WHEN MACHINES TALK

a data challenge by SNCB-NMBS



check out our GitHub repository

TEAM MEMBERS

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Context of the problem and description of the challenge





Recent railway vehicles are equipped with sensors on most of their Subsystems. The latter report some states via a wired network to a central on-board computer





They receive thousands of sequences of events from thousands of vehicles. Since machines tend to degrade, sometimes technical failures appear

With that information, they labeled dataset of sequence of events with technical incident types.





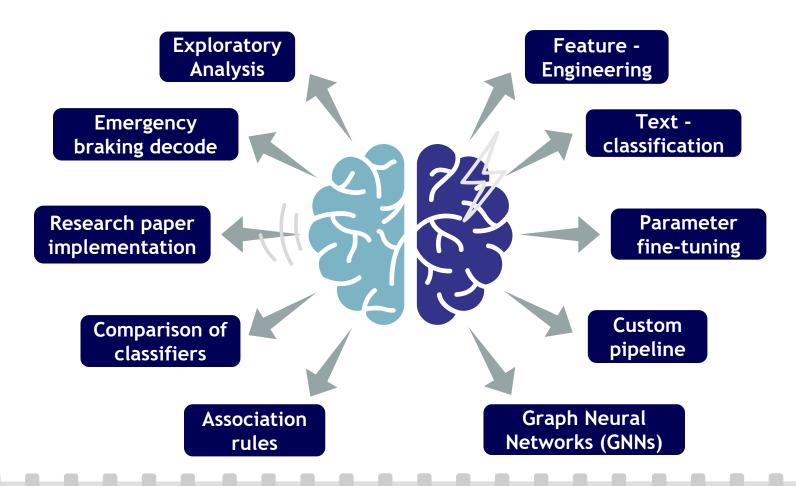
The main challenges are to, find sub sequences of events (scenarios) that seem to be highly associated to some types of incidents and automatically suggest incident types based on new sequences of events







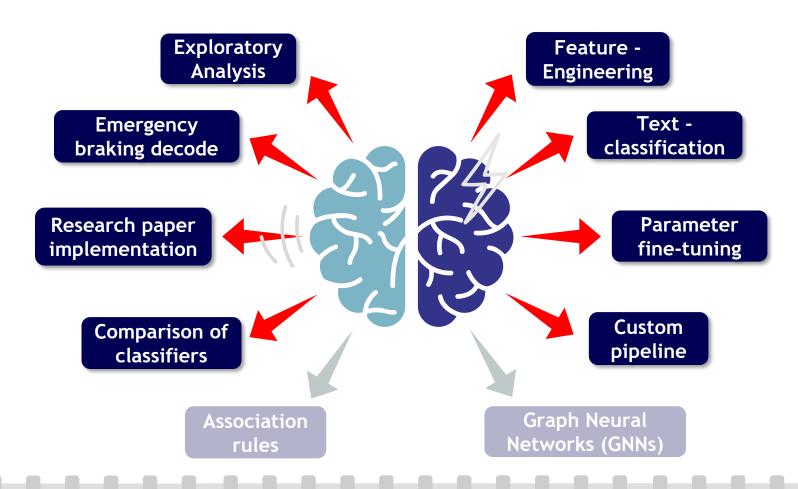
We used several methodologies to explore options and different points of view, ranging from exploratory analysis and feature engineering to applying multiple types of models







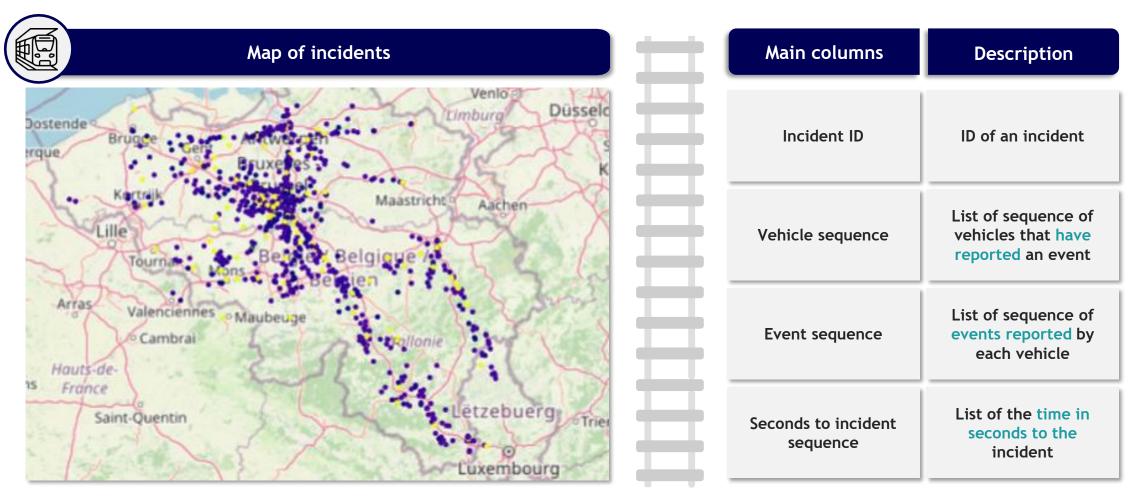
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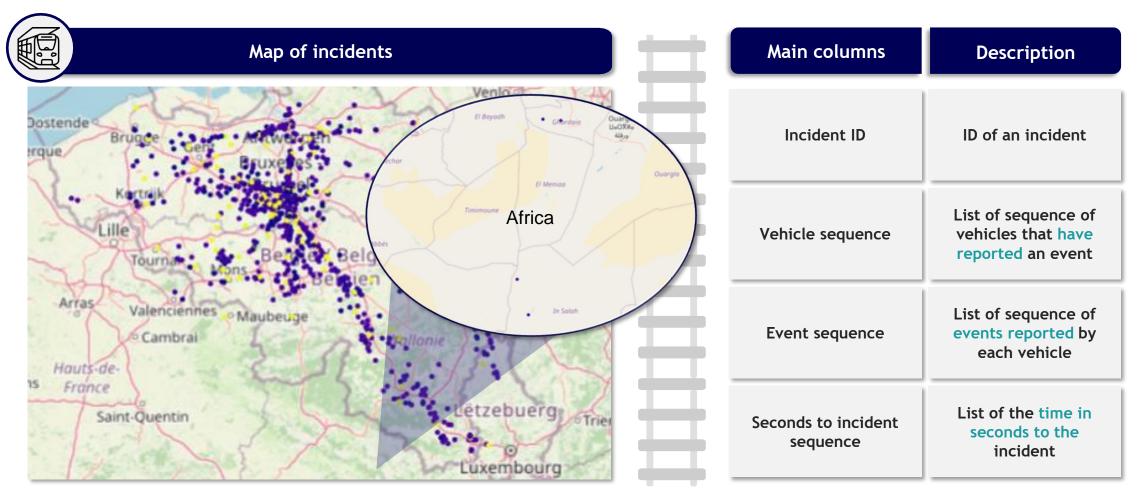


As expected, most events are in Belgium, with high density near Brussels. However, some "data errors" show incidents in Africa.



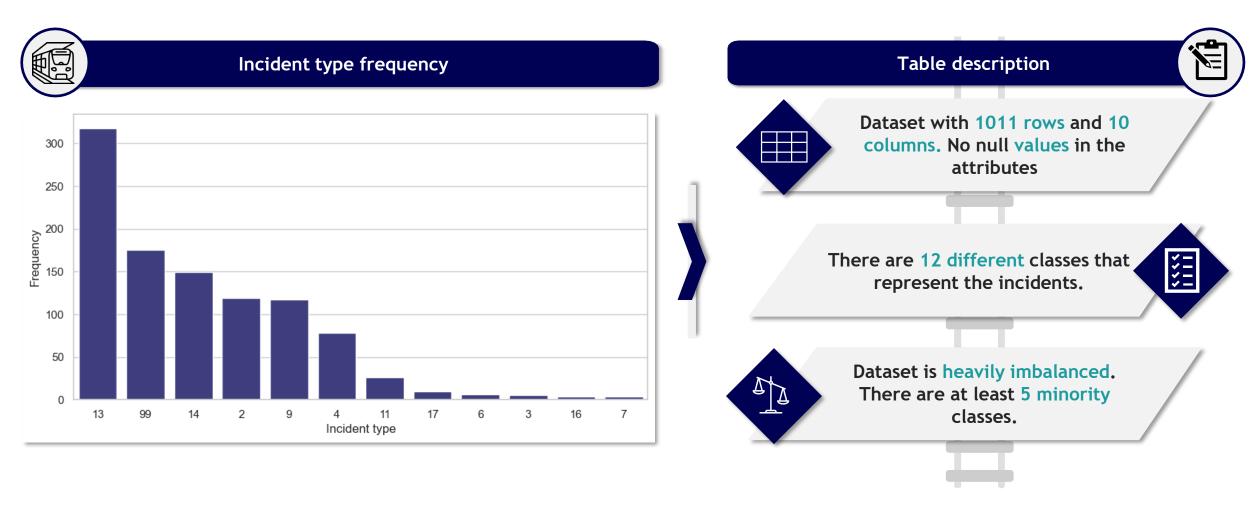


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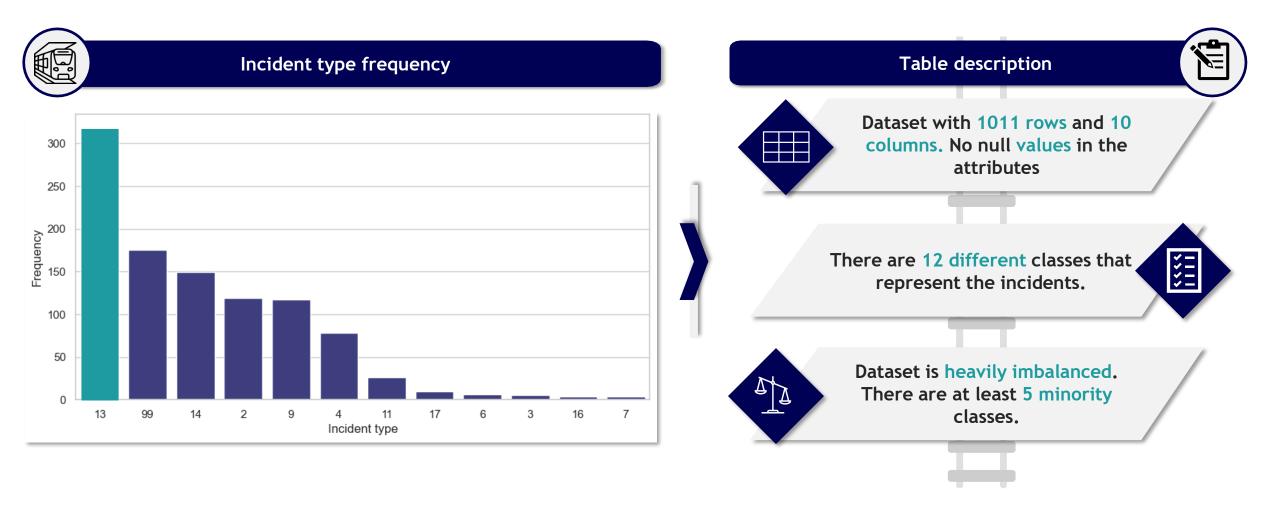


The first overview of the data show us that the dataset is "small" and the classes to be predicted are imbalanced. This indicates that we have to deal with those inconvenient when developing the models





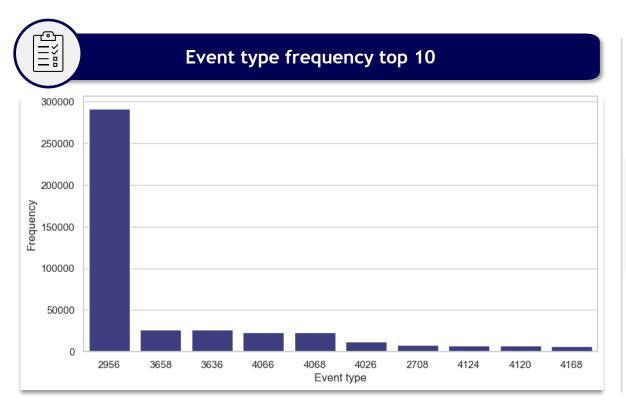
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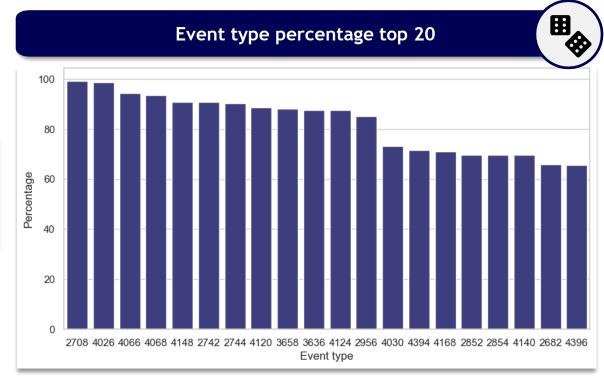


Incidents and event type frequency



It is possible to observe that some event types appears in more than 90% of the events sequences, which show us that those could not provide valuable information





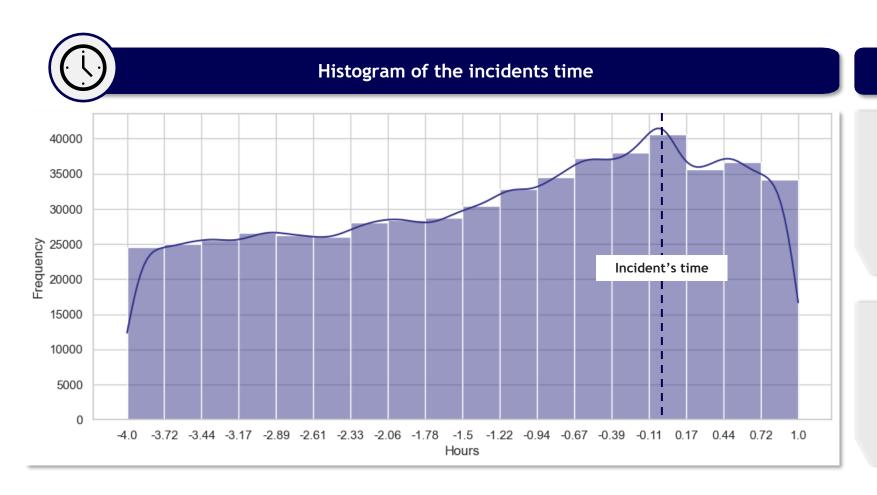
- Event type 2956 happens very often compared to the other events
- There are 917 events that occur at least one time in this dataset

- Multiple events appear in more than 90% of the events sequences. Those do not provide enough information
- Event types that appears with less frequency could provide more valuable information

Chronology of the events



We observed that it is possible to find events 4 hours before the incident and one hour after the incident. Most of the registered events happened before incident



Key points

- It is possible to observe a peak just before the event happens
- Most incidents registered occurs before the events

- It is possible to filter incidents using the time criteria.
- For example, braking emergency incidents could happen seconds before event

Emergency Braking Analysis



The latter gave us the idea of identifying Emergency Braking Codes for Feature Engineering for the Classification Model



General steps to develop the Braking emergency feature





Calculate the change in speed (Δv) in m/s and the change in time (Δt) in s between subsequent events. Determine the deceleration in m/s² between subsequent events



Identify the event codes where:

- >The end speed is 0
- >Deceleration is greater than 1 m/s²
- Δt is less than 10 s, but greater than 0 s





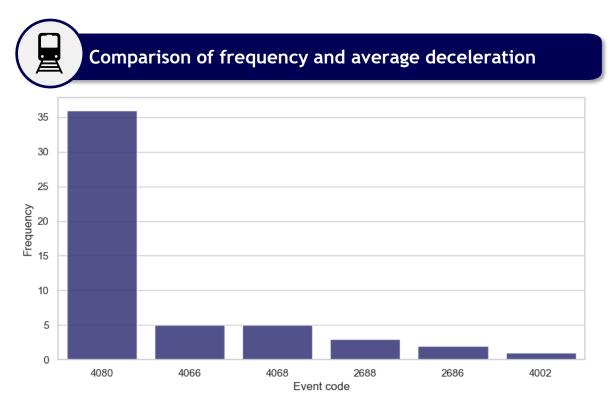


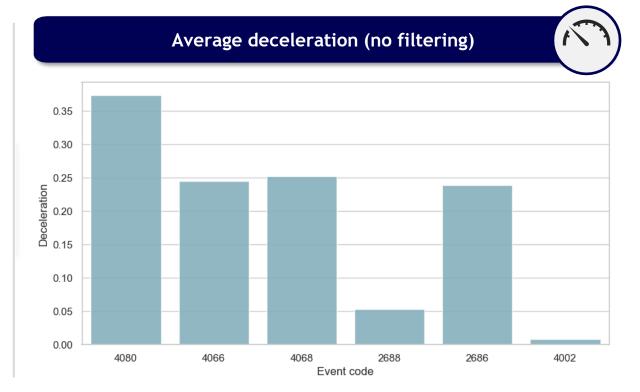
Calculate average deceleration of the most frequent event codes of previous step (excluding outlier values)

Emergency Braking Analysis



Analyzing the frequency and the average deceleration it was possible to find that the 4080 event may be related to an emergency braking





- Event 4080 shows the higher frequency in decelerations events.
- Many times, there was a short event before the 4080 which led to deceleration being 0.

- Event 4080 shows the highest deceleration with 0.38 m/s2.
- For codes 4066 and 4068 there were cases with acceleration (negative deceleration).



Paper implementation



Machine-Learning Model implementation based on SNCB paper

 $h_{\rm in\ class}$ **Filter out events** based on r metric (threshold 0.5) $h_{
m in~all~classes}$ **Reinclude filtered event codes** with avg F1 ≥ 0.6 using CountVectorizer Identify the most frequent one- and two-event sequences using the FP-Growth algorithm with a minimum support threshold of 0.05 Add binary columns for each frequent event sequence in each incident row Fine-tune the parameters of a Naive Bayes classifier using GridSearchCV with 5-fold stratified cross-validation

MAIN ISSUES DURING IMPLMEMENTATION

Apply Apriori algorithm for the whole data set



MemoryError: Unable to allocate 60.9 GiB for an array with shape (12926995, 5, 1011).



The number of possible itemsets grows exponentially.



Same issues with Fpgrowth for sequences > 4 or with adding new Boolean attributes where sequences > 2.



Paper implementation

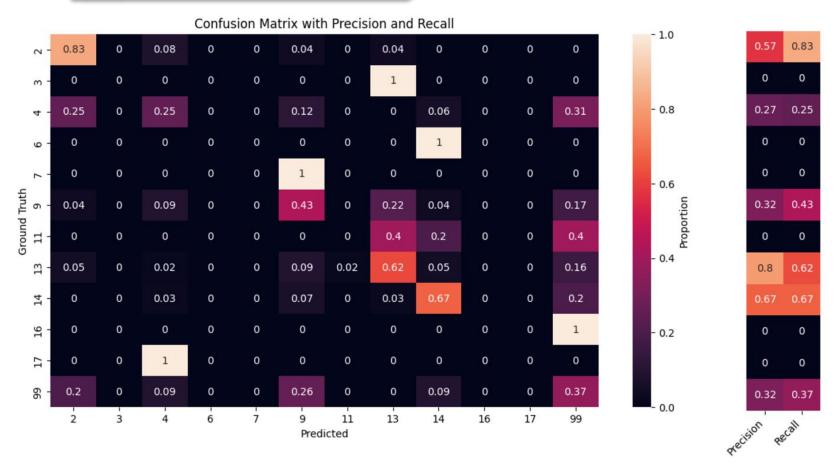


Test Dataset Results



F1-score: **0.52**

Accuracy: 0.53



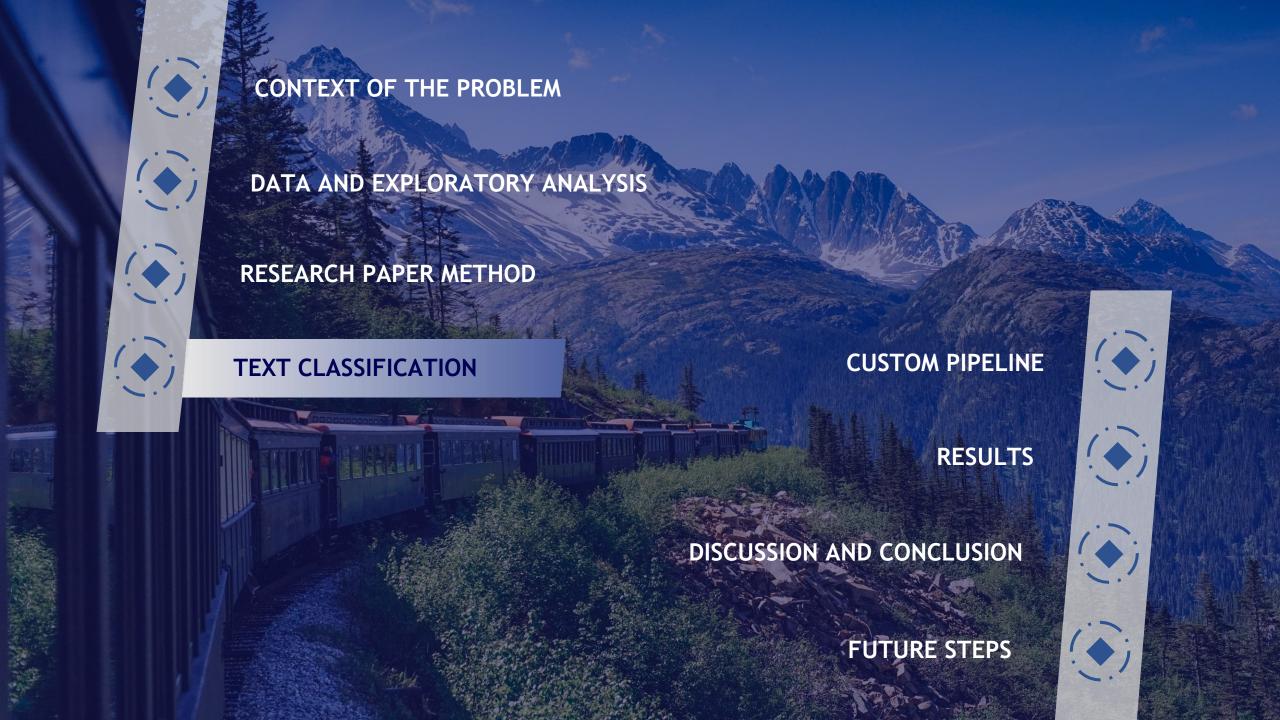
POSSIBLE IMPROVEMENTS

Use longer sequences, not just the most frequent one- and two-event sequences.



For full testing, we would need Virtual Machines with high memory or distributed processing (e.g., Spark's FP-Growth implementation).





Text classification Methodology





Current tabular ML Techniques do not support sequential data and do not perform well on severely imbalanced and scarce data





Sequence Representation: Represent events in sequences as "words" in a sentence





Class Imbalance: Test oversampling techniques for improved performance





Brute-force approach: Test multiple embedding representations, oversampling strategies and classification models

Text classification Methodology





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Sequence Representation: Represent events in sequences as "words" in a sentence





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Brute-force approach: Test multiple embedding representations, oversampling strategies and classification models



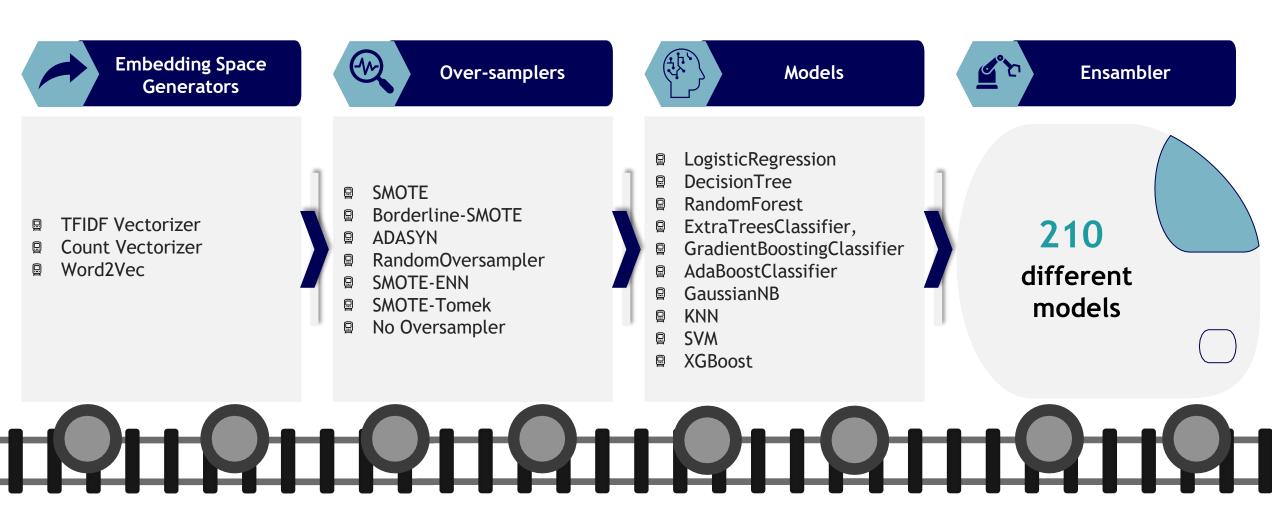


Goal: Maximize accurate classifications and minimize mistakes (Maximize F1-Score)

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The pipeline at a glance









B

This methodology could be divided in four main steps that implies trying more than 200 different

models.

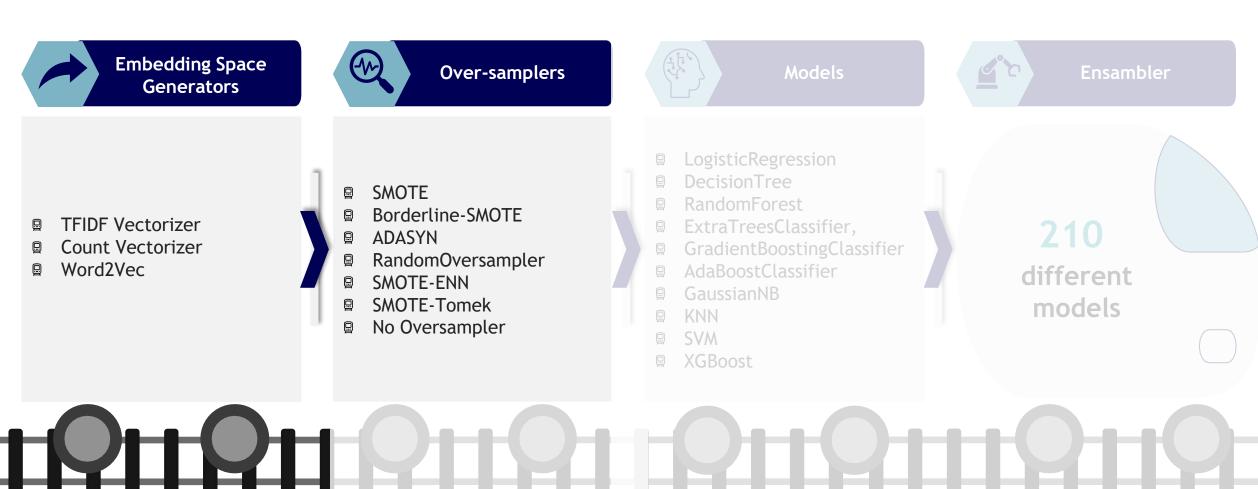


- TFIDF Vectorizer
- Count Vectorizer
- ₩ord2Vec

We will **train embedding space generators on the training fold** and **transform the test fold** using the learned representations. Below are the strengths and weaknesses of each generator:

METHOD	STRENGTHS	WEAKNESSES					
TF-IDF	 Mitigates noise from frequent events across sequences. Highlights unique patterns by emphasizing events frequent in one sequence but rare in others. 	 Ignores sequential and semantic relationships. Produces high-dimensional, sparse vectors, challenging computational efficiency and interpretability. 					
Count Vectorizer	 Provides a straightforward representation of event frequency. Indicates the significance of event frequency over order in outcomes. 	 Disregards sequential and semantic information. Produces sparse, high-dimensional vectors, hindering computational and analytical efficiency. 					
Word2Vec	 Captures semantic relationships by grouping similar events. Encodes event context, preserving order and meaning. 	Requires substantial training data for quality embeddings and struggles with limited datasets.					







This methodology could be divided in four main steps that implies trying more than 200 different

models.



- TFIDF Vectorizer
- Count Vectorizer
- Word2Vec



Over-samplers

- SMOTE
- Borderline-SMOTE
- ADASYN
- RandomOversampler
- SMOTE-ENN
- SMOTE-Tomek
- No Oversampler

Extra Processing:

We duplicated training records for classes with fewer than three samples, ensuring oversamplers could function for all classes.

Oversampling at first was infeasible since it requires at least three samples per class.

(5-fold split would leave folds with only two samples)

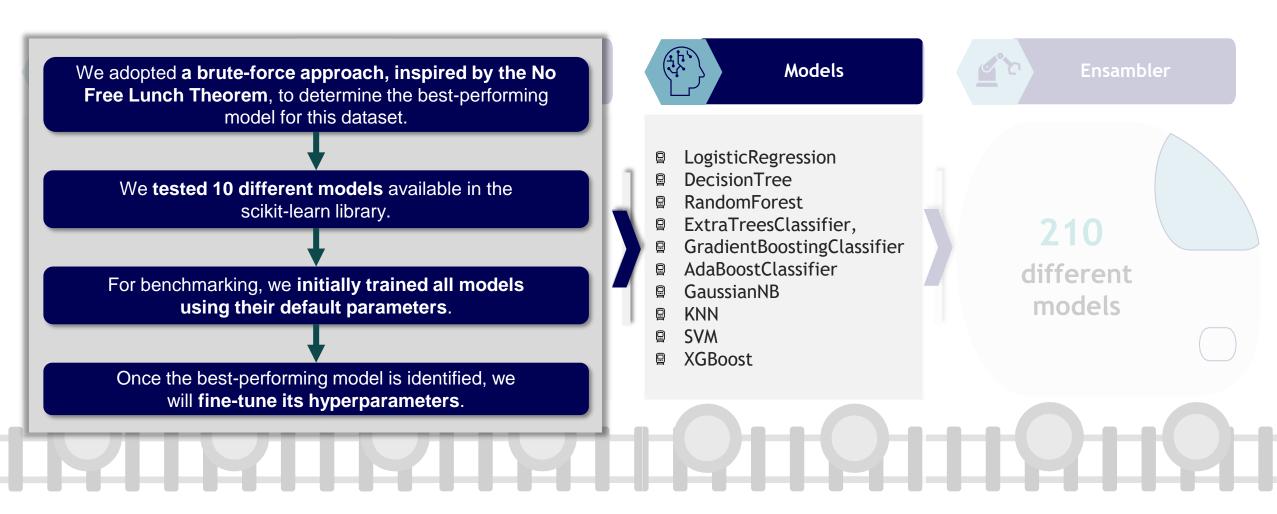
We applied the **default oversampling strategy** for each sampler **exclusively to the training data** to prevent information leakage into the test data.

This approach enhanced the training dataset while maintaining the validity of the evaluation process.









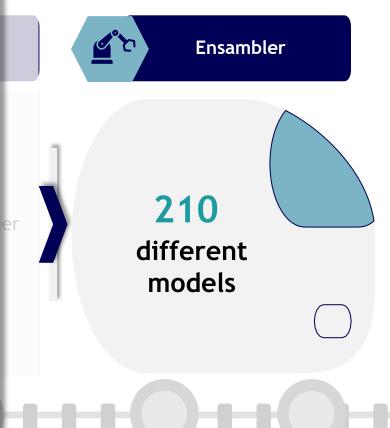






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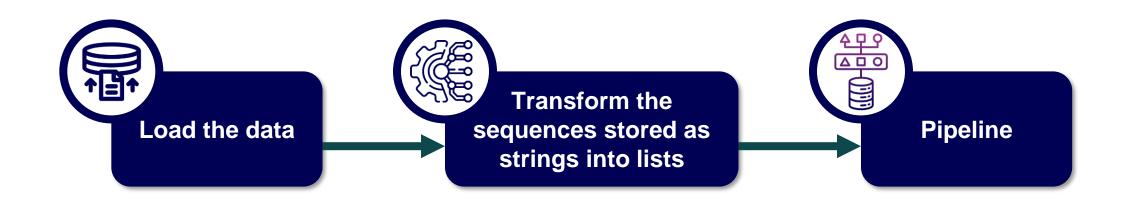
To construct the ensemble model, we trained 210 individual models. We used the differential evolution (DE) algorithm to determine the optimal weights for combining their predictions. DE is well-suited for optimizing ensemble models due to its global search capability, which avoids local minima and effectively Count explores the solution space. Word2\ The objective was to maximize predictive performance, specifically the F1-score. The **fitness function**, defined as the F1-score of the ensemble model's predictions compared to true values, ensured weight optimization aligned with the performance metric.





Dataset with no extra processing results

Data Preprocessing



Dataset with no extra processing results



Embedding Generator + Over Sampler + Model



F1-score: **69.10**%

Accuracy: **69.92**%

	Model	Vectorizer	Sampler	Accuracy Mean	Accuracy Std	Recall Mean	Recall Std	Precision Mean	Precision Std	F1 Mean	F1 Std
94	GradientBoostingClassifier	Count	ADASYN	0.699298	0.009880	0.699298	0.009880	0.693292	0.009541	0.691044	0.009947
104	GradientBoostingClassifier	Count	RandomOversampler	0.694333	0.019053	0.694333	0.019053	0.705052	0.017707	0.689394	0.018435
74	GradientBoostingClassifier	Count	SMOTE	0.693347	0.023312	0.693347	0.023312	0.698465	0.015648	0.687498	0.021960
84	GradientBoostingClassifier	Count	Borderline-SMOTE	0.688407	0.021736	0.688407	0.021736	0.684475	0.023663	0.680387	0.022421
54	GradientBoostingClassifier	TFIDF	SMOTE-Tomek	0.677515	0.032724	0.677515	0.032724	0.708091	0.018617	0.677958	0.028411
124	GradientBoostingClassifier	Count	SMOTE-Tomek	0.680500	0.015156	0.680500	0.015156	0.681979	0.012754	0.675060	0.014813
34	GradientBoostingClassifier	TFIDF	RandomOversampler	0.677486	0.034528	0.677486	0.034528	0.686205	0.026626	0.674007	0.031581
64	GradientBoostingClassifier	TFIDF	NoSamp	0.679496	0.027137	0.679496	0.027137	0.691487	0.023965	0.671905	0.024160
24	GradientBoostingClassifier	TFIDF	ADASYN	0.673555	0.022593	0.673555	0.022593	0.697297	0.016998	0.671654	0.016708
134	GradientBoostingClassifier	Count	NoSamp	0.680491	0.018784	0.680491	0.018784	0.689769	0.025222	0.669836	0.018454

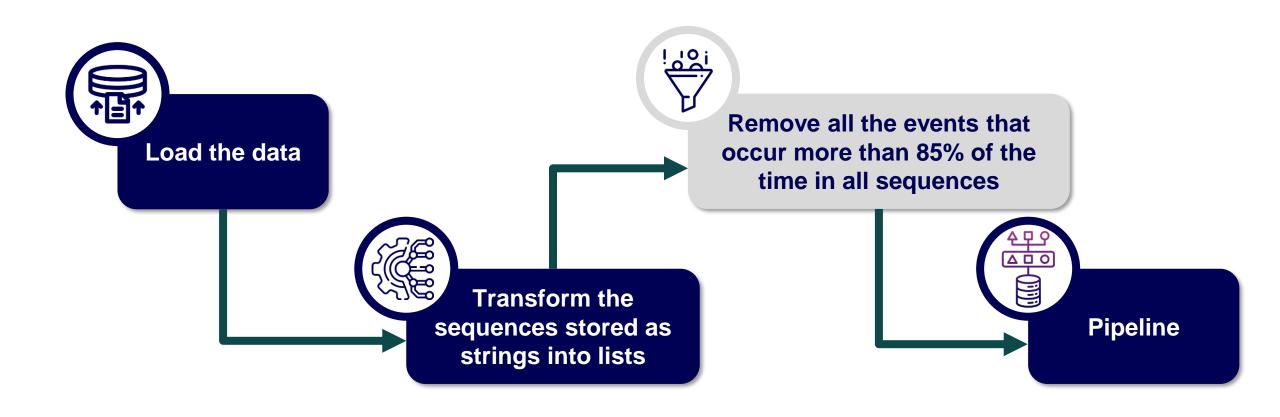
Ensambler(Embedding Generator + Over Sampler + Model) = Ensemble Model

Model	Vectorizer	Sampler	Accuracy Mean	Accuracy Std	Recall Mean	Recall Std	Precision Mean	Precision Std	F1 Mean	F1 Std
0 Ensemble	Multiple	Multiple	0.675574	0.019847	0.675574	0.019847	0.676288	0.019961	0.667454	0.018378



Dataset keeping the events that occur less than 85% of the time

Data Preprocessing





Dataset keeping the events that occur less than 85% of the time

Test Dataset Results

Embedding Generator + Over Sampler + Model



F1-score: **68.89**%

Accuracy: **69.23**%

	Model	Vectorizer	Sampler	Accuracy Mean	Accuracy Std	Recall Mean	Recall Std	Precision Mean	Precision Std	F1 Mean	F1 Std
104	GradientBoostingClassifier	Count	RandomOversampler	0.692362	0.015539	0.692362	0.015539	0.713046	0.015279	0.689194	0.014109
4	GradientBoostingClassifier	TFIDF	SMOTE	0.677564	0.026962	0.677564	0.026962	0.704565	0.021570	0.677456	0.025040
134	GradientBoostingClassifier	Count	NoSamp	0.685451	0.010444	0.685451	0.010444	0.701284	0.012506	0.675476	0.008441
74	GradientBoostingClassifier	Count	SMOTE	0.678501	0.023227	0.678501	0.023227	0.680099	0.023338	0.672320	0.023137
9	XGBoost	TFIDF	SMOTE	0.679564	0.029786	0.679564	0.029786	0.676154	0.037139	0.670813	0.030060
94	GradientBoostingClassifier	Count	ADASYN	0.678520	0.020992	0.678520	0.020992	0.674466	0.023335	0.670713	0.021415
59	XGBoost	TFIDF	SMOTE-Tomek	0.676564	0.022819	0.676564	0.022819	0.679385	0.027989	0.669826	0.022084
84	GradientBoostingClassifier	Count	Borderline-SMOTE	0.675545	0.015661	0.675545	0.015661	0.679817	0.011690	0.669716	0.014653
124	GradientBoostingClassifier	Count	SMOTE-Tomek	0.673599	0.011871	0.673599	0.011871	0.681708	0.008188	0.668974	0.013821
64	GradientBoostingClassifier	TFIDF	NoSamp	0.676569	0.028997	0.676569	0.028997	0.689269	0.031692	0.667489	0.029637

Ensambler(Embedding Generator + Over Sampler + Model) = Ensemble Model

Model	Vectorizer	Sampler	Accuracy Mean	Accuracy Std	Recall Mean	Recall Std	Precision Mean	Precision Std	F1 Mean	F1 Std
0 Ensemble	Multiple	Multiple	0.684485	0.009068	0.684485	0.009068	0.671497	0.02027	0.669622	0.013434



Dataset keeping the events that occur less than 85% of the time

Test Dataset Results

Embedding Generator + Over Sampler + Model

KEY INSIGHTS



F1-score: **68.89**%

Accuracy: 69.23%

104	Model GradientBoostingClassifier			ectorizer r n the freq				idents relies ces.		
		TFIDE	SMOTE	0.677564	0.026962	0.677564	0.026962	0.704565	0.021570	
	GradientBoostingClassifier	Onunt	CMOTE	0.670504	0.00007	0.670501	0.00007	0.600000	0.023338	
	XGBoost	of ro	It does no	t conside	r relation	ships an	nong eve	nts in terms	37139	
	GradientBoostingClassifier	ನ್ನ¦್ಡಿ ▮		semantics		_			23335	
	XGBoost								.027989	
	GradientBoostingClassifier		This insig	ght can gu	ide future	e analysi	s to unco	ver the	731692	

Ensambler (Em

Model	Vectorizer	Sampler	Accuracy Mean	Accuracy Std	Recall Mean	Recall Std	Precision Mean	Precision Std	







Manipulation of data to align with custom pipeline



Reordering chronologically all the events, speeds, states of an incident based on the relative timestamp





Store the event sequence column without commas and [] symbols





Add new columns for the number of vehicles and the index of the timestamp right before 0 sec.



The attributes events, speed, pantograph states, and vehicle sequences are **not sorted in absolute chronological** order based on the relative timestamp. Instead, they are sorted by vehicle, and within each vehicle, they are ordered chronologically.



Custom ML pipeline

Enhancing Model Performance: Incorporating Unexploited Attributes

	EXISTING ATTRIBUTE	NEW ATTRIBUTE
Č	Events sequence	The last n events leading up to the incident (timepoint 0 sec)
	Train kph sequence	Average speed during the last k events prior to the incident
	Dj ac state & dj dc state	State of each pantograph in the last x events before the incident
	Events sequence	Emergency braking occurrence in the last m events prior to the incident
	Events sequence	New event sequence that excludes the most common event codes appearing in at least a certain percentage of incidents
	Vehicles sequence	Number of vehicles in incident



Custom ML pipeline

Custom Machine-Learning Pipeline with Feature Engineering and Hyperparameter Optimization

- Binary features of the last n events before the incident, where n is a hyperparameter, created using a MultiLabelBinarizer is
- Numeric feature of the average speed in the last k events before the incident, with k as a hyperparameter
- Boolean features for the two pantograph states in the last x events before the incident, where x is a hyperparameter
- Boolean feature of emergency braking occurrence in the last m events, with m as a hyperparameter
- Event sequence excluding the most common event codes (occurring in at least a certain percentage per incidents)
- Removal of unnecessary attributes used in earlier steps
- Event codes transformed into numerical features using count vectorizer
- Oversampling technique of ADASYN
- Use of Gradient Boosting classifier

Custom ML pipeline

Optimized Parameters and Key Attributes after RandomSearchCV



- Fine-tuning parameters using RandomSearchCV with 1500 iterations
- Comparison with cross-validation weighted F1 and F1 score of validation dataset

ATTRIBUTE ☐	OPTIMAL PARAMETER
Last n events prior to incident	n = 6
Average speed in the last k events before the incident	k = 12
Boolean state of pantographs in the last x events	x = 3
Emergency braking occurrence in the last m events	m = 15
Event sequence excluding the most common event codes	percentage = 80
ADASYN Oversampling	Add 30% of the majority class count to the current count of any non-majority class
Gradient Boosting classifier	<pre>n_estimators = 400, max_depth = 5, learning_rate = 0.05, max_features = 'sqrt'</pre>



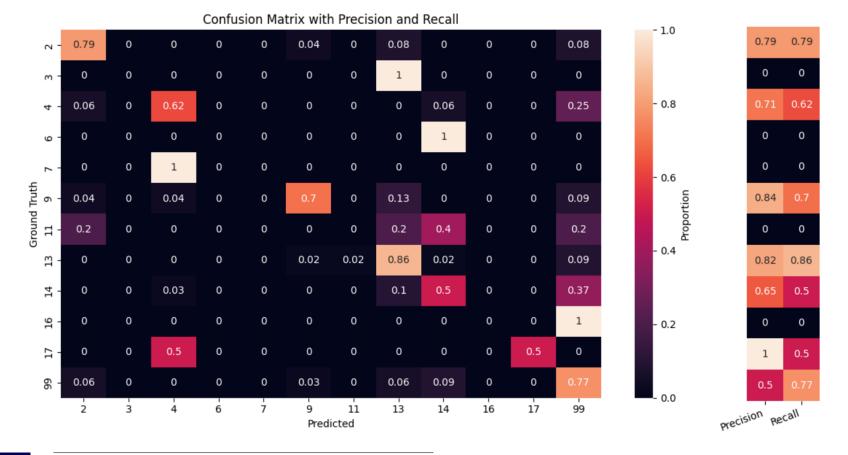


Test Dataset Results - not included in randomsearchCV fine-tuning



F1-score: 69.2%

Accuracy: 70%



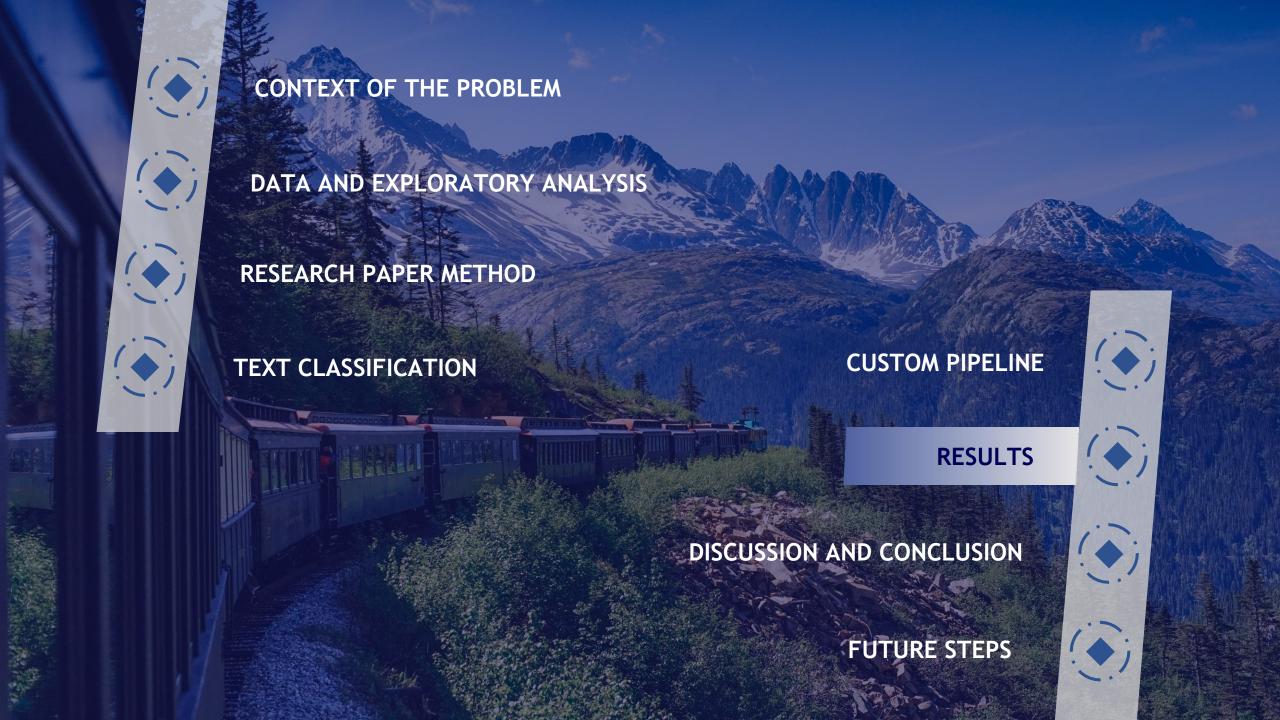
INSIGHTS

The pipeline performs poorly in all minority classes except for 17



Excluding the minority classes, the performance would reach 72.5% F1-score 74% accuracy





F1-Score



The metric we choose to measure the performance of the models and makes the comparison was the F1-Score



Precision

- Measures how accurate a model is at identifying positive cases.
- ☐ It evaluates the model's overall ability to distinguish relevant objects from irrelevant ones

$$Precision = \frac{TP}{TP + FP}$$



Recall

- Ratio of true positives to all actual positives
- Focuses on how well a model captures all the positive cases

$$Recall = \frac{TP}{TP + FN}$$



F1-Score

- It incorporates the trade-off between precision and recall
- The value of the F1 Score lies between 0 and 1
- It is the harmonic mean of precision and recall

$$F1 = \frac{2 \times Precision \times Recall}{Precision + Recall}$$

Pros

- It can handle imbalanced data sets: It penalizes low precision or recall. It rewards when high values for both
- It can be used to compare different classifiers on the same data set

Cons

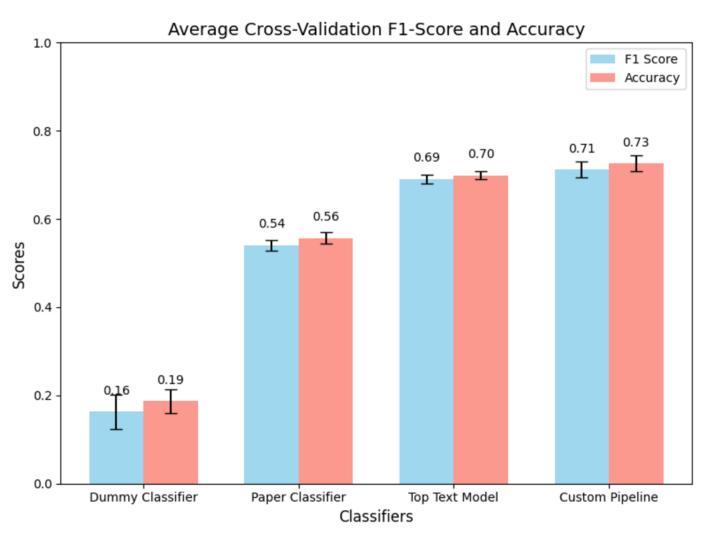
- It assumes that precision and recall are equally important
- It does not consider the distribution of errors or the confidence of predictions

We selected the F1-score because the nature of the problem requires and equilibrium in the predictions of TP and FN considering an imbalanced data set. Also, it is a fair metric to compare different models including the paper's results





Comparison of cross-validation F1 and Accuracy



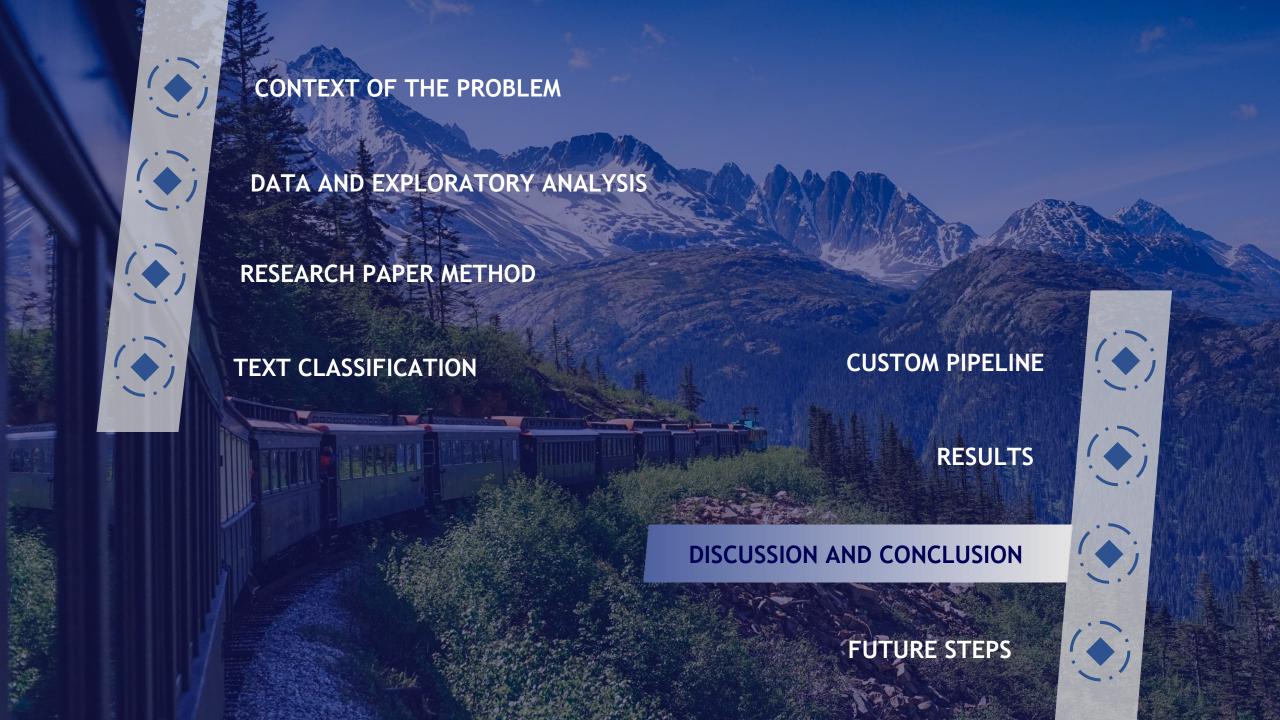
INSIGHTS

All approaches outperform the baseline model of Dummy Classifier.



Custom pipeline slightly increases performance of best text classification approach.





Conclusions - Discussion





The encryption of event and incident codes made it harder to understand the data and see the connections between different events which is crucial for problem solving.





The scarcity of minority class incidents made it nearly impossible to achieve reliable results for those classes.





Representing the events as sequences increased the complexity of the task, yet allows room for creative solutions.



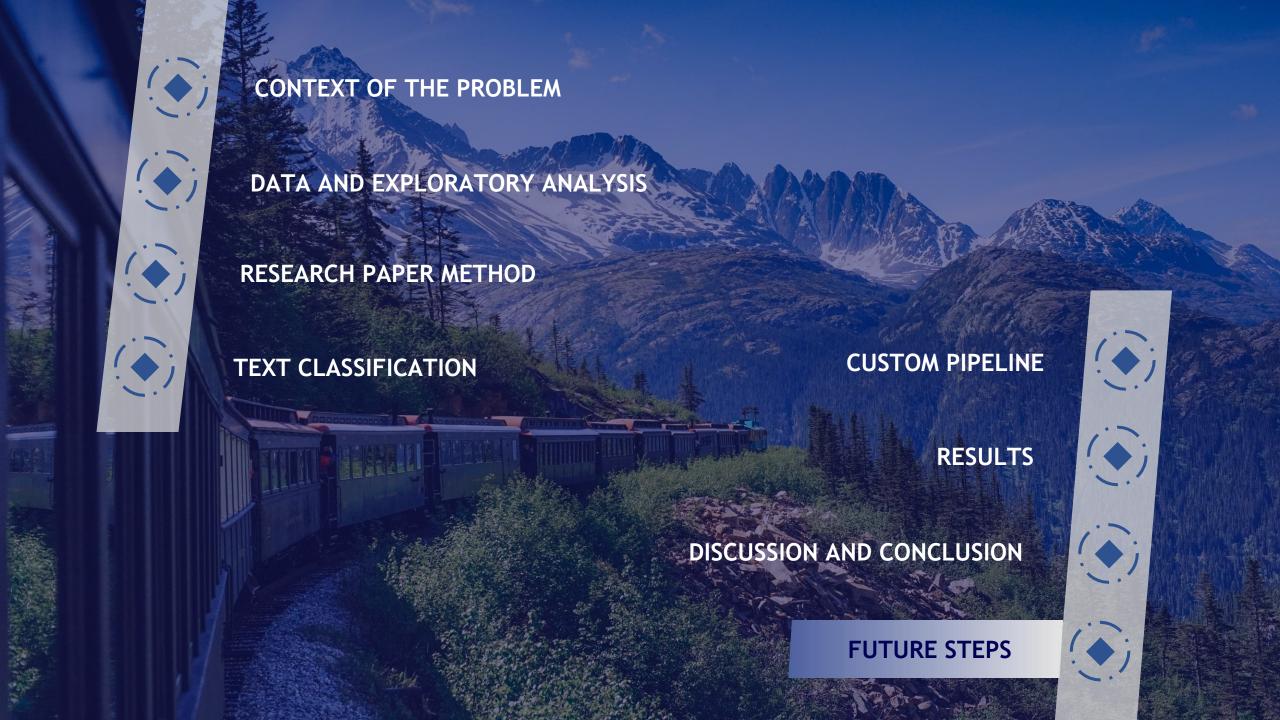


The text classification approach proved efficient due to the limited vocabulary size (a maximum of 917 events) as well as its simplicity and effectiveness.





With more computational resources, better results could be achieved using algorithms like FP-growth or GNNs, especially with more data samples and balanced data.



Predictive maintenance



Predictive maintenance system greatly helps in preventing damage and accidents using artificial intelligence, thereby saving companies time and money.



Predictive maintenance is a data-driven system that anticipates when a particular part of a train or railway is likely to fail.



Condition-based maintenance and predictive maintenance are related maintenance strategies.





Both use real-time monitoring system and analysis to improve effectiveness and reduce costs.

- CBM monitors equipment in real-time to identify potential issues based on current condition and performance.
- The main operator of the system is artificial intelligence, which can be used to predict errors on the railways.

Top 5 Benefits of Predictive Maintenance

- 1 Minimize the duration of system or service unavailability.
- Take measures to avoid harm to both the locomotive and the railway infrastructure.
- 3 Enhance the ability to identify empty spaces or gaps.
- Reduce the occurrence of failures in the point machines.
- The combination of anticipating maintenance needs and ensuring protection against cyber threats.

Companies which had implemented this technology









Predictive maintenance - Implementers



Many companies around the world deal with predictive maintenance because their goal is to provide the best solutions and services to companies operating in all industries.



EKE - Electronics

SmartVision™ Track Condition

Monitoring measures ride smoothness of in-service trains, complementing track geometry measurements.



It detects issues like broken rails and wheel slip, enabling early and cost-effective repairs.

Largest partners





SIEMENS Siemens

Predictive Maintenance is often used in factories and industries with automation systems like Siemens.



These systems produce significant data used to implement supervised machine learning algorithms.

Largest partners





ALSTOM Alstom

HealthHub is a predictive maintenance tool, which utilizes advanced data analytics to monitor the health of trains, infrastructure, and signaling assets.



HealthHub is supported by **TrainScanner**, a **high-tech data capture solution** that measures the condition of key train components.



Predictive maintenance - Best Practices



Predictive maintenance is very popular in the railway industry, more and more companies are using the technology to save money and increase their traffic, like SBB Cargo and GE Transportation.



SBB Cargo plays a critical role in Switzerland's freight services.



To maintain its position as a trusted service provider, SBB Cargo has been using Railnova's remote monitoring solutions.

This allows the company to gather telematic data from its trains and prevent potential failures.



This approach helps to eliminate the inconvenience caused by small component failures.



The São Paulo Metro has created an Albased predictive maintenance system, called the Asset Monitoring System (AMS).



It can forecast potential malfunctions in various systems, including escalators, lifts, trains, tunnel ventilation, and power supply systems.



The AMS provides data to expedite decision-making.



GE Research's predictive maintenance technologies have been incorporated into the Expert on AlertTM solution for GE Transportation.

AlertTM solution provides instant health checks and diagnostic reports for essential locomotive components.



Allowing for proactive planning of resources and parts.

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