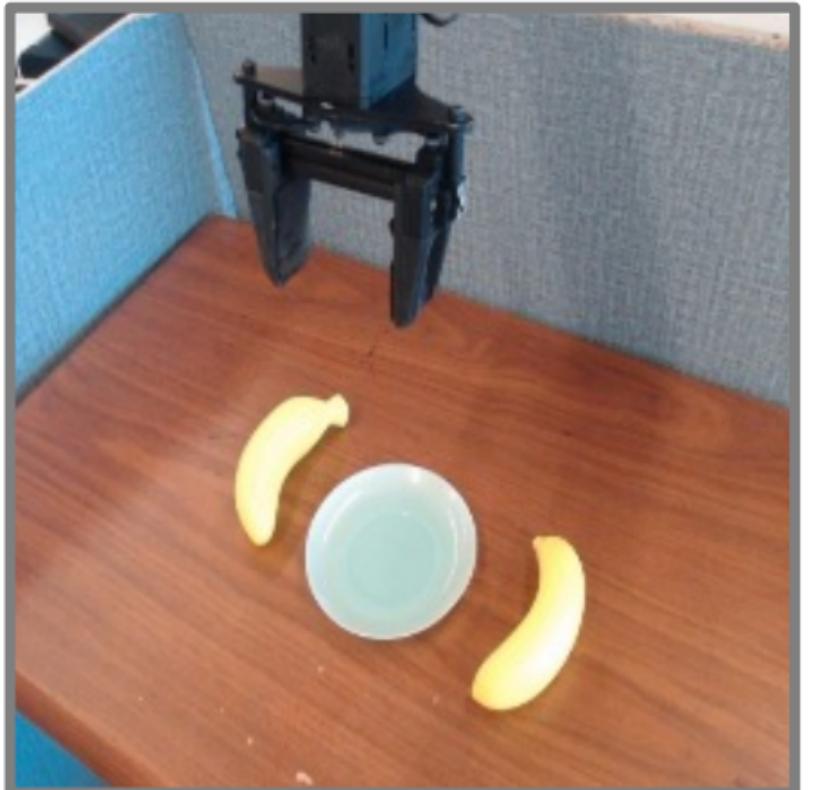**Put the banana on the right on the plate**

A previous attempt using a position-based command failed to target the correct banana.
   I will now **use a different level of abstraction**, atomic motion commands, to guide the robot toward the right side of the workspace to ensure it approaches the correct object.

move right and down to the banana on the right