

*"Put the toothbrush  
on the towel"*



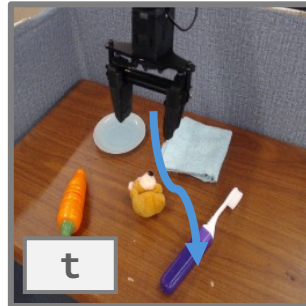
Observation

High-level  
Policy

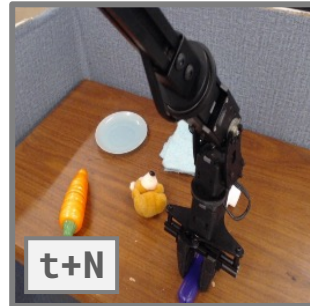
Steerable Command:  
*"Move right to [x y]"*

Low-level  
Steerable VLA

Action



$t$



$t+N$