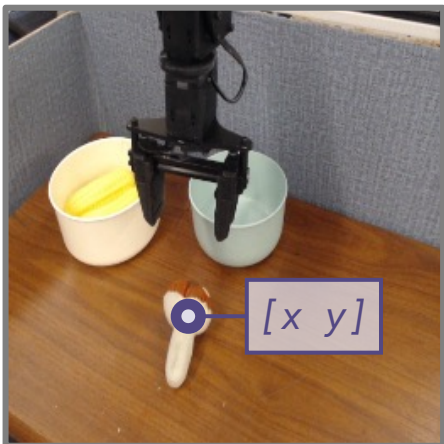


Put all the food in the blue pot and stuffed toys in the tan pot



High-level & combination commands have been attempted without lifting the object.

Since the gripper is already well-positioned above the mushroom, a position command will help re-calculate a more precise grasp to ensure the mushroom is actually secured before lifting.

pick up the object at $[x, y]$

