Intro to Thinc: Defining Model and Config and Wrapping PyTorch, TensorFlow and MXNet

Defining Model in Thinc

```
from thinc.api import prefer_gpu
prefer_gpu() # returns boolean indicating if GPU was activated
False
```

Declaring data below for the whole file: Using ml-datasets package in Thinc for some common datasets including MNIST:

```
import ml_datasets

# note: these are numpy arrays
(trainX, trainY), (devX, devY) = ml_datasets.mnist()
print(f"Training size={len(trainX)}, dev size={len(devX)}")
Training size=54000, dev size=10000
```

Step 1: Define the Model

Defining a model with two *Relu-activated hidden layers*, followed by a *softmax-activated output layer*. Also add *dropout* after the two hidden layers to help model generalize better.

The *chain* combinator: acts like *Sequential* in PyTorch or Keras since it combines a list of layers together with a feed-forward relationship.

Step 2: Initialize the Model

Initializing model

Call Model.initialize after creating the model and pass in a small batch of input data X and small batch of output data Y. Lets Thinc *infer the missing dimensions* (when we defined the model we didn't tell it the input size nI or the output size n0)

When passing in the data, call model.ops.asarray to make sure the data is on the right device (transforms the arrays to cupy when running on GPU)

```
# Making sure the data is on the right device
trainX: ArrayXd = model.ops.asarray(trainX)
trainY: ArrayXd = model.ops.asarray(trainY)
devX: ArrayXd = model.ops.asarray(devX)
devY: ArrayXd = model.ops.asarray(devY)
```

model.initialize(X=trainX[:5], Y=trainY[:5])

```
nI: int = model.get_dim("nI")
nO: int = model.get_dim("nO")

print(
    f"Initialized model with input dimension nI = {nI} and output dimension nO = {nO}"
)

Initialized model with input dimension nI = 784 and output dimension nO = 10
```

Step 3: Train the Model

NUM_ITERATIONS: int = 10

Create optimizer and make several passes over the data, randomly selecting paired batches of the inputs and labels each time.

** Key difference between Thinc and other ML libraries:** other libraries provide a single .fit() method to train a model all at once, but Thinc lets you shuffle and batch your data.

```
from tqdm.notebook import tqdm
def trainModel(data, model, optimizer, numIter: int, batchSize: int):
    (trainX, trainY), (devX, devY) = data
    # todo why need indices?
   # indices = model.ops.xp.arange(trainX.shape[0], dtype="i")
   for i in range(numIter):
        # multibatch(): minimatch one or more sequences of data and yield lists with one batch per sequence.
        batches = model.ops.multibatch(batchSize, trainX, trainY, shuffle=True)
        for X, Y in tqdm(batches, leave=False):
            # begin_update(self, X: InT) -> Tuple[OutT, Callable[[InT], OutT]]:
           # Purpose: run the model over a batch of data, returning the output and a callback to complete the ba
            # Returned: tuple (Y, finishedUpdated), where Y = batch of output data, and finishedUpdate = callback
            Yh, backprop = model.begin_update(X=X)
            backprop(Yh - Y)
            # finish_update(): update parameters with current gradients. The optimizer is called with each parame
            model.finish_update(optimizer=optimizer)
        # Evaluate and print progress
        numCorrect: int = 0
        totalCount: int = 0
        for X, Y in model.ops.multibatch(batchSize, devX, devY):
            # predict(X: InT) -> OutT: calls the model's forward function with is_train=False, and returns only t
            Yh = model.predict(X=X)
           numCorrect += (Yh.argmax(axis=1) == Y.argmax(axis=1)).sum()
            totalCount += Yh.shape[0]
        score = numCorrect / totalCount
        print(f" {i}: {float(score):.3f}")
from thinc.api import Adam, fix_random_seed
fix_random_seed(0)
adamOptimizer = Adam(0.001)
BATCH_SIZE: int = 128
```

```
print("Measuring performance across iterations: ")
trainModel(data=((trainX, trainY), (devX, devY)),
           model=model,
           optimizer=adamOptimizer,
           numIter=NUM_ITERATIONS,
           batchSize=BATCH_SIZE)
Measuring performance across iterations:
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 0: 0.844
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 1: 0.882
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 2: 0.891
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 3: 0.904
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 4: 0.909
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 5: 0.914
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 6: 0.916
```

```
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
7: 0.923

HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
8: 0.923

HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
9: 0.926
```

Another Way to Define Model: Operator Overloading

- Thinc lets you *overload operators* and bind arbitrary functions to operators like +, *, and » or @.
- The Model.define_operators contextmanager takes a dictionary of operators mapped to functions (typically combinators like chain)
- Operators in the dict are onl valid for the with block

```
# Example of using the operators:
from thinc.api import Model, chain, Relu, Softmax

numHidden: int = 32
dropout: float = 0.2

with Model.define_operators({">>": chain}):
    modelByMyOp = Relu(nO=numHidden, dropout=dropout) >> Relu(
    nO=numHidden, dropout=dropout) >> Softmax()
```

NOTE: bunch of things here in source tutorial about config files ...

Wrapping TensorFlow, PyTorch, and MXNet models

Can wrap the underlying model using Thinc interface to get type hints and use config system.

1. Wrapping TensorFlow Models

Tensorflow's Sequential layer is equivalent to Thinc's chain. Defining here model with two Relu and dropout and softmax output.

```
from tensorflow.keras.layers import Dense, Dropout
from tensorflow.keras.models import Sequential
from thinc.api import TensorFlowWrapper, Adam

width: int = 32
n0: int = 10
nI: int = 784
dropout: float = 0.2

tfModel: Sequential = Sequential()
```

```
tfModel.add(Dense(width, activation="relu", input_shape=(nI, )))
tfModel.add(Dropout(dropout))
tfModel.add(Dense(width, activation="relu", input_shape=(nI, )))
tfModel.add(Dropout(dropout))
tfModel.add(Dense(n0, activation="softmax"))
tfModel
<tensorflow.python.keras.engine.sequential.Sequential at 0x7fdd29e2eeb8>
The wrapped tensorflow model:
wrappedTFModel: Model = TensorFlowWrapper(tensorflow_model=tfModel)
wrappedTFModel
<thinc.model.Model at 0x7fdd29e44840>
Training the wrapped tensorflow model:
data = ml datasets.mnist()
#data
from thinc.optimizers import Optimizer
adamOptimizer: Optimizer = Adam(learn_rate=0.001)
adamOptimizer
<thinc.optimizers.Optimizer at 0x7fdd2a0536d8>
# Providing batch of input data and batch of output data to do shape inference.
wrappedTFModel.initialize(X=trainX[:5], Y=trainY[:5])
<thinc.model.Model at 0x7fdd29e44840>
# Training the model
NUM ITERATIONS = 10
BATCH\_SIZE = 128
trainModel(data=data,
           model=wrappedTFModel,
           optimizer=adamOptimizer,
           numIter=NUM_ITERATIONS,
           batchSize=BATCH_SIZE)
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 0: 0.915
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 1: 0.927
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 2: 0.933
```

```
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 3: 0.939
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 4: 0.945
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 5: 0.946
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 6: 0.947
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 7: 0.949
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 8: 0.950
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 9: 0.951
2. Wrapping PyTorch Models
Thinc's PyTorchWrapper wraps the model and turns it into a regular Thinc Model.
import torch
import torch.nn
# Renaming imports for reading clarity:
#import torch.nn.modules.dropout.Dropout2d as Dropout2d
#import torch.nn.Linear as Linear
import torch.tensor as Tensor
```

```
import torch.nn.functional as F
# Thinc imports
from thinc.api import PyTorchWrapper, Adam
width: int = 32
n0: int = 10
nI: int = 784
dropout: float = 0.2
class PyTorchModel(torch.nn.Module):
    def __init__(self, width: int, nO: int, nI: int, dropout: float):
        super(PyTorchModel, self).__init__()
        self.firstDropout: torch.nn.Dropout2d = torch.nn.Dropout2d(dropout)
        self.secondDropout: torch.nn.Dropout2d = torch.nn.Dropout2d(dropout)
        self.firstLinearLayer: torch.nn.Linear = torch.nn.Linear(in_features=nI,
                                                out_features=width)
        self.secondLinearLayer: torch.nn.Linear = torch.nn.Linear(in_features=width,
                                                out_features=n0)
    def forward(self, x: Tensor) -> Tensor:
        x: Tensor = F.relu(x)
        x: Tensor = self.firstDropout(x)
        x: Tensor = self.firstLinearLayer(x)
        x: Tensor = F.relu(x)
        x: Tensor = self.secondDropout(x)
        x: Tensor = self.secondLinearLayer(x)
        output: Tensor = F.log_softmax(input = x, dim = 1)
        return output
wrappedPyTorchModel: Model = PyTorchWrapper(pytorch_model=
                                            PyTorchModel(width = width,
                                                         n0 = n0,
                                                          nI = nI,
                                                          dropout=dropout))
wrappedPyTorchModel
<thinc.model.Model at 0x7fdd2a6e38c8>
Training the wrapped pytorch model:
data = ml_datasets.mnist()
adamOptimizer: Optimizer = Adam(learn_rate = 0.001)
wrappedPyTorchModel.initialize(X = trainX[:5], Y = trainY[:5])
wrappedPyTorchModel
<thinc.model.Model at 0x7fdd2a6e38c8>
NUM_ITERATIONS = 10
BATCH_SIZE = 128
```

```
trainModel(data=data,
          model=wrappedPyTorchModel,
           optimizer=adamOptimizer,
           numIter=NUM_ITERATIONS,
           batchSize=BATCH_SIZE)
#
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 0: 0.913
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 1: 0.920
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
2: 0.925
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 3: 0.925
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
4: 0.931
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 5: 0.931
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 6: 0.933
```

```
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
7: 0.936

HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
8: 0.938

HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
9: 0.939
```

3. Wrapping MXNet Models

Thinc's MXNetWrapper wraps the model and turns it into a regular Thinc Model.

MXNet uses a <code>.softmax()</code> method instead of a <code>Softmax</code> layer so to integrate it with the rest of the components, we must combine it with a <code>Softmax()</code> Thinc layer using the <code>chain</code> combinator. * NOTE: make sure to <code>initialize()</code> the MXNet model and the Thinc model (both).

```
from mxnet.gluon.nn import Dense, Sequential, Dropout
from thinc.api import MXNetWrapper, chain, Softmax
width: int = 32
n0: int = 10
nI: int = 784
dropout: float = 0.2
mxnetModel = Sequential()
mxnetModel.add(Dense(units = width, activation = "relu"))
mxnetModel.add(Dropout(rate = dropout))
mxnetModel.add(Dense(units = width, activation = "relu"))
mxnetModel.add(Dropout(rate = dropout))
mxnetModel.add(Dense(units = n0))
mxnetModel
Sequential(
  (0): Dense(None -> 32, Activation(relu))
  (1): Dropout(p = 0.2, axes=())
  (2): Dense(None -> 32, Activation(relu))
  (3): Dropout(p = 0.2, axes=())
  (4): Dense(None -> 10, linear)
mxnetModel.initialize()
mxnetModel
Sequential(
  (0): Dense(None -> 32, Activation(relu))
  (1): Dropout(p = 0.2, axes=())
  (2): Dense(None -> 32, Activation(relu))
```

```
(3): Dropout(p = 0.2, axes=())
  (4): Dense(None -> 10, linear)
wrappedMxnetModel: Model = chain(layer1 = MXNetWrapper(mxnet_model = mxnetModel),
                                 layer2 = Softmax())
wrappedMxnetModel
<thinc.model.Model at 0x7fdd2a6ef6a8>
Training the wrapped mxnet model
data = ml_datasets.mnist()
adamOptimizer: Optimizer = Adam(learn_rate = 0.001)
wrappedMxnetModel.initialize(X = trainX[:5], Y = trainY[:5])
wrappedMxnetModel
<thinc.model.Model at 0x7fdd2a6ef6a8>
NUM ITERATIONS = 10
BATCH_SIZE = 128
trainModel(data=data,
           model=wrappedMxnetModel,
           optimizer=adamOptimizer,
           numIter=NUM_ITERATIONS,
           batchSize=BATCH_SIZE)
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 0: 0.744
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 1: 0.877
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 2: 0.909
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 3: 0.925
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
 4: 0.932
```

```
HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
5: 0.937

HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
6: 0.941

HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
7: 0.944

HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
8: 0.945

HBox(children=(FloatProgress(value=0.0, max=422.0), HTML(value='')))
9: 0.950
```