

GETTING STARTED WITH ROBOTICS

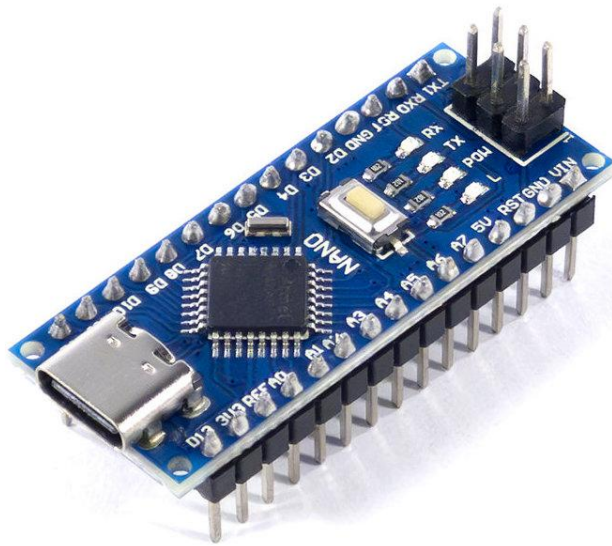


Course Information and Resources

Board Architecture and Overview

Introduction

Welcome to Getting Started with Robotics — your entry into the world of robotics and embedded systems. This beginner-focused course uses the popular Arduino Nano board, known for its compact size, affordability, and versatility. You'll learn to interface it with sensors, LEDs, displays, and motors through practical experiments.



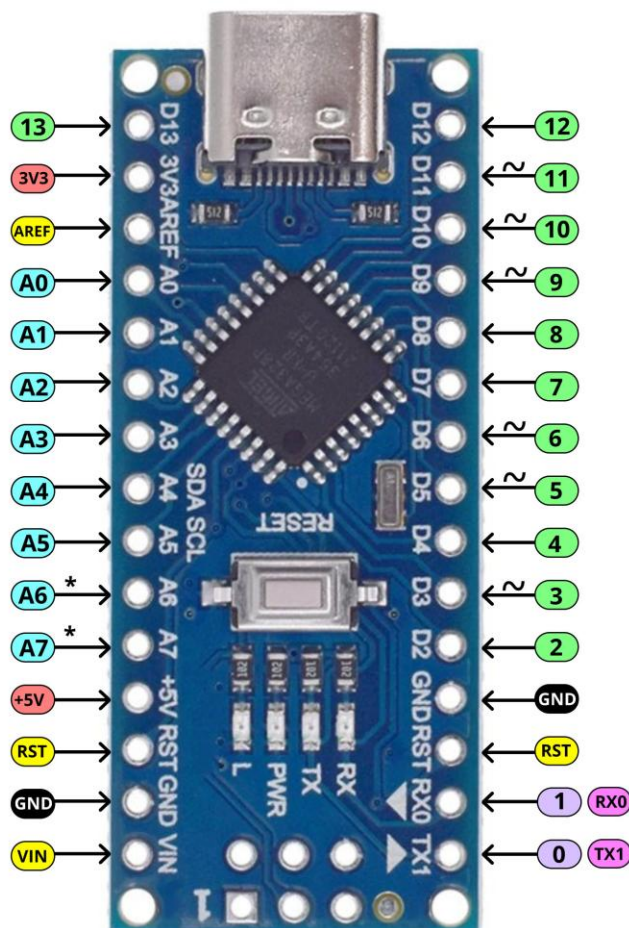
Arduino Nano Pin Functions

The image shows the Arduino Nano microcontroller with all digital and analog pins labeled. Programs are uploaded via USB, and the board automatically begins execution immediately after transfer.

important !



Important to know: The Arduino Nano has 14 digital pins (D0–D13) that can be used as input or output. Six of them (D3, D5, D6, D9, D10, D11) can also do PWM. It also has 8 analog input pins (A0–A7) for 0–5V signals and (A0–A5) can also be used as digital input or output.



| PIN | DIGITAL | | | ANALOG INPUT |
|-----|--------------------|-----|-----|-----------------|
| | IN | OUT | PWM | |
| 12 | ✓ | ✓ | | |
| 11 | ✓ | ✓ | ~ | |
| 10 | ✓ | ✓ | ~ | |
| 9 | ✓ | ✓ | ~ | |
| 8 | ✓ | ✓ | | |
| 7 | ✓ | ✓ | | |
| 6 | ✓ | ✓ | ~ | |
| 5 | ✓ | ✓ | ~ | |
| 4 | ✓ | ✓ | | |
| 3 | ✓ | ✓ | ~ | |
| 2 | ✓ | ✓ | | |
| 1 | DO NOT USE FOR I/O | | | |
| 0 | DO NOT USE FOR I/O | | | |
| A7 | | | | ✓ |
| A6 | | | | ✓ |
| A5 | ✓ | ✓ | | ✓ |
| A4 | ✓ | ✓ | | ✓ |
| A3 | ✓ | ✓ | | ✓ |
| A2 | ✓ | ✓ | | ✓ |
| A1 | ✓ | ✓ | | ✓ |
| A0 | ✓ | ✓ | | ✓ |

What is a Digital Input or Output Pin?

Digital input reads ON/OFF signals (like a button), and digital output sends ON/OFF signals (like turning an LED on or off). You can configure each pin in your code depending on what task it needs to perform. This simple binary control forms the foundation of most basic Arduino projects.

What is an Analog Input Pin?

Analog input pins on the Arduino Nano (A0 to A7) read varying voltage levels between 0 and 5 volts. They convert these voltages into numbers (0–1023) using a built-in ADC (Analog-to-Digital Converter). This lets you measure sensors like temperature, light, or potentiometers that output variable signals.

Pin Assignments for the Getting Started with Robotics Board

For now, this isn't very important, but once we start programming, this information will be essential to control components, sensors, motors, and displays.

| DIGITAL OUT | |
|-------------|----|
| LED GREEN | A4 |
| LED YELLOW | A5 |
| LED RED | 13 |
| BUZZER | 9 |
| WS2812B LED | 8 |

| DIGITAL IN | |
|------------|----|
| SWITCH 1 | 6 |
| SWITCH 2 | 7 |
| PIR | A2 |

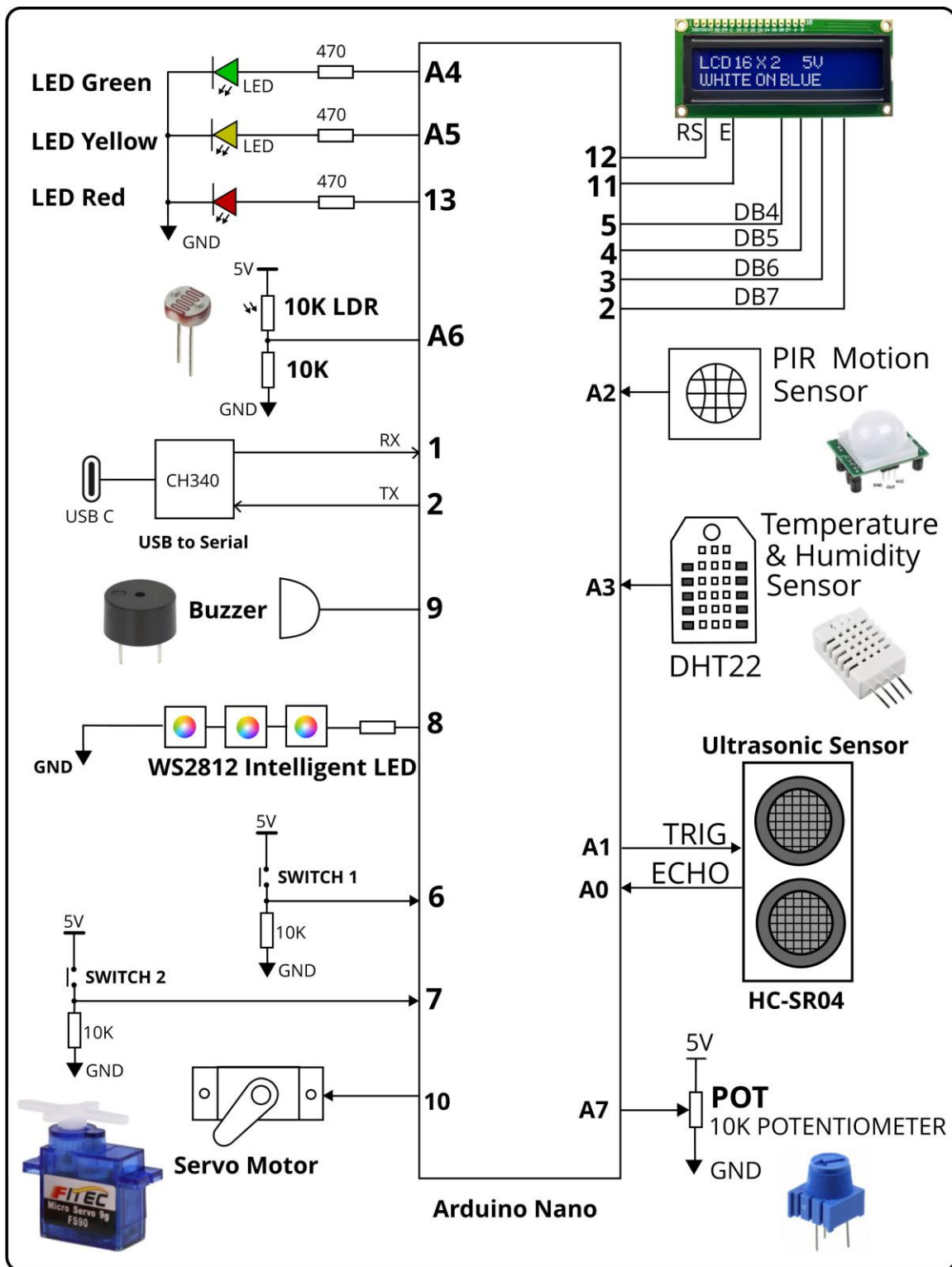
| HC-SR04 (DISTANCE) | |
|--------------------|----|
| TRIG | A1 |
| ECHO | A0 |

| MOTOR | |
|-------------|----|
| SERVO MOTOR | 10 |

| ANALOG IN | |
|-----------|----|
| POT | A7 |
| LDR | A6 |

| LCD DISPLAY | |
|-------------|----|
| RS | 12 |
| E | 11 |
| DB4 | 5 |
| DB5 | 4 |
| DB6 | 3 |
| DB7 | 2 |

| TEMP & HUM | |
|------------|----|
| DHT22 | A3 |



Power Requirements

During this course, the Mainboard is powered via the USB-C port. Alternative power options are available and will be covered in the Advanced Course.

Abbreviations and Terms

| | |
|----------------|---|
| LED | Light Emitting Diode |
| LDR | Light Dependent Resistor |
| USB | Universal Serial Bus |
| LCD | Liquid Crystal Display |
| PIR | Passive Infrared Sensor (Detect Movement) |
| POT | Potentiometer (Variable Resistor) |
| DHT22 | Temperature and Humidity Sensor |
| HC-SR04 | Ultrasonic Distance Sensor |
| WS2812B | A smart RGB LED with a built-in controller |
| PWM | Puls Width Modulation Signal |
| SERVO | Servo motor controlled with PWM Signal |