Multi-Dimensional arrays in CUDA

Matrix Squaring (CPU)

```
void squarecpu(unsigned *matrix, unsigned *result,
                  unsigned matrixsize /* = 32*/) {
  for (unsigned ii = 0; ii < matrixsize; ++ii) {
  for (unsigned jj = 0; jj < matrixsize; ++jj) {
     for (unsigned kk = 0; kk < matrixsize; ++kk) {
        result[ii * matrixsize + ji] +=
          matrix[ii * matrixsize + kk] * matrix[kk * matrixsize + jj];
```

Matrix Squaring (GPU-Version 2)

```
square<<<N, N>>>(matrix, result, N); // N = 32
```

```
global void square(unsigned *matrix,
                       unsigned *result,
                       unsigned matrixsize) {
  unsigned id = blockIdx.x * blockDim.x + threadIdx.x;
  unsigned ii = id / matrixsize;
  unsigned jj = id % matrixsize;
  for (unsigned kk = 0; kk < matrixsize; ++kk) {
    result[ii * matrixsize + jj] += matrix[ii * matrixsize + kk] *
                                 matrix[kk * matrixsize + ii];
```

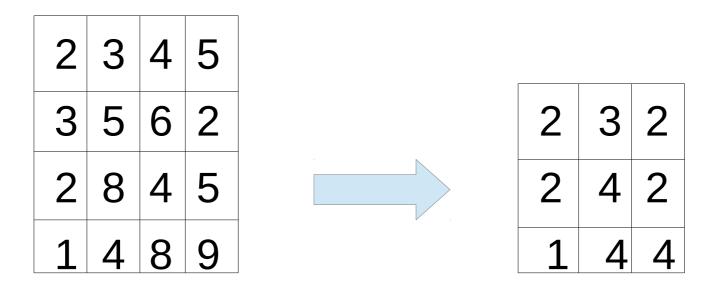
Matrix Squaring (GPU-Version 3)

```
int main(){
  int i, j;
  int A[N][N];
  int B[N][N];
  dim3 BlockPerGrid(1, 1);
  dim3 ThreadPerBlock(N, N);
  // Initialize A to required values B to all zeros
 cudaMemcpyToSymbol(dA,A,size,0,cudaMemcpyDefault);
 cudaMemcpyToSymbol(dB,B,size,0,cudaMemcpyDefault);
 sqr <<< BlockPerGrid, ThreadPerBlock >>> (N);
 cudaMemcpyFromSymbol(A,dB,size,0,cudaMemcpyDefault);
// Print the final results stored in A
return 0;
```

Matrix Squaring (GPU-Version 3)

```
sqr<<<BlockPerGrid,ThreadPerBlock>>>(N); // N = 32
  device int dA[N][N];
  device int dB[N][N];
  global void sample(int matrixsize)
  int j = threadIdx.x + blockDim.x * blockIdx.x;
  int i = threadIdx.y + blockDim.y * blockIdx.y;
  //printf("%d %d\n",i, j);
  for(int k=0;k<matrixsize;k++)
    dB[i][i] += dA[i][k] * dA[k][j];
```

2D Minimum Algorithm



- 2D operations like this are found in many fundamental algorithms like Interpolation, Convolution, Filtering
- Applications in seismic processing, weather simulation, image processing, etc

2D Minimum Algorithm

- Each output element is the minimum of input elements within the window
 - O[i][j] = min(A[i-1][j], A[i-1][j+1], A[i][j], A[i][j+1])
- The rows are in the range 0..N-1 and columns in 0..M-1
- The computation boundaries remains intact.
- Initialize all the values in A using rand() function.

2D Minimum Algorithm (CPU)

```
void init(int grid[[N], int prevgrid[[N])
           for(int i=0;i<N;i++){
              for(int j=0;j<N;j++){
                  int val = rand() \% 10;
                  grid[i][j] = val;
                  prevgrid[i][j] = val;
void compute(int grid[][N], int prevgrid[][N])
           // preform the computation
           for(int i=1;i<N;i++){
                 for(int j=0; j< N-1; j++){
                       grid[i][j] = min( min( prevgrid[i-1][j], prevgrid[i-1][j+1] ) ,
min( prevgrid[i][j], prevgrid[i][j+1] ) );
```

2D Minimum Algorithm (GPU)

```
void compute(int grid[][N], int prevgrid[][N]) // N = 32
    dim3 BlockPerGrid(1, 1);
    dim3 ThreadPerBlock(N, N);
    size t size = N * N * sizeof(int);
    cudaMemcpyToSymbol(dgrid, grid, size, 0, cudaMemcpyDefault);
    cudaMemcpyToSymbol(dprevgrid, prevgrid, size, 0,
cudaMemcpyDefault);
    sample <<<BlockPerGrid, ThreadPerBlock>>> (N);
    cudaMemcpyFromSymbol(grid, dgrid, size, 0, cudaMemcpyDefault);
```

2D Minimum Algorithm (GPU)

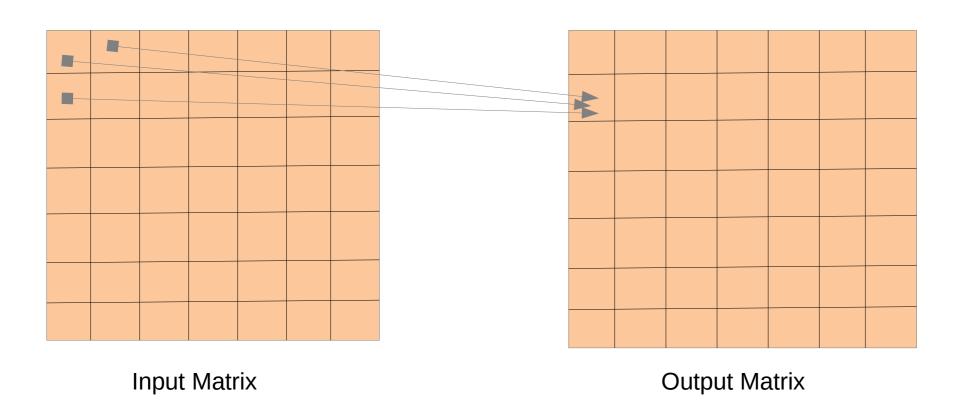
```
sample <<BlockPerGrid, ThreadPerBlock>>> (N); // N = 32
  device int dgrid[N][N];
  _device__ int dprevgrid[N][N];
  global void sample(int matrixsize){
  int j = threadIdx.x + blockDim.x * blockIdx.x;
  int i = threadIdx.y + blockDim.y * blockIdx.y;
  //printf("%d %d\n",i, j);
  if( i > 0 \&\& j < N-1 )
     dgrid[i][j] = min( min( dprevgrid[i-1][j], dprevgrid[i-1]
[j+1]), min(dprevgrid[i][j], dprevgrid[i][j+1]));
```

Stencil Computation

 Design and implement a stencil computation wherein in each iteration, cells compute their values using the neighboring ones, according to the following formula:

$$A[i][j] += A[i-1][j] + A[i-1][j+1]$$

- The rows are in the range 0..N-1 and columns in 0..M-1
- The computation boundaries remains intact.
- Initialize all the values in A to all 1s.
- Your program should run for ten iterations.



Stencil Computation (CPU)

```
// Perform the computation
     for(int itr=0;itr<10;itr++){</pre>
           // preform the computation for the current iteration
           for(int i=1;i<N;i++){
                 for(int j=0; j< N-1; j++){
                      stencil[i][j] += prevstencil[i-1][j] + prevstencil[i-1][j+1];
           // copy the result to the current iteration to the prevstencil so that can
be used for next iteration
           for(int i=0;i< N;i++){
                 for(int j=0; j<N; j++){
                      prevstencil[i][j] = stencil[i][j];
```

Stencil Computation (GPU)

```
dim3 BlockPerGrid(1, 1);
    dim3 ThreadPerBlock(N, N);
    size t size = N * N * sizeof(int);
    int itr;
    // Perform the computation
    for(itr=0;itr<10;itr++)
         cudaMemcpyToSymbol(dstencil, stencil, size, 0,
cudaMemcpyDefault);
         cudaMemcpyToSymbol(dprevstencil, prevstencil, size, 0,
cudaMemcpyDefault);
         sample <<<BlockPerGrid, ThreadPerBlock>>> (N);
         cudaMemcpyFromSymbol(prevstencil, dstencil, size, 0,
cudaMemcpyDefault);
         cudaMemcpyFromSymbol(stencil, dstencil, size, 0,
cudaMemcpyDefault);
```

Stencil Computation (GPU)

```
sample <<BlockPerGrid, ThreadPerBlock>>> (N); // N = 32
  device int dstencil[N][N];
  device int dprevstencil[N][N];
  global void sample(int matrixsize)
  int j = threadIdx.x + blockDim.x * blockIdx.x;
  int i = threadIdx.y + blockDim.y * blockIdx.y;
  //printf("%d %d\n",i, j);
  if( i > 0 \&\& j < N-1 )
    dstencil[i][j] += dprevstencil[i-1][j] + dprevstencil[i-1][j+1];
```

Stencil Computation(Original)

 Design and implement a stencil computation wherein in each iteration, cells compute their values using the neighboring ones, according to the following formula:

$$A[i][j] += A[i-1][j] + A[i-1][j+1]$$

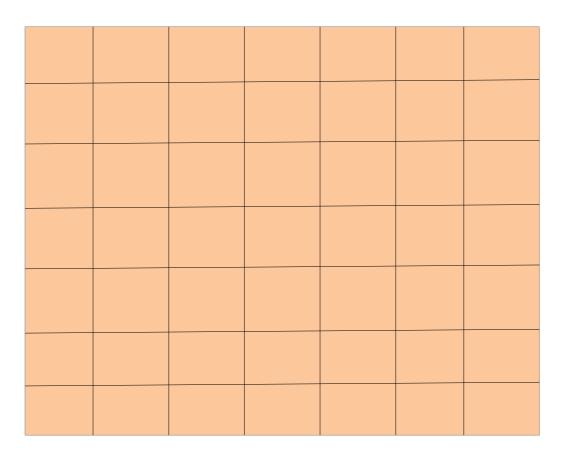
- The rows are in the range 0..N-1 and columns in 0..M-1
- The computation boundaries remains intact
- Initialize all the values in A to all 1s
- Your program should run for ten iterations

The updates should happen in-place inside the input matrix.

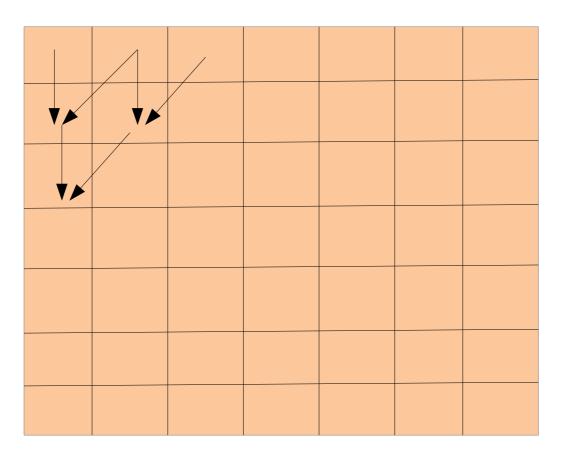
On CPU:

```
for(int itr=0;itr<10;itr++){
    for(int i=N-1;i>=1;i--){
        for(int j=0;j<N-1;j++){
            stencil[i][j] += stencil[i-1][j] + stencil[i-1][j+1];
        }
    }
}</pre>
```

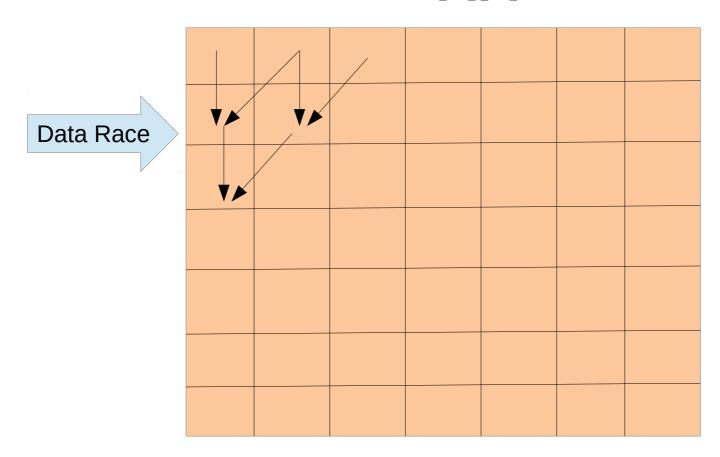
• The updates should happen in-place inside the input matrix



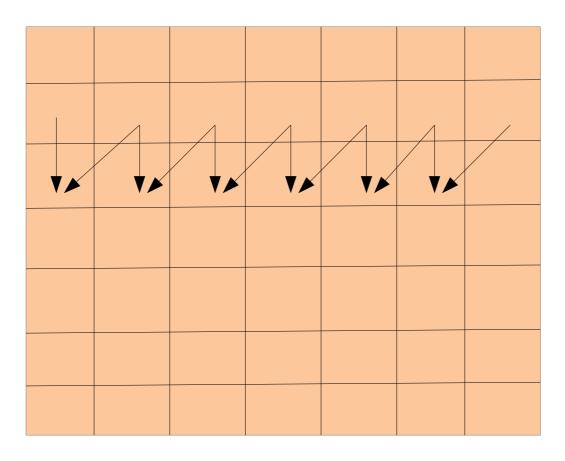
• The updates should happen in-place inside the input matrix



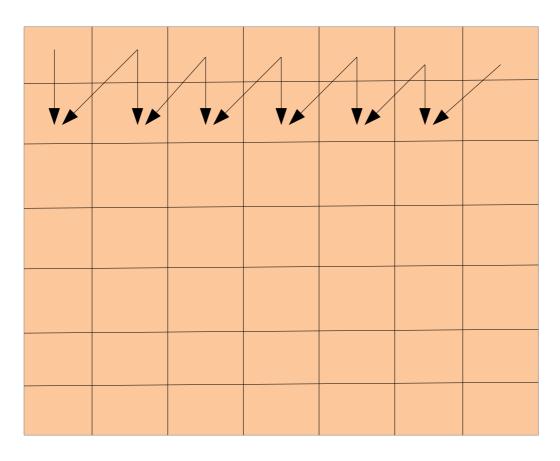
• The updates should happen in-place inside the input matrix



• The updates should happen in-place inside the input matrix



• The updates should happen in-place inside the input matrix



```
size_t size = N * N * sizeof(int);
    int itr;
    // Perform the computation
    for(itr=0;itr<10;itr++)
          cudaMemcpyToSymbol(dstencil, stencil, size, 0, cudaMemcpyDefault);
         for(int i=N-1;i>=1;i--)
            cudaMemcpyToSymbol(dstencil[i], stencil[i], N, 0,
cudaMemcpyDefault);
            sample <<<1, N>>> (N,i);
            cudaMemcpyFromSymbol(stencil[i], dstencil[i], N, 0,
cudaMemcpyDefault);
          cudaMemcpyFromSymbol(stencil, dstencil, size, 0,
cudaMemcpyDefault);
```

```
// N = 32, i = [1, N-1]
sample <<<1, N>>> (N,i);
 device int dstencil[N][N];
  _global___ void sample(int matrixsize, int i)
  int j = threadIdx.x + blockDim.x * blockIdx.x;
  //printf("%d %d\n",i, j);
  if( i > 0 \&\& j < N-1 )
    dstencil[i][i] += dstencil[i-1][j] + dstencil[i-1][j+1];
```