

Numerical analysis

Coursework 2

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Abstract

This paper solves the questions from the 2nd Coursework. I study a recurrence relation for the p^{th} derivative of Chebyshev polynomials and solve the differential equation $\ddot{y}(x) - xy(x) = 0$ using this result. Please refer to ⁽¹⁾ for full documentation.

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¹<https://github.com/stefan-obada/chebyshev-poly>

Problem 1

Definition: Chebyshev polynomials are defined by the relation

$$T_n(x) = \cos(n \cdot \arccos(x)) \quad (1)$$

Note: We use this definition, as in the lectures. However, this is just one of the 2 forms of Chebyshev polynomials. Moreover, this one holds only for $x \in [-1, 1]$, but we will work just with the open interval.

Recurrence for derivatives

To derive a recurrence relation for the p^{th} derivative we will firstly derive the differential equation that is verified by T_n and we will proceed by using Leibniz Lemma of differentiation.

Lemma 1: T_k verifies one of the Sturm-Liouville differential equations, which is:

$$(1 - x^2)\ddot{T}_k(x) = k^2 T_k(x) + x\dot{T}_k(x) \quad (2)$$

Proof: Differentiate $T_k(x)$ to obtain:

$$\dot{T}_k(x) = k \cdot \frac{\sin(k \cdot \arccos(x))}{\sqrt{1 - x^2}} \quad (3)$$

$$\begin{aligned} \ddot{T}_k(x) &= \frac{d}{dx} \dot{T}_k(x) = k \cdot \frac{\cos(k \cdot \arccos(x)) \frac{k\sqrt{1-x^2}}{\sqrt{1-x^2}} - \sin(k \cdot \arccos(x)) \cdot \frac{-2x}{2\sqrt{1-x^2}}}{(1 - x^2)} = \\ &= \frac{k^2 T_k(x) + x\dot{T}_k(x)}{1 - x^2} \Rightarrow (1 - x^2)\ddot{T}_k(x) = k^2 T_k(x) + x\dot{T}_k(x) \end{aligned}$$

Lemma 2: (Leibniz formula) For f and g real functions n times differentiable, we have:

$$(fg)^{(n)} = \sum_{k=0}^n \binom{n}{k} \cdot f^{(n-k)} g^{(k)}$$

Lemma 3: The recurrence relation between the derivatives of $T = T_n(x)$ is given by:

$$(1 - x^2)T^{(p)} = (2p - 3) \cdot xT^{(p-1)} + [k^2 + (p - 2)^2] \cdot T^{(p-2)} \quad (4)$$

Proof: Firstly, differentiate (2) from **Lemma 1**, $p - 2$ times. Note that all the terms involved are infinite times differentiable.

$$[(1 - x^2)\ddot{T}]^{(p-2)} = k^2 T^{(p-2)} + [x\dot{T}]^{(p-2)} \quad (5)$$

We proceed by applying **Lemma 2** on LHS and RHS. Note that $(1 - x^2)^{(p)} = 0, \forall p \geq 3$ and $x^{(p)} = 0, \forall p \geq 2$.

$$\begin{aligned} [(1 - x^2)\ddot{T}]^{(p-2)} &= \binom{p-2}{0} (1 - x^2) T^{(p)} + \binom{p-2}{1} (-2x) T^{(p-1)} + \binom{p-2}{2} (-2) T^{(p-2)} \\ &= (1 - x^2) T^{(p)} - (p-2) 2x \cdot T^{(p-1)} - (p-2)(p-3) T^{(p-2)} \\ [x\dot{T}]^{(p-2)} &= \binom{p-2}{0} x T^{(p-1)} + \binom{p-2}{1} T^{(p-2)} = x T^{(p-1)} + (p-2) T^{(p-2)} \end{aligned}$$

By plugging these 2 relations into (5) and rearranging results in:

$$(1 - x^2) T^{(p)} = [(p-2) 2x + x] T^{(p-1)} + [k^2 + (p-2)(p-3) + p-2] T^{(p-2)}$$

which finishes the proof.

Remark 1: $T_n^{(n+1)}(x) = 0$ and $T_n^{(p)}(x) \neq 0, \forall p \leq n$

Remark 2: The initial terms $T_n^{(0)}$ and $T_n^{(1)}$ are defined as in (1) and (3).

Evaluation at Gauss-Lobatto points

We simply evaluate (4) at $x_j = \cos(\frac{j\pi}{N})$, for $j \in (0, 1, \dots, N-1)$:

$$\sin^2(\frac{j\pi}{N}) \cdot T^{(p)} = (2p-3) \cdot \cos(\frac{j\pi}{N}) \cdot T^{(p-1)} + [k^2 + (p-2)^2] \cdot T^{(p-2)} \quad (6)$$

Where the initial terms are:

$$T_k^{(0)}(x_j) = \cos(\frac{kj\pi}{N}) \text{ and } T_k^{(1)}(x_j) = \frac{k \cdot \sin(\frac{kj\pi}{N})}{\sin(\frac{j\pi}{N})} \quad (7)$$

Remark: For $x_N = \cos(\pi)$ we have $T^{(0)}(x_N) = \cos(n\pi) = (-1)^n$ and $T^{(1)}(x_N) = k^2$ by applying L'Hospital rule on (3).

Problem 2

Idea

Step 0: Rescale the initial differential equation on the interval $[-1, 1]$ using the function $u(x) = y(40x)$.

$$\ddot{y}(x) - xy(x) = 0, \quad -40 \leq x \leq 40, \quad y(40) = 0, \quad \dot{y}(-40) = 1$$

is equivalent (due to linearity of the equation and basic differentiation) to:

$$\ddot{u}(x) - 40^3xu(x) = 0, \quad -1 \leq x \leq 1, \quad u(1) = 0, \quad \dot{u}(-1) = 40 \quad (8)$$

Step 1: Write the Chebyshev expansion for $u(x)$ (up to $N < \infty$) and differentiate to obtain a relation for $\ddot{u}(x)$:

$$u(x) = \sum_{k=0}^N a_k T_k(x)$$

$$\ddot{u}(x) = \sum_{k=0}^N a_k \ddot{T}_k(x)$$

where T_k is the k^{th} Chebyshev polynomial and \dot{T}_k its derivative.

Step 2: Evaluate these relations at Gauss-Lobatto points: $x_j = \cos(\frac{j\pi}{N})$, $\forall j = 0, 1, \dots, N$ using (1), (2) and (3):

$$u(x_j) = \sum_{k=0}^N a_k \cdot T_k(x_j)$$

$$\ddot{u}(x_j) = \sum_{k=0}^N a_k \cdot \left[\frac{k^2}{1-x_j^2} T_k(x_j) + \frac{x_j}{1-x_j^2} \dot{T}_k(x_j) \right]$$

Step 3: Rewrite the differential equation $\ddot{u}(x) - 40^3xu(x) = 0$ into matrix form:

$$\ddot{u}(x_j) - 40^3x_ju(x_j) = \sum_{k=0}^N a_k \cdot \left[\left(\frac{k^2}{1-x_j^2} - 40^3x_j \right) \cdot T_k(x_j) + \frac{x_j}{1-x_j^2} \dot{T}_k(x_j) \right] = 0$$

Therefore let $D_{jk} = \left[\left(\frac{k^2}{1-x_j^2} - 40^3x_j \right) \cdot T_k(x_j) + \frac{x_j}{1-x_j^2} \dot{T}_k(x_j) \right]$, for all $j, k \in (0, 1, \dots, N)$.

Step 4: Introduce boundary conditions $u(1) = 0$ and $\dot{u}(-1) = 40$. Note that these are equivalent to: $u(x_0) = 0$ and $\dot{u}(x_N) = 40$, which is therefore equivalent to changing the first and the last rows of D accordingly:

$$\begin{aligned} D_{0,k} &= [T_k(x_0)] \\ D_{N,k} &= [\dot{T}_k(x_N)] \end{aligned}$$

Finally, the equation reduces to solving $\mathbf{a} = (a_1, a_2, \dots, a_N)^T$ in:

$$D\mathbf{a} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 40 \end{bmatrix} \text{ which can be performed via several computational methods.}$$

Remark 1: $y(x)$ can be approximated via: $y(x) = u(\frac{x}{40}) = \sum_{k=0}^N a_k T_k(\frac{x}{40})$, where T_k are the Chebyshev polynomials.

Remark 2: We need to work with the polynomial form of T_k computed recursively (because we need to compute $\dot{T}_k(-1)$).

Implementation (Python)

```
import numpy as np
import matplotlib.pyplot as plt

# Set N
N = 20

# Create vector of evaluations [0, ..., 0, 40]
ev = np.zeros(shape=(N+1,1))
ev[-1] = 40

# Define functions T and its derivative, T_dot recursive
def T(x, k):
    if k==0:
        # 1st Chebyshev polynomial
        return 1
    elif k==1:
        # 2nd Chebyshev polynomial
        return x
    else:
        # Recurrence formula
        return 2*T(x, k-1)*x - T(x, k-2)

def T_dot(x, k):
    if k==0:
        # 1st Chebyshev poly derivative
```

```

        return 0
    elif k==1:
        # 2nd Chebyshev poly derivative
        return 1
    else:
        # Recurrence formula for derivatives
        return 2*T(x, k-1)+2*x*T_dot(x, k-1)-T_dot(x, k-2)

# Create the Gauss-Lobatto linear space, i.e. x_j
X = []
for j in range(N+1):
    X.append(np.cos(j * np.pi / N))

# Create D - matrix function, according to Step 3
def D_jk(j, k):
    return ( (k**2 / (1 - X[j]**2)) - 40**3 * X[j] ) * T(X[j], k) + ( X[j] / (1 - X[j]**2) ) * T_dot(X[j], k)

D = np.zeros(shape=(N+1, N+1)) # Matrix of zeros

for j in range(N+1):
    if j==0:
        # The 1st row (for boundary condition)
        for k in range(N+1):
            D[j, k] = T(X[j], k)
    elif j==N:
        # The last row (for boundary condition)
        for k in range(N+1):
            D[j, k] = T_dot(X[j], k)
    else:
        # Matrix body
        for k in range(N+1):
            D[j, k] = D_jk(j, k)

# Linear solver
D = np.array(D)
a = np.linalg.inv(D).dot(ev)

# Define the solution function y as in Remark 1
def y(x):
    Tk_vector = np.array([T(x/40, k) for k in range(N+1)])
    return Tk_vector.dot(a)[0]

# Plot the solution
linsp = np.linspace(start=-40, stop=40, num=300)
plt.plot(linsp, [y(x) for x in linsp], c='red')

```

Solution plot

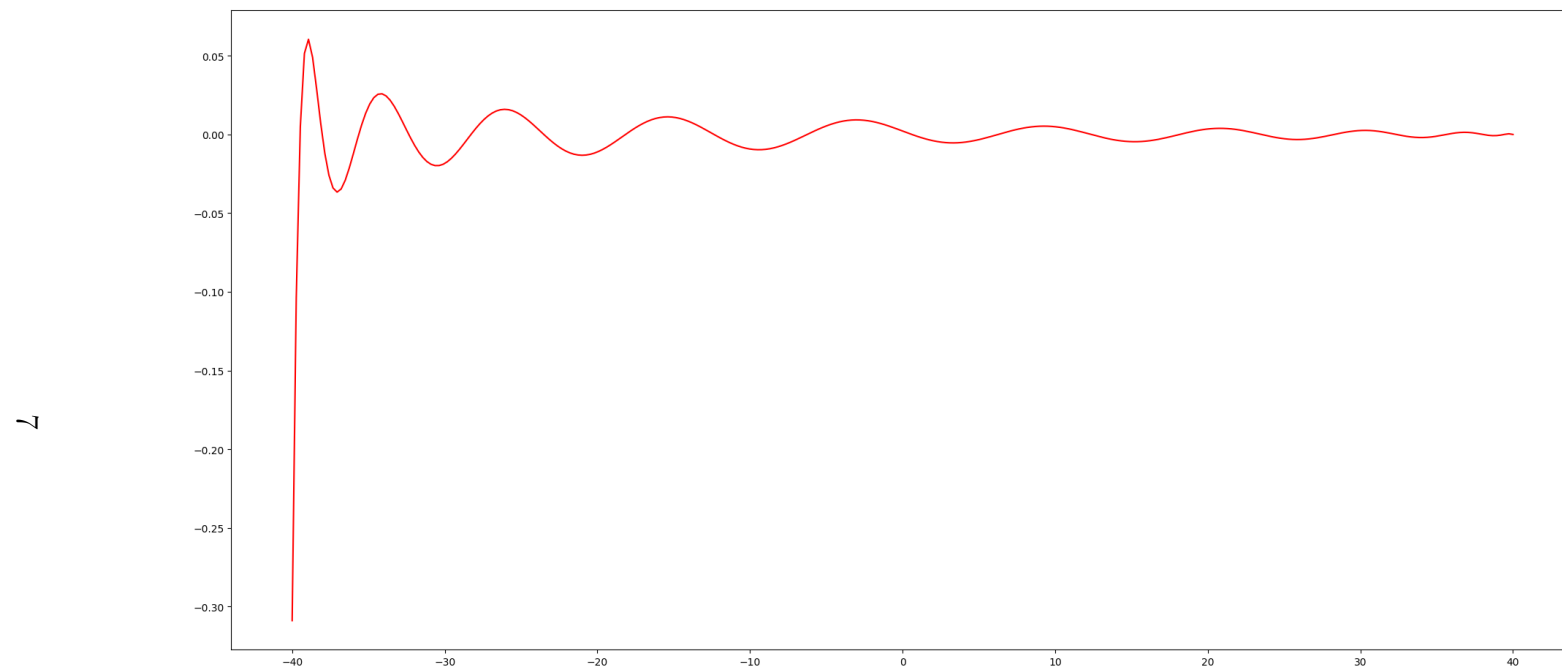


Figure 1: x vs. $y(x)$