NPTEL MOOC, JAN-FEB 2015 Week 8, Module 4

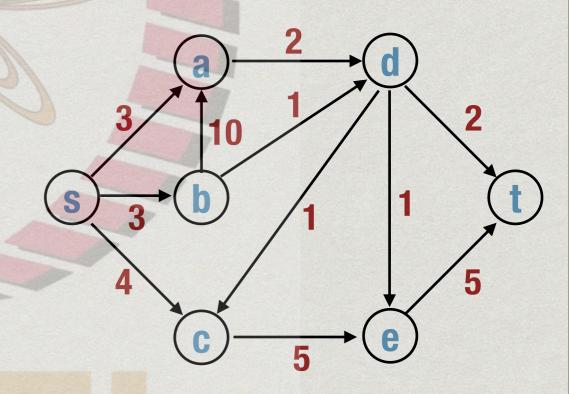
# DESIGN AND ANALYSIS OF ALGORITHMS

**Network Flows** 

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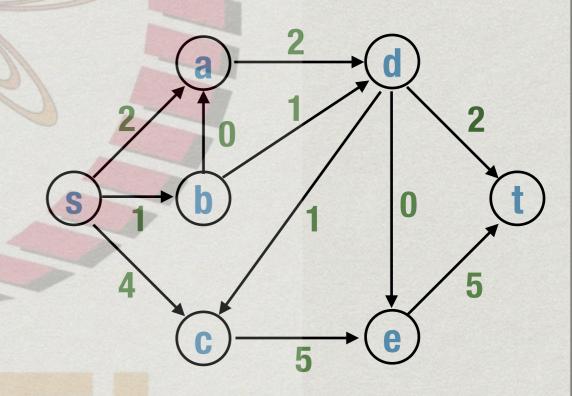
#### Oil network

- \* Network of pipelines
- \* Ship as much oil as possible from s to t
- \* No storage on the way
- \* A flow of 7 is possible
- \* Is this the maximum?



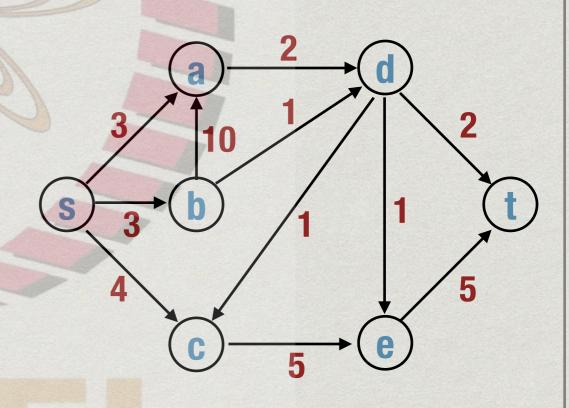
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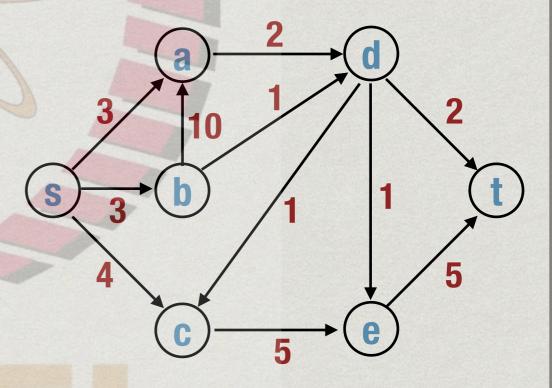
#### Oil network

- \* Network: graph G = (V,E)
- \* Special nodes: s (source), t (sink)
- \* Each edge e has capacity ce
- \* Flow: fe for each edge e
  - \*  $f_e \le C_e$
  - \* At each node, except s and t, sum of incoming flows equal sum of outgoing flows
- \* Total volume of flow is sum of outgoing flow from s



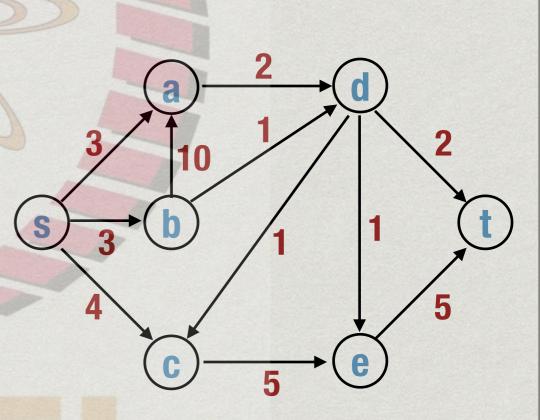
#### LP formulation

- \* Variable fe for each edge e
  - \* fsa, fbd, fce, ...
- \* Capacity constraints per edge
  - \*  $f_{ba} \le 10, ...$
- \* Conservation of flow at each internal node
  - \*  $f_{ad} + f_{bd} = f_{dc} + f_{de} + f_{dt}$ , ...
- \* Objective: maximize volume
  - \* maximize fsa + fsb + fsc

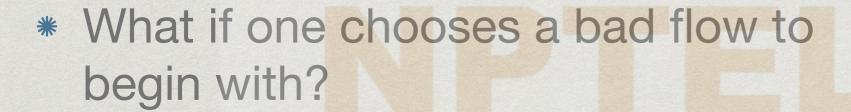


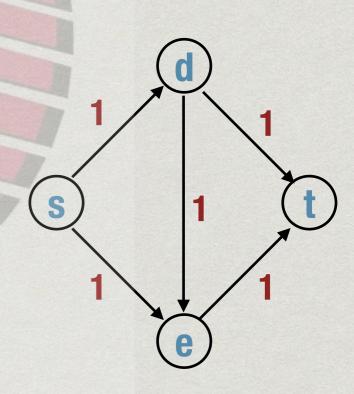
#### LP formulation

- \* Simplex solves LP, provides maximum flow, by exploring vertices of feasible region
- \* Moving from vertex to vertex actually corresponds to a more direct algorithm to find the maximum flow

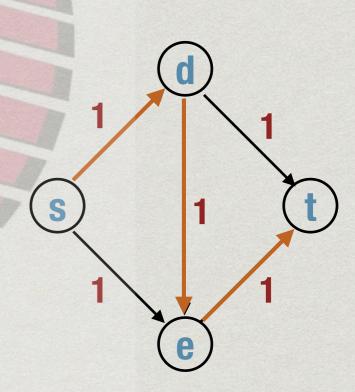


- \* Start with zero flow
- \* Choose a path from s to t that is not saturated and augment the flow as much as possible
- Network on the right has max flow

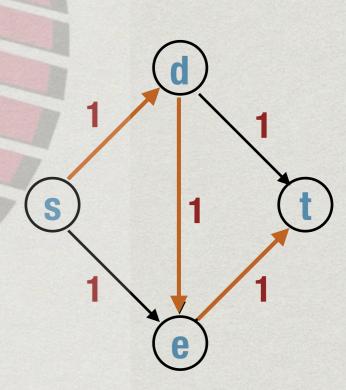




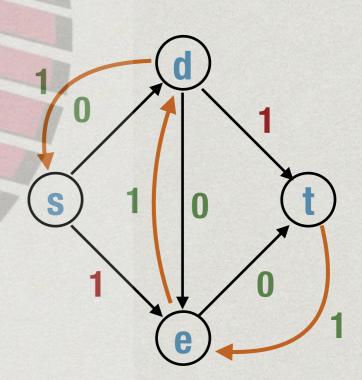
- \* Start with zero flow
- \* Choose a path from s to t that is not saturated and augment the flow as much as possible
- Network on the right has max flow
- \* What if one chooses a bad flow to begin with?



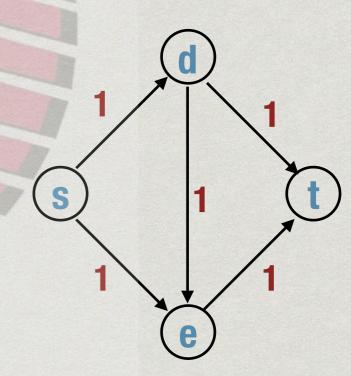
- \* Add reverse edges to undo flow from previous steps
- \* Residual graph: for each edge e with capacity ce and current flow fe
  - \* Reduce capacity to ce fe
  - \* Add reverse edge with capacity fe



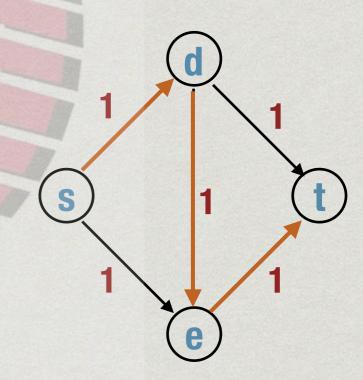
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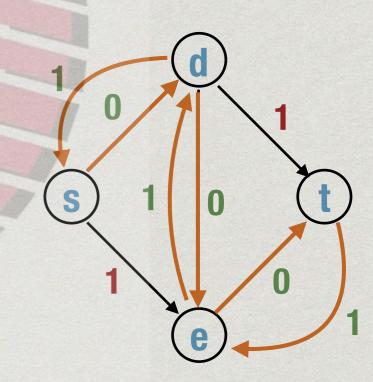
- \* Start with zero flow
- \* Choose a path from s to t that is not saturated and augment the flow as much as possible
- \* Build residual graph
- \* Repeat previous two steps till there is no feasible flow from s to t

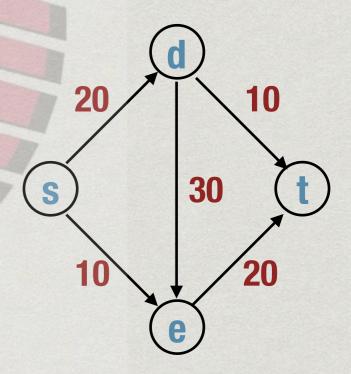


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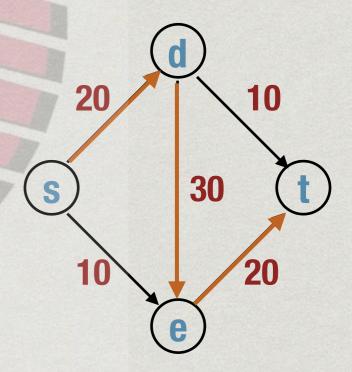


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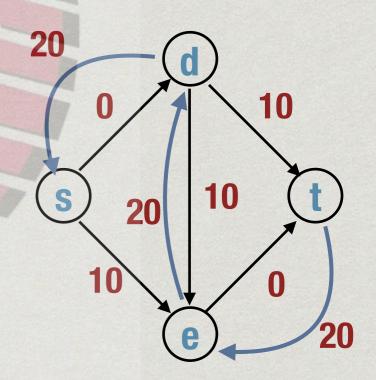




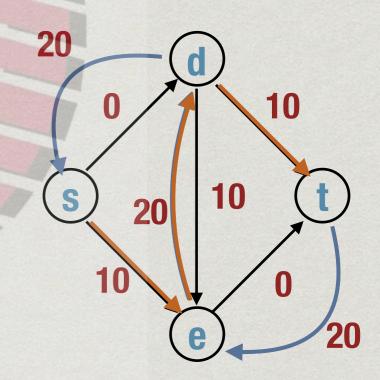
\* Start with flow 20, s-d-e-t



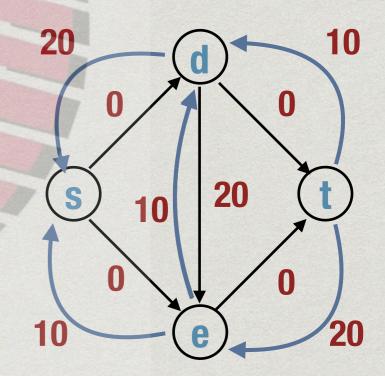
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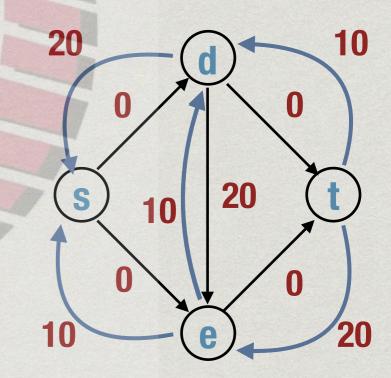
- \* Start with flow 20, s-d-e-t
- \* Build residual graph
- \* Add flow 10, s-e-d-t



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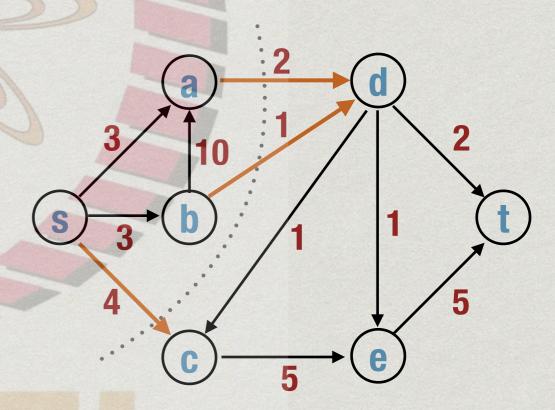


- \* Start with flow 20, s-d-e-t
- \* Build residual graph
- \* Add flow 10, s-e-d-t
- \* Build residual graph
- \* No more feasible paths from s to t



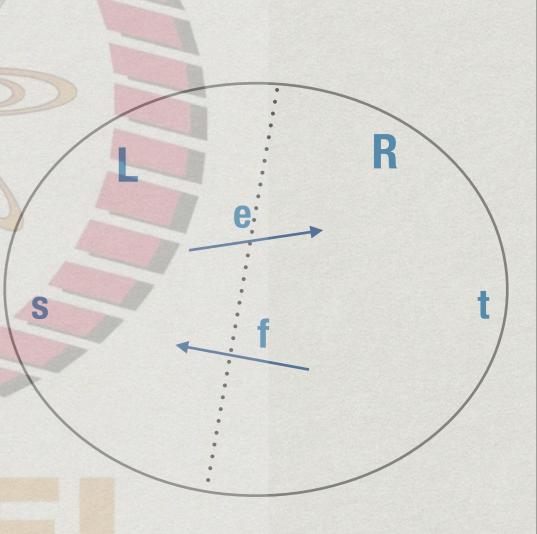
#### Certificate of optimality

- \* Edges {ad,bd,sc} disconnect
  s and t (s,t)-cut
- \* Flow from s to t must go through this cut
  - \* Cannot exceed cut capacity = 7
- \* In general, max flow cannot exceed min cut capacity



#### Max flow-min cut theorem

- \* In fact, max flow is always equal to min cut!
- \* At max flow, no path from s to t in residual graph
  - \* s can reach L, R can reach t
  - \* Any edge e from L to R must be at full capacity
  - \* Any edge f from R to L must be at zero capacity



- \* Choose augmenting paths wisely
- \* If we keep going through the middle edge, 200 iterations to find the max flow
  - \* FF can take time proportional to max capacity
- \* Use BFS to find augmenting path with fewest edges iterations bounded by |V|x|E|, regardless of capacities

