

## DG Methods for Advection Problems in Spherical Coordinates in $(r, \theta)$ .

Consider the following transport equation written in conservation form:

$$\begin{aligned} \frac{\partial u(x, t)}{\partial t} + \operatorname{div}(a(x)u(x, t)) &= 0, & x \in \Omega, t > 0. \\ u(x, t) &= g(x, t) & x \in \partial\Omega_{\text{in}} := \{x \in \partial\Omega : a(x) \cdot \mathbf{n} > 0\}, t > 0 \\ u(x, 0) &= u_0(x), & x \in \Omega, \end{aligned}$$

where  $a$  is the transport vector and  $\mathbf{n}$  is the unit outward normal of  $\partial\Omega$ .

Here we are representing the solution  $u$  and the domain  $\Omega$  in spherical coordinates. Let  $x = (r, \theta, \varphi)$  be the spherical coordinate representation of  $x$  and let

$$\Omega := \{(r, \theta, \varphi) : 0 \leq r_0 < r < R, 0 \leq \theta_0 \leq \theta \leq \Theta < \pi, 0 \leq \varphi < 2\pi\}.$$

with  $u(r, \theta, \varphi) = u(x)$ .

Let  $\hat{r} = \hat{r}(r, \theta, \varphi)$ ,  $\hat{\theta} = \hat{\theta}(r, \theta, \varphi)$ ,  $\hat{\varphi} = \hat{\varphi}(r, \theta, \varphi)$  be the orthonormal unit vectors in the  $r$ ,  $\theta$ , and  $\varphi$  directions respectively. We note that  $\hat{r}$ ,  $\hat{\theta}$  and  $\hat{\varphi}$  are not constant. Let  $a = [a_r, a_\theta, a_\varphi]$  be the coordinates of  $a$  w.r.t the basis vectors  $\hat{r}, \hat{\theta}, \hat{\varphi}$ , that is,  $a = a_r \hat{r} + a_\theta \hat{\theta} + a_\varphi \hat{\varphi}$ . For this problem, we assume  $a_r \geq 0$ ,  $a_\theta \geq 0$ , and  $a_\varphi = 0$  are constant. We note that  $a$  is not divergence free, so  $\operatorname{div}(au) \neq a \cdot \nabla u$ . Additionally, since  $a_r, a_\theta \geq 0$ , we have a representation for  $\partial\Omega_{\text{in}}$ :

$$\begin{aligned} \partial\Omega_{\text{in}} &= \{(r_0, \theta, \varphi) : \theta_0 \leq \theta \leq \Theta, 0 \leq \varphi < 2\pi\} \cup \{(r, \theta_0, \varphi) : r_0 < r < R : 0 \leq \varphi < 2\pi\} \\ &=: \Gamma_r \cup \Gamma_\theta \end{aligned}$$

Finally, we note that since  $a_\varphi = 0$ , then  $u$  is constant in  $\varphi$  and thusly  $u = u(r, \theta, t)$ .

We can now formulate the DG scheme. Let  $T$  be a control volume in  $\Omega$  that is a logical rectangle in our spherical coordinates, that is,

$$T = \{(r, \theta, \varphi) : \alpha < r < \beta, \gamma < \theta < \delta, 0 \leq \varphi < 2\pi\}.$$

We test the PDE by a smooth function  $v(r, \theta)$  defined on  $T$  to see

$$\int_T \frac{\partial u(r, \theta, t)}{\partial t} v(r, \theta) dT + \int_T \operatorname{div}(a(r, \theta, \varphi)u(r, \theta, t))v(r, \theta) dT = 0. \quad (1)$$

We parameterize the first integral in (1) and pull out the  $\varphi$  integral to see

$$\begin{aligned} \int_T \frac{\partial u(r, \theta, t)}{\partial t} v(r, \theta) dT &= \int_{r=\alpha}^{\beta} \int_{\theta=\gamma}^{\delta} \int_{\varphi=0}^{2\pi} \frac{\partial u(r, \theta, t)}{\partial t} v(r, \theta) r^2 \sin(\theta) d\varphi d\theta dr \\ &= \int_{\varphi=0}^{2\pi} 1 d\varphi \int_{r=\alpha}^{\beta} \int_{\theta=\gamma}^{\delta} \frac{\partial u(r, \theta, t)}{\partial t} v(r, \theta) r^2 \sin(\theta) d\theta dr \\ &= 2\pi \int_{r=\alpha}^{\beta} \int_{\theta=\gamma}^{\delta} \frac{\partial u(r, \theta, t)}{\partial t} v(r, \theta) r^2 \sin(\theta) d\theta dr \end{aligned}$$

For the second integral in (1) we perform integration by parts to achieve

$$\begin{aligned} \int_T \operatorname{div}(a(r, \theta, \varphi)u(r, \theta, t))v(r, \theta) dT &= - \int_T a(r, \theta, \varphi)u \cdot \nabla v(r, \theta) dT \\ &+ \int_{\partial T} \widehat{a(r, \theta, \varphi)}u \cdot \mathbf{n}(r, \theta, \varphi)v(r, \theta) dS. \end{aligned} \quad (2)$$

where  $\widehat{au}$  is our numerical flux to be determined. We parameterize the first integral on the right hand side of (2) as

$$\begin{aligned} &\int_T a(r, \theta, \varphi)u \cdot \nabla v(r, \theta) dT \\ &= \int_{r=\alpha}^{\beta} \int_{\theta=\gamma}^{\delta} \int_{\varphi=0}^{2\pi} (a_r \hat{r} + a_\theta \hat{\theta} + 0\hat{\varphi})u \cdot \left( \frac{\partial v}{\partial r}(r, \theta)\hat{r} + \frac{1}{r} \frac{\partial v}{\partial \theta}(r, \theta)\hat{\theta} + \frac{1}{r \sin(\theta)} \frac{\partial v}{\partial \varphi}(r, \theta)\hat{\varphi} \right) r^2 \sin(\theta) d\varphi d\theta dr. \end{aligned} \quad (3)$$

Note  $\hat{r}, \hat{\theta}, \hat{\varphi}$  are orthonormal, so (3) becomes

$$\begin{aligned} \int_T a(r, \theta, \varphi)u \cdot \nabla v(r, \theta) dT &= \int_{r=\alpha}^{\beta} \int_{\theta=\gamma}^{\delta} \int_{\varphi=0}^{2\pi} a_r u(r, \theta, t) \frac{\partial v}{\partial r}(r, \theta) r^2 \sin(\theta) d\varphi d\theta dr \\ &+ \int_{r=\alpha}^{\beta} \int_{\theta=\gamma}^{\delta} \int_{\varphi=0}^{2\pi} a_\theta u(r, \theta, t) \frac{1}{r} \frac{\partial v}{\partial \theta}(r, \theta) r^2 \sin(\theta) d\varphi d\theta dr \\ &= 2\pi \int_{r=\alpha}^{\beta} \int_{\theta=\gamma}^{\delta} a_r u(r, \theta, t) \frac{\partial v}{\partial r}(r, \theta) r^2 \sin(\theta) d\theta dr \\ &+ 2\pi \int_{r=\alpha}^{\beta} \int_{\theta=\gamma}^{\delta} a_\theta u(r, \theta, t) \frac{\partial v}{\partial \theta}(r, \theta) r \sin(\theta) d\theta dr \end{aligned} \quad (4)$$

We note that the dependence on  $\varphi$  in  $a$  is lost due to the orthonormality of  $\hat{r}, \hat{\theta}, \hat{\varphi}$ . Specifically,  $\hat{r}(r, \theta, \varphi) \cdot \hat{r}(r, \theta, \varphi) = 1$  which is constant in  $\varphi$ . Identical results hold for  $\hat{\theta}$  and  $\hat{\varphi}$ .

For the surface integrals in (2), we first parameterize the surface into four components with explicit unit outward normals given:

$$\begin{aligned} \partial T &= \{(\alpha, \theta, \varphi) : \gamma < \theta < \delta, 0 \leq \varphi < 2\pi\} & \mathbf{n} &= -\hat{r} \\ &\cup \{(\beta, \theta, \varphi) : \gamma < \theta < \delta, 0 \leq \varphi < 2\pi\} & \mathbf{n} &= \hat{r} \\ &\cup \{(r, \gamma, \varphi) : \alpha < r < \beta, 0 \leq \varphi < 2\pi\} & \mathbf{n} &= -\hat{\theta} \\ &\cup \{(r, \delta, \varphi) : \alpha < r < \beta, 0 \leq \varphi < 2\pi\} & \mathbf{n} &= \hat{\theta}. \end{aligned}$$

We then define the numerical flux as the upwind flux defined by

$$\widehat{au} = a\{u\} + \frac{|a(r, \theta, \varphi) \cdot \mathbf{n}(r, \theta, \varphi)|}{2} [u]$$

where  $\{u\} = \frac{u^+ + u^-}{2}$  and  $[u] = u^+ \mathbf{n}^+ + u^- \mathbf{n}^-$ . Note that since  $\mathbf{n}^\pm$  are only signed versions of  $\hat{r}$  and  $\hat{\theta}$ , then the orthonormality of  $\hat{r}, \hat{\theta}, \hat{\varphi}$  removes any dependence on  $\varphi$  in the integral

evaluation, thus we explicitly evaluate the surface integral in (2) as

$$\begin{aligned}
\int_{\partial T} a(\widehat{r, \theta, \varphi}) u \cdot \mathbf{n}(r, \theta, \varphi) v(r, \theta) \, dS = & \\
& - 2\pi \int_{\theta=\gamma}^{\delta} (a_r \hat{r} \{u(\alpha, \theta, t)\} + \frac{|a_r|}{2} [u(\alpha, \theta, t)]) \cdot \hat{r} v(\alpha, \theta) \alpha^2 \sin(\theta) \, d\theta \\
& + 2\pi \int_{\theta=\gamma}^{\delta} (a_r \hat{r} \{u(\beta, \theta, t)\} + \frac{|a_r|}{2} [u(\beta, \theta, t)]) \cdot \hat{r} v(\beta, \theta) \beta^2 \sin(\theta) \, d\theta \\
& - 2\pi \int_{r=\alpha}^{\beta} (a_\theta \hat{\theta} \{u(r, \gamma)\} + \frac{|a_\theta|}{2} [u(r, \gamma)]) \cdot \hat{\theta} v(r, \gamma) r \sin(\gamma) \, dr \\
& + 2\pi \int_{r=\alpha}^{\beta} (a_\theta \hat{\theta} \{u(r, \delta)\} + \frac{|a_\theta|}{2} [u(r, \delta)]) \cdot \hat{\theta} v(r, \delta) r \sin(\delta) \, dr
\end{aligned} \tag{5}$$

If a portion of the surface lies on  $\partial\Omega_{\text{in}}$ , that is,  $\alpha = r_0$  or  $\gamma = \theta_0$ , then replace  $\widehat{au}$  with  $ag$ . Those surface contributions become

$$\begin{aligned}
& - 2\pi \int_{\theta=\gamma}^{\delta} a_r g(r_0, \theta) v(r_0, \theta) r_0^2 \sin(\theta) \, d\theta, \text{ and} \\
& - 2\pi \int_{r=\alpha}^{\beta} a_\theta g(r, \theta_0) v(r, \theta_0) r \sin(\theta_0) \, dr
\end{aligned}$$

respectively.

Note that each integral contains a  $2\pi$  that can be dropped.

Since  $u$  and  $v$  in the DG scheme are meant to be a sum of separable functions, then if we let  $u = \psi_r(r)\psi_\theta(\theta)$  and  $v = \xi_r(r)\xi_\theta(\theta)$ , the volume integrals in (4) become

$$\begin{aligned}
\int_T a(r, \theta, \varphi) u \cdot \nabla v(r, \theta) \, dT & \\
& = 2\pi \int_{r=\alpha}^{\beta} a_r \psi_r(r) \xi'_r(r) r^2 \, dr \int_{\theta=\gamma}^{\delta} \psi_\theta(\theta) \xi_\theta(\theta) \sin(\theta) \, d\theta \\
& \quad + 2\pi \int_{r=\alpha}^{\beta} \psi_r(r) \xi_r(r) r \, dr \int_{\theta=\gamma}^{\delta} a_\theta \psi_\theta(\theta) \xi'_\theta(\theta) \sin(\theta) \, d\theta
\end{aligned} \tag{6}$$

and the surface integrals in (5) become

$$\begin{aligned}
\int_{\partial T} a(\widehat{r, \theta, \varphi}) u \cdot \mathbf{n}(r, \theta, \varphi) v(r, \theta) \, dS = & \\
& - 2\pi (a_r \{\psi_r(\alpha)\} + \frac{|a_r|}{2} [\psi_r(\alpha)]) \xi_r(\alpha) \alpha^2 \int_{\theta=\gamma}^{\delta} \varphi_\theta(\theta) \xi_\theta(\theta) \sin(\theta) \, d\theta \\
& + 2\pi (a_r \{\psi_r(\beta)\} + \frac{|a_r|}{2} [\psi_r(\beta)]) \xi_r(\beta) \beta^2 \int_{\theta=\gamma}^{\delta} \varphi_\theta(\theta) \xi_\theta(\theta) \sin(\theta) \, d\theta \\
& - 2\pi \int_{r=\alpha}^{\beta} \psi_r(r) \xi_r(r) r \, dr (a_\theta \{\psi_\theta(\gamma)\} + \frac{|a_\theta|}{2} [\psi_\theta(\gamma)]) \xi_\theta(\gamma) \sin(\gamma) \\
& + 2\pi \int_{r=\alpha}^{\beta} \psi_r(r) \xi_r(r) r \, dr (a_\theta \{\psi_\theta(\delta)\} + \frac{|a_\theta|}{2} [\psi_\theta(\delta)]) \xi_\theta(\delta) \sin(\delta).
\end{aligned} \tag{7}$$

Therefore, we need to calculate the following 1D integrals:

$$\begin{aligned}
& \int_{r=\alpha}^{\beta} a_r \psi_r(r) \xi'_r(r) r^2 \, dr \\
& \int_{r=\alpha}^{\beta} \psi_r(r) \xi_r(r) r \, dr \\
& \int_{\theta=\gamma}^{\delta} a_{\theta} \psi_{\theta}(\theta) \xi'_{\theta}(\theta) \sin(\theta) \, d\theta \\
& \int_{\theta=\gamma}^{\delta} \psi_{\theta}(\theta) \xi_{\theta}(\theta) \sin(\theta) \, d\theta
\end{aligned}$$