

Neural Collaborative Filtering

STAT3009 Recommender Systems

by **Ben Dai** (CUHK-STAT)

on **October 9, 2024**

» Recall LFM: NCF

Recall the basic Latent Factor Model:

$$\min_{\mathbf{P}, \mathbf{Q}} \frac{1}{|\Omega|} \sum_{(u,i) \in \Omega} (r_{ui} - \mathbf{p}_u^T \mathbf{q}_i)^2 + \lambda \left(\sum_{u=1}^n \|\mathbf{p}_u\|_2^2 + \sum_{i=1}^n \|\mathbf{q}_i\|_2^2 \right) \quad (1)$$

- * The **interaction** btw users and items are formulated as **inner production**.
- * It can be extended to **high-order** nonlinear interaction.

» Nonlinear interaction: NCF

- * For a general nonlinear function f , the predicted rating can be formulated as,

$$\hat{r}_{ui} = f(\mathbf{p}_u, \mathbf{q}_i).$$

- * Nonlinear methods: **polynomials**, **B-splines**, **kernel methods**, and **neural networks**
- * Now, we want to formulate the **nonlinear RS** as a **neural network**

» NCF: Goal

Let's summarize our goal:

LFM The idea of “**latent factor**” is quite useful for RS

NN Attempt to incorporate “**neural networks**” to formulate **high-order** interaction between users and items.

Quick solution:

Step 1 Mapping $u \rightarrow \mathbf{p}_u$; and mapping $i \rightarrow \mathbf{q}_i$

Step 2 Define a **network** $f: \mathbb{R}^K \times \mathbb{R}^K \rightarrow \mathbb{R}$

Step 3 The **final prediction** is $\hat{r}_{ui} = f(\mathbf{p}_u, \mathbf{q}_i)$

How to estimate **latent factors** (\mathbf{P}, \mathbf{Q}) and the **network** f ?

» NCF: Separate formulation

The neural network based on LFM can be formulated as:

$$\underset{\mathbf{P}, \mathbf{Q}, f}{\operatorname{argmin}} \frac{1}{|\Omega|} \sum_{(u,i) \in \Omega} (r_{ui} - f(\mathbf{p}, \mathbf{q}_i))^2 + \lambda \left(\sum_{u=1}^n \|\mathbf{p}_u\|_2^2 + \sum_{i=1}^n \|\mathbf{q}_i\|_2^2 \right)$$

» NCF: Separate formulation

The neural network based on LFM can be formulated as:

$$\operatorname{argmin}_{\mathbf{P}, \mathbf{Q}, f} \frac{1}{|\Omega|} \sum_{(u,i) \in \Omega} (r_{ui} - f(\mathbf{p}, \mathbf{q}_i))^2 + \lambda \left(\sum_{u=1}^n \|\mathbf{p}_u\|_2^2 + \sum_{i=1}^n \|\mathbf{q}_i\|_2^2 \right)$$

Opt: B-SGD

P Update **P** by fixing **Q** and f

Q Update **Q** by fixing **P** and f

f Update f by fixing **P** and **Q**

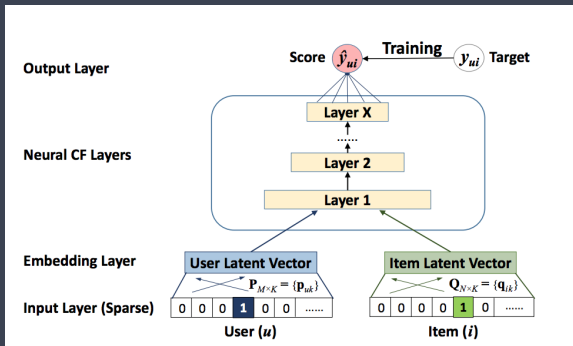
A bit cumbersome to implement

- * Auto-gradient in TensorFlow
- * Can we incorporate latent factors **P** and **Q** as params of a unified neural network
- * Then just SGD update all params in the network

» NCF: Unified formulation

A unified neural network

Input user-item pair $(u, i) \in \{0, \dots, n\} \times \{0, \dots, m\}$
Output the predicted rating



Source¹

¹He, X., Liao, L., Zhang, H., Nie, L., Hu, X., and Chua, T. S. (2017, April). Neural collaborative filtering. In Proceedings of the 26th International Conference on World Wide Web (pp. 173-182).

» NCF: embedding layer

We can incorporate **P** and **Q** by introducing **embedding layers** in the network;

A embedding layer attempt to

One-hot Encoding **userId** (**itemId**) as **one-hot encoding** (a binary dummy vector)

$$u \rightarrow \mathbf{e}_{n,u} = (0, \dots, \underbrace{1}_{u.th}, \dots, 0)^T, \quad i \rightarrow \mathbf{e}_{m,i} = (0, \dots, \underbrace{1}_{i.th}, \dots, 0)^T$$

Product Product **one-hot** encoding with the **embedding matrix**

$$\mathbf{p}_u = \mathbf{e}_{n,u}^T \mathbf{P}, \quad \mathbf{q}_i = \mathbf{e}_{m,i}^T \mathbf{Q}$$

Indeed, **embedding** is essentially same with **latent factors**; just different names...

» NCF: embedding layer

Let's summarize **Embedding Layer**...

Mapping $u \rightarrow \mathbf{p}_u$, or **cate_feat** \rightarrow **dense** representation

Params Embedding matrix: #User (or #Item) \times #LatentFactor

hp #LatentFactor or **embedding size**

Opt The model becomes

$$\hat{f}_{\theta} = \underset{f_{\theta}}{\operatorname{argmin}} \frac{1}{|\Omega|} \sum_{(u,i) \in \Omega} (r_{ui} - f_{\theta}(u,i))^2 + \lambda \operatorname{Reg}(\theta)$$

» NCF: RS formulation

Model The model for NCF is:

$$\hat{r}_{ui} = f([\mathbf{a}_u, \mathbf{b}_i])$$

Params All params in the network: two embedding matrices in embedding layers and weights in the other layers

hp embedding size and network architecture

Data $(u, i) \rightarrow r_{ui}$

Loss MSE

Metrics RMSE, MAE, ...

Opt SGD/B-SGD

InClass demo: Neural collaborative filtering #1

» ANCF: Additional formulation

Model We want to keep the LFM terms in the model...

$$\hat{r}_{ui} = \mathbf{p}_u^T \mathbf{q}_i + f([\mathbf{a}_u, \mathbf{b}_i])$$

Params All params in the network: **two** embedding matrices in embedding layers and weights in the other layers

hp **embedding size** and **network architecture**

Data $(u, i) \rightarrow r_{ui}$

Loss MSE

Metrics RMSE, MAE, ...

Opt SGD/B-SGD

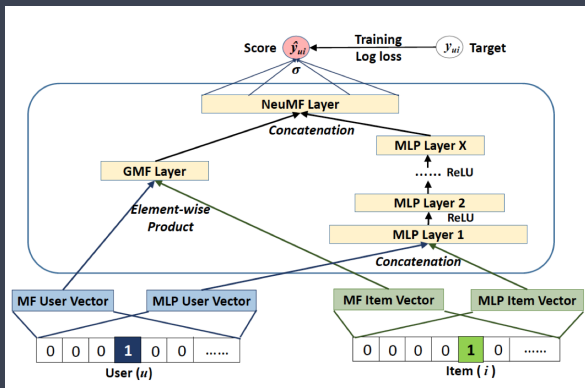
InClass demo: Neural collaborative filtering #2

» Neural-NCF: neural formulation

More general operators based on LFM terms

$$\hat{r}_{ui} = f_1([\mathbf{p}_u \circ \mathbf{q}_i, f_2(\mathbf{a}_u^T, \mathbf{b}_i)])$$

input and output remain the same



2

²He, X., Liao, L., Zhang, H., Nie, L., Hu, X., and Chua, T. S. (2017, April). Neural collaborative filtering. In Proceedings of the 26th International Conference on World Wide Web (pp. 173-182).

» NCF: RS formulation

Model The model becomes

$$\hat{r}_{ui} = f_1([\mathbf{p}_u \circ \mathbf{q}_i, f_2(\mathbf{a}_u^T, \mathbf{b}_i)])$$

Params All params in the network: **four** embedding matrices in embedding layers and weights in the other layers

hp **embedding size** and **network architecture**

Data $(u, i) \rightarrow r_{ui}$

Loss MSE

Metrics RMSE, MAE, ...

Opt SGD/B-SGD

InClass demo: Neural collaborative filtering #3