# Package 'vbayesGP'

July 30, 2023

Type Package			
Title Gaussian Variational Approximation to Gaussian Process Regression			
Version 0.1.0			
<b>Date</b> 2023-07-30			
Author Seongil Jo[aut, cre], Woojoo Lee[aut]			
Maintainer Seongil Jo <bstatsjo@gmail.com></bstatsjo@gmail.com>			
Description Implements Gaussian variational approximation to  Bayesian semiparametric regression with Gaussian process prior based on the Radial basis function (RBF) kernel. Consider the normal prior, the independent normal priors, or the horseshoe prior on the positive real number for the lengthscale parameters of the RBF kernel.			
License GPL-2			
Imports Rcpp (>= 1.0.8), fields, ggplot2, MASS			
LinkingTo Rcpp, RcppArmadillo			
RoxygenNote 7.2.3			
Encoding UTF-8			
LazyLoad yes			
R topics documented:  extractELBO			
summary.gpr			
inuex 10			

2 extractPostSamps

extractELB0

Extract ELBO from VGPR model fits

### **Description**

Compute the expected lower bound (ELBO) using the posterior samples for class "gpr"

### Usage

```
extractELBO(object, nsamples = 1000)
```

### **Arguments**

object an object of class gpr.

nsamples (positive integer), number of posterior samples to draw and save, defaults to

1000.

### Author(s)

Seongil Jo

#### See Also

gvagpr

extractPostSamps

Extract Posterior Samples from VGPR model fits

### **Description**

Generate the posterior samples for class "gpr"

## Usage

```
extractPostSamps(object, nsamples = 1000)
```

## Arguments

object an object of class gpr.

nsamples (positive integer), number of posterior samples to draw and save, defaults to

1000.

## Value

a data frame including posterior samples for  $\beta$ ,  $\sigma^2$ ,  $\lambda_f$ , and  $\gamma$ . If object\$id is not NULL, the data frame also includes  $b_i, i=1,\ldots,N$ .

#### Author(s)

Seongil Jo

fitted.gpr 3

### See Also

gvagpr

fitted.gpr

Extract GPR Model Fitted Values

# Description

**fitted** is a generic function which extracts fitted values of nonparametric part from an object of class "gpr"

## Usage

```
## S3 method for class 'gpr'
fitted(object, nsamples = 1000, ...)
```

# Arguments

object an object of class gpr.

nsamples (positive integer) number of posterior samples. Default value is 1000.

# Value

fmean

posterior mean of nonparametric part.

fcov

posterior variance of nonparametric part. an object of class "gprfit", which has the associated method:

```
* plot (i.e., plot.gprfit)
```

### Author(s)

Seongil Jo

## See Also

gvagpr

4 gyagpr

gvagpr

Gaussian Variational Approximation to Gaussian Process Regression

#### **Description**

Fits the Bayesian kernel machine regression using Gaussian variational approximation algorithm.

#### Usage

```
gvagpr(
   y,
   X,
   Z,
   id = NULL,
   random.slope = NULL,
   priors = list(),
   covstr = c("diagonal", "fullrank"),
   control = list(),
   minibatch = FALSE,
   verbose = TRUE,
   seed = 1
)
```

#### Arguments

V	a vector of response	of length n.

X an n-by-p matrix of covariates for parametric term. Should not contain an inter-

cept.

Z an n-by-M matrix of predictor variables to be included in nonparametric part.

optional vector (of length n) of grouping factors for fitting a model with random effects (including both a random intercept and a random slope). If NULL then no

random effects will be included.

random.slope a column index of the matrix (X) including covariates for random slope. If NULL

and id is given, the model considers the random intercept only.

priors a list giving the prior information. The list includes the following parameters

(with default values in parentheses): asig (0.001) and bsig (0.001) giving the hyper parameters for  $\sigma^2$ , alam (0.1) and blam (0.01) giving the hyper parameters for  $\lambda_f$ , lam0 (1) and tau0 (1) giving the hyper parameters of the

horseshoe prior.

covstr Either "diagonal" (the default) or "fullrank", indicating which covariance struc-

ture of variational distribution is used. The "diagonal" option uses a fully factorized Gaussian for the approximation whereas the fullrank option uses a Gaussian

with a full-rank covariance matrix for the approximation.

control a named list of parameters to control the algorithm's behavior. The list in-

cludes the following parameters (with default values in parentheses): max\_iter (100000) giving the maximum number of iterations, rho (0.95) giving the decaying constant, eps (1e-6) giving the small positive constant added to ensure the denominator of the step size is positive and the initial step size is nonzero, nws (2500) giving rolling window size for calculating the moving average of

the lower bounds, nsp (100) giving the maximum patience parameter.

gvagpr 5

minibatch TRUE or FALSE: If TRUE, nbatch (the number of batch size) should be given

in control argument. Default value is n/100.

verbose TRUE or FALSE: flag indicating whether to print intermediate diagnostic infor-

mation during the model fitting.

seed The seed for random number generation. The default is generated from 1 to the

maximum integer supported by  $\mathbf{R}$  on the machine.

#### **Details**

Jo, and Lee (2023+) proposed the Bayesian semiparametric regression model with Gaussian process prior based on the Radial basis function (RBF) kernel:

$$y_i = x_i^{\top} \beta + f(z_i) + \epsilon_i, \quad \epsilon_i \stackrel{iid}{\sim} N(0, \sigma^2),$$
  
 $f = (f(z_1), \dots, f(z_D))^{\top} \sim GP(0, \sigma^2 \lambda_f K_D), \ z_i = (z_{i1}, \dots, z_{iM})^{\top},$ 

where  $K_D$  denotes the RBF kernel given as

1) Equal lengthscale parameter:

$$K_D = \left(\exp\left(-\gamma \sum_{m=1}^{M} ||z_i - z_j||^2\right)\right)_{i,j=1}^D$$

2) Varying lengthscale parameters:

$$K_D = \left(\exp\left(-\sum_{m=1}^{M} \gamma_m ||z_i - z_j||^2\right)\right)_{i,j=1}^D$$

For the parameters, the following priors are used:

$$\pi(\beta) \propto 1,$$

$$\pi(\sigma^{-2}) = Gamma(a_{\sigma}, b_{\sigma}),$$

$$\pi(\lambda_f) = Gamma(a_{\lambda}, b_{\lambda}),$$

1) Normal prior:

$$\pi(\gamma) = N_+(0, \tau_0^2)$$

2) Independent Normal priors:

$$\pi(\gamma_m) = N_+(0, \tau_0^2), m = 1, \dots, M$$

3) Horseshoe prior:

$$\pi(\gamma_m \mid \lambda_m, \tau_\gamma) = N_+(0, \lambda_m^2 \tau_\gamma^2), \ m = 1, \dots, M$$

$$\pi(\lambda_m) = C_+(0, \lambda_0), \ m = 1, \dots, M$$

$$\pi(\tau_\gamma) = C_+(0, \tau_0),$$

where  $a_{\sigma}, b_{\sigma}, a_{\lambda}, b_{\lambda}, \lambda_0$  and  $\tau_0$  are positive constants specified by users.

For more details, see Jo and Lee (2023+).

6 gvagpr

#### Value

```
an object of class "gpr", which has the associated methods:

* extractELBO

* fitted (i.e., fitted.gpr)

* summary (i.e., summary.gpr)

* predict (i.e., predict.gpr)
```

#### Author(s)

Seongil Jo and Woojoo Lee

\* plot (i.e., plot.gpr)

#### References

Jo, S., and Lee, W. (2023+), "Gaussian variational inference for Bayesian kernel machine regression with Horseshoe prior for estimating high-dimensional exposures", *preprint*.

Titsias, M. K. and L\'azaro-Gredilla, M. (2014), "Doubly stochastic variational Bayes for non-conjugate inference", *Proceedings of the 31st ICML*.

Bobb, J. F., Valeri, L., Claus, H. B., Christiani, D. C., Wright, R. O., Mazumdar, M., Godleski, J. J., and Coull, B. A. (2015). "Bayesian Kernel Machine Regression for Estimating the Health Effects of Multi-Pollutant Mixtures", *Biostatistics*, 16, 493-508.

Chen, H., Zheng, L., Kontai, R. A., and Raskutti, G. (2022), "Gaussian process parameter estimation using mini-batch stochastic gradient descent: convergence guarantees and empirical benefits", *Journal of Machine Learning Research*, 23, 1-59.

## See Also

extractELBO, fitted.gpr, predict.gpr, plot.gpr, summary.gpr

## **Examples**

```
## Not run:
sdat <- bkmr::SimData()
y <- sdat$y
X <- sdat$X
Z <- sdat$Z

fout <- vbayesGP::gvagpr(y, X, Z, priors = list(lengthscale = 'normal'), covstr = 'diagonal')
plot(fout)
summary(fout)
vbayesGP::extractELBO(fout) # ELBO
## End(Not run)</pre>
```

plot.gpr 7

plot.gpr

Plot Diagnostics for a gpr Object

## Description

Provides a plot of the smoothed evidence lower bound (ELBO) against iterations for checking the convergence.

## Usage

```
## S3 method for class 'gpr'
plot(object, nsamples = 1000, ...)
```

## **Arguments**

object

gpr object, result of gvagpr.

### Author(s)

Seongil Jo

#### See Also

gvagpr

predict.gpr

Extract GPR Model Predicted Values

## Description

**predicted** is a generic function which extracts predicted values for nonparametric part from an object of class "gpr"

## Usage

```
## S3 method for class 'gpr'
predict(object, Z_new, ...)
```

## **Arguments**

object an object of class gpr.

Z\_new a matrix of new predictor values at which to predict new f, where each row

represents a new observation.

8 print.gpr

### Value

```
fmean
```

posterior mean of nonparametric part.

fcov

posterior variance of nonparametric part. an object of class "gprfit", which has the associated method:

```
* plot (i.e., plot.gprfit)
```

## Author(s)

Seongil Jo

## See Also

gvagpr

print.gpr

Print basic summary of gpr model fit

# Description

```
print method for class "gpr"
```

# Usage

```
## S3 method for class 'gpr'
print(object, ...)
```

# Arguments

object

an object of class gpr.

# Author(s)

Seongil Jo

## See Also

gvagpr

summary.gpr 9

summary.gpr

Summarizing gpr model fits

## Description

```
summary method for class "gpr"
```

# Usage

```
## S3 method for class 'gpr' summary(object, q = c(0.025, 0.975), digits = 5, nsamples = 1000, ...)
```

## Arguments

object an object of class gpr.

quantiles of posterior distribution (credible interval) to show.

digits the number of digits to show when printing.

nsamples (positive integer), number of posterior samples to draw and save, defaults to

1000.

## Author(s)

Seongil Jo

### See Also

gvagpr

# Index

```
extractELBO, 2
extractPostSamps, 2
fitted.gpr, 3
gvagpr, 4
plot.gpr, 7
predict.gpr, 7
print.gpr, 8
summary.gpr, 9
```