blatt04_nitschke_grisard

November 29, 2018

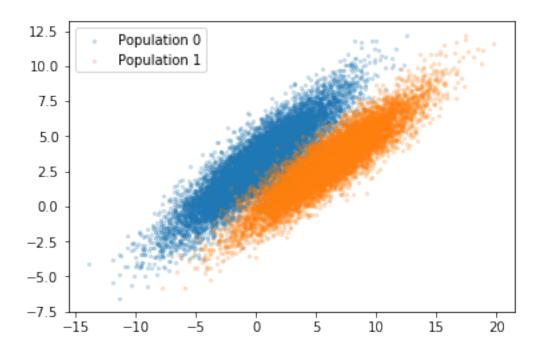
1 Blatt 4

1.1 Aufgabe 10: Zwei Populationen

```
In [1]: import numpy as np
        import matplotlib.pyplot as plt
        import pandas as pd
In [2]: mux0 = 0
       muy0 = 3
        sigx0 = 3.5
        sigy0 = 2.6
        cor0 = 0.9
        cov0 = cor0 * sigx0 * sigy0
        cov_mat0 = np.array([[sigx0**2, cov0], [cov0, sigy0**2]])
In [3]: population0_10000 = np.random.multivariate_normal([mux0, muy0], cov_mat0, 10000)
In [4]: mux1 = 6
       sigx1 = 3.5
       a = -0.5
       b = 0.6
       var_yx = 1
       muy1 = a + b * mux1
        sigy1 = np.sqrt(b**2 * sigx1**2 + var_yx)
        cor1 = np.sqrt(b**2 * sigx1**2 / sigy1**2)
        cov1 = cor1 * sigx1 * sigy1
        cov_mat1 = np.array([[sigx1**2, cov1], [cov1, sigy1**2]])
       print(muy1, sigy1, cor1)
3.0999999999999 2.3259406699226015 0.9028605188239304
In [5]: population1 = np.random.multivariate_normal([mux1, muy1], cov_mat1, 10000)
```

b) Zeichne Scatter-Plots:

Out[6]: <matplotlib.legend.Legend at 0x7f0a670799e8>



```
population0_1000_df.to_hdf('sample.hdf5', key = 'population0_1000')
population1_df.to_hdf('sample.hdf5', key = 'population1')
```

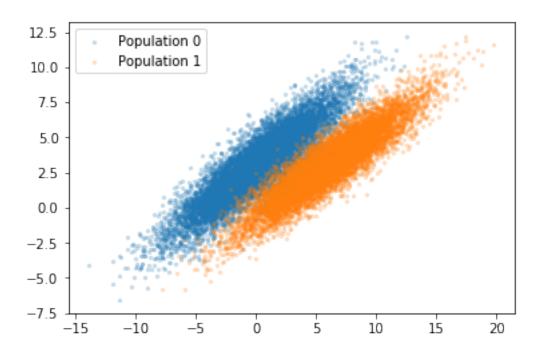
1.2 Aufgabe 11: Fisher-Diskriminante: Per Hand

siehe Abgabe

1.3 Aufgabe 12: Fisher-Diskriminante: Implementierung

Lade Daten:

```
In [8]: import pandas as pd
        P_0 = pd.read_hdf('sample.hdf5', key='population0_10000')
        P_1 = pd.read_hdf('sample.hdf5', key='population1')
        P 0.head()
Out[8]:
                  х
        0 -1.218659 3.137841
        1 -6.903642 -1.974535
        2 1.571834 3.171044
        3 0.575122 4.127489
        4 -2.033564 0.298584
  a) Berechne Mittelwerte:
In [9]: mu0 = np.matrix([P_0.x.mean(), P_0.y.mean()]).T
        mu1 = np.matrix([P_1.x.mean(), P_1.y.mean()]).T
  b) Berechne Kovarianzmatrizen:
In [10]: V_0 = P_0.cov()
         V_1 = P_0.cov()
In [11]: plt.scatter(P_0.x, P_0.y, s = 5, alpha = 0.2, label = 'Population 0')
         plt.scatter(P_1.x, P_1.y, s = 5, alpha = 0.2, label = 'Population 1')
         plt.legend()
Out[11]: <matplotlib.legend.Legend at 0x7f0a66fd9390>
```



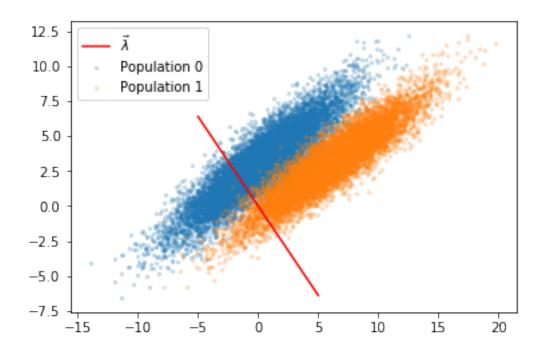
c) Konstruiere $\vec{\lambda}$:

[-1.27746743]

Die Geradengleichung lautet:

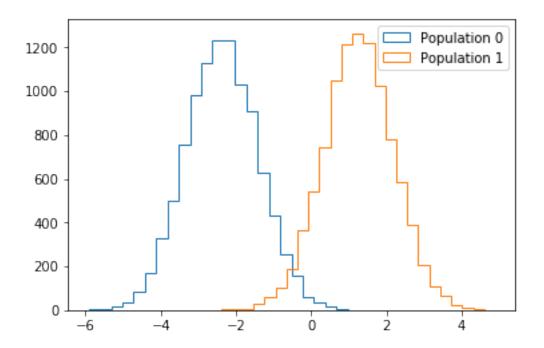
$$y(x) \approx -1.269 \cdot x$$

Out[14]: <matplotlib.legend.Legend at 0x7f0a61e2b7b8>



d) Stelle die Projektionen in einem Histogramm dar:

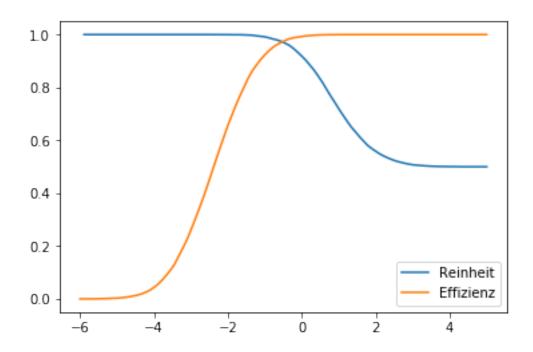
Out[16]: <matplotlib.legend.Legend at 0x7f0a61e04208>



```
e)
In [17]: def precision(signal, noise, cut):
             true_pos = np.array([len(signal[signal < cut]) for cut in cut])</pre>
             false_pos = np.array([len(noise[noise < cut]) for cut in cut])</pre>
             return true_pos / (true_pos + false_pos)
In [18]: def recall(signal, noise, cut):
             true_pos = np.array([len(signal[signal < cut]) for cut in cut])</pre>
             false_neg = np.array([len(signal[signal > cut]) for cut in cut])
             return true_pos / (true_pos + false_neg)
In [19]: signal = projection_0
         noise = projection_1
         lam_cut = np.linspace(-6, 5, 100)
         plt.plot(lam_cut, precision(signal, noise, lam_cut),
                  label = 'Reinheit')
         plt.plot(lam_cut, recall(signal, noise, lam_cut),
                  label = 'Effizienz')
         plt.legend()
```

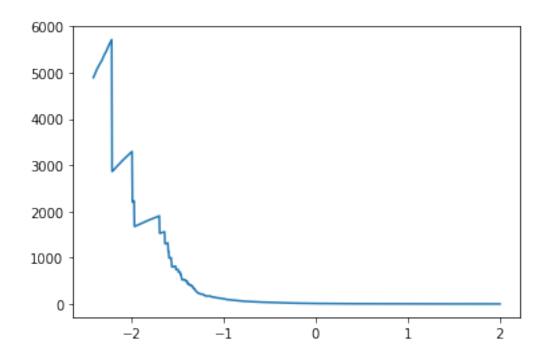
/home/stefan/.local/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:4: RuntimeWarn after removing the cwd from sys.path.

```
Out[19]: <matplotlib.legend.Legend at 0x7f0a61f621d0>
```



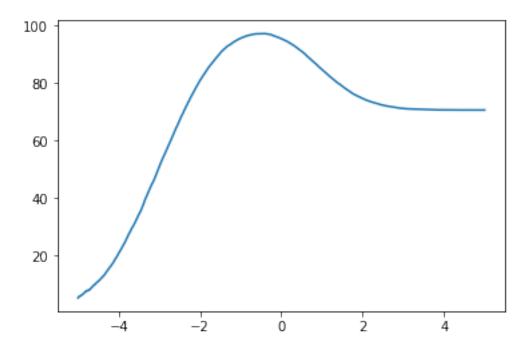
f) Untersuche Signal-Untergrundverhältnis:

Out[21]: -2.211143186757372



g) Untersuche Signifikanz:

Out [23]: -0.4554554554554553



1.3.1 Nun alles nochmal mit der kleineren Population

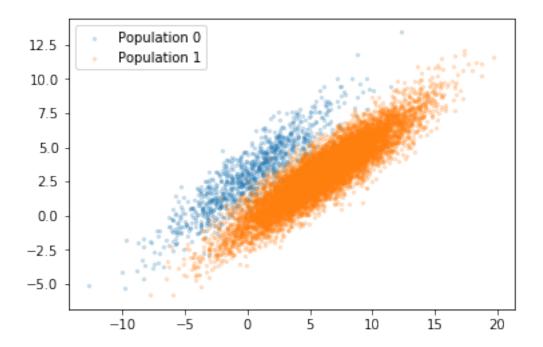
Lade Daten:

b) Berechne Kovarianzmatrizen:

In [26]:
$$V_0 = P_0.cov()$$

 $V_1 = P_0.cov()$

Out[27]: <matplotlib.legend.Legend at 0x7f0a61e9d978>



c) Konstruiere $\vec{\lambda}$:

```
In [28]: S_0 = np.sum([(xi.T - mu0) * (xi.T - mu0).T for xi in np.matrix(P_0)], axis = 0)
    S_1 = np.sum([(xi.T - mu1) * (xi.T - mu1).T for xi in np.matrix(P_1)], axis = 0)
    S_W = np.matrix(S_0 + S_1)
```

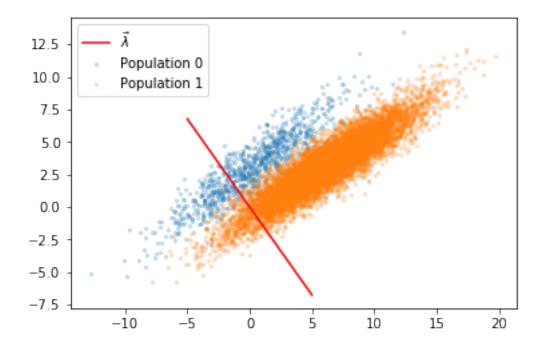
[-1.35197869]

Die Geradengleichung lautet:

$$y(x) \approx -1.329 \cdot x$$

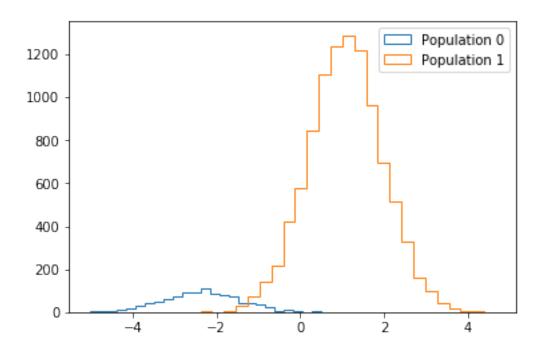
```
plt.scatter(P_0.x, P_0.y, s = 5, alpha = 0.2, label = 'Population 0')
plt.scatter(P_1.x, P_1.y, s = 5, alpha = 0.2, label = 'Population 1')
plt.legend()
```

Out[30]: <matplotlib.legend.Legend at 0x7f0a61f38198>



d) Stelle die Projektionen in einem Histogramm dar:

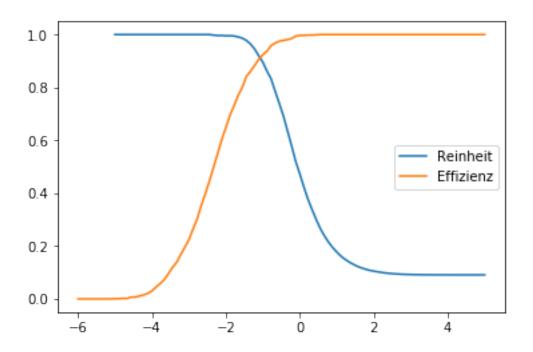
Out[32]: <matplotlib.legend.Legend at 0x7f0a61f474e0>



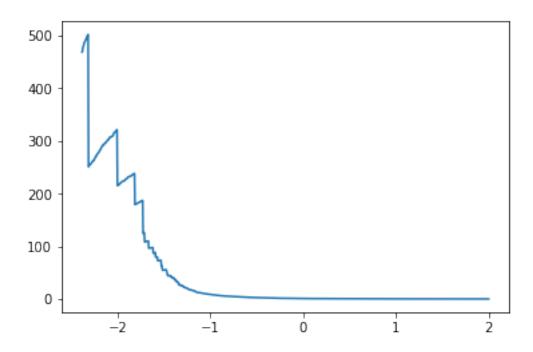
```
e)
In [33]: def precision(signal, noise, cut):
             true_pos = np.array([len(signal[signal < cut]) for cut in cut])</pre>
             false_pos = np.array([len(noise[noise < cut]) for cut in cut])</pre>
             return true_pos / (true_pos + false_pos)
In [34]: def recall(signal, noise, cut):
             true_pos = np.array([len(signal[signal < cut]) for cut in cut])</pre>
             false_neg = np.array([len(signal[signal > cut]) for cut in cut])
             return true_pos / (true_pos + false_neg)
In [35]: signal = projection_0
         noise = projection_1
         lam_cut = np.linspace(-6, 5, 100)
         plt.plot(lam_cut, precision(signal, noise, lam_cut),
                  label = 'Reinheit')
         plt.plot(lam_cut, recall(signal, noise, lam_cut),
                  label = 'Effizienz')
         plt.legend()
```

/home/stefan/.local/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:4: RuntimeWarn after removing the cwd from sys.path.

```
Out[35]: <matplotlib.legend.Legend at 0x7f0a61d92518>
```

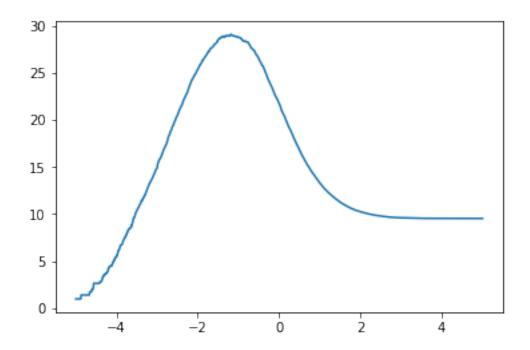


f) Untersuche Signal-Untergrundverhältnis:



g) Untersuche Signifikanz:

Out[39]: -1.1761761761762



In []: