

UNIVERSITY OF DUBLIN TRINITY COLLEGE

Faculty of Engineering, Mathematics and Science

School of Computer Science & Statistics

**Integrated Engineering
Year 3 Examination**

Trinity Term 2013

3D2 Microprocessor Systems 2

Monday April 29, 2013

Sports Centre (455)

09:30–11:30

Dr Mike Brady

Instructions to Candidates:

Attempt **two** questions. All questions carry equal marks. Each question is scored out of a total of 20 marks.

You may not start this examination until you are instructed to do so by the Invigilator.

Materials permitted for this examination:

An ASCII code table (one page) and an ARM Instruction Set Summary (six pages) accompany this examination paper.

Non-programmable calculators are permitted for this examination — please indicate the make and model of your calculator on each answer book used.

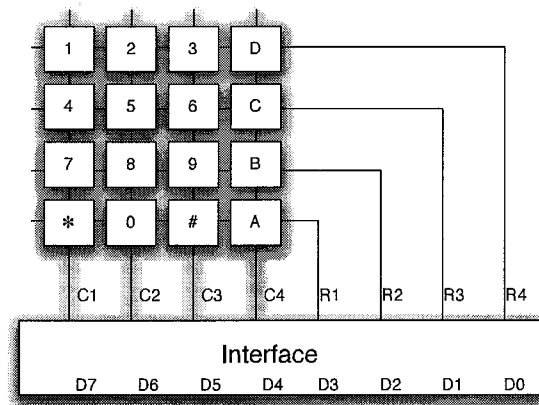
1. (a) Explain how a pipelined architecture can speed up the execution of instructions on a processor. Explain the issues that can slow a pipeline down and discuss ways of getting around some of these problems.

[10 marks]

- (b) List the components and properties of the *memory hierarchy*, and hence explain why a memory hierarchy seems to be necessary in the first place. Describe the function and operation of cache memories. In your answer, discuss the different types of cache organization and replacement policies, and list their advantages and disadvantages.

[10 marks]

2. (a) Two ways to detect activity on peripheral interfaces are by *polling* and by *interrupt handling*. Briefly explain both approaches, and explain the difference between them. [5 marks]
- (b) Imagine you have a 16-key keypad (see diagram) where the keys are arranged as a four-by-four square, interfaced to your computer at location 0xE0F05204, providing a 2-of-8 code for each key. When a key is pressed, the value of its row line and its column line, which are normally 1, are pulled down to 0.



When a key is pressed, it *bounces*; as it changes state (from open to closed or from closed to open), the springiness and inertia of the moving parts combine to make the electronic contacts open and close rapidly and irregularly for a short period, less than 5 milliseconds, making the output code change rapidly before finally settling down its true value.

Write a polling subroutine that reliably returns, in R0, the ASCII code of a key when it is pressed. Explain clearly how your subroutine works.

[15 marks]

3. (a) What are the differences between an IRQ and a FIQ? [2 marks]
- (b) What is meant by latency in the context of an interrupt handler. [2 marks]
- (c) Explain the difference between vectored and non-vectored interrupt handling. Which is better? [4 marks]
- (d) Design and write the code for a main program and an interrupt handler, to make an LED flash a particular number of times. The interrupt handler is called by a timer interrupt every one millisecond (1 ms). Each flash of the LED should consist of 60 ms of the LED being lit followed by 40 ms of the LED being off; thus, for example, it would take 5 seconds to flash the LED 50 times. When the LED has flashed the required number of times, it should remain dim for a further 500 ms.

Do not attempt to write the timer initialisation code. Assume it has already been set up—your code doesn't have to do any further setup. Just write a comment in your code where you would finally enable interrupts when everything else in your code is ready.

Likewise, assume the interface to the LED has already been set up. To turn on the LED, write a 1 to bit 7 of location 0x0E004003A; to turn it off, write a 0. [12 marks]

ASCII Code

Row Number	Column Number							
	000	001	010	011	100	101	110	111
0000	<i>NUL</i>	<i>DLE</i>	◇	0	@	P	`	p
0001	<i>SOH</i>	<i>DC1</i>	!	1	A	Q	a	q
0010	<i>STX</i>	<i>DC2</i>	"	2	B	R	b	r
0011	<i>ETX</i>	<i>DC3</i>	#	3	C	S	c	s
0100	<i>EOT</i>	<i>DC4</i>	\$	4	D	T	d	t
0101	<i>ENQ</i>	<i>NAK</i>	%	5	E	U	e	u
0110	<i>ACK</i>	<i>SYN</i>	&	6	F	V	f	v
0111	<i>BELL</i>	<i>ETB</i>	'	7	G	W	g	w
1000	<i>BS</i>	<i>CAN</i>	(8	H	X	h	x
1001	<i>HT</i>	<i>EM</i>)	9	I	Y	i	y
1010	<i>LF</i>	<i>SUB</i>	*	:	J	Z	j	z
1011	<i>VT</i>	<i>ESC</i>	+	;	K	[k	{
1100	<i>FF</i>	<i>FS</i>	,	<	L	\	l	
1101	<i>CR</i>	<i>GS</i>	-	=	M]	m	}
1110	<i>SO</i>	<i>RS</i>	.	>	N	^	n	~
1111	<i>SI</i>	<i>US</i>	/	?	O	_	o	<i>DEL</i>

The ASCII code of a character is found by combining its Column Number (given in 3-bit binary) with its Row Number (given in 4-bit binary).

The Column Number forms bits 6, 5 and 4 of the ASCII, and the Row Number forms bits 3, 2, 1 and 0 of the ASCII.

Example of use: to get ASCII code for letter "n", locate it in Column **110**, Row **1110**. Hence its ASCII code is **1101110**.

The **Control Code** mnemonics are given in italics above; e.g. *CR* for Carriage Return, *LF* for Line Feed, *BELL* for the Bell, *DEL* for Delete.

The Space is ASCII 0100000, and is shown as ◇ here.

ARM® Instruction Set Quick Reference Card

CS3D2-1

Key to Tables	Condition Field. Omit for unconditional execution.
<cond>	Refer to Table Flexible Operand 2 . Shift and rotate are only available as part of Operand2.
<Operand2>	Refer to Table Flexible Operand 2 . Shift and rotate are only available as part of Operand2.
<fields>	Refer to Table PSR fields .
<PSR>	Either CPSR (Current Processor Status Register) or SPSR (Saved Processor Status Register).
{S}	Updates condition flags if S present.
C*, V*	Flag is unpredictable in Architecture v4 and earlier, unchanged in Architecture v5 and later. Sticky flag. Always updates on overflow (no S option). Read and reset using MRS and MSR.
Q	Four Greater than or Equal flags. Always updated by parallel adds and subtracts.
GE	Sticky flag. Always updates on overflow (no S option). Read and reset using MRS and MSR.
x, y	B meaning half-processor [15:0], or T meaning [31:16].
<immed_8r>	A 32-bit constant, formed by right-rotating an 8-bit value by an even number of bits.
{X}	RsX is Rs rotated 16 bits if X present. Otherwise, RsX is Rs.
<prefix>	Refer to Table Prefixes for Parallel Instructions .
<P_mode>	Refer to Table Processor Modes .
R13m	R13 for the processor mode specified by <P_mode>

endianness	Can be BE (Big Endian) or LE (Little Endian).
<a_mode2>	Refer to Table Addressing Mode 2 .
<a_mode2P>	Refer to Table Addressing Mode 2 (Post-indexed only) .
<a_mode3>	Refer to Table Addressing Mode 3 .
<a_mode4L>	Refer to Table Addressing Mode 4 (Block load or Stack pop) .
<a_mode4S>	Refer to Table Addressing Mode 4 (Block store or Stack push) .
<a_mode5>	Refer to Table Addressing Mode 5 .
<regList>	A comma-separated list of registers, enclosed in braces { and }.
<regList-PC>	As <regList>, must not include the PC.
<regList+PC>	As <regList>, including the PC.
{;}	Updates base register after data transfer if ; present.
+/-	+ or -, (+ may be omitted.)
\$	Refer to Table ARM architecture versions .
<iflags>	Interrupt flags. One or more of a, i, f (abort, interrupt, fast interrupt).
{R}	Rounds result to nearest if R present, otherwise truncates result.

Operation	Assembler	S updates	Q	Action
Arithmetic				
Add	ADD{cond}{S} Rd, Rn, <Operand2>	N Z C V	Q	Rd := Rn + Operand2
with carry	ADC{cond}{S} Rd, Rn, <Operand2>	N Z C V	Q	Rd := Rn + Operand2 + Carry
saturation	SE QADD{cond} Rd, Rm, Rn	N Z C V	Q	Rd := SAT(Rm + Rn)
double saturation	SUB{cond}{S} Rd, Rn, <Operand2>	N Z C V	Q	Rd := Rn - Operand2
Subtract	SBC{cond}{S} Rd, Rn, <Operand2>	N Z C V	Q	Rd := Rn - Operand2 - NOT(Carry)
with carry	RSB{cond}{S} Rd, Rn, <Operand2>	N Z C V	Q	Rd := Operand2 - Rn
reverse subtract	RSC{cond}{S} Rd, Rn, <Operand2>	N Z C V	Q	Rd := Operand2 - Rn - NOT(Carry)
reverse subtract with carry	SE QSUB{cond} Rd, Rm, Rn	N Z C V	Q	Rd := SAT(Rm - Rn)
saturation	SE QDSUB{cond} Rd, Rm, Rn	N Z C V	Q	Rd := SAT(Rm - SAT(Rn * 2))
double saturation	2 MUL{cond}{S} Rd, Rm, Rs	N Z C*	Q	Rd := (Rm * Rs)[31:0]
and accumulate	M UML{cond}{S} Rdlo, Rdhi, Rm, Rs	N Z C*	Q	Rdlo := (Rm * Rs) + Rn[31:0]
unsigned long	M UML{cond}{S} Rdlo, Rdhi, Rm, Rs	N Z C*	Q	Rdhi, Rdlo := unsigned(Rdhi, Rdlo + Rm * Rs)
unsigned accumulate long	M UML{cond}{S} Rdlo, Rdhi, Rm, Rs	N Z C*	Q	Rdhi, Rdlo := unsigned(Rdhi, Rdlo + Rm * Rs)
unsigned double accumulate long	M UML{cond}{S} Rdlo, Rdhi, Rm, Rs	N Z C*	Q	Rdhi, Rdlo := signed(Rdhi, Rdlo + Rm * Rs)
Signed multiply long	M SML{cond}{S} Rdlo, Rdhi, Rm, Rs	N Z C*	Q	Rdhi, Rdlo := signed(Rdhi, Rdlo + Rm * Rs)
and accumulate long	M SML{cond}{S} Rdlo, Rdhi, Rm, Rs	N Z C*	Q	Rd := Rm[X] * Rs[Y]
16 * 16 bit	SE SMULXY{cond} Rd, Rm, Rs	N Z C*	Q	Rd := (Rm * Rs)[47:16]
32 * 16 bit	SE SMULXY{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rn + Rm[X] * Rs[Y]
16 * 16 bit and accumulate	SE SMULXY{cond} Rd, Rm, Rs	N Z C*	Q	Rdhi, Rdlo := Rdhi, Rdlo + Rm[X] * Rs[Y]
32 * 16 bit and accumulate	SE SMULXY{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rm[15:0] * RsX[15:0] + Rm[31:16] * RsX[31:16]
16 * 16 bit and accumulate	SE SMULXY{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rn + Rm[15:0] * RsX[15:0] + Rm[31:16] * RsX[31:16]
16 * 16 bit and accumulate	SE SMULXY{cond} Rd, Rm, Rs	N Z C*	Q	Rdhi, Rdlo := Rdhi, Rdlo + Rm[15:0] * RsX[15:0] + Rm[31:16] * RsX[31:16]
Dual signed multiply, add	6 SMLAD{X}{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rm[15:0] * RsX[15:0] - Rm[31:16] * RsX[31:16]
and accumulate	6 SMLAD{X}{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rn + Rm[15:0] * RsX[15:0] - Rm[31:16] * RsX[31:16]
Dual signed multiply, subtract	6 SMLSD{X}{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rm[15:0] * RsX[15:0] - Rm[31:16] * RsX[31:16]
and accumulate	6 SMLSD{X}{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rn + Rm[15:0] * RsX[15:0] - Rm[31:16] * RsX[31:16]
Signed most significant word multiply	6 SMLSXD{X}{cond} Rdhi, Rdlo, Rm, Rs	N Z C*	Q	Rdhi, Rdlo := Rdhi, Rdlo + Rm[15:0] * RsX[15:0] - Rm[31:16] * RsX[31:16]
and accumulate	6 SMLSXD{X}{cond} Rdhi, Rdlo, Rm, Rs	N Z C*	Q	Rd := (Rm * Rs)[63:32]
and accumulate	6 SMLSXD{X}{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rn + (Rm * Rs)[63:32]
and accumulate	6 SMLSXD{X}{cond} Rd, Rm, Rs	N Z C*	Q	Rd := Rn - (Rm * Rs)[63:32]
Multiply with internal 40-bit accumulate	XS MIA{cond} Ac, Rm, Rs	N Z C*	Q	Ac := Ac + Rm * Rs
packed halfword	XS MIA{cond} Ac, Rm, Rs	N Z C*	Q	Ac := Ac + Rm[15:0] * Rs[15:0] + Rm[31:16] * Rs[31:16]
halfword	XS MIA{cond} Ac, Rm, Rs	N Z C*	Q	Ac := Ac + Rm[X] * Rs[Y]
Count leading zeroes	CLZ{cond} Rd, Rm	N Z C*	Q	Rd := number of leading zeroes in Rm

ARM Addressing Modes Quick Reference Card

Operation	Assembler	S updates	Q	GE Action
Parallel arithmetic	Halfword-wise addition	6		GE Rd[31:16] := Rn[31:16] + Rm[31:16], Rd[15:0] := Rn[15:0] + Rm[15:0]
	Halfword-wise subtraction	6		GE Rd[31:16] := Rn[31:16] - Rm[31:16], Rd[15:0] := Rn[15:0] - Rm[15:0]
	Byte-wise addition	6		GE Rd[31:24] := Rn[31:24] + Rm[31:24], Rd[23:16] := Rn[23:16] + Rm[23:16], Rd[15:8] := Rn[15:8] + Rm[15:8], Rd[7:0] := Rn[7:0] + Rm[7:0]
	Byte-wise subtraction	6		GE Rd[31:24] := Rn[31:24] - Rm[31:24], Rd[23:16] := Rn[23:16] - Rm[23:16], Rd[15:8] := Rn[15:8] - Rm[15:8], Rd[7:0] := Rn[7:0] - Rm[7:0]
	Halfword-wise exchange, add, subtract	6		GE Rd[31:16] := Rn[31:16] + Rm[15:0], Rd[15:0] := Rn[15:0] - Rm[31:16]
	Halfword-wise exchange, subtract, add	6		GE Rd[31:16] := Rn[31:16] - Rm[15:0], Rd[15:0] := Rn[15:0] + Rm[31:16]
	Unsigned sum of absolute differences	6		Rd := Rn + Abs(Rm[31:24] - Rn[31:24]) + Abs(Rm[23:16] - Rn[23:16]) + Abs(Rm[15:8] - Rn[15:8]) + Abs(Rm[7:0] - Rn[7:0])
	and accumulate	6		Rd := Operand2 + Abs(Rm[15:8] - Rn[15:8]) + Abs(Rm[7:0] - Rn[7:0])
Move	Move			Rd := Operand2
	NOT		N Z C	Rd := 0xFFFFFFFF EOR Operand2
	PSR to register	3	N Z C	Rd := PSR
	register to PSR	3		PSR := Rm (selected bytes only)
	immediate to PSR	3		PSR := immmed_8r (selected bytes only)
	40-bit accumulator to register	XS		RdLo := Ac[31:0], RdHi := Ac[39:32]
	register to 40-bit accumulator	XS		Ac[31:0] := RdLo, Ac[39:32] := RdHi
	Copy	6		Rd := Operand2
Logical	Test		N Z C	Update CPSR flags on Rn AND Operand2
	Test equivalence		N Z C	Update CPSR flags on Rn EOR Operand2
	AND		N Z C	Rd := Rn AND Operand2
	EOR		N Z C	Rd := Rn EOR Operand2
	ORR		N Z C	Rd := Rn OR Operand2
	Bit Clear		N Z C	Rd := Rn AND NOT Operand2
	BIC		N Z C	Rd := Rn AND NOT Operand2
	Bit Set		N Z C	Rd := Rn OR Operand2
Compare	Compare		N Z C V	Update CPSR flags on Rn - Operand2
	negative		N Z C V	Update CPSR flags on Rn - Operand2
	CMN		N Z C V	Update CPSR flags on Rn - Operand2
	CMN		N Z C V	Update CPSR flags on Rn - Operand2
Saturate	Signed saturate word, right shift	6		Rd := SignedSat((Rn ASR sh), sat), <sat> range 0-31, <sh> range 1-32.
	left shift	6		Rd := SignedSat((Rn LSL sh), sat), <sat> range 0-31, <sh> range 0-31.
	Signed saturate two halfwords	6		Rd[31:16] := SignedSat(Rn[31:16], sat), <sat> range 0-15.
	Unsigned saturate word, right shift	6		Rd := UnsignedSat((Rn ASR sh), sat), <sat> range 0-31, <sh> range 1-32.
	left shift	6		Rd := UnsignedSat((Rn LSL sh), sat), <sat> range 0-31, <sh> range 0-31.
	Unsigned saturate two halfwords	6		Rd[31:16] := UnsignedSat(Rn[31:16], sat), <sat> range 0-15.
	Unsigned saturate two halfwords	6		Rd[15:0] := UnsignedSat(Rn[15:0], sat), <sat> range 0-15.
	Unsigned saturate two halfwords	6		Rd[15:0] := UnsignedSat(Rn[15:0], sat), <sat> range 0-15.

ARM Instruction Set Quick Reference Card

CS3D2-1

Operation	\$	Assembler	Action	Notes
Pack	6	PKHBT{cond} Rd, Rn, Rm{, LSL #<sh>}	Rd[15:0] := Rn[15:0], Rd[31:16] := (Rm LSL sh)[31:16], sh 0-31.	
Signed extend	6	PKHTB{cond} Rd, Rn, Rm{, ASR #<sh>}	Rd[31:16] := Rn[31:16], Rd[15:0] := (Rm ASR sh)[15:0], sh 1-32.	
	6	SXTBH{cond} Rd, Rm{, ROR #<sh>}	Rd[31:0] := SignExtend((Rm ROR (8 * sh))[15:0]), sh 0-3.	
	6	SXTB{cond} Rd, Rm{, ROR #<sh>}	Rd[31:16] := SignExtend((Rm ROR (8 * sh))[23:16]), Rd[15:0] := SignExtend((Rm ROR (8 * sh))[7:0]), sh 0-3.	
Unsigned extend	6	SXTB{cond} Rd, Rm{, ROR #<sh>}	Rd[31:0] := SignExtend((Rm ROR (8 * sh))[7:0]), sh 0-3.	
	6	UXTBH{cond} Rd, Rm{, ROR #<sh>}	Rd[31:0] := ZeroExtend((Rm ROR (8 * sh))[15:0]), sh 0-3.	
	6	UXTB{cond} Rd, Rm{, ROR #<sh>}	Rd[31:16] := ZeroExtend((Rm ROR (8 * sh))[23:16]), Rd[15:0] := ZeroExtend((Rm ROR (8 * sh))[7:0]), sh 0-3.	
Signed extend with add	6	SXTAB{cond} Rd, Rn, Rm{, ROR #<sh>}	Rd[31:0] := Rn[31:0] + SignExtend((Rm ROR (8 * sh))[15:0]), sh 0-3.	
	6	SXTAB{cond} Rd, Rn, Rm{, ROR #<sh>}	Rd[31:16] := Rn[31:16] + SignExtend((Rm ROR (8 * sh))[23:16]), Rd[15:0] := Rn[15:0] + SignExtend((Rm ROR (8 * sh))[7:0]), sh 0-3.	
Unsigned extend with add	6	UXTAB{cond} Rd, Rn, Rm{, ROR #<sh>}	Rd[31:0] := Rn[31:0] + ZeroExtend((Rm ROR (8 * sh))[15:0]), sh 0-3.	
	6	UXTAB{cond} Rd, Rn, Rm{, ROR #<sh>}	Rd[31:16] := Rn[31:16] + ZeroExtend((Rm ROR (8 * sh))[23:16]), Rd[15:0] := Rn[15:0] + ZeroExtend((Rm ROR (8 * sh))[7:0]), sh 0-3.	
Reverse bytes	6	REV{cond} Rd, Rm	Rd[31:24] := Rm[7:0], Rd[23:16] := Rm[15:8], Rd[15:8] := Rm[23:16], Rd[7:0] := Rm[31:24]	
	6	REV16{cond} Rd, Rm	Rd[15:8] := Rm[7:0], Rd[7:0] := Rm[15:8], Rd[31:24] := Rm[23:16], Rd[23:16] := Rm[31:24]	
	6	REVSH{cond} Rd, Rm	Rd[15:8] := Rm[7:0], Rd[7:0] := Rm[15:8], Rd[31:16] := Rm[7] * &HFF	
Select	6	SEL{cond} Rd, Rn, Rm	Rd[7:0] := Rn[7:0] if GE[0] = 1, else Rd[7:0] := Rm[7:0] Bit[15:8], [23:16], [31:24] selected similarly by GE[1], GE[2], GE[3]	
Branch		B{cond} label	R15 := label	label must be within ±32Mb of current instruction.
		B{cond} label	R14 := address of next instruction, R15 := label	label must be within ±32Mb of current instruction.
	4T, 5	BX{cond} Rm	R15 := Rm, Change to Thumb if Rm[0] is 1	
	5T	BLX label	R14 := address of next instruction, R15 := label, Change to Thumb	Cannot be conditional, label must be within ±32Mb of current instruction.
	5	BLX{cond} Rm	R14 := address of next instruction, R15 := Rm[31:1]	
	5T, 6	BLX{cond} Rm	Change to Thumb if Rm[0] is 1	
		Change to Java state		
Processor state change	6	CPSID <flags> {, #<p_mode>}	Disable specified interrupts, optional change mode.	Cannot be conditional.
	6	CPSIE <flags> {, #<p_mode>}	Enable specified interrupts, optional change mode.	Cannot be conditional.
	6	CPS #<p_mode>	Sets endianness for loads and saves.	Cannot be conditional.
	6	SETEND <endianness>	<endianness> can be BE (Big Endian) or LE (Little Endian).	Cannot be conditional.
	6	SRS<a_mode4> #<p_mode>{!}	[R13m] := R14, [R13m + 4] := CPSR	Cannot be conditional.
	6	RFE<a_mode4> Rn{!}	PC := [Rn], CPSR := [Rn + 4]	Cannot be conditional.
	5	BKPT <immed_16>	Prefetch abort or enter debug state.	Cannot be conditional.
Software interrupt		SWT{cond} <immed_24>	Software interrupt processor exception.	24-bit value encoded in instruction.
No Op	5	NOP	None	

ARM Addressing Modes Quick Reference Card

CS3D2-1

Operation		\$	Assembler	Action	Notes
Load	Word		LDR{cond} Rd, <a_mode2> LDR{cond}T Rd, <a_mode2P> LDR{cond} R15, <a_mode2>	Rd := [address] R15 := [address][3:1] (§ 5T: Change to Thumb if [address][0] is 1) Rd := ZeroExtend[byte from address]	Rd must not be R15. Rd must not be R15.
	Byte		LDR{cond}B Rd, <a_mode2> LDR{cond}BT Rd, <a_mode2P>	Rd := SignExtend[byte from address]	Rd must not be R15.
	User mode privilege signed		LDR{cond}SB Rd, <a_mode3>	Rd := ZeroExtend[halfword from address]	Rd must not be R15.
	Halfword signed		LDR{cond}H Rd, <a_mode3> LDR{cond}SH Rd, <a_mode3>	Rd := SignExtend[halfword from address] Rd := [address], Rd(+1) := [address + 4]	Rd must not be R15. Rd must not be R15.
	Doubleword		LDR{cond}D Rd, <a_mode3> LDR{cond} <a_mode4L> Rn{ }, <reglist-PC> LDR{cond} <a_mode4L> Rn{ }, <reglist+PC>	Load list of registers from [Rn] Load registers, R15 := [address][3:1] (§ 5T: Change to Thumb if [address][0] is 1) Load registers, branch (§ 5T: and exchange), CPSR := SPSR	Rd must be even, and not R14.
Load multiple	Pop, or Block data load return (and exchange)				
Soft preload	and restore CPSR User mode registers Memory system hint		LDM{cond} <a_mode4L> Rn{ }, <reglist+PC> LDM{cond} <a_mode4L> Rn, <reglist-PC> PLD <a_mode2>	Load list of User mode registers from [Rn] Memory may prepare to load from address	Use from exception modes only. Use from privileged modes only. Cannot be conditional.
Load exclusive	Semaphore operation	SE*	LDR{cond} Rd, [Rn] LDREX{cond}	Rd := [Rn], tag address as exclusive access Outstanding tag set if not shared address	Rd, Rn must not be R15.
Store	Word		STR{cond} Rd, <a_mode2> STR{cond}T Rd, <a_mode2P>	[address] := Rd	
	User mode privilege		STR{cond}B Rd, <a_mode2> STR{cond}BT Rd, <a_mode2P>	[address][7:0] := Rd[7:0] [address][15:0] := Rd[15:0]	
	Byte		STR{cond}H Rd, <a_mode3> STR{cond}D Rd, <a_mode3>	[address] := Rd, [address + 4] := Rd(+1)	Rd must be even, and not R14.
	Halfword		STM{cond} <a_mode4S> Rn{ }, <reglist> STM{cond} <a_mode4S> Rn{ }, <reglist+PC>	Store list of registers to [Rn] Store list of User mode registers to [Rn]	Rd must be even, and not R14.
	Doubleword	SE*	STR{cond} <a_mode4L> Rn{ }, <reglist> STR{cond} <a_mode4L> Rn, <reglist+PC>	[Rn] := Rn if allowed. Rd := 0 if successful, else 1	Use from privileged modes only.
Store multiple	Push, or Block data store User mode registers				
Store exclusive	Semaphore operation		STREX{cond} Rd, [Rn]		Rd, Rn, Rn must not be R15.
Swap	Word	3	SWP{cond} Rd, [Rn] SWP{cond}B Rd, [Rn]	temp := [Rn], [Rn] := Rn, Rd := temp temp := ZeroExtend([Rn][7:0]). [Rn][7:0] := Rn[7:0], Rd := temp	
	Byte	3			

ARM Addressing Modes Quick Reference Card

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Addressing Mode 2 - Word and Unsigned Byte Data Transfer		
Pre-indexed	Immediate offset Zero offset Register offset Scaled register offset	[Rn], #+/-<immed_12>{i} [Rn], +/-Rm {i} [Rn], +/-Rm, LSL #<shift>{i} [Rn], +/-Rm, LSR #<shift>{i} [Rn], +/-Rm, ASR #<shift>{i} [Rn], +/-Rm, ROR #<shift>{i} [Rn], #+/-<immed_12> [Rn], +/-Rm [Rn], +/-Rm, LSL #<shift> [Rn], +/-Rm, LSR #<shift> [Rn], +/-Rm, ASR #<shift> [Rn], +/-Rm, ROR #<shift> [Rn], +/-Rm, RRR
Post-indexed	Immediate offset Register offset Scaled register offset	[Rn], #+/-<immed_12> [Rn], +/-Rm [Rn], +/-Rm, LSL #<shift> [Rn], +/-Rm, LSR #<shift> [Rn], +/-Rm, ASR #<shift> [Rn], +/-Rm, ROR #<shift> [Rn], +/-Rm, RRR
Equivalent to [Rn,#0]		
Addressing Mode 3 - Halfword, Signed Byte, and Doubleword Data Transfer		
Pre-indexed	Immediate offset Zero offset Register Post-indexed	[Rn], #+/-<immed_8>{i} [Rn] [Rn], +/-Rm {i} [Rn], #+/-<immed_8> [Rn], +/-Rm
Post-indexed	Immediate offset Zero offset Register Post-indexed	[Rn] [Rn] [Rn], +/-Rm {i} [Rn], #+/-<immed_8> [Rn], +/-Rm
Equivalent to [Rn,#0]		
Addressing Mode 4 - Multiple Data Transfer		
Block load		Stack pop
IA	Increment After	FD
IB	Increment Before	ED
DA	Decrement After	FA
DB	Decrement Before	EA
Block store		Stack push
IA	Increment After	EA
IB	Increment Before	FA
DA	Decrement After	ED
DB	Decrement Before	FD
		Empty Ascending Full Ascending Empty Descending Full Descending
Addressing Mode 5 - Coprocessor Data Transfer		
Pre-indexed	Immediate offset Zero offset	[Rn], #+/-<immed_8*4>{i} [Rn]
Post-indexed	Immediate offset No offset	[Rn], #+/-<immed_8*4> [Rn], {8-bit copro. option}
Unindexed		

ARM architecture versions	
n	ARM architecture version n and above.
nT, nJ	T or J variants of ARM architecture version n and above.
M	ARM architecture version 3M, and 4 and above, except xM variants.
mE	All E variants of ARM architecture version n and above.
mE*	E variants of ARM architecture version n and above, except xP variants.
XS	XScale coprocessor instruction

Flexible Operand 2	
Immediate value	#<immed_8r>
Logical shift left immediate	Rm, LSL #<shift>
Logical shift right immediate	Rm, LSR #<shift>
Arithmetic shift right immediate	Rm, ASR #<shift>
Rotate right immediate	Rm, ROR #<shift>
Register	Rm, RRR
Rotate right extended	Rm, RRE
Logical shift left register	Rm, LSL Rs
Logical shift right register	Rm, LSR Rs
Arithmetic shift right register	Rm, ASR Rs
Rotate right register	Rm, ROR Rs

PSR fields	
Suffix	Meaning
C	Control field mask byte
F	Flags field mask byte
S	Status field mask byte
X	Extension field mask byte

Condition Field	
Mnemonic	Description
EQ	Equal
NE	Not equal
CS / HS	Carry Set / Unsigned higher or same
CC / LO	Carry Clear / Unsigned lower
MI	Negative
PL	Positive or zero
VS	Overflow
VC	No overflow
HI	Unsigned higher
LS	Unsigned lower or same
GE	Signed greater than or equal
LE	Signed less than or equal
GT	Signed greater than
LT	Signed less than
IE	Signed less than or equal
AL	Always (normally omitted)

Processor Modes	
16	User
17	FIQ Fast Interrupt
18	IRQ Interrupt
19	Supervisor
23	Abort
27	Undefined
31	System

Prefixes for Parallel Instructions	
S	Signed arithmetic modulo 2 ⁸ or 2 ¹⁶ , sets CPSR GE bits
Q	Signed saturating arithmetic
SH	Signed arithmetic, halving results
U	Unsigned arithmetic modulo 2 ⁸ or 2 ¹⁶ , sets CPSR GE bits
UQ	Unsigned saturating arithmetic
UH	Unsigned arithmetic, halving results

ARM Addressing Modes
Quick Reference Card

Coprocessor operations	\$	Assembler	Action	Notes
Data operations	2	CDP{cond} <copr>, <op1>, CRd, CRn, CRm{, <op2>}	Coprocessor dependent	
Alternative data operations	5	CDP2 <copr>, <op1>, CRd, CRn, CRm{, <op2>}	Coprocessor dependent	Cannot be conditional.
Move to ARM register from coprocessor	2	MRC{cond} <copr>, <op1>, Rd, CRn, CRm{, <op2>}	Coprocessor dependent	
Alternative move	5	MRC2 <copr>, <op1>, Rd, CRn, CRm{, <op2>}	Coprocessor dependent	Cannot be conditional.
Two ARM register move	5F*	MRC{cond} <copr>, <op1>, Rd, CRn, CRm	Coprocessor dependent	
Alternative two ARM register move	6	MRC2 <copr>, <op1>, Rd, CRn, CRm	Coprocessor dependent	Cannot be conditional.
Move to coproc from ARM reg	5	MCR{cond} <copr>, <op1>, Rd, CRn, CRm{, <op2>}	Coprocessor dependent	
Alternative move	5	MCR2 <copr>, <op1>, Rd, CRn, CRm{, <op2>}	Coprocessor dependent	Cannot be conditional.
Two ARM register move	5F*	MCR{cond} <copr>, <op1>, Rd, CRn, CRm	Coprocessor dependent	
Alternative two ARM register move	6	MCR2 <copr>, <op1>, Rd, CRn, CRm	Coprocessor dependent	Cannot be conditional.
Load	2	LDC{cond} <copr>, CRd, <a_mode5>	Coprocessor dependent	
Alternative loads	5	LDC2 <copr>, CRd, <a_mode5>	Coprocessor dependent	Cannot be conditional.
Store	2	STC{cond} <copr>, CRd, <a_mode5>	Coprocessor dependent	
Alternative stores	5	STC2 <copr>, CRd, <a_mode5>	Coprocessor dependent	Cannot be conditional.

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Change Log

Issue	Date	By	Change
A	June 1995	BJH	First Release
B	Sept 1996	BJH	Second Release
C	Nov 1998	BJH	Third Release
D	Oct 1999	CKS	Fourth Release
E	Oct 2000	CKS	Fifth Release
F	Sept 2001	CKS	Sixth Release
G	Jan 2003	CKS	Seventh Release
H	Oct 2003	CKS	Eighth Release