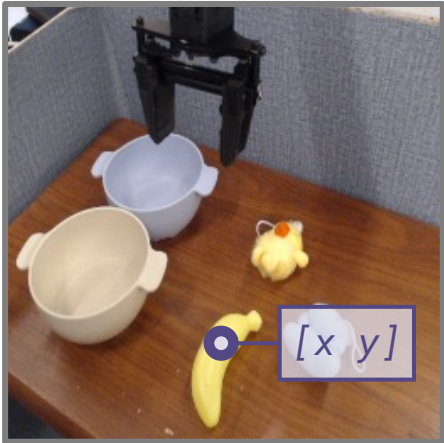
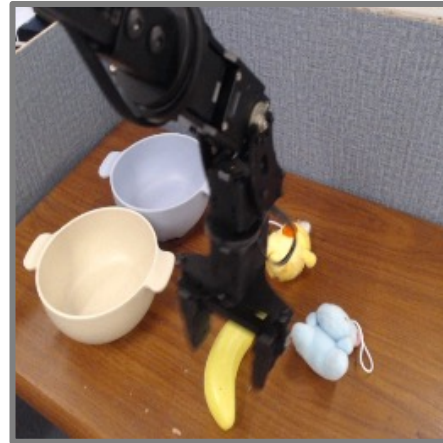


Put all the food in the blue pot and stuffed toys in the tan pot



Since the gripper is centered over the blue pot & away from the items, a **position command** is **most efficient** to direct the robot to a specific target.

move above $[x \ y]$



Since the robot is already **precisely aligned with the banana**, a **high-level instruction** is the **most efficient** and **reliable** way to execute the grasp.

grasp the banana