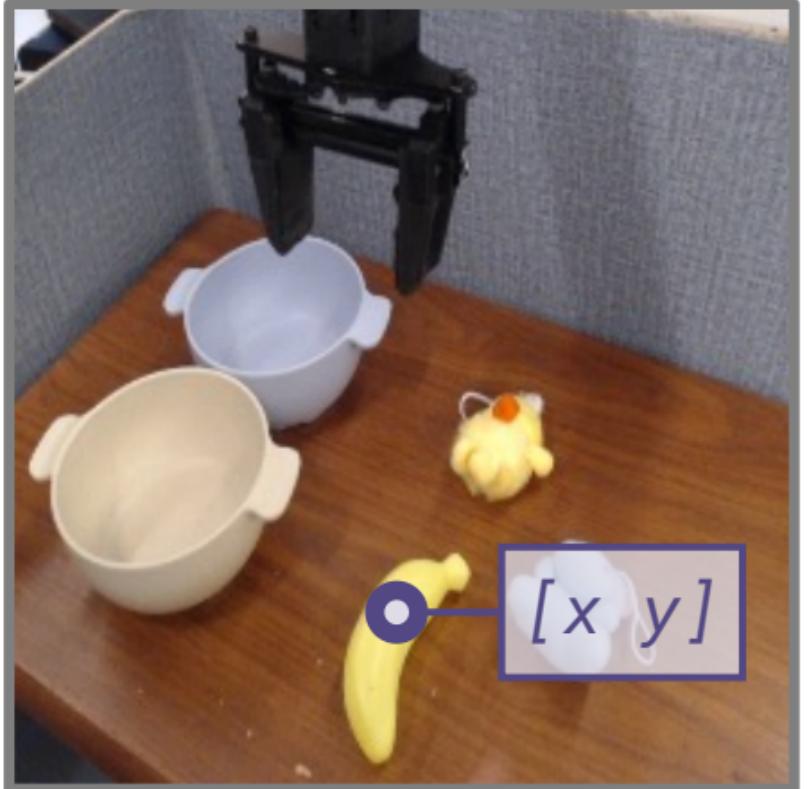


Put all the food in the blue pot and stuffed toys in the tan pot



Since the gripper is centered over the blue pot & away from the items, a **position command is most efficient** to direct the robot to a specific target.

move above [x y]



Since the robot is already **precisely aligned with the banana**, a **high-level instruction is the most efficient** and reliable way to execute the grasp.

grasp the banana