# Reinforcement Learning Lab 5

## Policy gradient

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# Policy gradient for linear function approximation

Define:

$$h(s, a, \theta) = \theta^T x(s, a) \tag{1}$$

and consider Policy:

$$\pi(a|s, \theta) = \frac{e^{h(s,a,\theta)}}{\Sigma_b e^{h(s,b,\theta)}} \tag{2}$$

The gradient is defined as:

$$\nabla \hat{J}(\theta) = G_t \nabla_\theta ln(\pi(a|s, \theta)) \tag{3}$$

# Computation

$$\nabla_\theta ln(\pi(a|s,\theta)) = \nabla_\theta ln\left(\frac{e^{h(s,a,\theta)}}{\Sigma_b e^{h(s,b,\theta)}}\right) = \nabla_\theta \left(ln(e^{h(s,a,\theta)}) - ln(\Sigma_b e^{h(s,b,\theta)})\right)$$

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$$= \nabla_\theta h(s,a,\theta) - \nabla_\theta ln(\Sigma_b e^{h(s,b,\theta)}) = x(s,a) - \frac{\nabla_\theta \Sigma_b e^{h(s,b,\theta)}}{\Sigma_b e^{h(s,b,\theta)}}$$

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