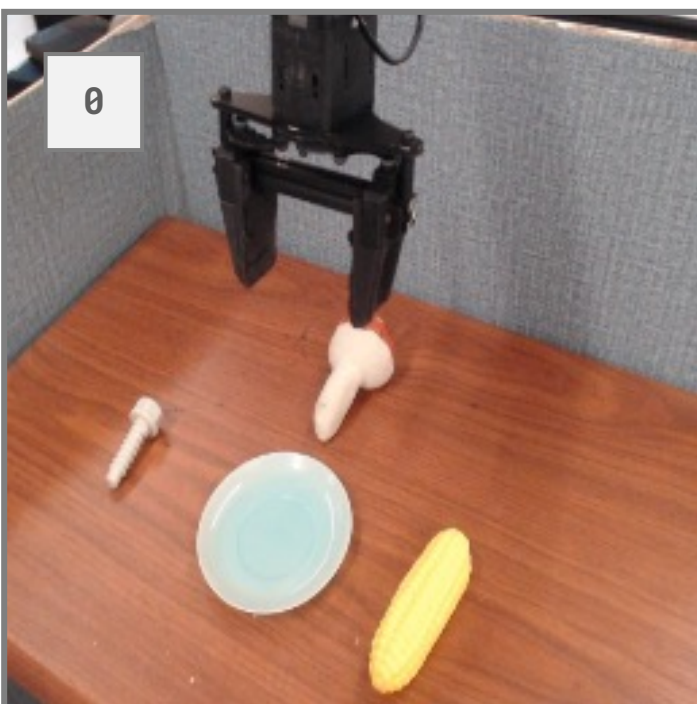# Put the screw on the plate

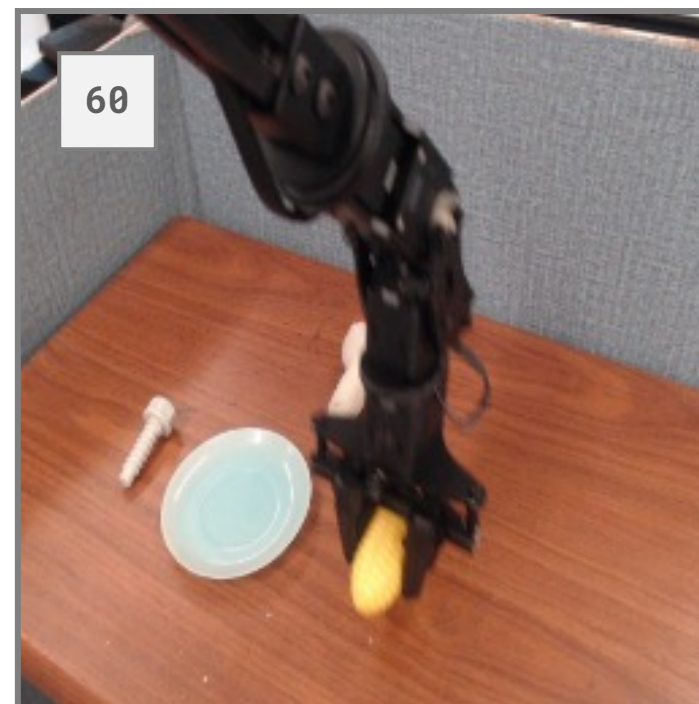

0

The scene shows a robot gripper hovering over a mushroom on a wooden table, with a screw, a plate, and a corn cob also present nearby. The robot has not yet interacted with the screw or the plate.

The robot needs to move its gripper to the screw and pick it up to begin the task.

Grasp the screw

20

The current observation shows the robot gripper holding the yellow corn, while the white screw remains on the table to the left. This indicates the previous command to grasp the screw was unsuccessful.

The robot must release the corn to free its gripper before it can attempt to grasp the screw again.

Release the corn

40

In the current observation, the robot arm has successfully released the corn and is now empty, with the gripper open above the table. The white screw remains on the left side of the table, while the blue plate is positioned in the center.

The robot must now move to and pick up the white screw to proceed with the task of moving it to the plate.

Grasp the screw

60

The scene shows the robot gripper holding the yellow corn object on the table, while the white screw and the blue plate remain in their original positions. The robot has mistakenly grasped the corn instead of the screw as previously commanded.

The robot must release the corn to free its gripper so it can move towards and grasp the screw.
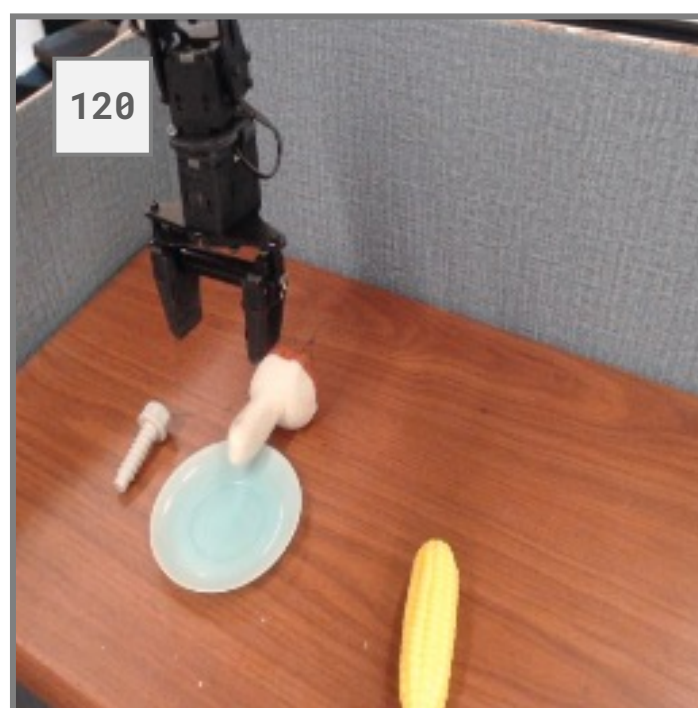
Release the corn

80
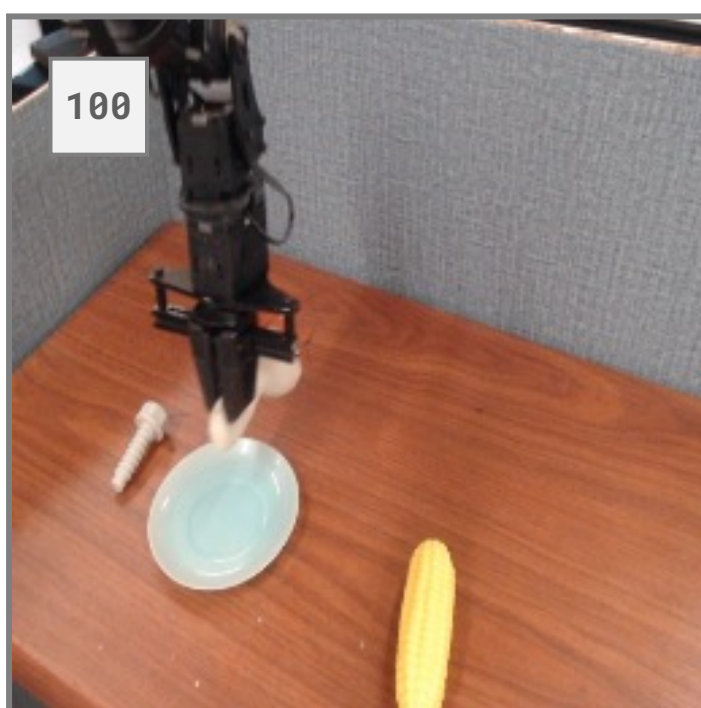
The current observation shows the robot's gripper open and positioned above the corn, with the screw and plate remaining on the table. The corn has been released, and the robot needs to redirect its attention to the target object.

The robot must now target and pick up the screw to move it toward the plate.

Grasp the screw

100

In the current observation, the robot is grasping the mushroom instead of the screw, while the screw and the plate remain in their original positions on the table.

The robot needs to release the mushroom so it can proceed to pick up the correct object.

Release the mushroom

120

The robot has released the mushroom, which is now lying on the table next to the plate. The gripper is open and positioned above the mushroom, while the screw remains on the left side of the table.

The robot needs to move its gripper to the screw and grasp it to proceed with moving it to the plate.

Grasp the screw

140

The robot is currently holding the mushroom with its gripper. To move the screw to the plate, the robot first needs to clear its gripper of any other objects.

The robot must release the mushroom to proceed with the main task.

Release the mushroom