

PulseEKKO GPR Quick Guide

The guide below provides the basic information on how to assemble the GPR system, and collect the GPR data, taken from the [PulseEKKO GPR user manual](#) and a reconnaissance trip on 4th -5th March, 2023 by Stefan Nielsen, Jenny Jenkins and Jeroen van Hunen.

Assembly



1) Layout of the GPR equipment in the two storage boxes



2) Place the transmitter and receiver electronic boxes each onto the black mounting blocks in the middle of an antenna, ensuring the brass sockets connect to the brass pins in the antenna. Connect the electronics boxes to the mounting block using the two plastic draw latch connectors.



- 3) Place one battery on each side of each of the electronics boxes. Make sure the positive (+) terminal faces inward toward the electronics. NOTE: The battery is “keyed” with a notch in one side, so it only fits properly in this orientation. Close and latch the battery covers – **Don’t try to force anything if it won’t go!**

- 4) To attach the adjustable handle to the antenna, place the handle blocks over the 4 posts on the antenna and insert the pins to secure. Adjust the handle height by loosening the two black levers by hand. Move the handle to the desired height and then retighten the levers. Once the handles are adjusted, lock them by tightening the levers until they click into place.



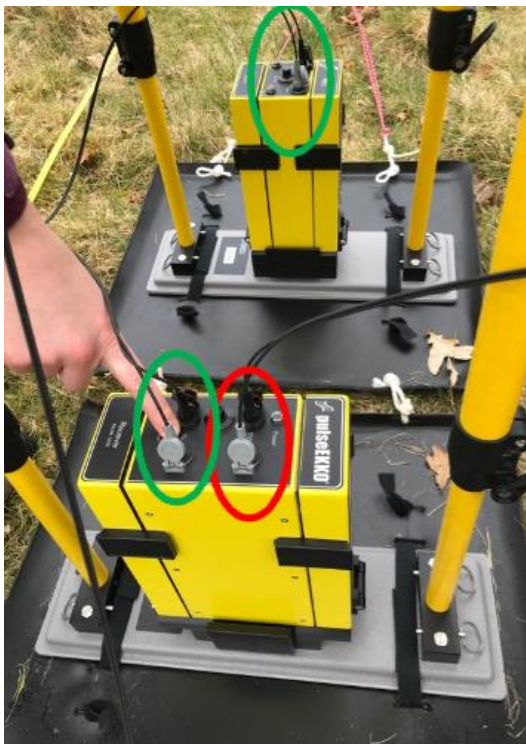
- 5) Attach antennas to the skid plates with Velcro ties.

- 6) Connect the cables: one connection runs a fibre-optic cable from the back of the DVL to the receiver (red circles) and then another from the receiver to the transmitter (green circles). Make sure the colour on the jackets match the colour of the sockets: black to black and grey to grey.







FIBRE OPTIC CABLES ARE DELICATE & EXPENSIVE – HANDLE WITH CARE

- 7) Connect the power cable from DVL viewer (blue circle) to the DVL battery that can be carried in the designated backpack.



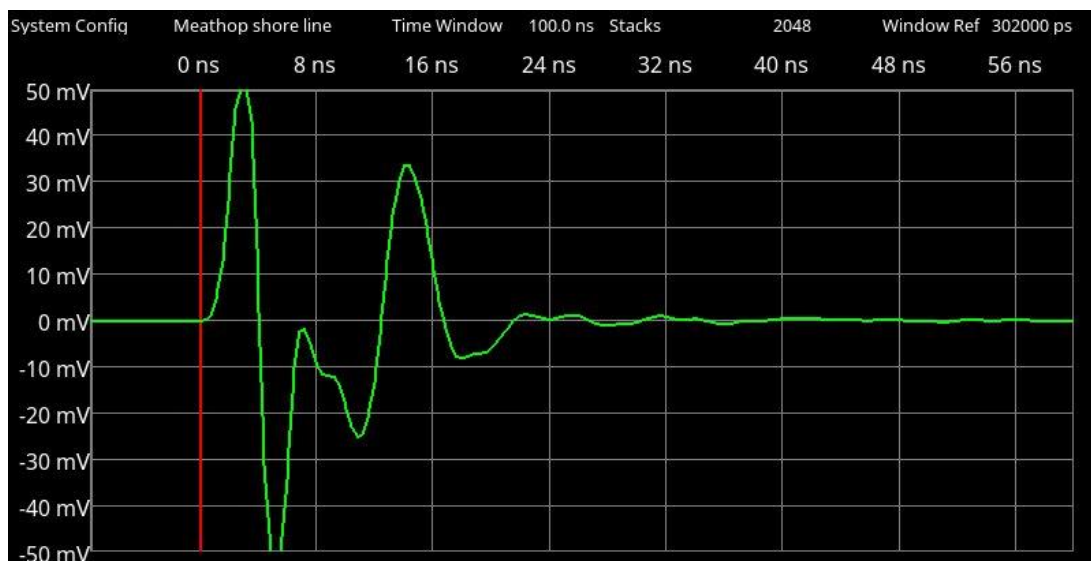
Data Collection

- 8) First power up the transmitter and receiver (by pressing the On/Off button on the top of the units). The red Power LED on the top of the unit will flash five times and then stay on to indicate the unit is ready for operation. If the unit doesn't turn on, check that the transmitter and receiver batteries are fully charged and installed correctly.
- 9) To start the DVL viewer system, press the red power button. The LED on the front panel will light up red. The smaller LED directly above it indicates the battery status: from green (>20%) to orange to red (<10%).
- 10) The DVL is operated through the touch-screen or the buttons below the screen:

Item	Description
Menu Buttons 	The yellow buttons labelled 1 to 8 correspond to menu choices that appear on the screen.
4-way directional keypad 	Controls Up/Down/Left/Right operations in certain menus.
Camera 	Saves an image of what is displayed on the screen.
Asterisk / Special Function 	Used for adding Flags during data acquisition.

- 11) Choose System Configuration. This will show the screen below. Choose a survey name (white bar on top). Small antennas are for 200 MHz recordings (large ones are for 50 MHz). The number of stacks is a multiple of two: 32768 doesn't take too long to record (<1 sec) but gives high signal/noise results. The skid plates on the photo above are set up for a 0.5 m antenna separation and 'broadside' polarisation. Set the step size to the distance between subsequent measurements. Press 'back' to go back to the main menu.

System Configuration:		Meathop shore line	
GPR Parameters		Survey Parameters	
Frequency:	200 MHz	Survey Type:	Reflection
Time Window:	100 ns (4.6 m)	Start Offset:	0 m
Step Size:	0.250 m	GPR Trigger:	Manual (Keypad / Bluetooth)
Sampling Interval:	Normal (400 ps)	Bluetooth:	Not Connected
Stacks:	32768	Antenna Separation:	0.5 m
Transmitter:	pE PRO Auto	Antenna Polarization:	Broadside
Receiver:	pulseEKKO Ultra	Antenna Orientation:	Perpendicular
Velocity:	0.1 m/ns	GPS:	Internal



- 12) Choose 'scope mode': Scope Mode enables you to correctly set the First Break. The red line should be as indicated in the figure to the left. If not, adjusting can be done by the 'Auto Detect First Break' option (can crash the system...), although this does not always work well for the high frequencies used in our setup. With the arrows you can adjust it manually (large arrows to start moving, press again to stop moving; small arrows move the red line by a small increment). Once finished, press 'back'. Worth noting that you will be able to set the first break of each trace during post-processing as well.

13) Choose 'run system' to select the name of the project. Then press 'back'.

The screenshot shows a 'Run System' interface with a black background and white text. At the top, it says 'Run System' in white. Below that, in red text, it says 'Project15 was last collected on March 5 2023'. Underneath is the title 'Project Summary'. The main content area lists several fields: 'Name:' with a value of 'Project15' in a white box; 'Lines:' with a value of '0'; 'Grids:' with a value of '0'; 'Screenshots:' with a value of '5'; and 'System Configuration:' with a value of 'Meathop shore line'. There is a small edit icon (pencil) next to the 'Project15' box.

Field	Value
Name:	Project15
Lines:	0
Grids:	0
Screenshots:	5
System Configuration:	Meathop shore line

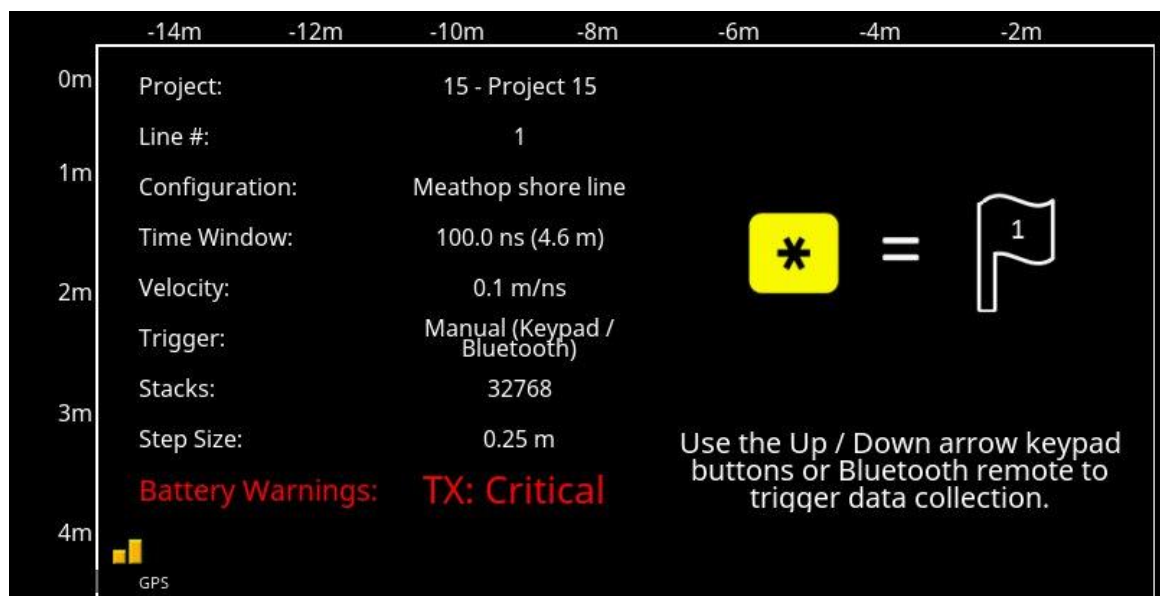
14) Choose 'line scan' to start the actual survey.

The screenshot shows a 'Line Scan' interface with a black background and white text. The title 'Line Scan' is at the top. Below it, several parameters are listed: 'System Config:' with 'Meathop shore line'; 'Project:' with '15 - Project 15'; 'Line:' with '1' in a white box; 'Time Window:' with '100.0 ns (4.6 m)'; 'Trigger Method:' with 'Manual (Keypad / Bluetooth)'; 'Velocity:' with 'Moist Soil (0.1 m/ns)'; and 'GPS Status:' with 'Internal GPS' and a small yellow signal icon.

Parameter	Value
System Config:	Meathop shore line
Project:	15 - Project 15
Line:	1
Time Window:	100.0 ns (4.6 m)
Trigger Method:	Manual (Keypad / Bluetooth)
Velocity:	Moist Soil (0.1 m/ns)
GPS Status:	Internal GPS

- Note 1: the system always seems to complain about low battery "battery critically low" message – this is inaccurate – ignore it.
- Note 2: DON'T press the 'no save mode'.
- Note 3: try to keep electronics (such as the GPS system) away from the GPR during measurements, as they will interfere.

15) Press 'start'. Then press the 'down' button to make a single measurement (a beep will sound during the measurement: don't move the device during this beep). Keep repeatedly pressing the down button to make new measurements.



16) A display of results will slowly move in from the right of the screen. Once finished, press 'stop' and then 'back'.

You can adjust the display of results, changing the colour palette, gain or depth extent shown using the viewing options at the bottom of the screen

