# Denis Pleshkov

Senior C++ Developer

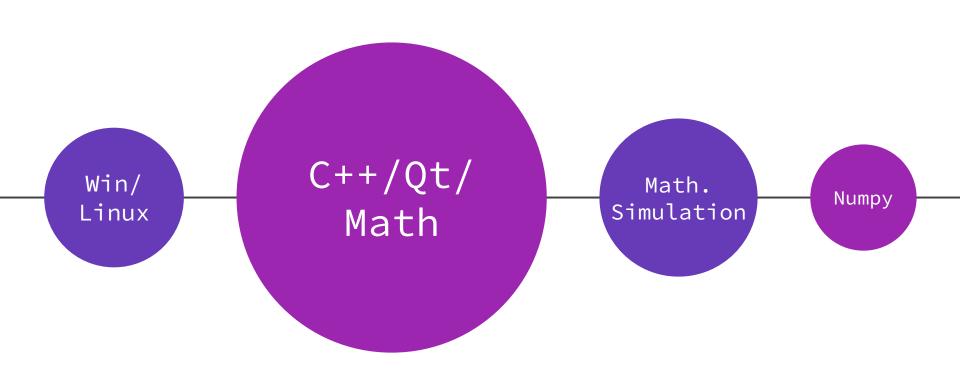
## **About me**

I do love designing and implementing a cool/complex things that could simplify mine job and others'. Negotiate and implement.

More than 10 years of production experience with C++/Qt.

Hobby: Linear Algebra, Linear ODE, FEA, Vibration Theory, Control Theory, bike riding, Rubik's cube, drum playing

## Knowledge



### Project name: NDA (Feb23-now)

- Software for dentist
- 3D computational geometry, quaternions, vector algebra
- in contact with QA and stakeholders: implement new features, bug fixing
- calculate 'optimal' plane and provide rich GUI to edit/show this plane
- CleanUpDlg, py-framework downloading/batch testing
- parsing log files
- unit testing, 3d rotation via keyboard
- Tech. stack: C++17/Qt/OpenGl, cmake,
   VisualStudio2020/ReSharper, MeshLab



## AD for OEM from Munich

### Project name: NDA (Aug21-Feb23)

- Low level functionality for data transfer between ECU's and HeadUnit (FrancaIDL/AutoSAR)
- Math.Library: Common Wrapper, Linear Algebra,
   Optimization, Kalman Filtration, Rectangles Intersection in 2D
- Found error in Intel AdLib
   (<a href="https://en.wikipedia.org/wiki/Hungarian algorithm">https://en.wikipedia.org/wiki/Hungarian algorithm</a>)
- Tech. stack: C++14/Python (Numpy, Jupyter),
   Bazel/FrancaIDL/Blaze/AdLib, vsCode



## **HMI for OEM from Stuttgart**

### Project name: NDA (Jan2016-Aug2021)

- Rich GUI for HMI/Navigation
- Instrument Cluster display (no simulator, no debug, only dlt-logs)
- Virtual keyboard
- Check translation files (Kotlin)
- Tech. stack: C++14/Qt/Qml/C#/cmake/dlt-viewer, Qt Creator



## TeamCenter's plugin

# Project name: Digital signature (Dec2013-Dec2015)

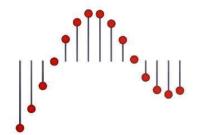
- Secured document flow with digital signature
- Plugin for <u>TeamCenter</u>
- Tech.stack: Java, JNI, C++, Qt, QtCreator/Eclipse
- 3rd-party Crypto-Lib

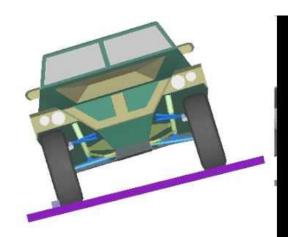


## Dynamic simulation

# Project name: Euler, roboTester (Sep2006-Dec2013)

- <a href="http://www.euler.ru">http://www.euler.ru</a> simulate vehicle dynamics
   <a href="https://www.youtube.com/user/EulerCAE/videos">https://www.youtube.com/user/EulerCAE/videos</a>
- improve simulation core
- interface to Simulink WorkShop
- Node remuneration for Sparse Matrix representation
- Craig-Bampton (<a href="https://en.wikipedia.org/wiki/Dynamic substructuring">https://en.wikipedia.org/wiki/Dynamic substructuring</a>)
- Export data from CAD (NX, SolidWorks, Autodesk Inventor)
- DSL for list comprehension
- Tools for create custom Application
- Tool for auto testing
- CI-pipeline via bat-files
- Fork boost::tuple, QDialog
- Tech.stack: C++03/11, Boost, Qt, VS/QtCreator



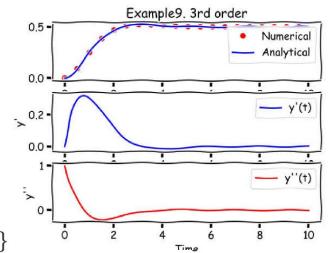


#### **FEA**

- Finite Element Analysis of an Inverse Problem Static/Dynamics
- Direct problem: find x from [K]{x}={P}
- Inverse problem: having [K] and x\_i, find {x} and P\_i
- same for dynamics problem
- Transient analysis
- Steady state response
- Sensitivity analysis

### **Control theory**

- Calculate transfer function by Adjacency Matrix
- Transient analysis for input with
   Dirac delta function



Due to [A] is lower-triangle matrix and  $\{d\}=\{0,0,\ldots,b\}$ 

$$egin{cases} L_n(\{a\},y) = b\delta(t) \ IC_0 \end{cases} \equiv egin{cases} L_n(\{a\},y) = \mathbf{0} \ IC_0 + [\mathbf{A}]^{-1}\{\mathbf{d}\} \end{cases} \equiv egin{cases} L_n(\{a\},y) = 0 \ IC_0 + \{0,0,\dots,b/a_0\}^{\intercal} \end{cases}$$

#### Courses & Certificates

- Math
  - Calculus (<u>1Functions</u>, <u>2Differentiation</u>, <u>3Integration</u>, <u>4Application</u>)
  - Mathematics for Engineers Spec.: Matrix Algebra for Engineers, Vector Calculus for Engineers, Differential Equations for Engineers
  - Linear Algebra from Elementary to Advanced Spec.: Linear Systems and Matrix Equations; Matrix Algebra Determinants & Eigenvectors; Linear Algebra:
     Orthogonality and Diagonalization
  - Mathematics for Machine Learning Spec. (Linear Algebra, Multivariate Calculus, PCA)
  - Linear Algebra for Data Science Using Python Spec.: Introduction to Linear Algebra and Python, Fundamental Linear Algebra Concepts with Python
  - Math for AI beginner part 1 Linear Algebra
  - o Statistic:
- DSP: Digital Signal Processing 1: Basic Concepts and Algorithms
- ML
- o Pandas: <u>Mastering Data Analysis with Pandas</u>
- o Regression: Linear Regression with NumPy and Python,
- JuliaLang: <u>Julia Scientific Programming</u>, <u>Julia for Beginners in Data Science</u>, <u>Decision Tree and Random Forest Classification</u>,
   <u>Linear Regression and Multiple Linear Regression</u>
- Rocket Science: Rigid Body Dynamics, Mastering Statics
- Computer Vision
  - Computer Vision Basics
  - o First Principles of Computer Vision Specialization: (in progress)Camera and Imaging
  - Object Localization with TensorFlow, Deep Learning with PyTorch
- CFD:
- Vibration:
- Matlab: Matlab Onramp,
- Wolfram:
- R: Introduction to R: Basic R syntax, Getting Started with R
- Kotlin/Java: Kotlin for Java Developers, Create an Android App with Kotlin, Kotlin For Beginners: Data Types and Conditional Expressions, Create Your First Multithreaded Application in Java
- Rust: Rust for Beginners: Building Target Proximity Game, Rust Secret Cipher CLI
- Python:
- SQL: Create a Python Application using MySQL
- Docker: Introduction to Docker: The Basics, Docker for absolute beginners, Containerization Using Docker, Docker Essentials & Building a Containerized Web Application, Introduction to Docker: Build Your Own Portfolio Site

#### Courses & Certificates-2

- C++: Writing Secure Code in C++ Specialization (<u>Introduction to C++</u>, <u>C++ Interacting with the World and Error Handling</u>)
- Youtube courses
  - o 3Blue1Brown: Lockdown Math, Essence of linear algebra, Essence of calculus, Differential equations
  - Math for Game Devs (part1)
  - [RU] <u>Магистерский курс C++ (МФТИ, 2022-2023)</u>, <u>Цикл лекций о великих математиках</u>, <u>матан|Борис Трушин, Линейные системы автоматического управления</u>
- Oct22, <u>C++ online test</u>
- 2022 AUTOSAR Classic MATLAB, Multithreading fundamentals in C++, C++17 Fundamentals Part I, Adaptive AUTOSAR Basics, C++ Code Refactoring for C++, Haskell fundamentals

### Which topics I'm into

- CLI for editing/simulation/analysis of model
- State Equation (Observability/Controllability)
- Transient analysis (Free response, Impulse response, nonZero IC
- Transfer function
- Parallel Sparse direct Solver
- Inverse problem: find parameter value delivering expected characteristics
- Sensitivity analysis
- Optimization problem
- Model reduction
- Krylov subspace projection
- Structure preserving reduced order
- Craig-Bampton analog

## **Contact**

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#### **Denis Pleshkov**

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