- 1. Load, Effort and Fulcrum
 - a. Using Diagrams and in your own words explain what you have learnt about in the context of a lever.
 - i. Load
 - ii. Effort
 - iii. Fulcrum
- 2. First class lever Scissors, see saw, crow bar, pliers, tongs, can opener
 - a. Research and find three 1st class levers
 - i. Label the pictures with Load, Effort and Fulcrum
 - ii. Explain what you know about a 1st class lever
 - b. Using Wacano build yourself a 1st class lever
- 3. Second Class lever Wheel barrow, Nutcrackers, hole punch, Wheel barrow, stapler, bottle opener, nail clipper, pliers, can opener, paper cutter(guillotine)
 - a. Research and find three 2nd class levers
 - i. Label the pictures with Load, Effort and Fulcrum
 - ii. Explain what you know about a 1st class lever
 - b. Using Wacano build yourself a 2nd class lever
- 4. Third class lever tweezers, tongs, fishing rod, Arm, Baseball bat, Broom, Doors, Mouse Trap, Diving board, Fork, Knife
 - a. Research and find three 2nd class levers
 - i. Label the pictures with Load, Effort and Fulcrum
 - ii. Explain what you know about a 1st class lever
 - b. Using Wacano build yourself a 2nd class lever
- 5. Simple lever
 - a. Explain in your own words what you understand a simple Lever to be
- 6. Simple linkage
 - a. Explain in your own words what makes a simple linkage
- 7. Levers and Linkages
 - a. Using Wacano build yourself a simple linkage, different from the ones above
 - b. Take a photo and explain the motions you see
- 8. Mechanical advantage (MA= load ÷ effort) for example (500N load ÷ 100N effort = 5 MA)
 - a. Using what you have learnt above work out the MA below
 - i.
 - ii.
 - iii.

- 9. Using your Wacano build yourself a 1st class lever and show the Force as 500N then explain showing all workings out what the effort would be.
 - i. Fulcrum is on the SECOND notch of the 5 pin con rod
 - ii. Fulcrum is on the THIRD notch
 - iii. Fulcrum is on the FORTH notch
- 10. Using Mechanical advantage can help you work out how to manoeuvre something heavy with very little effort, explain in your own words
 - i. Why
 - ii. What is the pay-off for this (clue: read about Velocity ratio)

11. Reverse motion

- a. Research a reverse motion linkage and explain using words and pictures what you have found
- b. Using Wacano build yourself a reverse linkage, take a picture and label
 - i. The fixed pivot point
 - ii. Any other pivot points
 - iii. Explain with arrows the input and output directions

12. Parallel motion

- a. Research a Parallel motion linkage and explain using words and pictures what you have found
- b. Using Wacano build yourself a Parallel motion linkage, take a picture and label
 - i. The different pivot points
 - ii. Explain with arrows the input and output directions

13. Bell crank

- a. Research a Bell crank linkage and explain using words and pictures what you have found
- b. Using Wacano build yourself a Bell crank linkage, take a picture and label
 - i. The fixed pivot point
 - ii. Any other pivot points
 - iii. Explain with arrows the input and output directions
- 14. Motions, there are four different types of Motion, with words and pictures rotary
 - a. Rotary
 - b. Reciprocating
 - c. Linear
 - d. Oscillating

- 15. We can join different levers together to change direction of motion, you have written about changing direction on a linear path. Now research and show in words and pictures how we can change rotary into;
 - a. Linear
 - b. Reciprocating
 - c. Oscillating

16. Crank, link and slider

- a. Research a Crank link and slider then explain using words and pictures what you have found
- b. Using Wacano build yourself a Crank link and slider, take a picture and label
 - i. All pivot points
 - ii. Show all motions
 - iii. Explain with arrows the input and output directions

17. Peg and pivot

- a. Research a Peg and Pivot (otherwise known as a peg and slot) then explain using words and pictures what you have found.
- b. Using Wacano build yourself a peg and pivot, take a picture and label
 - i. All pivot points
 - ii. Show all motions
 - iii. Explain with arrows the input and output directions

18. Treadle link

- a. Research a Treadle link then explain using words and pictures what you have found.
- b. Using Wacano build yourself a peg and pivot, take a picture and label
 - i. All pivot points
 - ii. Show all motions
 - iii. Explain with arrows the input and output directions

19. Spur Gears

a. Research Spur Gears and in your own words with diagrams explain what a gear is.

20. Gear train,

When you put 2 or more spur gears together you form a gear train. Research gear trains then

- a. Using Wacano build yourself a gear train, take a picture and label
 - i. Direction of the gears
 - ii. Driven and driver gears
 - iii. Speed of the different gears (faster, slower or the same speed as the driven)
- b. Explain what you mean by driver and driven

21. Gear ratio's

- a. The different speeds of the gears we call Gear ratio
 - i. What is another name for gear ratio?
 - ii. Show the formula we use to work out a gear ratio
- b. In the Wacano set look at the four different size spur gears
 - i. Choose two work out the gear ratios
 - ii. Choose another two and show the gear ratio
 - iii. Now put three or four together and show the gear ratio

22. Idle gear

Research idle gears and explain using words and pictures

- i. What they are
- ii. What they do
- iii. Where you will find them

23. Compound gear train

- a. Research compound gear trains and in your own words explain the
 - i. Difference between a compound gear train and a normal gear train
 - ii. Advantages and disadvantages if any between the two
- b. Using Wacano build yourself a compound gear train and show the pictures with labels

24. Rack and pinion

- a. Research and explain using words and pictures
 - i. Rack
 - ii. Pinion
 - iii. How they work together
 - iv. Where you would find one in the real world
- b. Using Wacano build a rack and pinion, take a picture and label it. (clue: you will need to use sliders guides)

25. Pulleys

- a. Research pulley systems and explain using words and pictures
 - i. Pulley wheel
 - ii. Pulley system
 - iii. Torque
- b. Show using the Wacano a simple pulley system
- c. Show reverse motion on the same pulley system