

GPR Quick guide

The guide below provides the basic information to assemble the GPR system, and collect the GPR data, taken from the [PulseEKKO GPR user manual](#) and a reconnaissance trip on 4+5 March, 2023 by Stefan Nielsen, Jenny Jenkins and Jeroen van Hunen.

ASSEMBLY

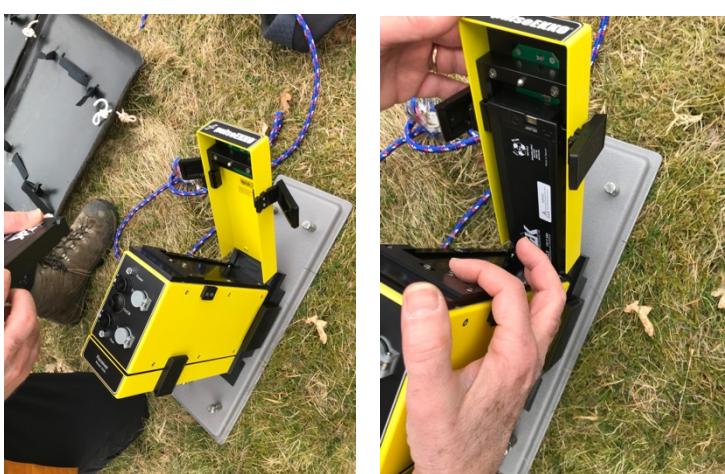


1. Transmitter (T)
2. Receiver (R)
3. Power cables
4. DVL battery
5. T/R Batteries
6. 200-Mhz antennas
7. Fibre-optics cables
8. DVL
9. Adjustable handles

1) Layout of the GPR equipment in the two storage boxes

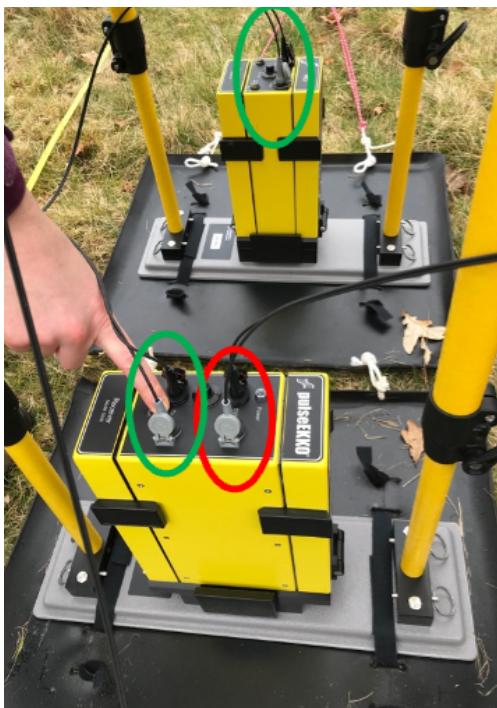


2) Place the transmitter and receiver electronic boxes each onto the black mounting blocks in the middle of an antenna, ensuring the brass sockets connect to the brass pins in the antenna. Connect the electronics boxes to the mounting block using the two plastic draw latch connectors.



3) Place one battery on each side of each of the electronics boxes. Make sure the positive (+) terminal faces inward toward the electronics. NOTE: The battery is “keyed” with a notch in one side so it only fits properly in this orientation. Close and latch the battery covers.

- 4) To attach the adjustable handle to the antenna, place the handle blocks over the 4 posts on the antenna and insert the pins to secure. Adjust the handle height by loosening the two black levers by hand. Move the handle to the desired height and then retighten the levers. Once the handles are adjusted, lock them by tightening the levers until they click into place.



- 5) Attach antennas to the skid plates with Velcro ties.
 6) Connect cables: one connection runs a fibre-optic cable from the back of the DVL to the receiver (red circles) and then another from the receiver to the transmitter (green circles). Make sure the colour on the jackets match the colour of the sockets: black to black and grey to grey.

- 7) Connect power cable from DVL (blue circle) to DVL battery that can be carried in the designated backpack.

DATA COLLECTION

- 8) First power up the transmitter and receiver (by pressing the On/Off button on the top of the units). The red Power LED on the top of the unit will flash five times and then stay on to indicate the unit is ready for operation. If the unit doesn't turn on, check that the transmitter and receiver batteries are fully charged and installed correctly.
 9) To start the DVL system, press the red power button. The LED on the front panel will light up red. The smaller led directly above it indicates the battery status: from green (>20%) to orange to red (<10%).
 10) The DVL is operated through touch-screen or the buttons below the screen:

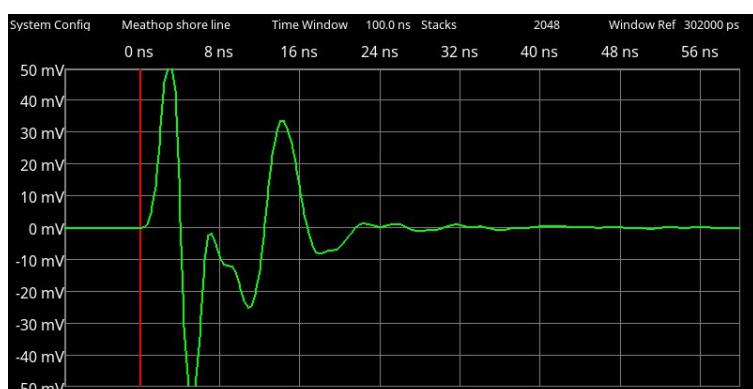
Item	Description
Menu Buttons 	The yellow buttons labelled 1 to 8 correspond to menu choices that appear on the screen.
4-way directional keypad 	Controls Up/Down/Left/Right operations in certain menus.
Camera 	Saves an image of what is displayed on the screen.
Asterisk / Special Function 	Used for adding Flags during data acquisition.

System Configuration: Meathop shore line 

GPR Parameters		Survey Parameters	
Frequency:	200 MHz	Survey Type:	Reflection
Time Window:	100 ns (4.6 m)	Start Offset:	0 m
Step Size:	0.250 m	GPR Trigger:	Manual (Keypad / Bluetooth)
Sampling Interval:	Normal (400 ps)	Bluetooth:	Not Connected
Stacks:	32768	Antenna Separation:	0.5 m
Transmitter:	pE PRO Auto	Antenna Polarization:	Broadside
Receiver:	pulseEKKO Ultra	Antenna Orientation:	Perpendicular
Velocity:	0.1 m/ns	GPS:	Internal

11) Choose System Configuration. This will show the screen on the left. Choose a survey name (white bar on top). Small antennas are for 200 MHz recordings (large ones are for 50 MHz). Nr of stacks is a multiple of two: 32768 doesn't take too long to record (<1 sec) but gives high signal/noise

results. The skid plates on the photo above are set up for a 0.5 m antenna separation and 'broadside' polarisation. Set the step size to the distance between subsequent measurements. Press 'back' to go back to the main menu.



12) Choose 'scope mode': Scope Mode enables you to correctly set the First Break. The red line should be as indicated in the figure to the left. If not, adjusting can be done by the 'Auto Detect First Break' option, although this does not always work well for the high frequencies used in our setup. With the arrows you can adjust it manually (large arrows to start moving, press again to stop moving; small arrows move the red line by a small increment).

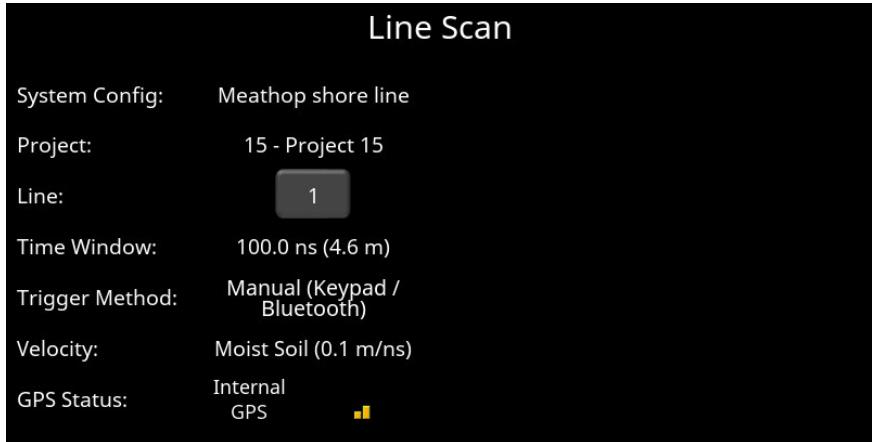
Once finished, press 'back'.

Run System
Project15 was last collected on March 5 2023
Project Summary

Name:	Project15	
Lines:	0	
Grids:	0	
Screenshots:	5	

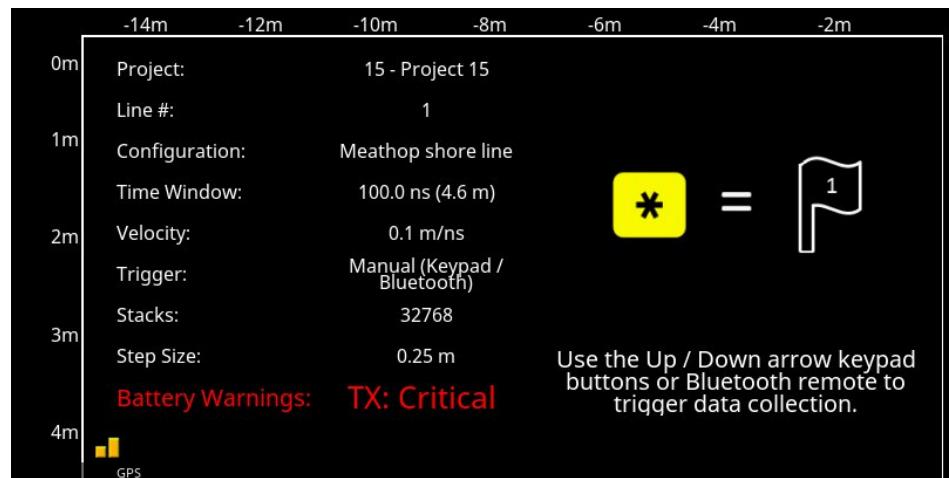
System Configuration: Meathop shore line

13) Choose 'run system' to select the name of the project. Then press 'back'.

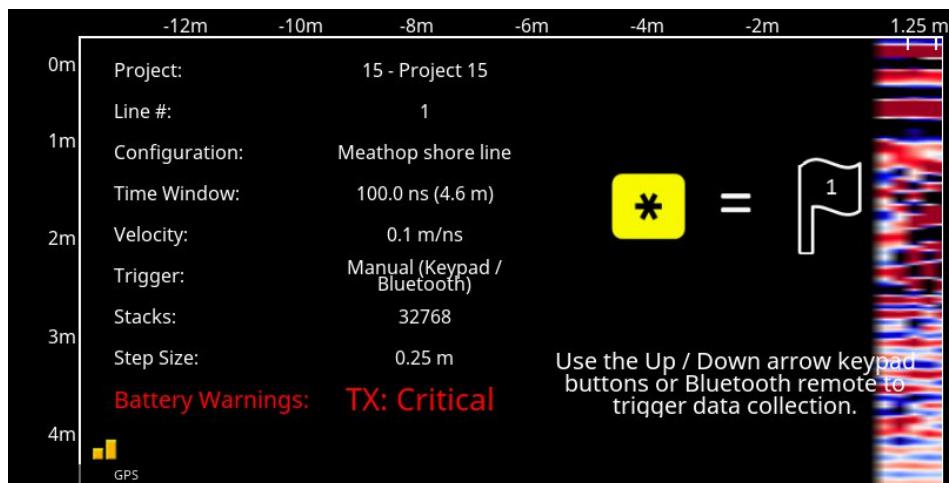


14) Choose ‘line scan’ to start the actual survey. Note 1: the system always seems to complain about low battery. Note 2: don’t press the ‘no save mode’. Note 3: try to keep electronics (such as the GPS system) away from the GPR during measurements.

15) Press ‘start’. Then press the ‘down’ button to make a single measurement (a beep will sound during the measurement: don’t move the device during this beep). Keep pressing the down button to make new measurements.



A display of results will slowly move in from the right of the screen. Once finished, press ‘stop’ and then ‘back’.



SYNC WITH THE GPS

Configure the GPS for streaming through the serial port:

- 1) GPS Settings > Position Streaming 1 > Serial RS232*

*(if the serial port says “port already used for correction”, you need to go to Base Settings and select “Base mode off”)
- 2) In Serial hit EDIT button on the side (pencil symbol):
- 3) Select Baud rate 9600
- 4) Select NMEA Settings >
 - a. GN

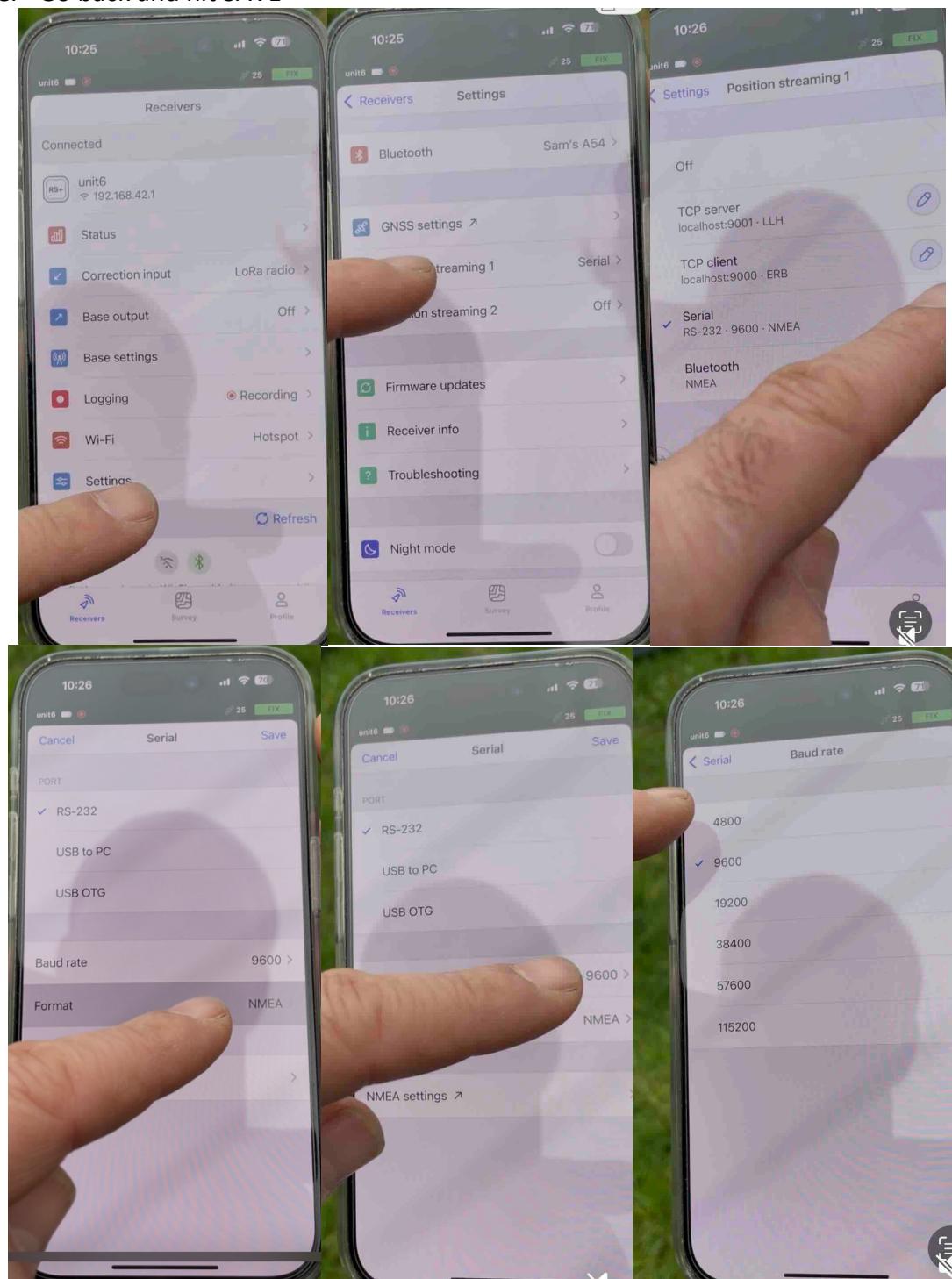
b. GGA at 5 Hz*

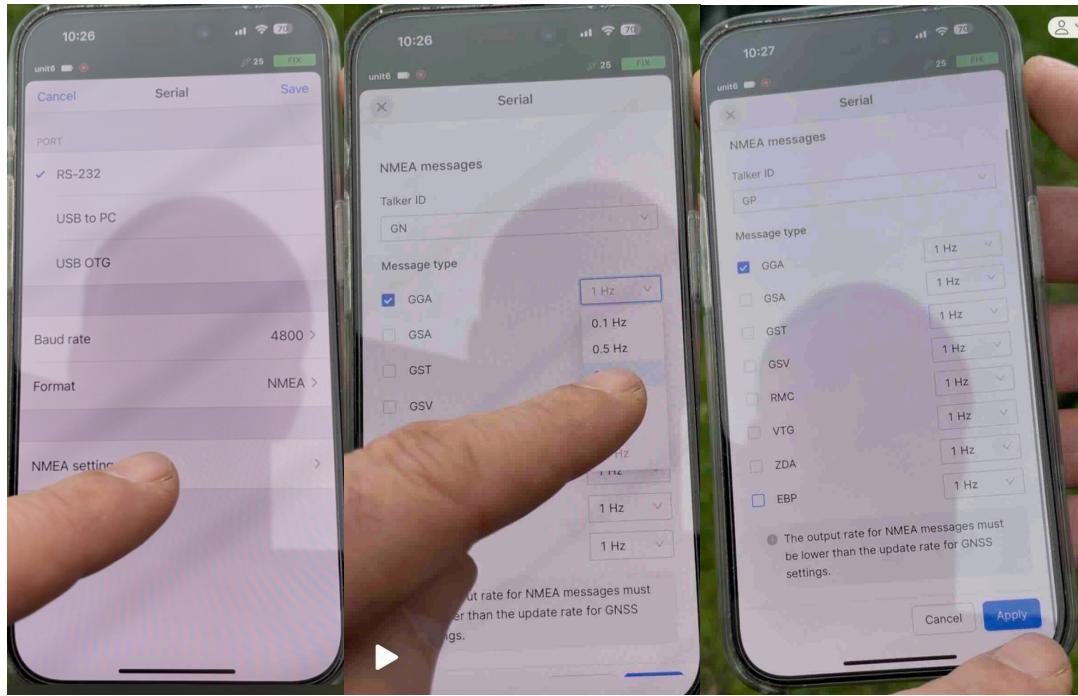
*If it does not allow the 5HZ, you need to increase the frequency in the GNSS settings first.

c. Deselect all other fields (GSA, GST,)

d. Hit APPLY at bottom of tab

e. Go back and hit SAVE





Configure the GPR to receive position through the serial port:

- 1) Connect the RS232 cable [one end serial plug in the GPR terminal, other end round Lemo plug in the GPS].
- 2) Make sure all is connected and power is on, also on the receiver/transmitter (these need to be on and connected before turning on the terminal)
- 3) System Configuration on the terminal
- 4) Select GPS > External
- 5) Set Baud rate 9600
- 6) GPS test (strings or info). Info will show position if connection works, or N/A if not. Strings will show a stream of locations that are refreshed dynamically on the screen if connection works, or nothing if not. In both cases failed connection will print message "test failed". Sometimes restarting transmitter, receiver and GPR terminal helps.
- 7) Go back to System Configuration and set "GPR trigger" to "FREE RUN"