

Swarm Intelligence

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Introduction

- Swarm Intelligence. Nature inspired algorithms to solve:
 - Combinatorial domain optimization problems (ACO, MTPSO, RFD...)
 - Continuous domain optimization problems (PSO, ABC, DE...)
- Many (partially) independent entities cooperating to find a solution.
- Individuals are relatively homogeneous and interact with simple rules
- Balance:
 - Exploration of the overall search space
 - Exploitation of the most promising areas



Introduction

- There are many (many, many, many) swarm intelligence metaheuristics.
- EvolutionaryComputationBestiary https://github.com/fcampelo/EC-Bestiary



- Let's try to focus on the mathematical basis of classical metaheuristics
- Most of the original metaheuristics only provide a new analogy, but are

essentially the same as other more classical metaheuristics



Swarm Intelligence: Overall view

- Comprehensive Taxonomies of Nature- and Bio-inspired Optimization: Inspiration versus Algorithmic Behavior, Critical Analysis and Recommendations Clasification by behavior:
 - Differential vector movement (207/323 => 64.09%).
 - All population (13/323 => 4.02%). FA, CDA, ...
 - Groups based (25/323 => 7.75%). CSO, BA, ...
 - Representative based (169/323 => **52.32%**). **PSO**, ABC, ...
 - Solution creation (116/323 => 35.91%):
 - Combination (108/323 => 33.43%). GA, Cuckoo Search,...
 - Stigmergy (8/323 => 2.48%). ACO, RFD,...

- Inspired on social behavior of a colony of bird flocks
- Minimize fitness function $f: \mathbb{R}^n \rightarrow \mathbb{R}$
- Each particle has an initial random position and an initial random v vector
- In each iteration: $\mathbf{v}_{i,d} \leftarrow \omega \ \mathbf{v}_{i,d} + \phi_p \ r_p \ (\mathbf{p}_{i,d} \mathbf{x}_{i,d}) + \phi_g \ r_g \ (\mathbf{g}_d \mathbf{x}_{i,d})$
 - Inertia
 - Vector towards best local position p_{i,d} found by itself
 - Vector towards best global position g_d found by the swarm



- In each iteration:
 - $\mathbf{v}_{i,d} \leftarrow \omega \, \mathbf{v}_{i,d} + \phi_p \, r_p \, (\mathbf{p}_{i,d} \mathbf{x}_{i,d}) + \phi_g \, r_g \, (\mathbf{g}_d \mathbf{x}_{i,d})$
 - \bullet $\mathbf{x}_{i} \leftarrow \mathbf{x}_{i} + \mathbf{v}_{i}$
 - if $f(\mathbf{x}_i) < f(\mathbf{p}_i)$ then Update the particle's best known position: $\mathbf{p}_i \leftarrow \mathbf{x}_i$
 - if $f(\mathbf{p}_i) < f(\mathbf{g})$ then Update the swarm's best known position: $\mathbf{g} \leftarrow \mathbf{p}_i$
 - \bullet r_p and r_g are random numbers between 0 and 1
 - \bullet ϕ_p ϕ_g are parameters of the metaheuristic. (inertia, cognitive component, and social component)



- Initialization:
 - Randomly distributed or around candidate solution
 - Velocity vectors randomly distributed or zero
- Implementation details:
 - Keep positions (and velocity) inside search space
 - Closest position inside search space
 - Velocity zero or inverse (whip back)



- Parameter tunning:
 - Classical values: social and cognitive around 2.
 - Pedersen values:

https://www.researchgate.net/profile/Mohamed-Mourad-Lafifi/post/Which-is-the-best-swarm-size-in-

PSO/attachment/5b5b6f85b53d2f89289c14e1/AS%3A653084896288769%40153271898 1208/download/Good+Parameters+for+Particle+Swarm+Optimization.pdf

https://eprints.soton.ac.uk/71755/



- Variations
 - Neighborhood (ring, adaptive topologies, etc.)
 - Mutations, hybrid methods, simplifications, discrete version, etc.
 - Multiobjective versions



- Your next task:
 - Develop your own PSO program
 - Check it with classical benchmark functions (Sphere, Rastringin,
 - Rosenbrock, etc.) Evolutionary programming made faster
 - Compare results with different parameters. Apply statistical tests:
 - https://www.isa.us.es/3.0/tool/statservice/
 - http://tec.citius.usc.es/stac/ranking.html
 - https://www.statskingdom.com/kruskal-wallis-calculator.html



Swarm Intelligence: Artificial Bee Colony

- Inspired on social behavior of a colony of bees
- Minimize fitness function f: Rⁿ -> R
- Three types of bees (balance local/global search):
 - Employed bees: work on a concrete food source (location)
 - Onlooker bees: select food sources depending on the dance of employed bees (quality of the solutions)
 - Scout bees: Randomly search for new food sources



Artificial Bee Colony: Employed Bees

- Half of the bees are employed bees
- Employed bee b_i (working on position p_i in R^n):
 - Randomly select a dimension k
 - Randomly select another bee b' (at position p_i)
 - Generate new position modifying dimension k of p_i combining it with the position of b':
 - \bullet $p'_i = p_i$
 - \bullet $p'_{i,k} = p_{i,k} + r (p_{i,k} p'_{i,k})$

r random value in [-1,1]

Artificial Bee Colony: Employed Bees

- Employed bee b_i (working on position p_i in R^n):
 - Generate **new position** modifying dimension k of p_i combining it with the position of b':

$$p'_{i,k} = p_{i,k} + r (p_{i,k} - p'_{i,k})$$

- if the fitness function improves in the new position
 - Then update position of employed bee
 - else decrement trials counter (main parameter of ABC)



Artificial Bee Colony: Onlooker and abandoned bees

- Onlooker bees (half of the total number of bees):
 - Weighted selection of position p of an employed bee. The most promising positions are selected with higher probability =>
 exploitation
 - Work one step on that position exactly as an employed bee
- Abandoned bee: After sc fails in the position of an employed bee:
 - Employed bee becomes scout: new random position => exploration
 - Continue as employed bee in the new position



Artificial Bee Colony

- Initialization: Randomly distributed or around candidate solution
- Parameter tunning:
 - Half of the bees are employed bees and half onlooker bees
 - scoutingCounter = swarmSize * numberOfDimensions
 - Only one parameter (number of bees)!!! (and number of iterations)
- Variations
 - Mutations, hybrid methods, discrete version, etc.
 - Multiobjective versions



Swarm Intelligence: Differential Evolution

- Minimize fitness function f: Rⁿ -> R
- Initialize agents at random positions of the search space
- In each iteration, every agent tries to improve its position:
 - Pick three other and different agents (a,b,c)
 - Choose randomly one of the n dimensions (i)
 - Modify dimension i of the agent, and also (probably) other dimensions, by combining the positions of agents a, b, and c



Swarm Intelligence: Differential Evolution

• In each iteration, every agent tries to improve its position:

- For each *j* of the rest of dimensions:
 - Generate random number r_i
 - If rj < CR then $x_j = a_j + F(b_j c_j)$
- If the fitness of the new position improves then update position
- CR: crossover parameter. CR in [0,1]
- F: Differential weight. F in [0,2]



Swarm Intelligence: Differential Evolution

- Parameter tunning:
 - Population size, number of iterations, CR, F
- Very sensitive!!! See e.g.

https://pdfs.semanticscholar.org/48aa/36e1496c56904f9f6dfc15323e0c45e34a4c.pdf



Swarm Intelligence: Firefly Algorithm

- Every particle influences each other particle. Attraction depends on:
 - Quality of solution (light intensity)
 - Distance between them (light absortion of the air)
- Only difference with PSO: Every particle influences each other. Depending on parameters used, it can be converted into PSO.



Swarm Intelligence:Water Cycle Algorithm

- Hierarchical organization. 3 categories depending on quality of solutions:
 - 1 sea
 - r rivers. Each river flows towards the sea
 - Streams associated to rivers. Each stream flows towards its river. More promising rivers have more streams
- If a stream (or river) improves its river (sea), it becomes the river (the sea)
- If a stream (river) is very close to the river (sea), it is removed
- Less promising streams evaporate
- It rains to create new streams

Swarm Intelligence: Parallel implementations

- Many (partially) independent entities cooperating to find a solution
- Current personal computers:
 - Multicore
 - Graphics Processing Units (GPUs)
- E.g. PSO: $\mathbf{v}_{i,d} \leftarrow \omega \mathbf{v}_{i,d} + \phi_p r_p (\mathbf{p}_{i,d} \mathbf{x}_{i,d}) + \phi_g r_g (\mathbf{g}_d \mathbf{x}_{i,d})$
- Each particle and each dimension can be computed in parallel
 - Find appropriate granularity level



Swarm Intelligence: Parallel implementations

- Any of the previous methods can be easily parallelized:
 - Splitting list of candidates into nPE (processors available) islands
 - 2) Each group evolves in parallel independently during pit iterations
 - 3) Processes communicate among them to redistribute the candidates
- This mechanism is repeated it times
- Total number of iterations = it*pit



Swarm Intelligence: Cooperation among metaheuristics

- The previous methods can cooperate in parallel:
 - 1) Each metaheuristic run in a different island (or even several islands)
 - 2) Each group evolves in parallel independently during pit iterations
 - 3) Processes communicate among them to *migrate* candidates
- This mechanism is repeated it times
- Total number of iterations = it*pit
- Each method can help others to go out from local minima



Swarm Intelligence: Conclusions and your future work

- Swarm metaheuristics are very easy to define and use
- Parameter tunning sensitivity... and cheating

Your Future work:

- Implement ABC and/or DE
- Compare results with PSO using a simple benchmark (e.g. the one presented in the paper <u>Evolutionary programming made faster</u>)
- Repeat with a not so simple benchmark (e.g. the one used in <u>BBOB workshop</u>)