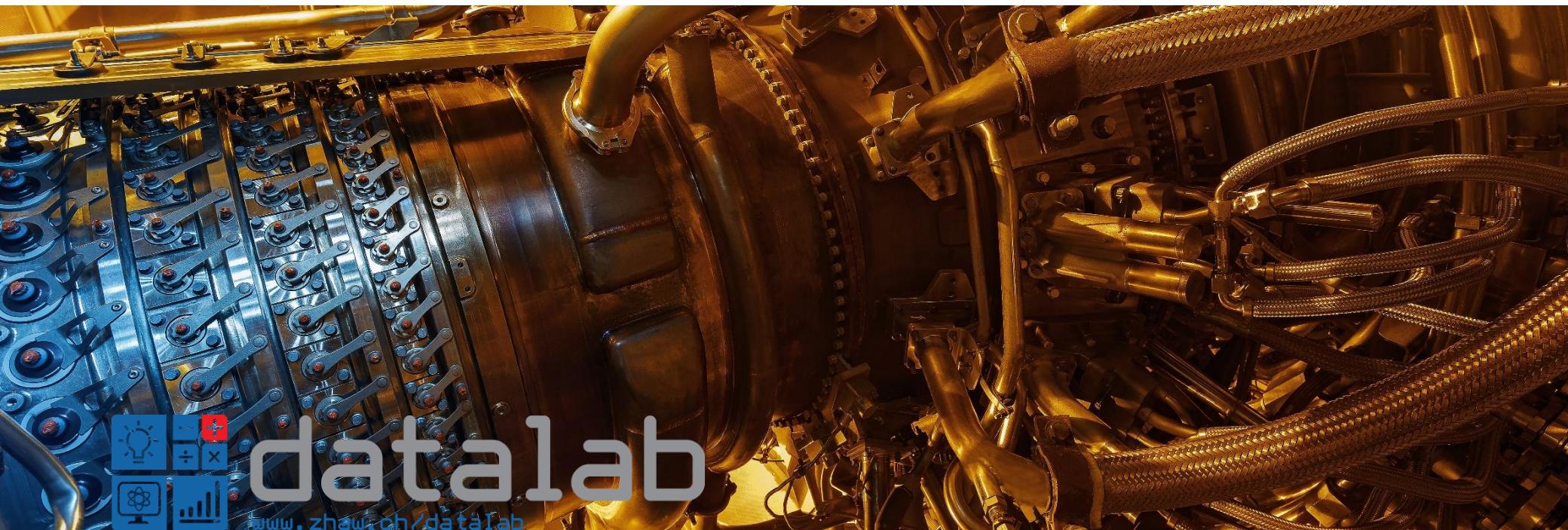


Deep Learning in an industrial context: predictive maintenance, inspection and beyond

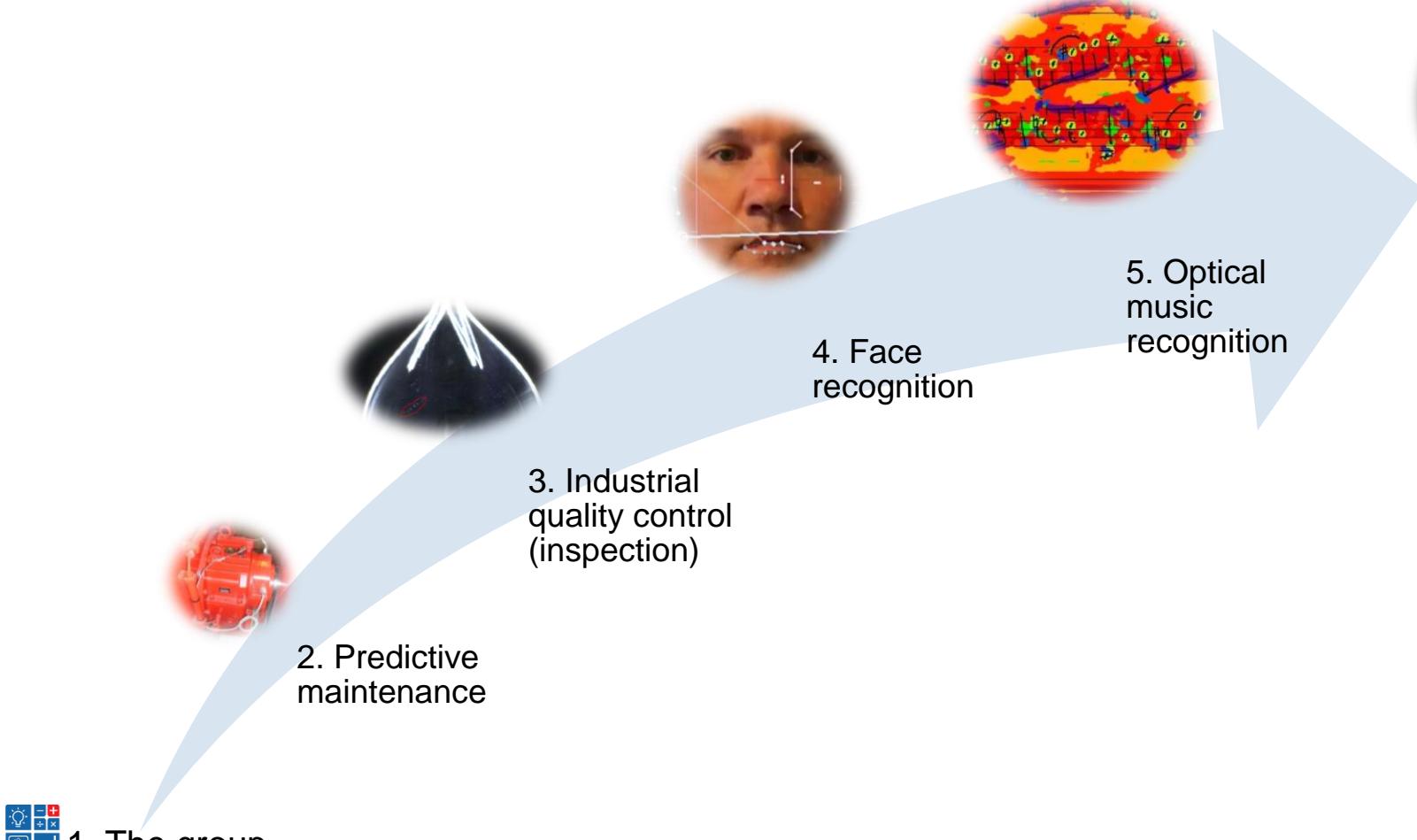
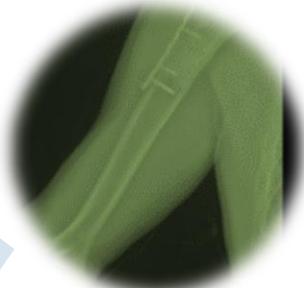
Data+Service Expert Group Predictive Maintenance, May 10, 2019



Thilo Stadelmann



Agenda



1. ZHAW Datalab: Est. 2013



Forerunner

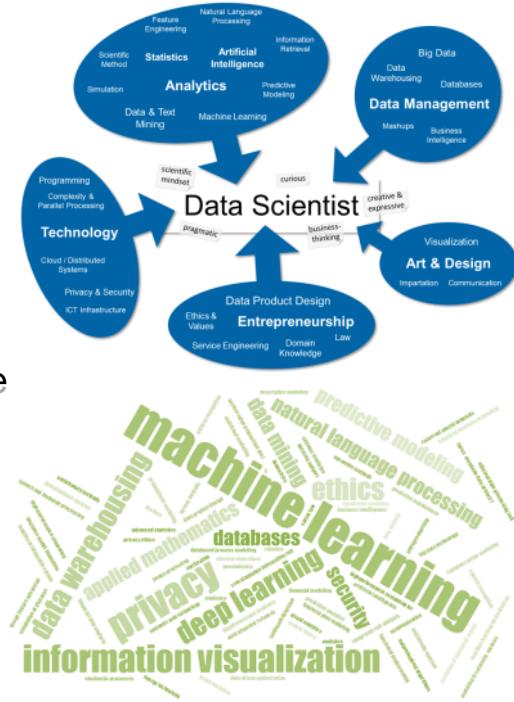
- **One of the first** interdisciplinary data science initiatives in Europe
- One of the first interdisciplinary centers at ZHAW

Foundation

- **People:** ca. 90 researchers from 7 institutes / 3 departments opted in
- Vision: Nationally leading and internationally recognized center of excellence
- Mission: Generate projects through critical mass and mutual relationships
- Competency: Data product design with structured and unstructured data

Success factors

- **Lean** organization and operation → geared towards projects
- Years of successful **pre-Datalab collaboration**



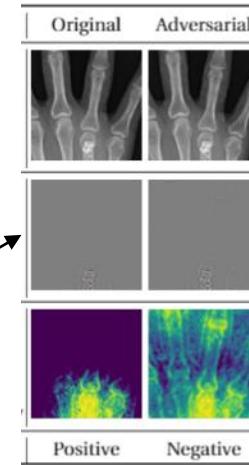
1. ML @ Information Engineering Group

Institute of Applied Information Technology, School of Engineering

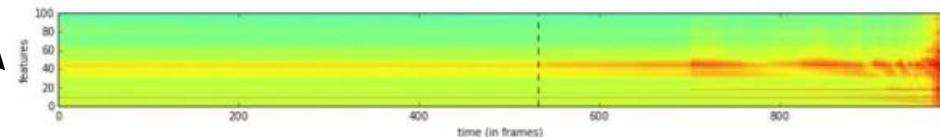


Machine learning-based Pattern Recognition

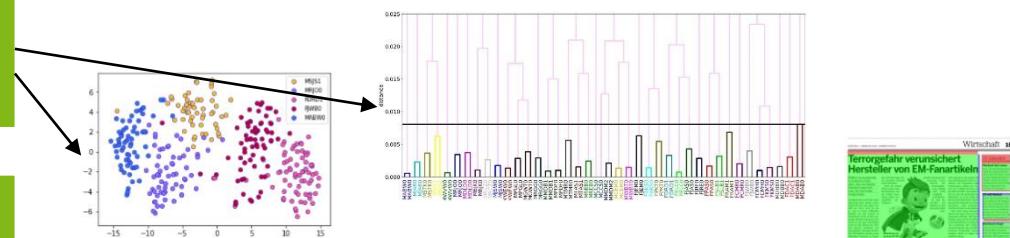
Robust Deep Learning



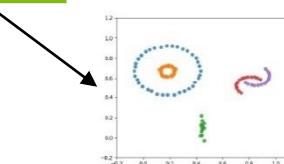
Voice Recognition



Document Analysis



Learning to Learn & Control



2. Data-driven Condition Monitoring

Situation: Maintaining big (rotating) machinery is expensive, defect is more expensive

Goal: Schedule maintenance shortly before defect is expected, not merely regularly

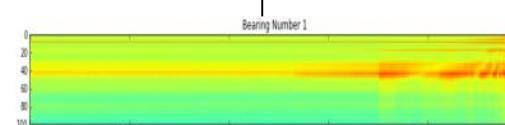
Challenge: Develop an approach that adapts to each new machine automatically

Solution: Use machine learning approaches for **anomaly detection** to learn the normal state of each machine and deviations of it purely from observed sensor signals; the approach combines classic and industry-proven features with e.g. deep learning auto-encoders

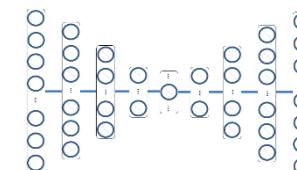
vibration sensors



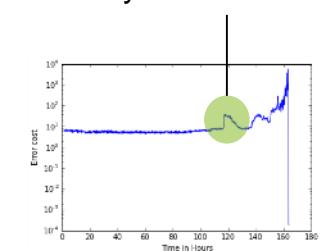
feature extraction



e.g., RNN autoencoder



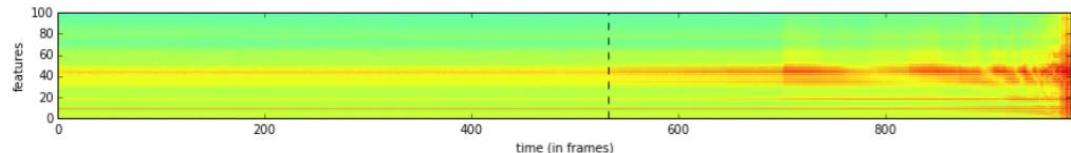
early detection of fault



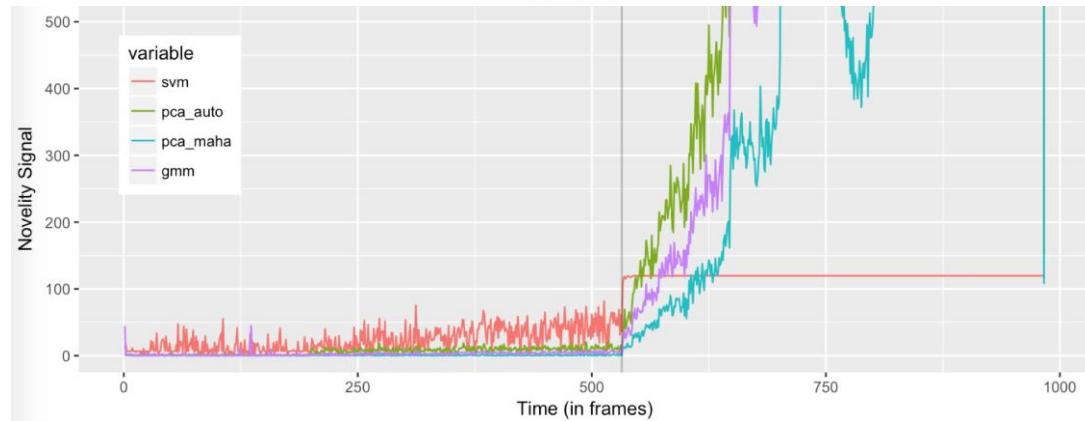
Stadelmann, Tolkachev, Sick, Stampfli & Dürr (2019): «*Beyond ImageNet—Deep Learning in Industrial Practice*». In: Braschler et al. (Ed.), «*Appl. Dat. Sci.*», Springer.

2. Data-driven Condition Monitoring: Results

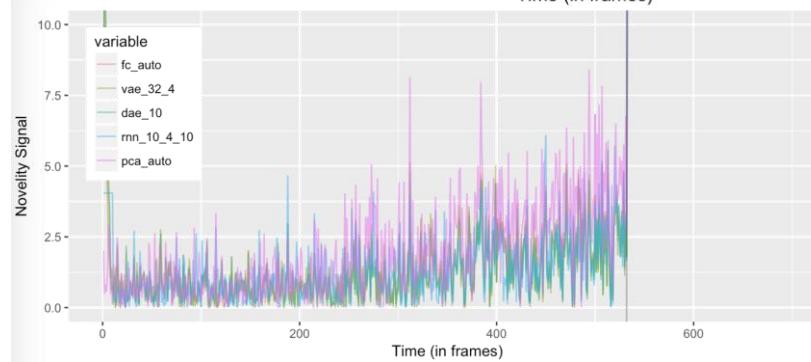
Signal:



Shallow learning methods:



Deep learning methods:



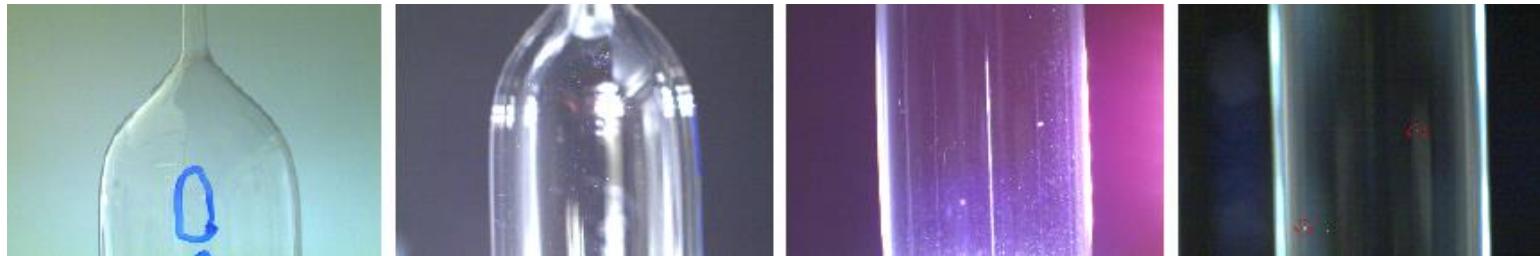
→ DL and standard methods detect the defect time; DL show **less novelty** where there is **still no defect**

3. Industrial quality control



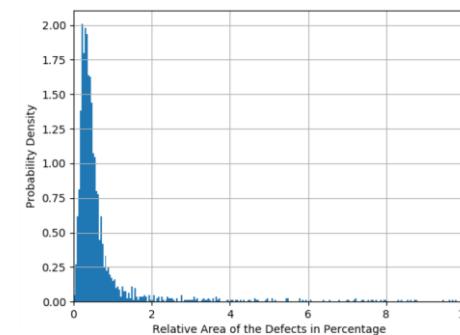
Task

- Reliably **sort out faulty balloon catheters** in image-based production quality control



Challenges

- Non-natural image source, class **imbalance**, optical conditions, **variation** in defect size & shape



Stadelmann, Amirian, Arabaci, Arnold, Duivesteijn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.

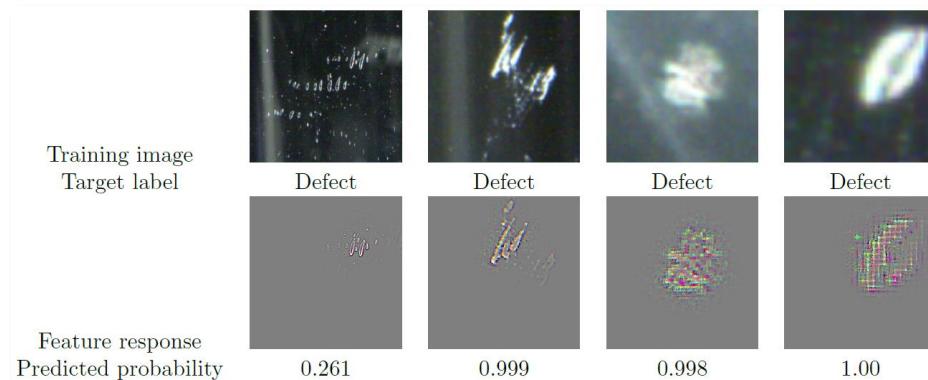
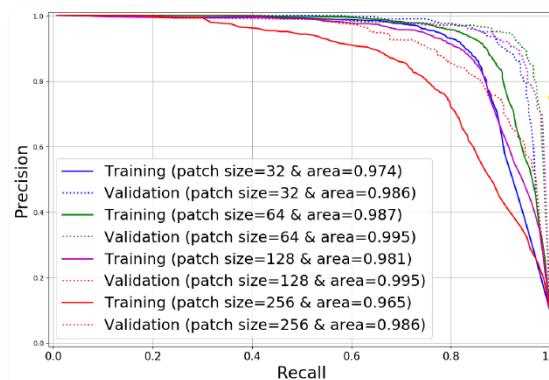
3. Industrial quality control – baseline results

Ingredients

- Weighted loss
- Defect cropping
- Careful customization



Interim results



3. Industrial quality control – recent results

- Human performance isn't flawless
- Tailoring pays off
- Data shortage may be outsmarted

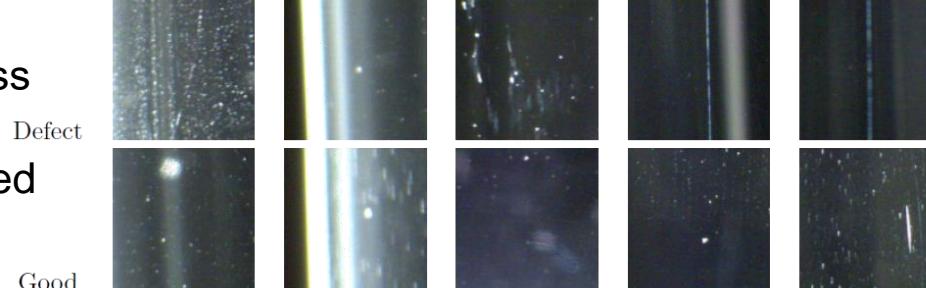
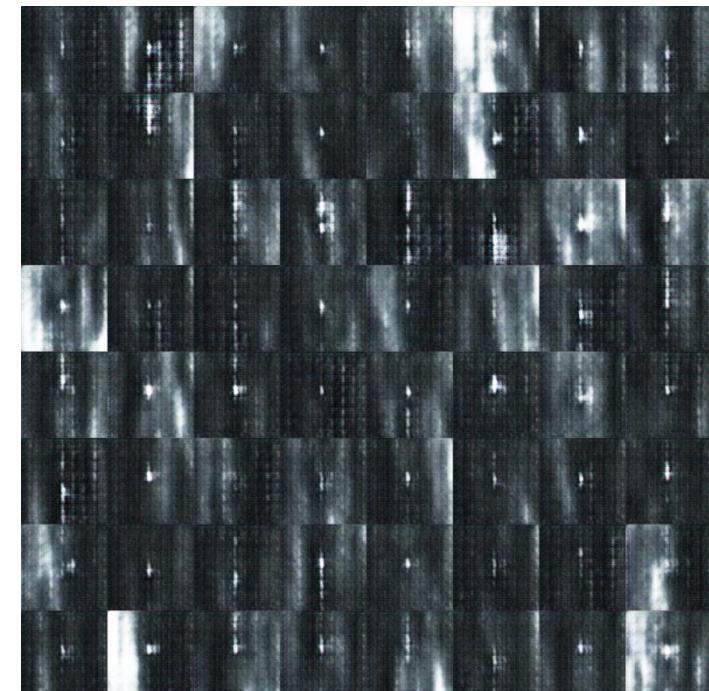
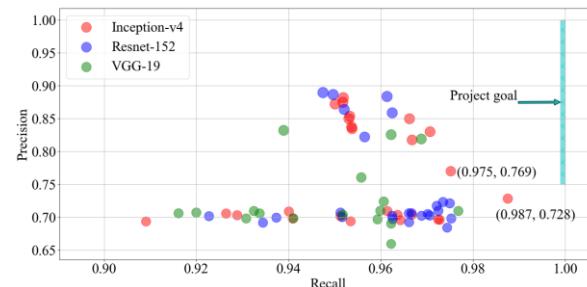
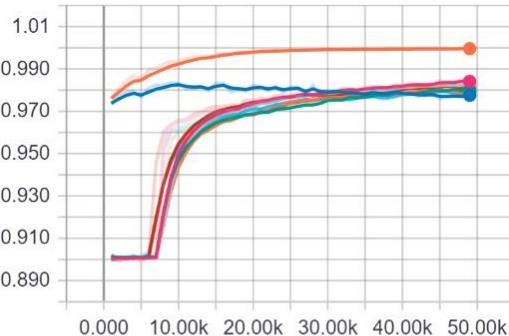


Figure 2: Samples of failure cases in classification. The shown *defect* samples in the table are not recognized as a defects, and the *good* images are misclassified as defects.

Accuracy



Name	Smoothed	Value	Step	Time	Relative
Batch_01\QualitAI_VGG19_Full_Pretrained\train	0.9996	0.9996	49.00k	Tue Jan 22, 02:32:13	8h 30m 56s
Batch_01\QualitAI_VGG19_Full_Pretrained\validation	0.9776	0.9783	49.00k	Tue Jan 22, 02:32:24	8h 30m 56s
Batch_02\QualitAI_VGG19_Full_Random\train	0.9841	0.9841	49.00k	Thu Jan 24, 19:28:02	10h 29m 2s
Batch_02\QualitAI_VGG19_Full_Random\validation	0.9798	0.9798	49.00k	Thu Jan 24, 19:28:14	10h 29m 2s
Batch_03\QualitAI_VGG19_Half\train	0.9827	0.9835	49.00k	Thu Jan 24, 13:01:47	4h 9m 12s
Batch_03\QualitAI_VGG19_Half\validation	0.9792	0.9798	49.00k	Thu Jan 24, 13:01:54	4h 9m 11s
Batch_04\QualitAI_VGG19_Quarter\train	0.9817	0.9823	49.00k	Thu Jan 24, 10:53:52	2h 17m 21s
Batch_04\QualitAI_VGG19_Quarter\validation	0.9791	0.9806	49.00k	Thu Jan 24, 10:53:56	2h 17m 21s

3. Industrial quality control – future work

Trying to overcome class imbalance and small training set sizes

Medical Image Analysis 54 (2019) 30–44

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Medical Image Analysis

journal homepage: www.elsevier.com/locate/media

f-AnoGAN: Fast unsupervised anomaly detection with generative adversarial networks

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 Wasserstein generative adversarial network
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Detecting expert labels in clinical imaging is difficult since exhaustive annotation is time-consuming. Furthermore, not all possibly relevant markers may be known and sufficiently well described a priori to even guide annotation. While supervised learning yields good results if expert labeled training data is available, the visual variability, and thus the vocabulary of findings, we can detect and exploit, is limited to the labeled training data. Here, we propose f-AnoGAN, a fast unsupervised learning approach based on a generative adversarial learning framework capable of detecting anomalous images and image segments that can serve as imaging biomarker candidates. We build a generative model of healthy training data, and propose and evaluate a fast mapping technique of new data to the latent space. The mapping is based on a U-Net encoder trained to map images to a common latent space. A corresponding decoder and two learning blocks of the trained model – comprising a discriminative feature residual error and an image reconstruction error. In the experiments on optical coherence tomography data, we compare the proposed method with two other approaches and show that f-AnoGAN outperforms them. f-AnoGAN also provides two alternative approaches and yields high anomaly detection accuracy. In addition, a visual Turing test with two retina experts showed that the generated images are indistinguishable from real normal retinal OCT images. The f-AnoGAN code is available at <https://github.com/Schlegl/f-AnoGAN>.

* Corresponding author.
E-mail address: georg.lang@meduniwien.ac.at (G. Lang).
^{a,b}URL: <https://github.com/Schlegl/f-AnoGAN> (T. Schlegl)
<http://www.cdi.meduniwien.ac.at> (G. Lang).

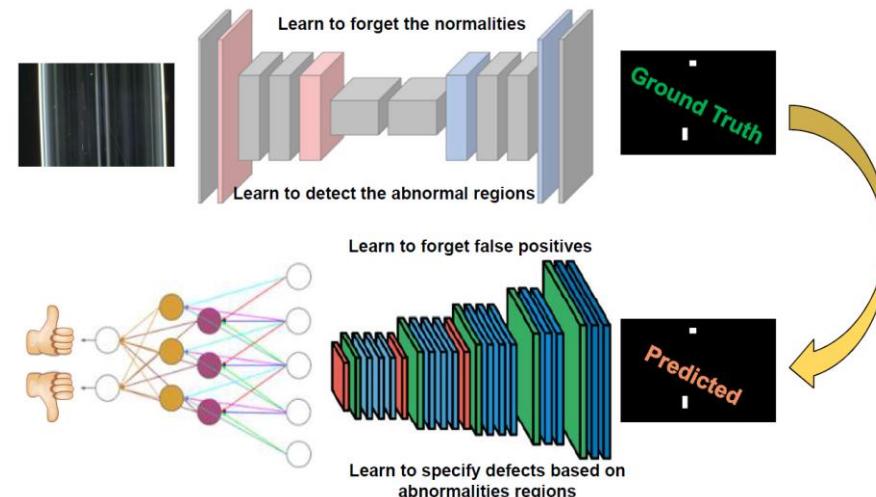
© 2019 Published by Elsevier B.V.

1. Introduction

The detection and localization of imaging biomarkers correlating with disease status is important for initial diagnosis, assessment of treatment response and follow-up examinations. Specifically, fundus photographs (Klein et al., 2001), microcalcification in X-ray mammography images for breast screening (Wang et al., 2014), or macular fluid in OCT scans of the retina (Schmidt-Erfurth et al., 2015) are examples of imaging biomarkers used in medical practice. Training of highly accurate deep learning methods for the identification of these biomarkers has shown promising results reaching clinical expert level accuracies, but requires expert annotated data (Koel et al., 2017; Estevez et al., 2017; Rajapakar et al., 2017; Grewal et al., 2017). In practice, expert annotations suffer from two limitations. First, their num-

ber is typically limited due to the time costly acquisition, specifically for difficult to identify findings for which machine learning approaches would be particularly desirable. Second, even if annotated training corpora are available, supervised learning is limited to already known markers. In some contexts, they exhibit high inter-class variability (e.g., fundus photographs of the retina (Walsh et al., 2015)) and we suspect that relevant markers exist beyond those already described. Here, we propose a fast anomaly detection technique trained on large-scale imaging data only comprising normal images. In the need of annotations, no learning targets during training. Only a few expert prior training, volume-level information is needed, namely to select imaging data for training that show solely normal appearance. We perform unsupervised learning on these data to train a generative model that captures a distribution of normal variability. Subsequently, we train an encoder to enable fast mapping of images to latent space¹ and thus facil-

¹ In the context of generative adversarial networks, the latent space is also termed z-space. We use both terms interchangeably.



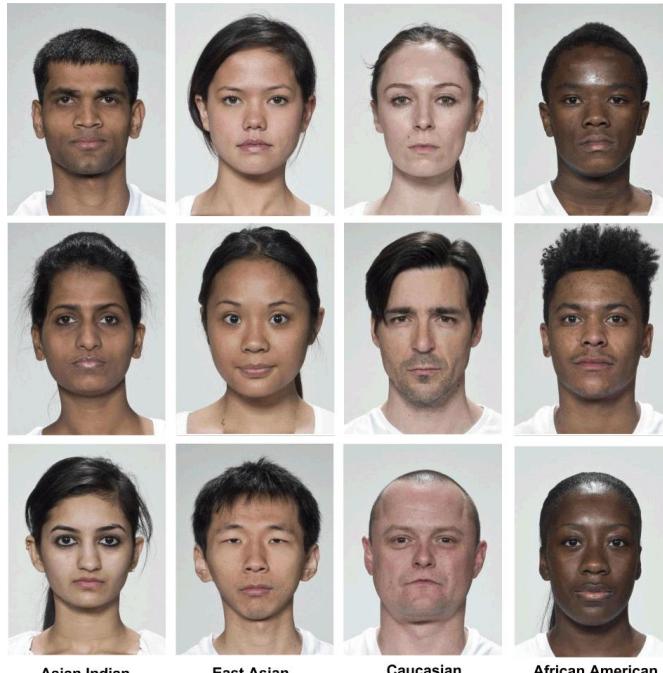
3. Face matching



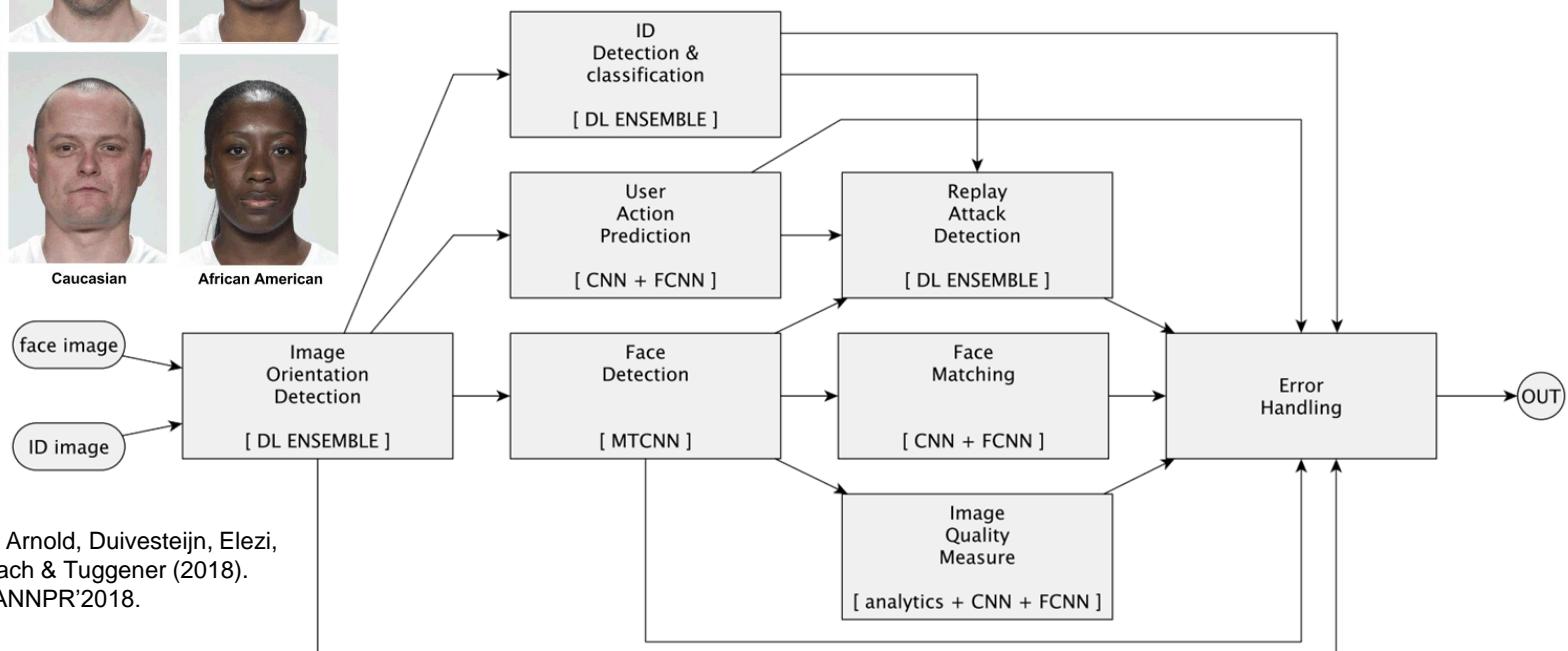
DEEPIMPACT

 Schweizerische Eidgenossenschaft
Confédération suisse
Confederazione Svizzera
Confederaziun svizra
Swiss Confederation
Innosuisse – Swiss Innovation Agency

3. Face matching – challenges & solutions



Asian Indian East Asian Caucasian African American



Stadelmann, Amirian, Arabaci, Arnold, Duivesteijn, Elezi,
Geiger, Lörwald, Meier, Rombach & Tuggener (2018).
«Deep Learning in the Wild». ANNPR'2018.

4. Music scanning

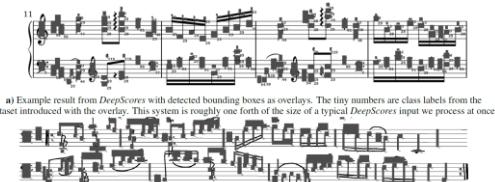
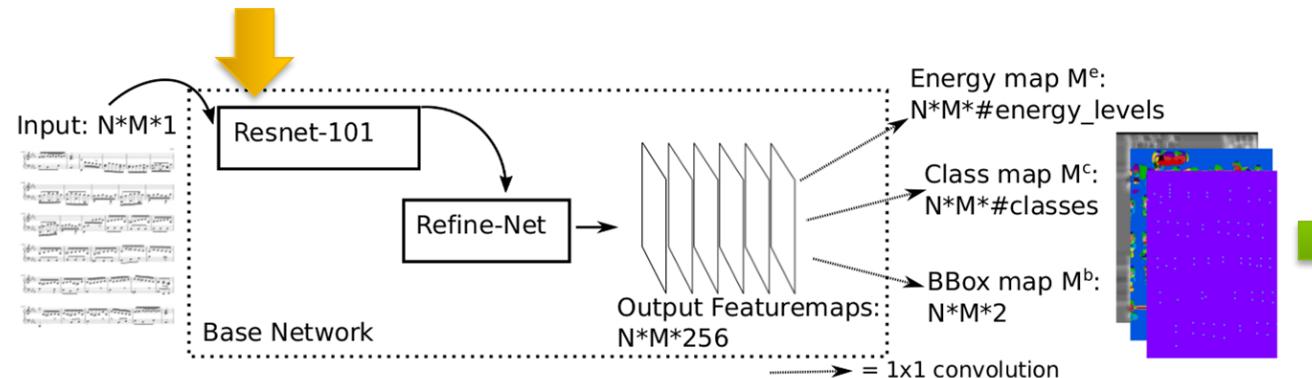
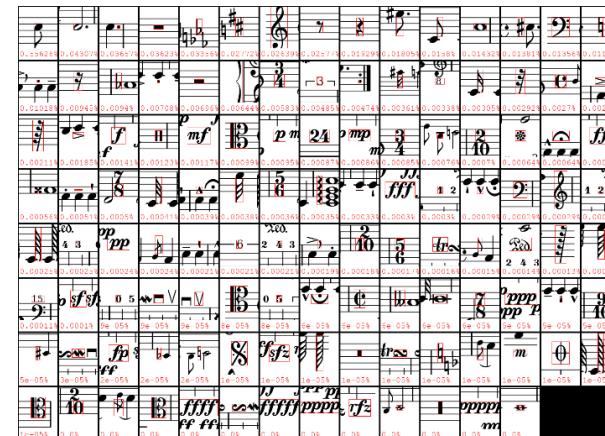
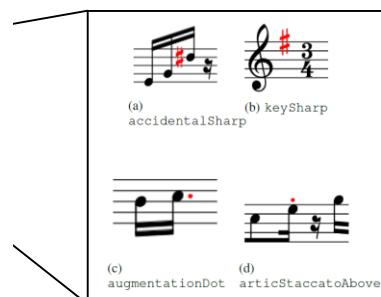


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```



4. Music scanning – challenges & solutions



a) Example result from DeepScores with detected bounding boxes as overlays. The tiny numbers are class labels from the dataset introduced with the overlay. This system is roughly one forth of the size of a typical DeepScores input we process at once.



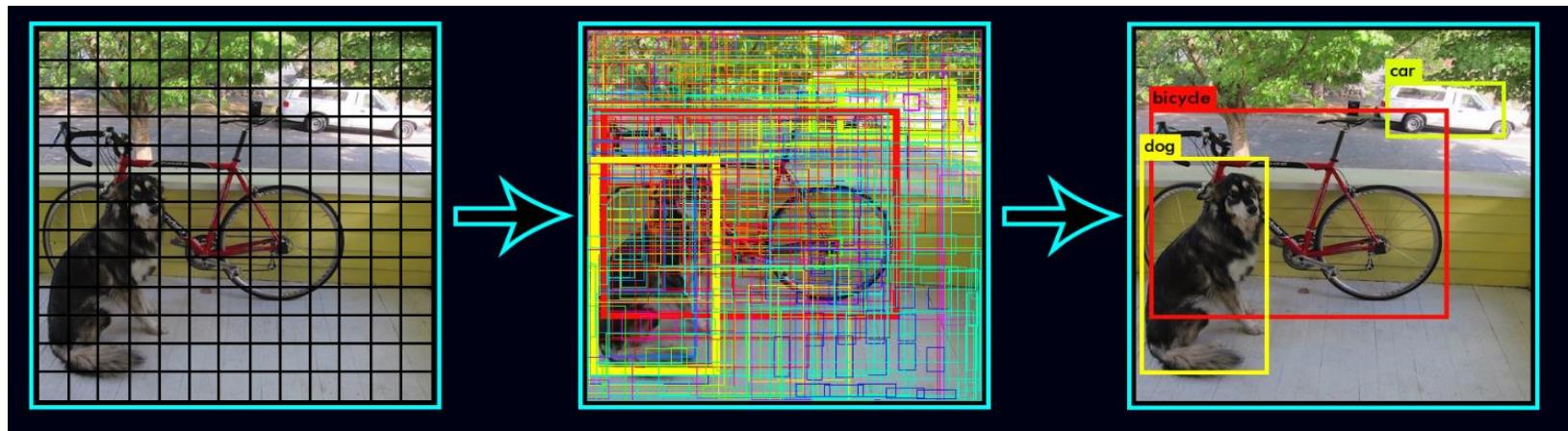
b) Example result from MuSCIMA++ with detected bounding boxes and class labels as overlays. This system is roughly one half of the size of a typical processed MuSCIMA++ input. The images are random picks amongst inputs with many symbols.

Tuggener, Elezi, Schmidhuber, Pelillo & Stadelmann (2018). «DeepScores – A Dataset for Segmentation, Detection and Classification of Tiny Objects». ICPR'2018.
Tuggener, Elezi, Schmidhuber & Stadelmann (2018). «Deep Watershed Detector for Music Object Recognition». ISMIR'2018.

4. Music scanning – methodology

OMR vs state of the art object detectors

YOLO/SSD-type detectors



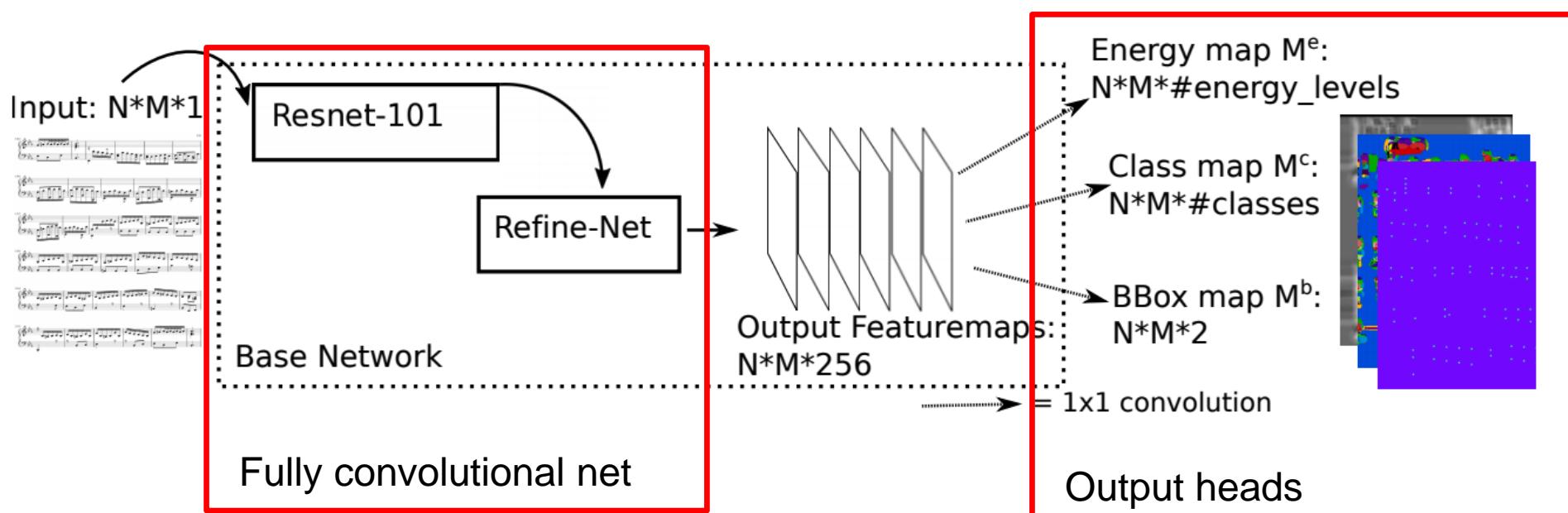
Source: <https://pjreddie.com/darknet/yolov2/> (11.09.2018)

R-CNN

- Two-step proposal and refinement scheme
- Very large amount of proposals at high resolution needed

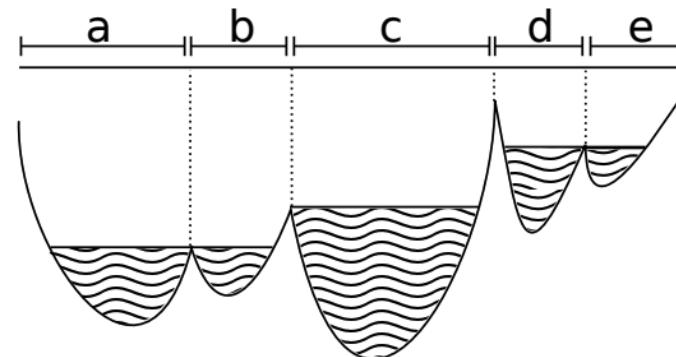
4. Music scanning – methodology (contd.)

The deep watershed detector



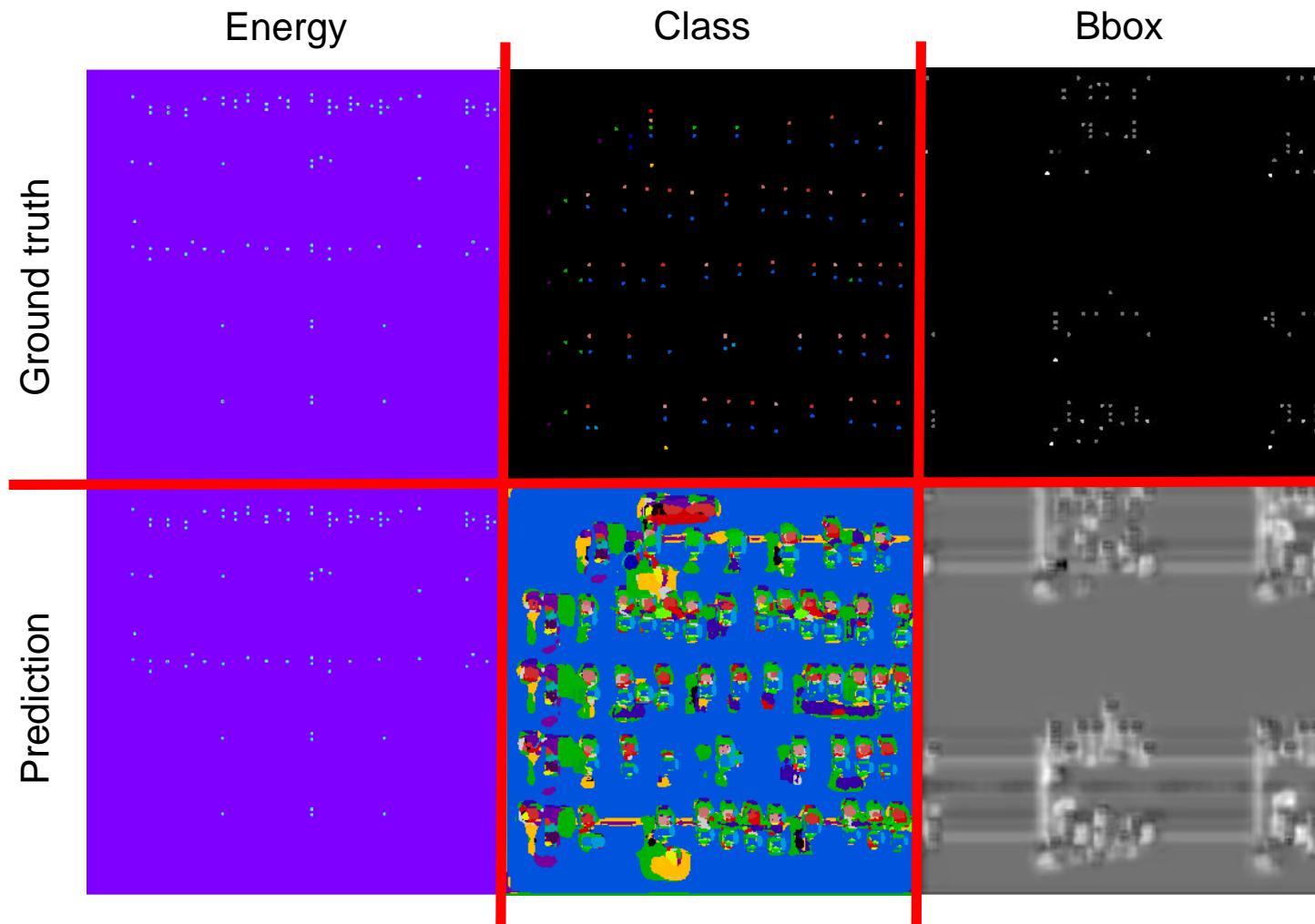
4. Music scanning – methodology (contd.)

The (deep) watershed transform



4. Music scanning – methodology (contd.)

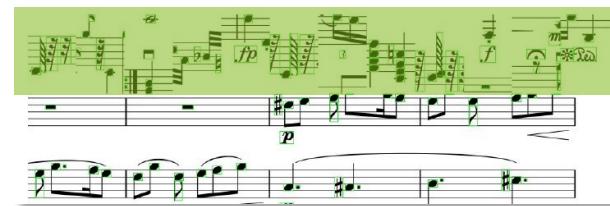
Output heads of the deep watershed detector



4. Music scanning – industrialization

Recent results on **class imbalance** and **robustness** challenges

1. Added sophisticated **data augmentation** in every page's margins



2. Put additional effort (and compute) into hyperparameter **tuning** and **longer training**
3. Trained also on scanned (more **real-worldish**) scores



→ Improved our **mAP** from 16% (on purely synthetic data) to 73% on more challenging real-world data set (additionally, using Pacha et al.'s evaluation method as a 2nd benchmark: from 24.8% to 47.5%)

Elezi, Tuggener, Pelillo & Stadelmann (2018). «DeepScores and Deep Watershed Detection: current state and open issues». WoRMS @ ISMIR'2018.
Pacha, Hajic, Calvo-Zaragoza (2018). «A Baseline for General Music Object Detection with Deep Learning». Appl. Sci. 2018, 8, 1488, MDPI.

5. Lessons learned

Data is key.

- Many real-world projects miss the required **quantity & quality** of data
→ even though «big data» is not needed
- **Class imbalance** needs careful dealing
→ special loss, resampling (also in unorthodox ways), exploitation of every possible learning signal
- **Unsupervised** methods need to be used creatively
- Users & label providers need to be **trained**

Robustness is important.

- **Training processes** can be tricky
→ give hints via a unique loss, proper preprocessing and pretraining



5. Lessons learned – model interpretability

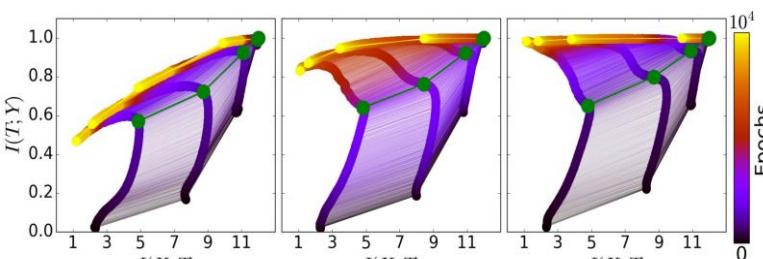
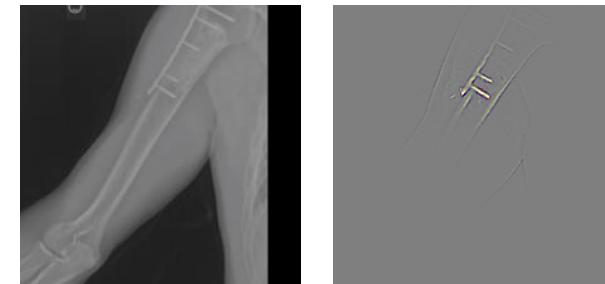
Interpretability is required.

- Helps the developer in «debugging», needed by the user to trust
→ visualizations of learned features, training process, learning curves etc. should be «always on»

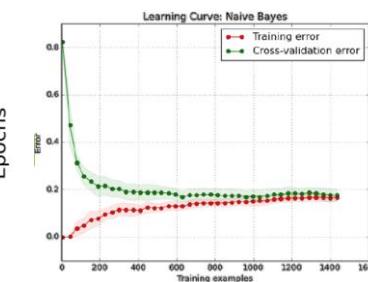
negative X-ray



positive X-ray



DNN training on the Information Plane



a learning curve



feature visualization

Stadelmann, Amirian, Arabaci, Arnold, Duivesteijn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.

Schwartz-Ziv & Tishby (2017). «Opening the Black Box of Deep Neural Networks via Information».

<https://distill.pub/2017/feature-visualization/>, <https://stanfordmlgroup.github.io/competitions/mura/>

Conclusions



- Important for DL in practice, and hence target of applied research:
sample efficiency, robustness, interpretability
- Future work will include:
Unsupervised and semi-supervised learning approaches
Novel **object detection** approaches **for many tiny objects**
Work on **explainable DL**



Swiss Alliance for
Data-Intensive Services



On me:

- Prof. AI/ML, scientific director ZHAW digital, board Data+Service
- thilo.stadelmann@zhaw.ch
- 058 934 72 08
- <https://stdm.github.io/>



Further contacts:

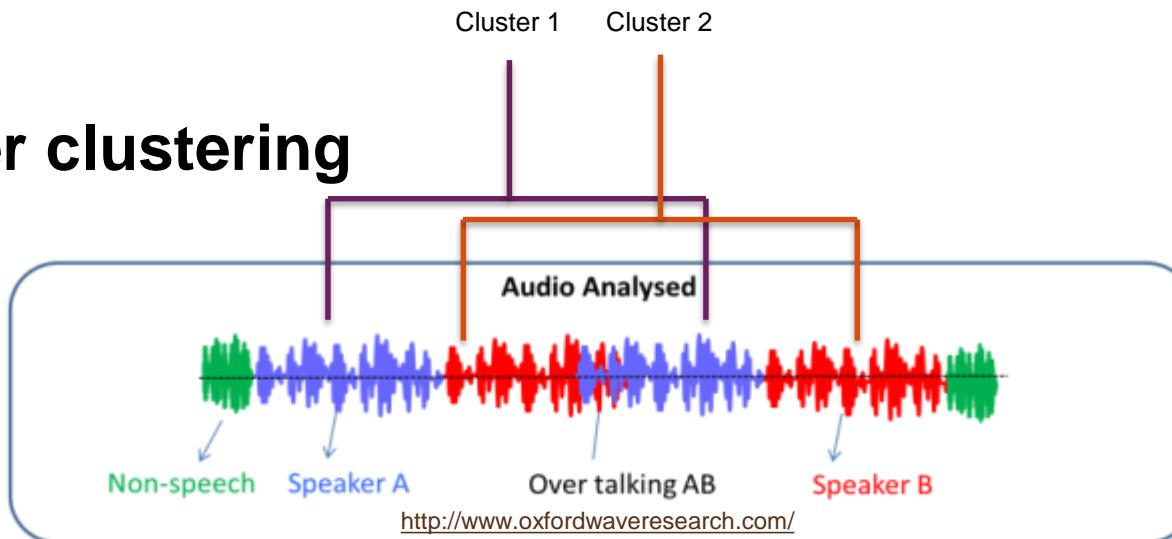
- Data+Service Alliance: www.data-service-alliance.ch
- Collaboration: datalab@zhaw.ch

→ Happy to answer questions & requests.



APPENDIX

6. Speaker clustering



For the 630 training utterances, GMMs with 32 mixtures are built a priori, then an identification experiment is run for the 630 test utterances. It yields a satisfactory 0.5% closed set identification error.

[34]. Evaluations typically concentrate on data sets built from broadcast news/shows and meeting recordings, where diarization error rates ranging from 8% to 24% are reported [28][34][45]. These results are confirmed by more recent

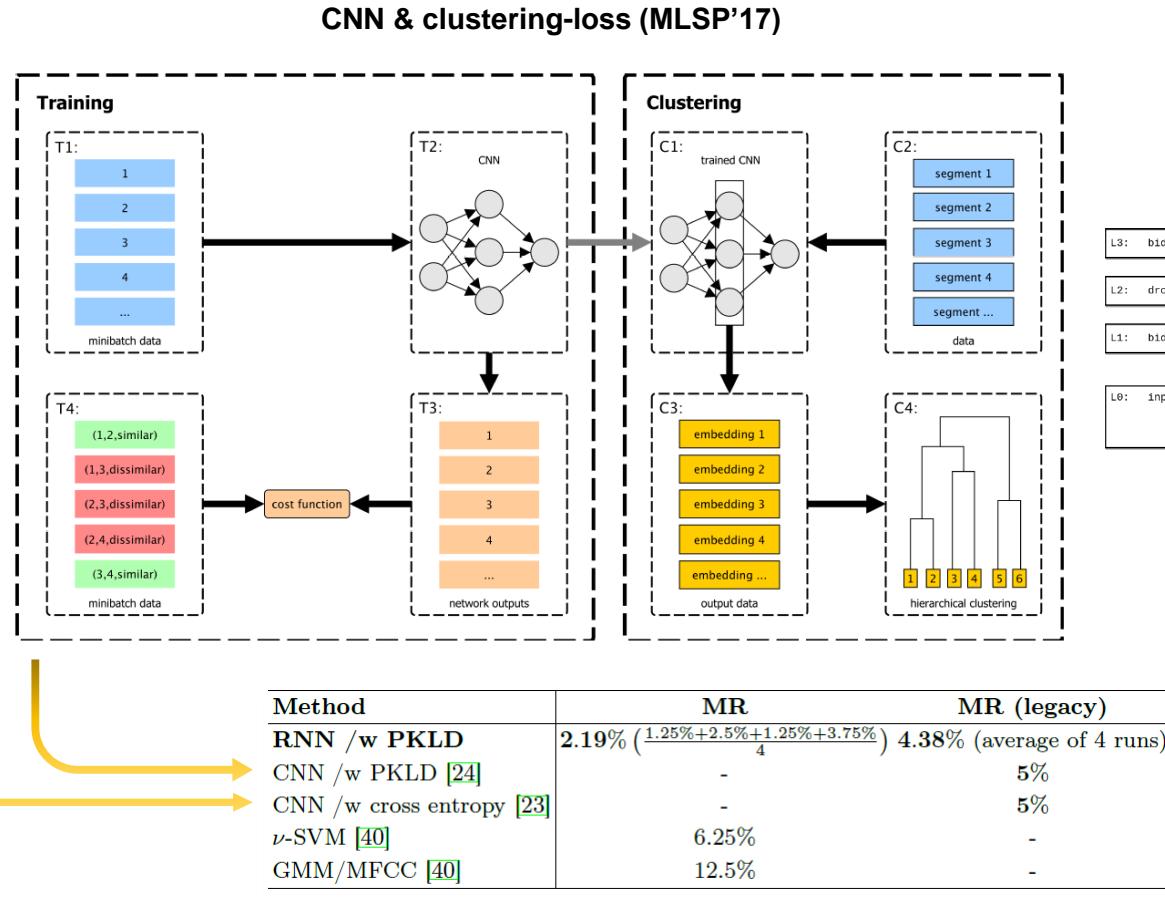
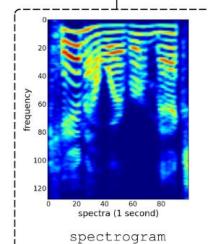
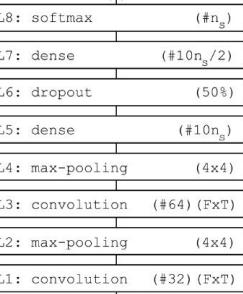
The hypothesis of this paper is: the techniques originally developed for speaker verification and identification are not suitable for speaker clustering, taking into account the escalated difficulty of the latter task. However, the processing chain for speaker clustering is quite large – there are many potential areas for improvement. The question is: *where* should improvements be made to improve the *final* result?

The interpretation of our results has shown that it is the stage of modeling that bears the highest potential: the inclusion of temporal context information among feature vectors is what is crucially missing there. Furthermore, the inclusion

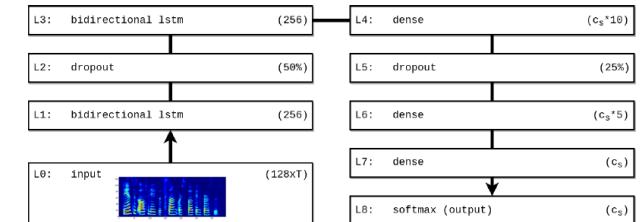
context vector. This corresponds to a syllable length of 130 ms and is found to best capture speaker specific sounds in informal listening experiments over a range of 32–496 ms (in intervals of 16 ms). Our context vector step is one orig-

6. Speaker clustering – exploiting time information

CNN (MLSP'16)
speaker labels



RNN & clustering-loss (ANNPR'18)

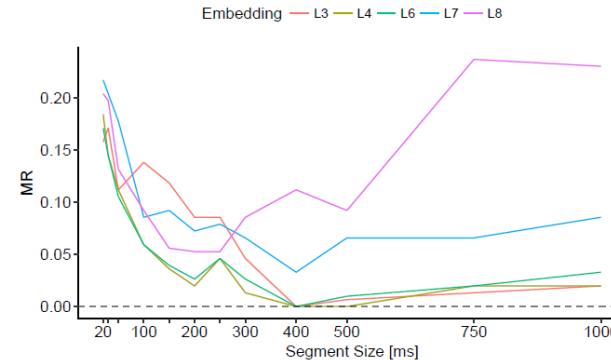
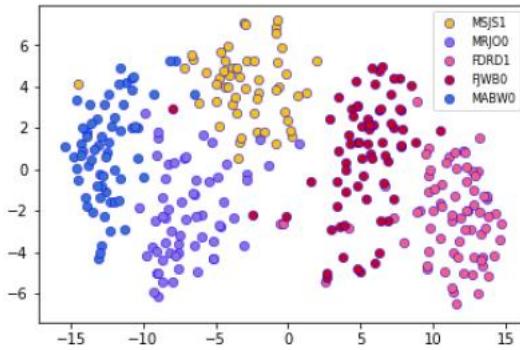


Lukic, Vogt, Dürr & Stadelmann (2016). «Speaker Identification and Clustering using Convolutional Neural Networks». MLSP'2016.

Lukic, Vogt, Dürr & Stadelmann (2017). «Learning Embeddings for Speaker Clustering based on Voice Equality». MLSP'2017.

Stadelmann, Glinski-Haefeli, Gerber & Dürr (2018). «Capturing Suprasegmental Features of a Voice with RNNs for Improved Speaker Clustering». ANNPR'2018.

6. Speaker clustering – learnings & future work



«Pure» voice modeling seems largely solved

- RNN **embeddings work well** (see t-SNE plot of single segments)
- RNN model robustly exhibits *the predicted «sweet spot» for the used time information*
- Speaker clustering on clean & reasonably long input works **an order of magnitude better** (as predicted)
- Additionally, using a smarter clustering algorithm on top of embeddings makes **clustering on TIMIT as good as identification** (see ICPR'18 paper on dominant sets)

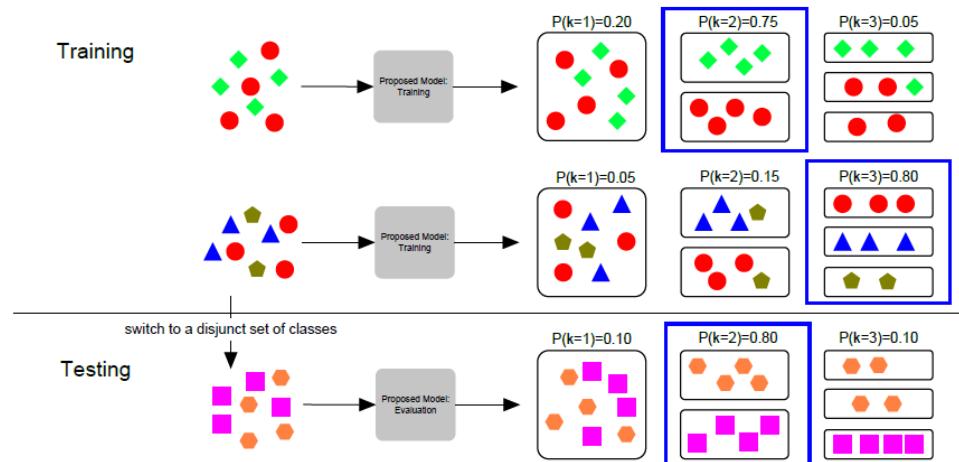
Future work

- Make models robust on **real-worldish data** (noise and more speakers/segments)
- Exploit findings for robust reliable **speaker diarization**
- **Learn** embeddings and the clustering algorithm **end to end**

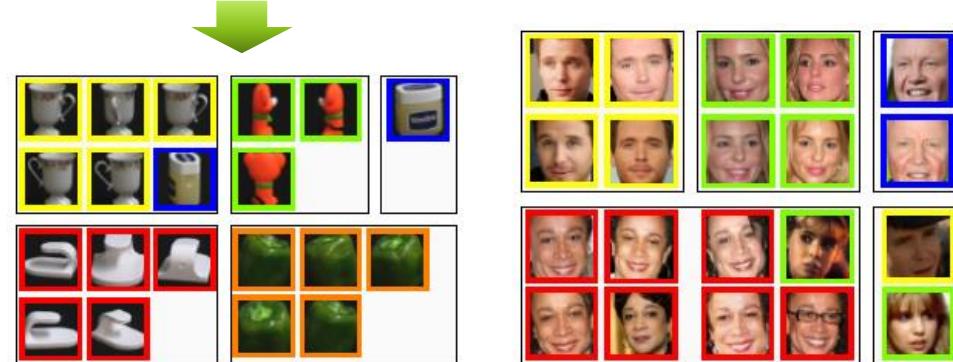
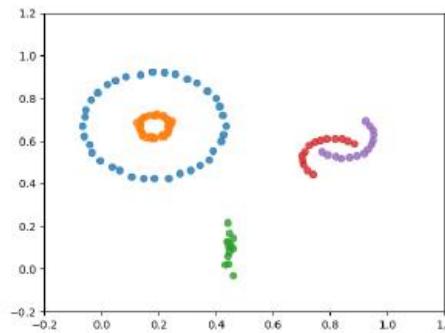
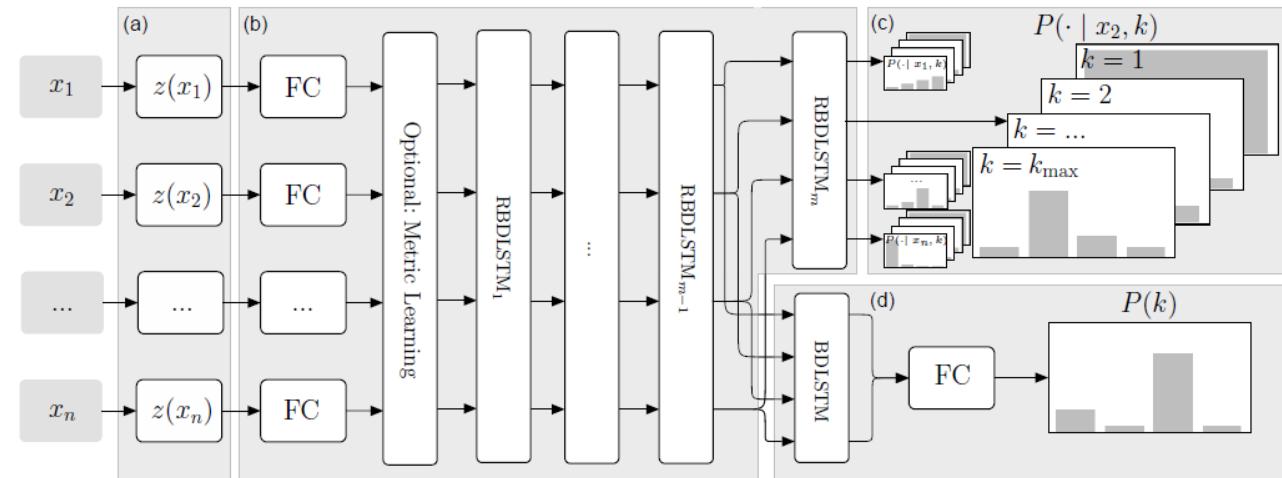
Hibray, Vascon, Stadelmann & Pelillo (2018). «Speaker Clustering Using Dominant Sets». ICPR'2018.

Meier, Elezi, Amirian, Dürr & Stadelmann (2018). «Learning Neural Models for End-to-End Clustering». ANNPR'2018.

7. Learning to cluster



7. Learning to cluster – architecture & examples



Meier, Elezi, Amirian, Dürr & Stadelmann (2018). «Learning Neural Models for End-to-End Clustering». ANNPR'2018.

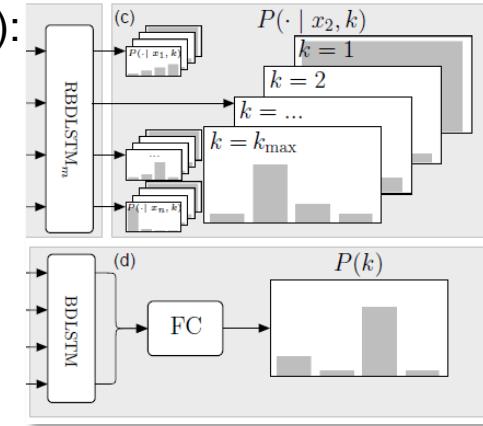
7. Learning to cluster – loss

Probability of two instances i, j being in the same cluster ℓ (of k clusters):

$$P_{ij}(k) = \sum_{\ell=1}^k P(\ell | x_i, k) P(\ell | x_j, k).$$

Probability of two instances i, j being in the same cluster ℓ **in general**:

$$P_{ij} = \sum_{k=1}^{k_{\max}} P(k) \sum_{\ell=1}^k P(\ell | x_i, k) P(\ell | x_j, k).$$



Cluster assignment loss (with $y_{ij} = 1$ *iff* the two instances are from the same cluster, 0 otherwise):

Weighted binary cross entropy (weights account for imbalance due to more dissimilar pairs)

$$L_{\text{ca}} = \frac{-2}{n(n-1)} \sum_{i < j} (\varphi_1 y_{ij} \log(P_{ij}) + \varphi_2 (1 - y_{ij}) \log(1 - P_{ij}))$$

Number of cluster loss:

Categorical cross entropy

$$L_{\text{cc}} = -\log(P(k))$$

Total loss:

$$L_{\text{tot}} = L_{\text{cc}} + \lambda L_{\text{ca}}$$



Swiss Alliance for
Data-Intensive Services



The Swiss Alliance for Data-Intensive Services provides a significant contribution to **make Switzerland an internationally recognized hub for data-driven value creation.**

In doing so, we rely on **cooperation in an interdisciplinary expert network** of innovative **companies** and **universities** to combine knowledge from different fields into marketable products and services.

Industrial Members



Academic Members

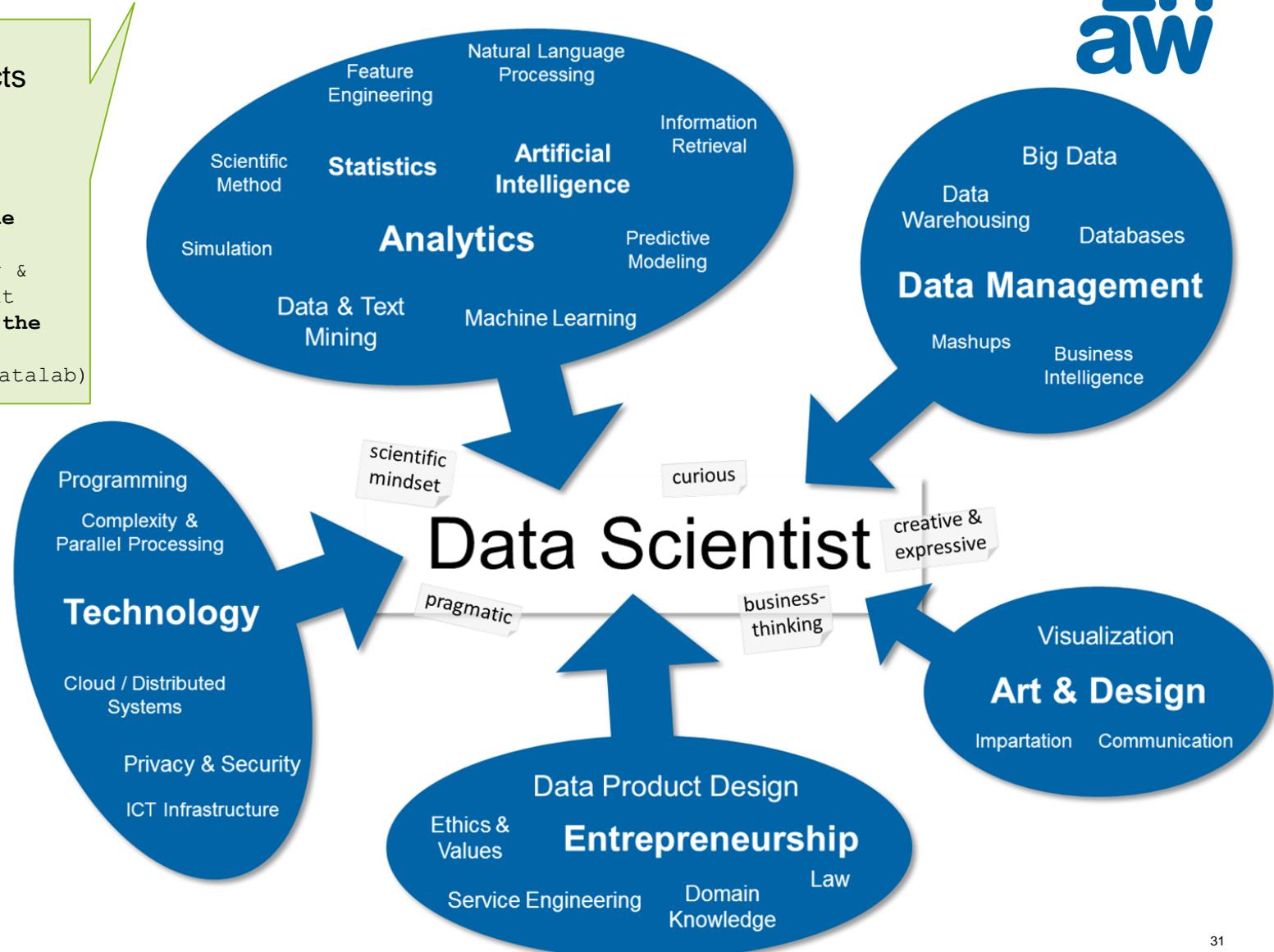


National & International Partners

What is Data Science?

Enables Data Products
 ➔ Applied Science
 ➔ Interdisciplinary

Data Science := "Unique blend of skills from analytics, engineering & communication aiming at generating value from the data itself [...]"
 (ZHAW Datalab)



Overview

Partners

Who are we

- ARGUS der Presse AG**
 - Switzerland's leading media monitoring and information provider
 - Experience of more than 100 years

- ZHAW Datalab**
 - Interdisciplinary research group at Zurich University of Applied Sciences
 - Combining the knowledge of different fields related to machine learning

The Project

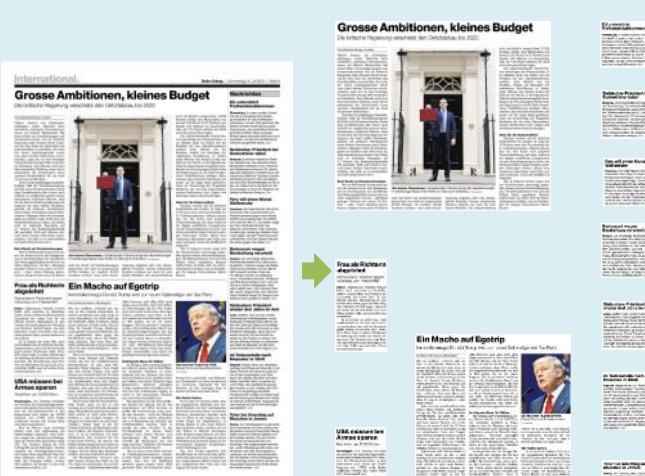
What do we do

Goal

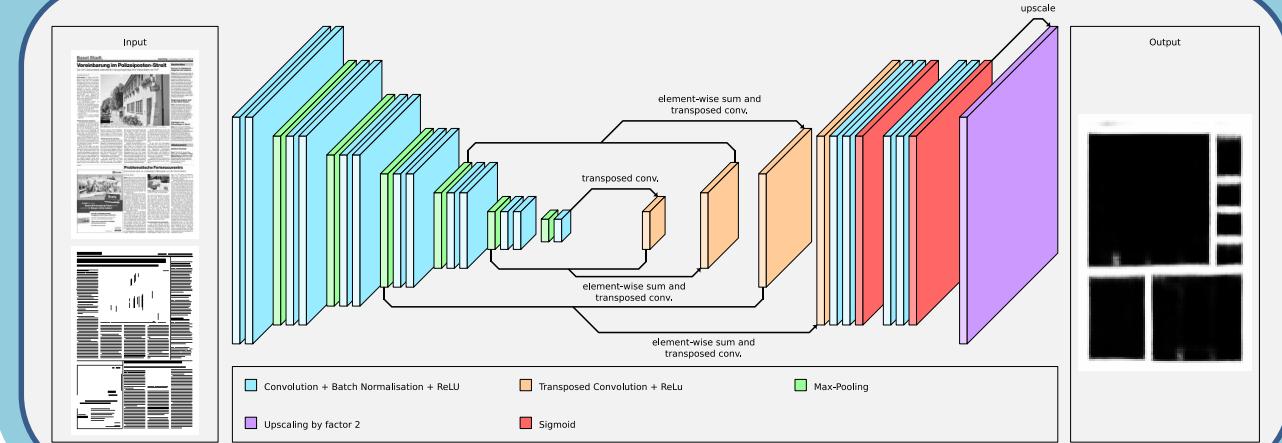
- Real Time Print Media Monitoring
 - Extraction of relevant articles from newspaper pages
 - Delivering articles to customers

Problem

- Fully automated article segmentation
- Identification of article elements (e.g. title, subtitle, etc.)

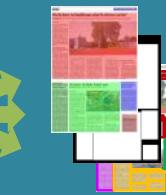


Most Successful Approach [3]



Combination

Combination of rules, visual and textual features



Result

References

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- [2] T. Mikolov, K. Chen, G. Corrado, and J. Dean. Efficient Estimation of Word Representations in Vector Space. In Proceedings of Workshop at ICLR, 2013.
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