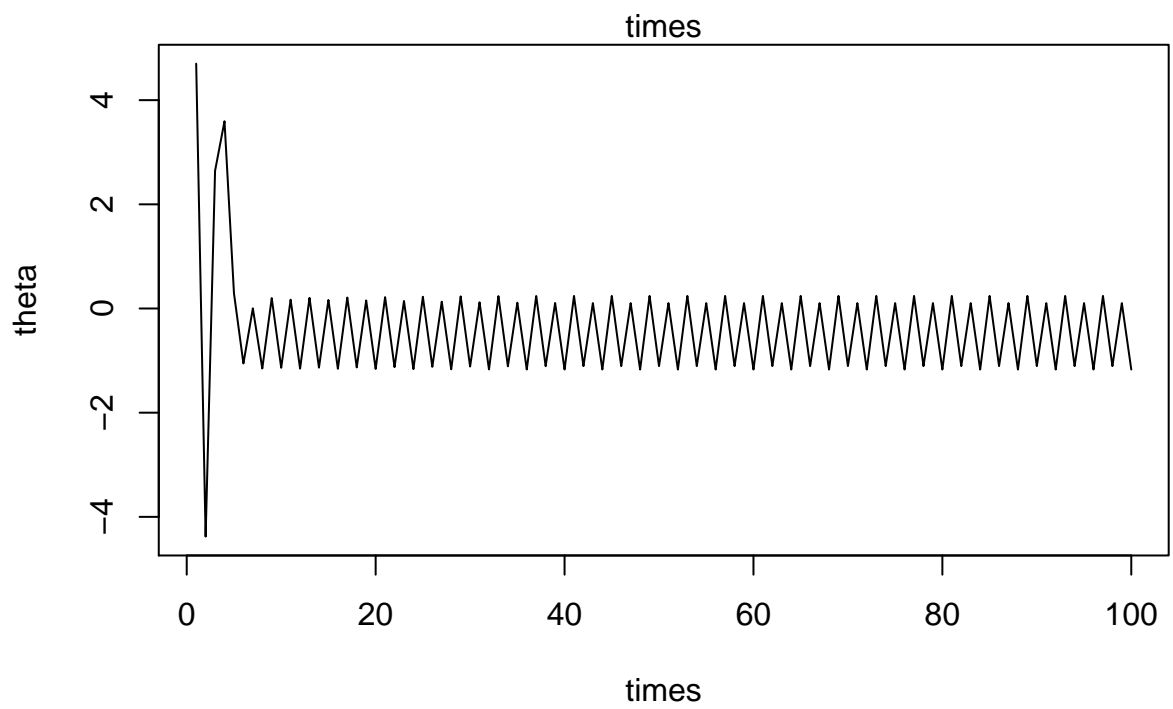
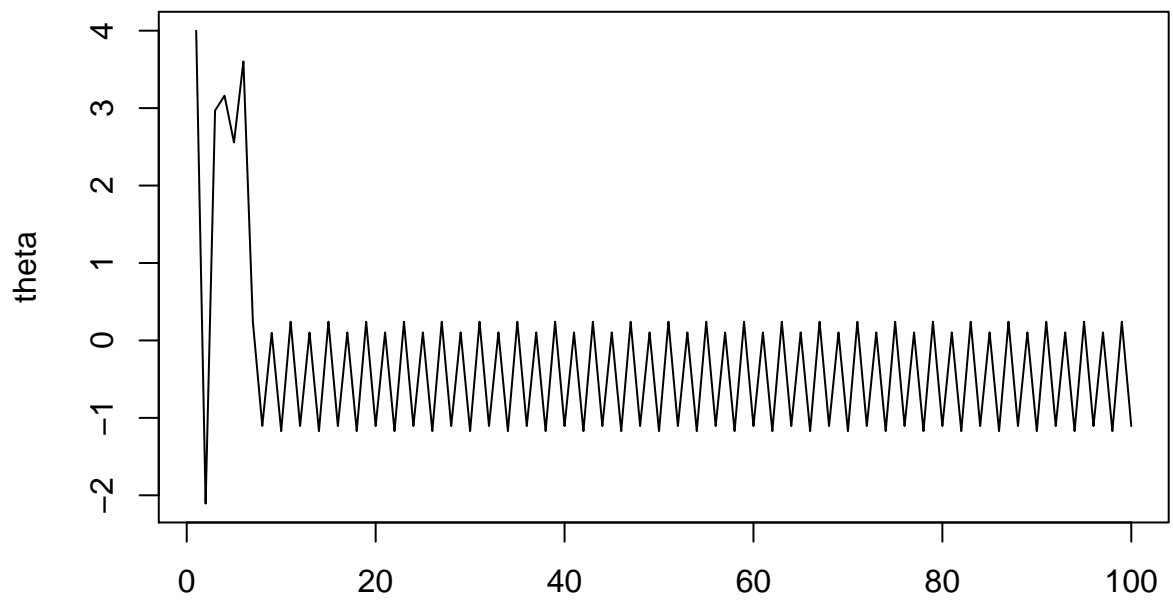


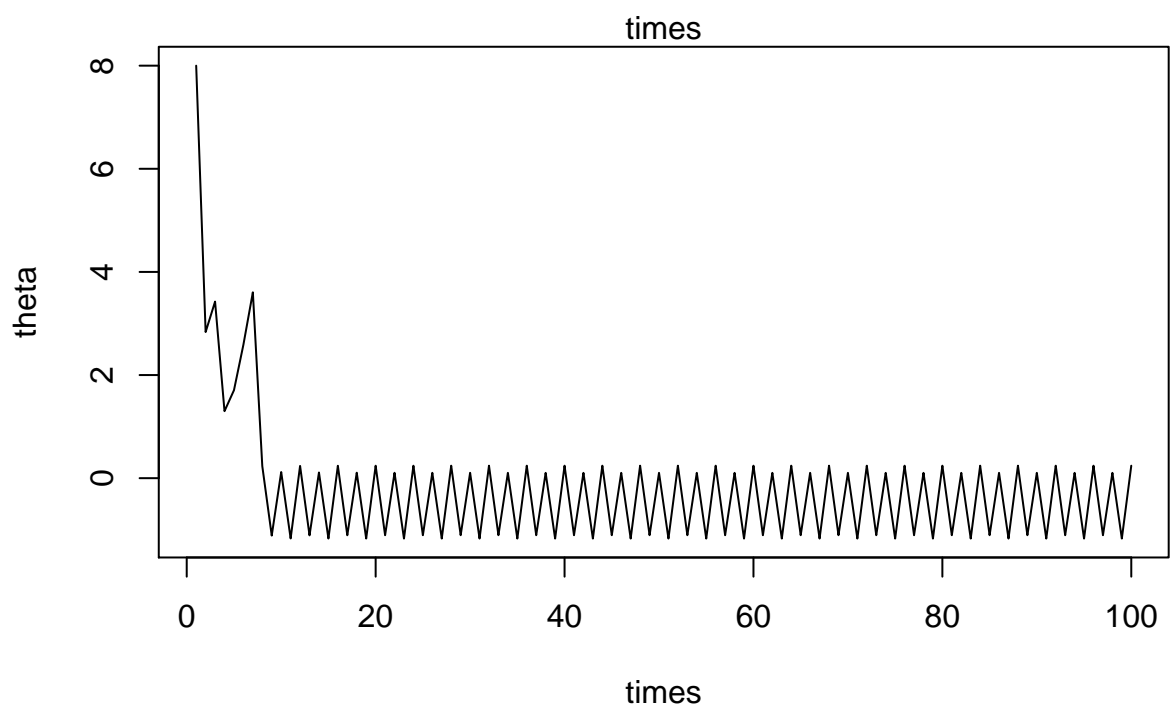
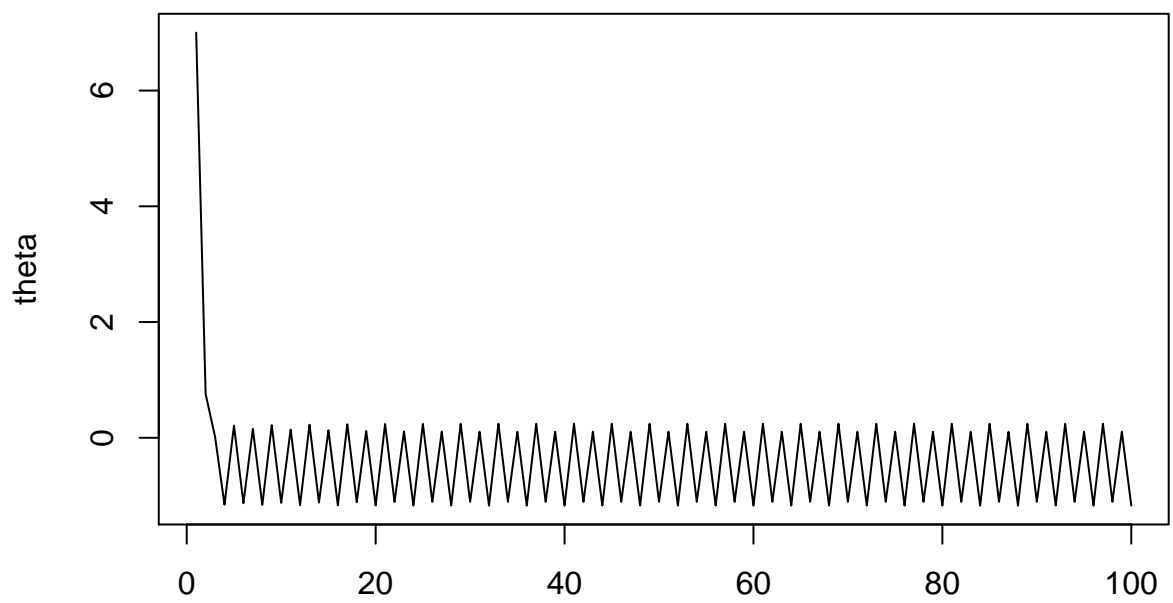
Theta's value of the graph above is -1. I tried all sample starting values, and I found there were no converging value starting from -11, 7, 8 and 38. The mean value is about 3.26, and this is a good starting point since I can find a converging value around 3.

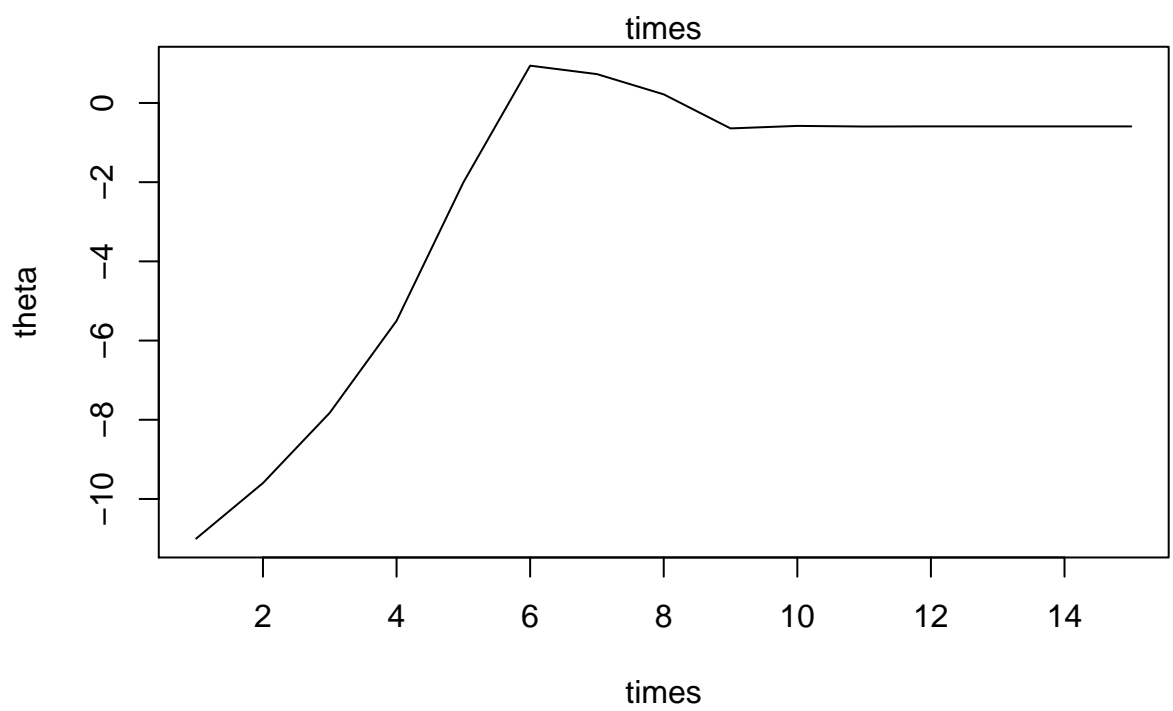
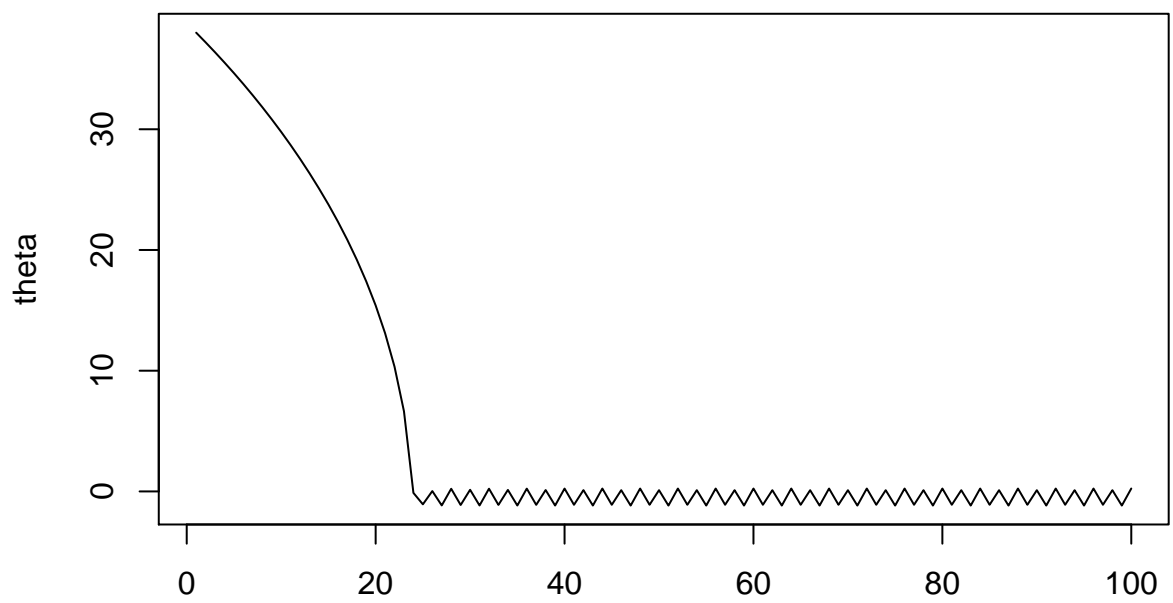
1(c)

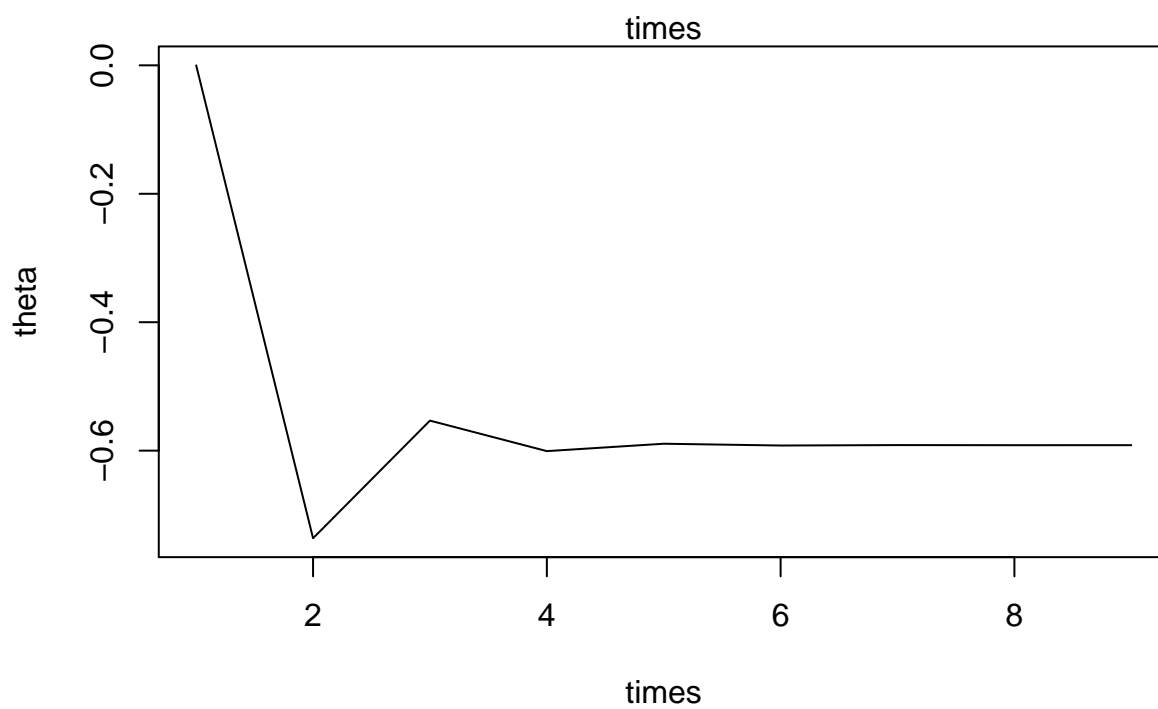
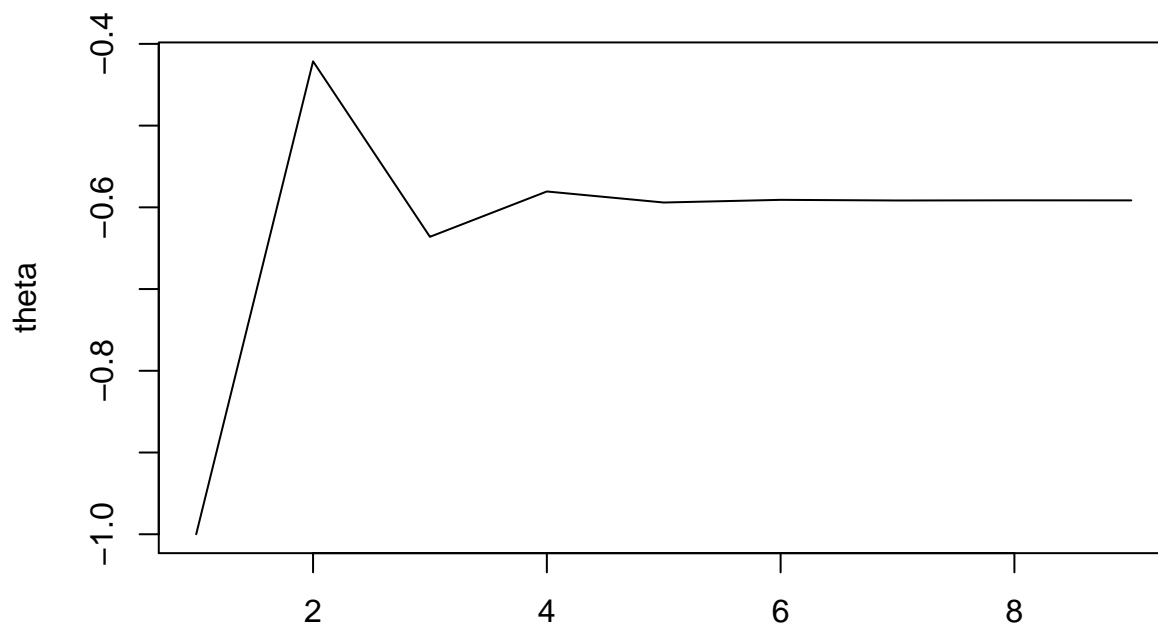


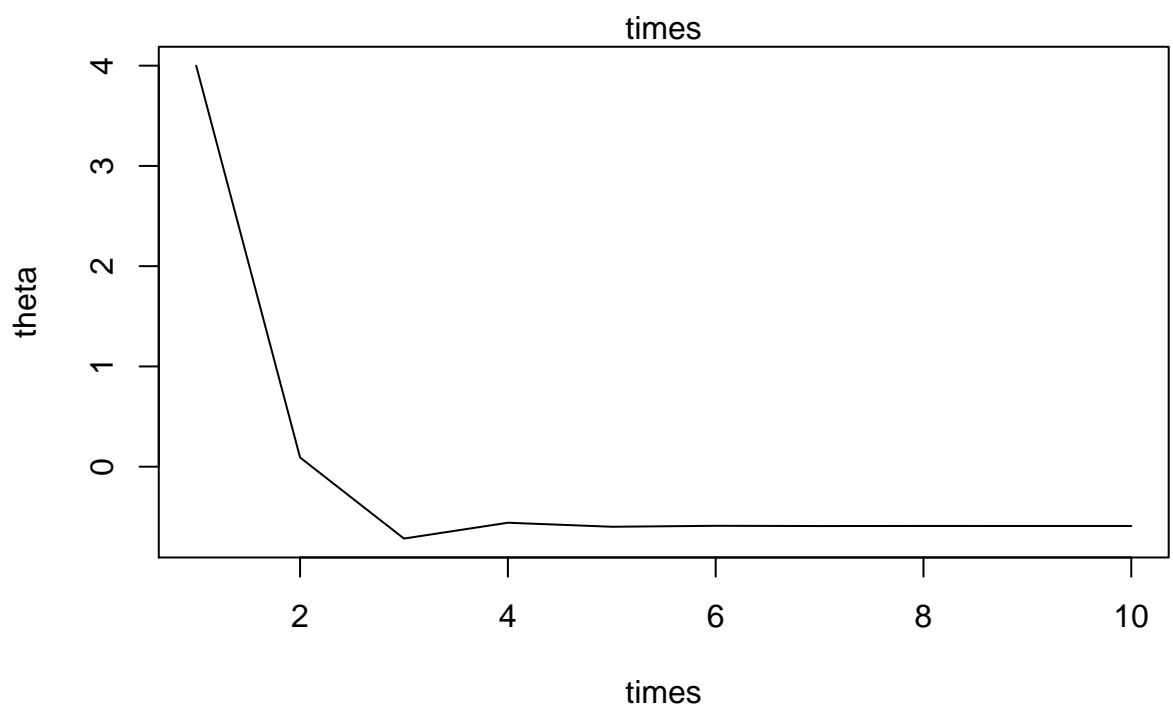
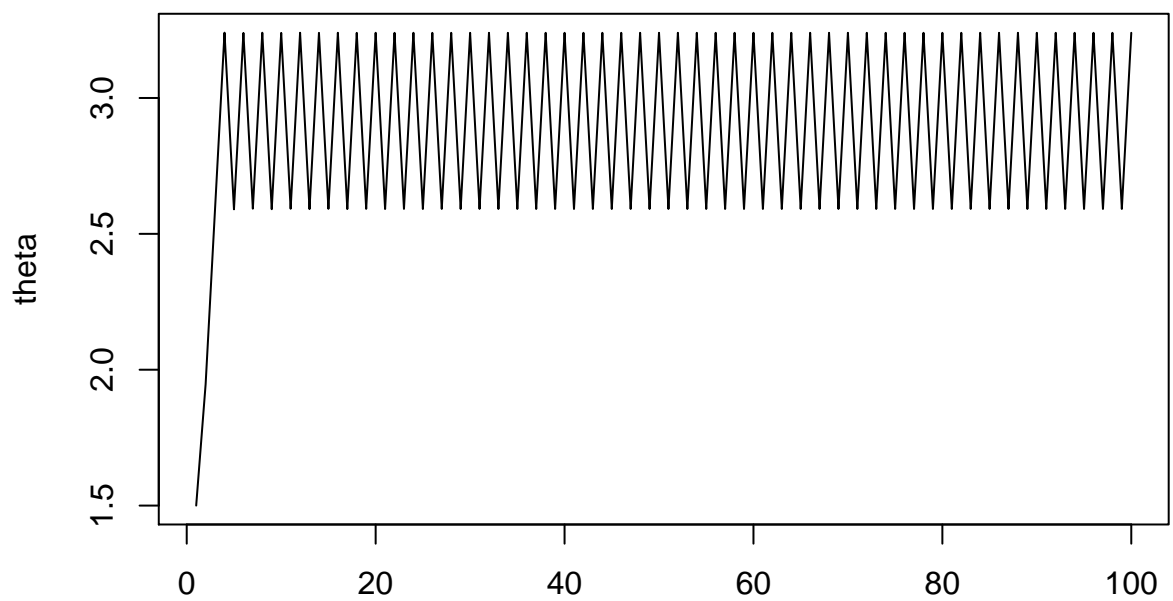


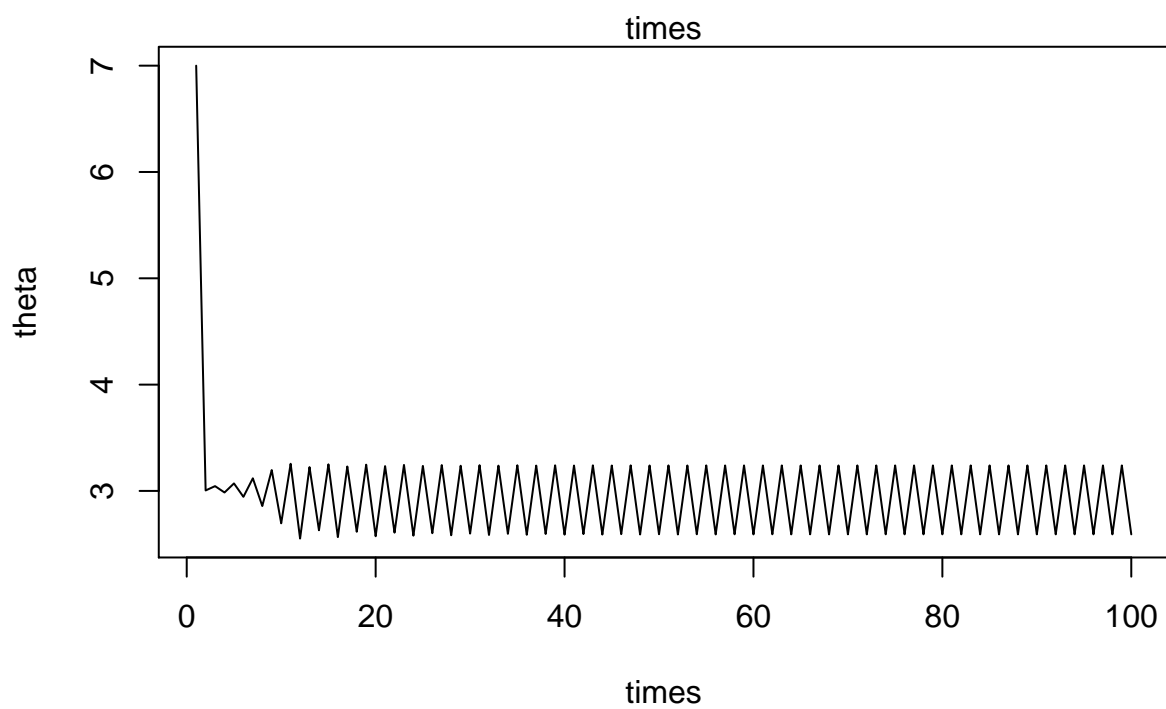
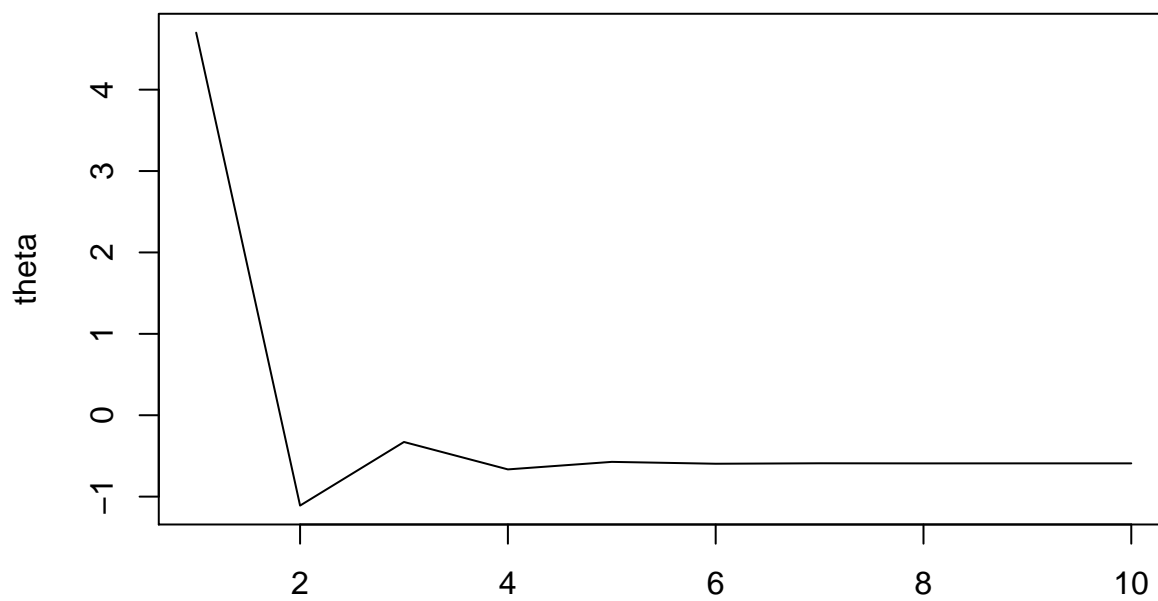


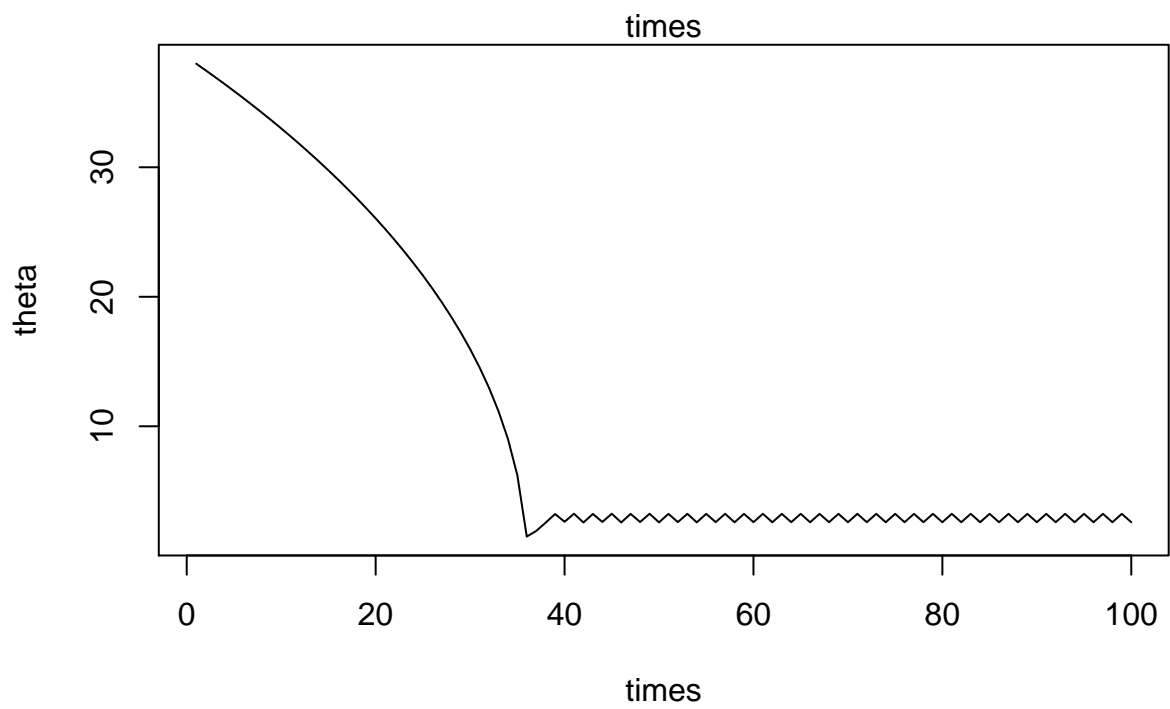
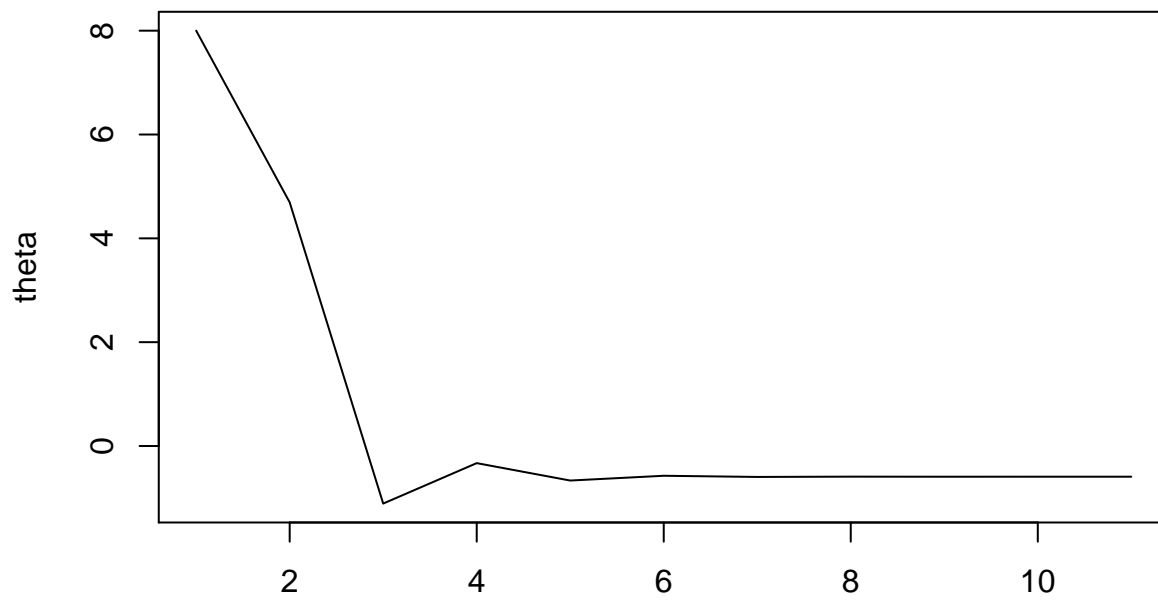


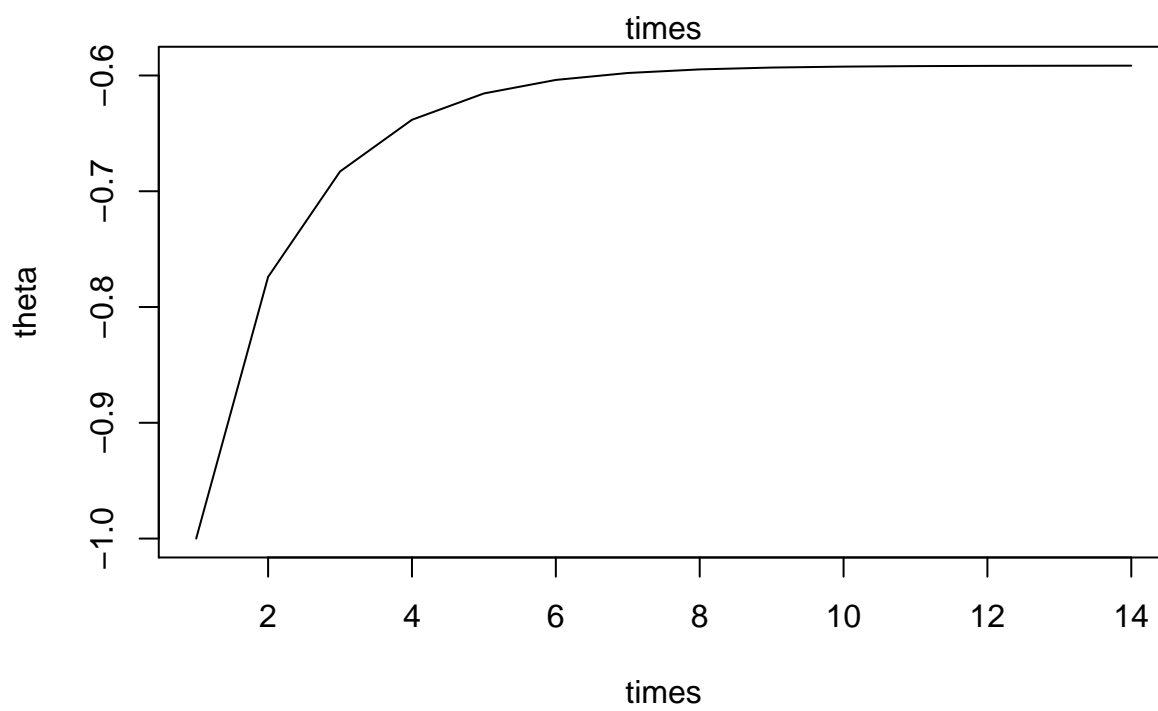
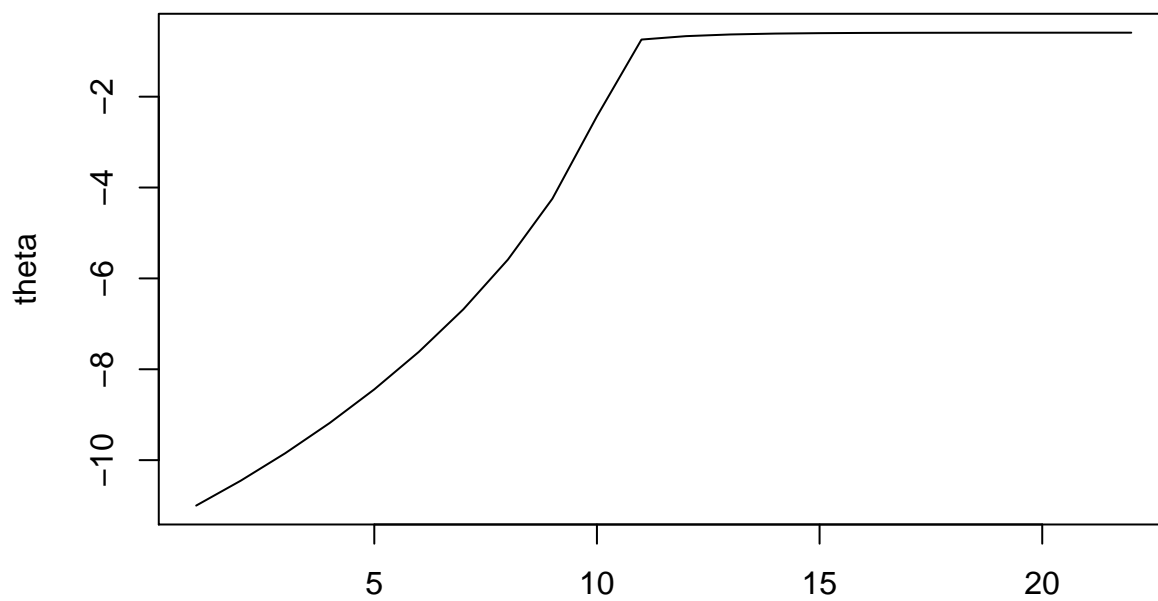


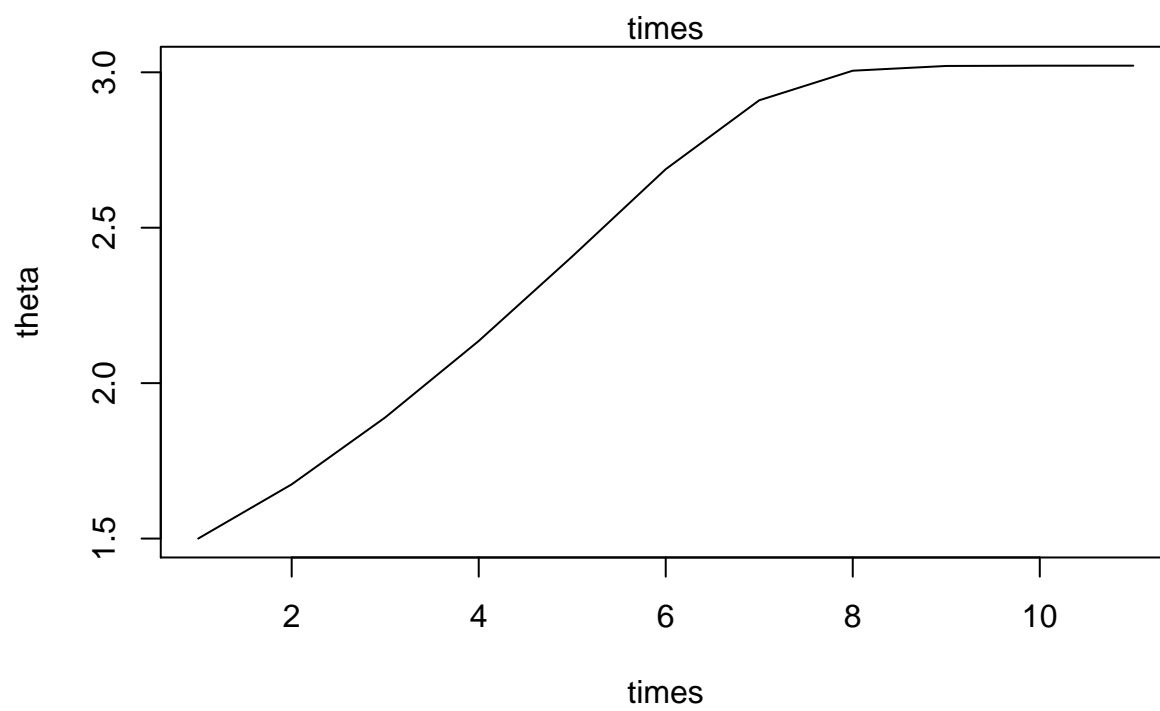
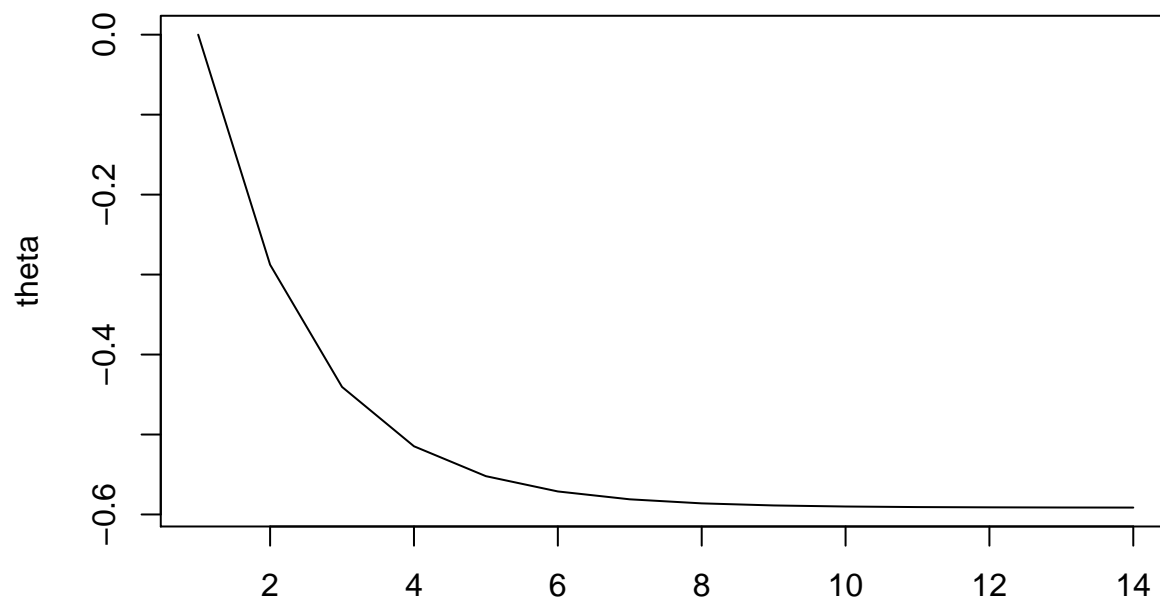


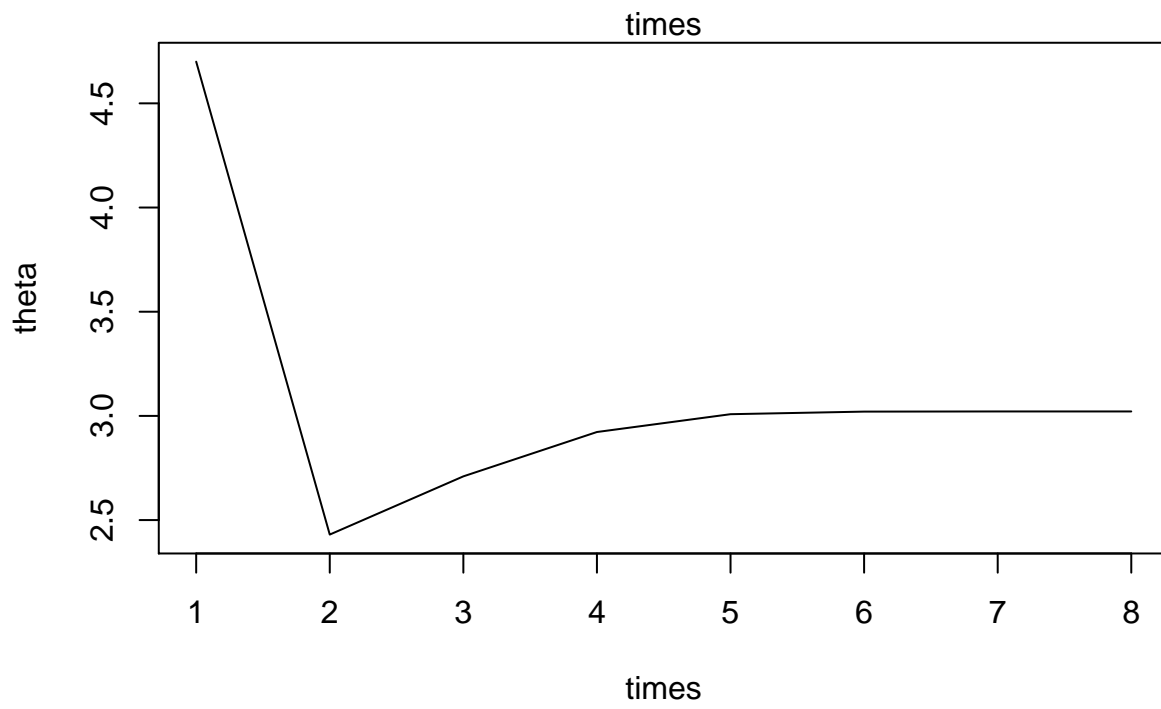
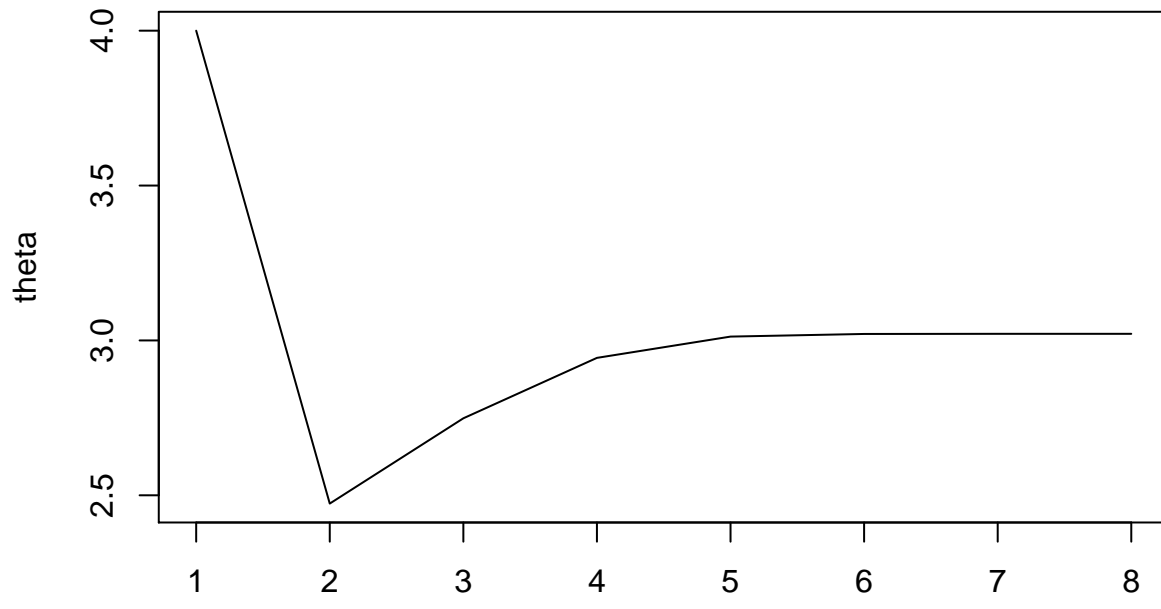


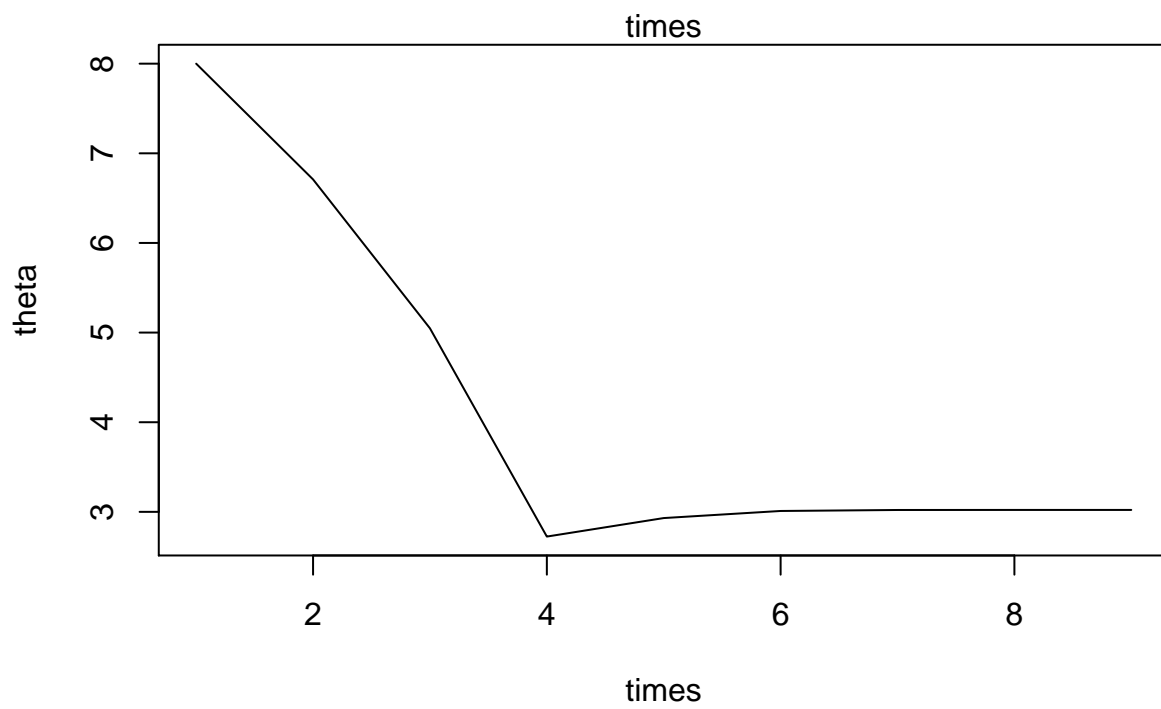
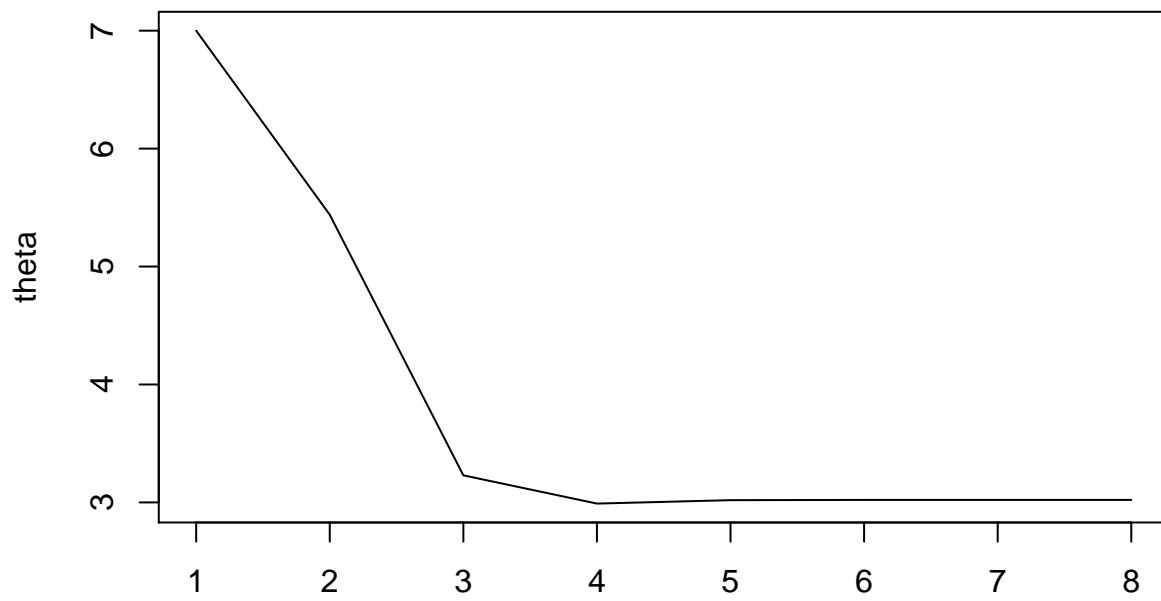


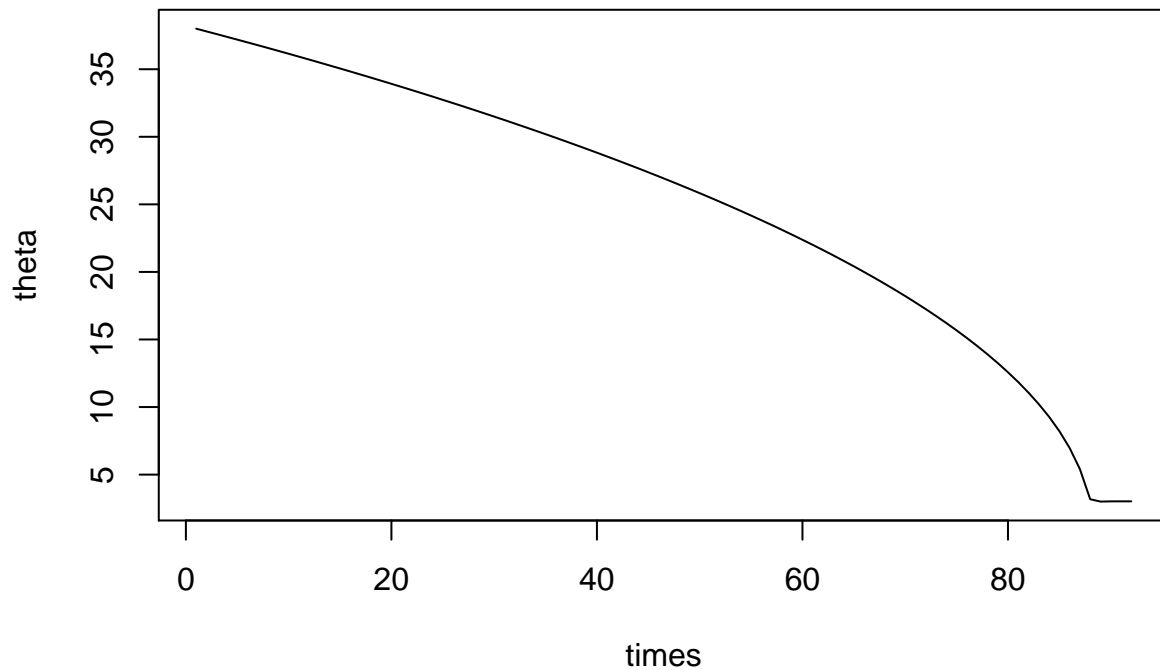








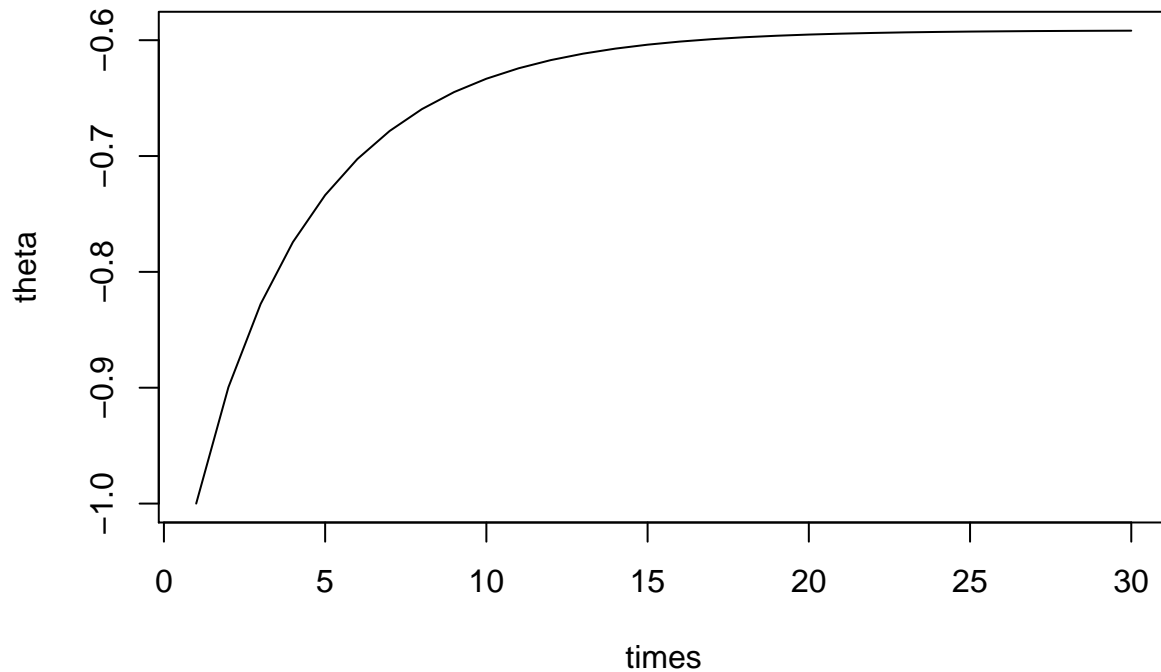




As we can see graphs above, some starting points have ideal converging values. Some values after iteration are isolating and continues without stopping.

1(d)

```
x <- c(1.77, -0.23, 2.76, 3.80, 3.47, 56.75, -1.34, 4.24, -2.44,
      3.29, 3.71, -2.40, 4.53, -0.07, -1.05, -13.87, -2.53, -1.75)
llh1 <- function(x, theta){
  value <- 0
  for (i in 1:length(x)){
    value <- value - 2*(theta-x[i])/(1+(theta-x[i])^2)
  }
  value
}
theta <- array()
theta[1] <- -1
diff <- 100
i <- 1
while(abs(diff)>10^(-4)){
  theta[i+1] <- theta[i]+llh1(x, theta[i])/(length(x)/2)
  diff <- theta[i+1]-theta[i]
  i <- i+1
}
plot(theta, xlab = 'times', type = 'l')
```



In this point of view, I just print one figure which starting point is -1.

1(e)

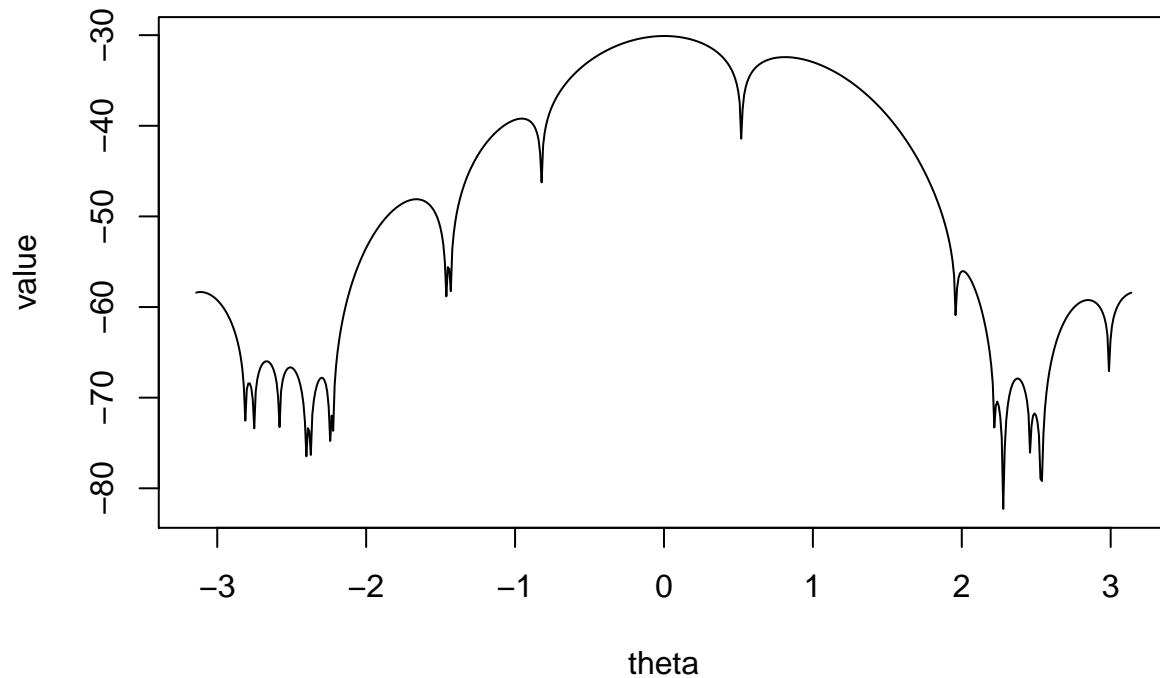
After using different methods to measure the value of theta, we can easily see that Newton-Raphson method is the fastest to converge, fixed-point iteration is the second fast, and Fisher scoring is the least. As we can see the graphs above, the fix-point iterations' stability is the worst.

2(a)

$$l(\theta) \tag{29}$$

$$= \sum_{i=1}^n \ln \sin^2 \frac{x_i - \theta}{2} - n \ln \pi \tag{30}$$

```
x <- c(3.91, 4.85, 2.28, 4.06, 3.70, 4.04, 5.46, 3.53, 2.28, 1.96,
       2.53, 3.88, 2.22, 3.47, 4.82, 2.46, 2.99, 2.54, 0.52)
theta <- seq(-pi, pi, 0.01)
loglikelihood <- function(x, theta){
  value <- -length(x)*log(pi)
  for (i in 1:length(x)){
    value <- value + log((sin((x[i]-theta)/2)^2))
  }
  value
}
value <- array()
for (i in 1:length(theta)){
  value[i] <- loglikelihood(x, theta[i])
}
plot(theta, value, type = 'l')
```



2(b)

I integrated the function $x \cdot p$ from 0 to 2π , and get the expression for

$$E[X|\theta] = \pi + \sin(\theta) \quad (31)$$

Here is my two roots:

```
x <- c(3.91, 4.85, 2.28, 4.06, 3.70, 4.04, 5.46, 3.53, 2.28, 1.96,
      2.53, 3.88, 2.22, 3.47, 4.82, 2.46, 2.99, 2.54, 0.52)

theta <- seq(-pi, pi, 0.01)
theta_bar <- function(theta){
  pi + sin(theta) - mean(x)
}

uniroot(theta_bar, c(-pi, 2))$root

## [1] 0.09539438

uniroot(theta_bar, c(2, pi))$root

## [1] 3.046199
```

2(c)

```
x <- c(3.91, 4.85, 2.28, 4.06, 3.70, 4.04, 5.46, 3.53, 2.28, 1.96,
      2.53, 3.88, 2.22, 3.47, 4.82, 2.46, 2.99, 2.54, 0.52)
theta <- seq(-pi, pi, 0.01)
theta_bar <- function(theta){
  pi + sin(theta) - mean(x)
}
```

```

}

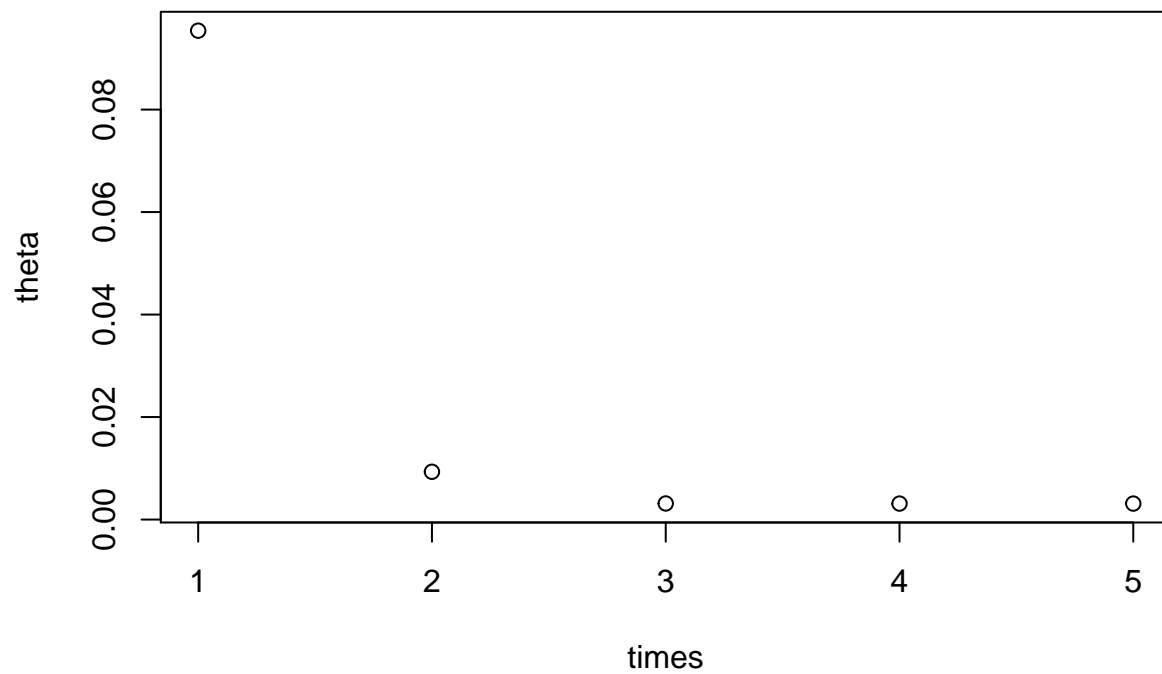
theta_moment <- c(uniroot(theta_bar, c(-pi, 2))$root, uniroot(theta_bar, c(2, pi))$root)

### First derivative of loglikelihood
llh1 <- function(x, theta){
  value <- 0
  for (i in 1:length(x)){
    value <- value + sin(x[i]-theta)/(1-cos(x[i]-theta))
  }
  value
}

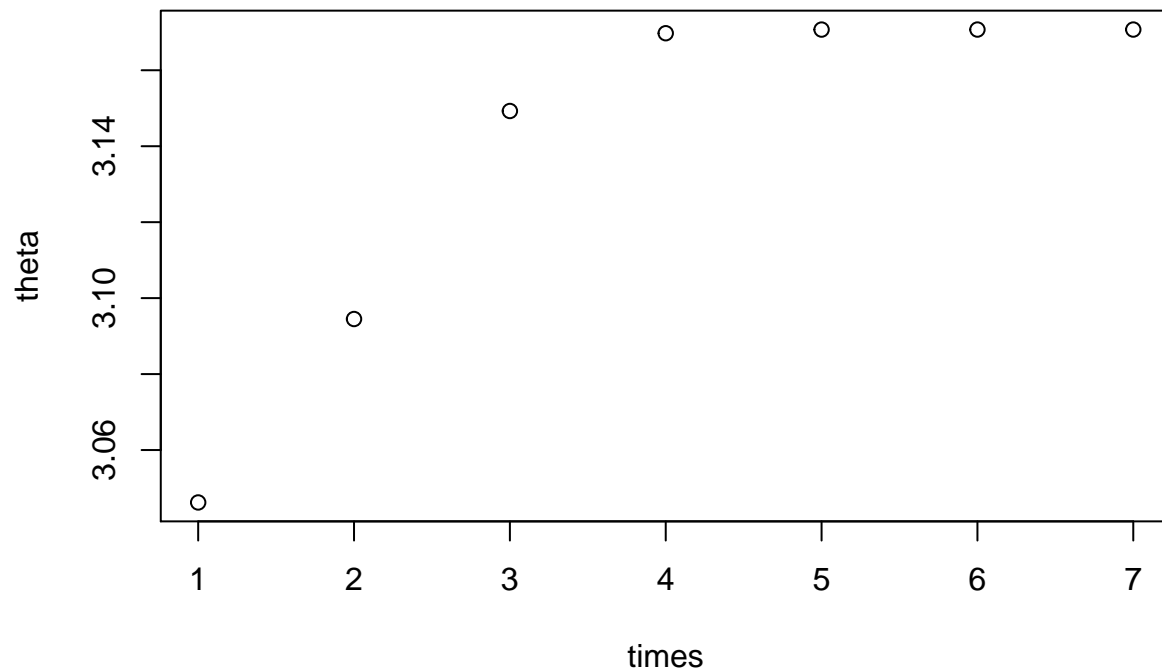
### Second derivative of loglikelihood
llh2 <- function(x, theta){
  value <- 0
  for (i in 1:length(x)){
    value <- value + 1/(1-cos(x[i]-theta))
  }
  value
}

### Compute theta value when getting MLE
theta <- array()
theta[1] <- theta_moment[1]
difference <- 100
i <- 1
while(abs(difference)>10^(-8)){
  theta[i+1] <- theta[i] - llh1(x, theta[i])/llh2(x, theta[i])
  difference <- theta[i+1] - theta[i]
  i <- i+1
}
plot(theta, xlab = 'times')

```



```
### Compute theta value when getting MLE
theta <- array()
theta[1] <- theta_moment[2]
difference <- 100
i <- 1
while(abs(difference)>10-8){
  theta[i+1] <- theta[i] - llh1(x, theta[i])/llh2(x, theta[i])
  difference <- theta[i+1] - theta[i]
  i <- i+1
}
plot(theta, xlab = 'times')
```



Here is my two plots of two theta moments.

2(d)

When I use the 2(c) functions to calculate the MLE solutions for theta, I got 2.848415 when starting from 2.7, and -2.668857 when starting from -2.7.

2(e)

This is the group what I have got:

##		value	Freq
## 1	-3.112471	11	
## 2	-2.786557	2	
## 3	-2.668857	5	
## 4	-2.509356	6	
## 5	-2.388267	1	
## 6	-2.297926	4	
## 7	-2.232192	1	
## 8	-1.662712	24	
## 9	-1.447503	1	
## 10	-0.954406	19	
## 11	0.003118	42	
## 12	0.812637	46	
## 13	2.007223	8	
## 14	2.237013	2	
## 15	2.374712	6	
## 16	2.48845	2	
## 17	2.848415	15	
## 18	3.170715	5	

3(a)

In this problem, I both created my own function with Gauss Newton Method and used built-in function called nls to solve the problem and get the result:

```
Gauss_Newton <- function(r0,k0){
  start <- c(0.5,1000)
  error <- sum(abs(start))
  i <- 1
  while(error>10^(-4)){
    r0 <- r0 + theta_calculate(r0,k0)[1]
    k0 <- k0 + theta_calculate(r0,k0)[2]
    error <- sum(abs(theta_calculate(r0,k0)))
    i <- i + 1
  }
  theta <- c(r0, k0, i)
  theta
}
```

```
Gauss_Newton(0.2,2000)
```

```
## [1] 0.1182697 1049.4064234 8.0000000
```

```
model <- nls(N~(2*k)/(2+(k-2)*exp(-r*times)), start = list(k = 100, r = 0.1))
model
```

```
## Nonlinear regression model
##   model: N ~ (2 * k)/(2 + (k - 2) * exp(-r * times))
##   data: parent.frame()
##           k           r
## 1049.4065    0.1183
## residual sum-of-squares: 73420
##
## Number of iterations to convergence: 10
## Achieved convergence tolerance: 9.33e-06
```

3(b)

Here is my contour plot of the sum of squared errors:

```
###Plot the contour of the sum of squared errors
i <- 1
error <- 1
r0 <- array()
k0 <- array()
r0[1] <- 0.2
k0[1] <- 1000
while(error>10^(-4)){
  r0[i+1] <- r0[i] + theta_calculate(r0[i],k0[i])[1]
  k0[i+1] <- k0[i] + theta_calculate(r0[i],k0[i])[2]
  error <- sum(abs(theta_calculate(r0[i+1],k0[i+1])))
  i <- i + 1
}

value <- array()
for (i in 1:length(r0)){
  value[i] <- sum((N - 2*k0[i]/(2+(k0[i]-2)*exp(-r0[i]*times)))^2)
  value
}
plot(value, xlab = 'times', ylab = 'squared errors', type = 'l')
```

