

Optimization and equilibrium problems with discrete choice models

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PhD Public Defense

18 March 2022

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- 1 Introduction
- 2 A simulation-based heuristic to find approximate equilibria with disaggregate demand models
- 3 Price-based regulation of oligopolistic markets under discrete choice models of demand
- 4 Benders decomposition for choice-based optimization problems
- 5 Conclusion

Choices



- People have **different socioeconomic characteristics and tastes** that influence their **choices**.

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- **Disaggregate models** of demand can capture this heterogeneity.

Discrete choice models



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Discrete choice models

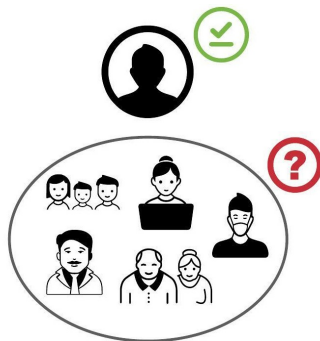


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- They are probabilistic models, generally **non-linear and non-convex**.
- Choice probabilities of advanced DCMs cannot be expressed with a closed form.
- Difficult to integrate into **supply optimization** and **market equilibrium** models.

Choice-based optimization and choice-based equilibrium

- *Dominant paradigm:*

Sacrifice complexity at the demand level
to obtain tractable optimization and
equilibrium problems.



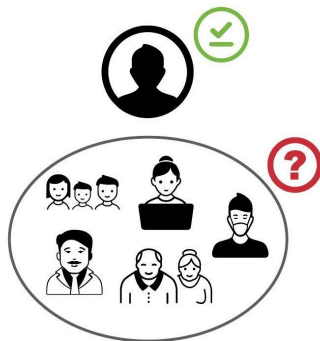
Choice-based optimization and choice-based equilibrium

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- *Complementary view:*

Models and algorithms that **accommodate advanced discrete choice models**.



Value of advanced discrete choice models

Some reasons to take this alternative point of view:

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Some reasons to take this alternative point of view:

- ① **Specification tests**: quantifiable trade-off between different demand models.
- ② Estimation from increasingly large data sets → **richer specifications**
- ③ Disaggregate choice-based models → **differentiated offers and policies** to target specific groups of the population.

Positioning the doctoral thesis

Research directions

- ① Development of mathematical models and algorithms for **choice-based equilibrium problems**.
- ② Identification of problem reformulations and efficient algorithmic approaches for **choice-based optimization problems**.

Outline of the thesis

Chapter 2

Based on the article

Bortolomiol, S., Lurkin, V., Bierlaire, M. (2021). A simulation-based heuristic to find approximate equilibria with disaggregate demand models. *Transportation Science*, 55(5):1025–1045.

Chapter 3

Based on the article

Bortolomiol, S., Lurkin, V., Bierlaire, M. (2021). Price-based regulation of oligopolistic markets under discrete choice models of demand. *Transportation*.

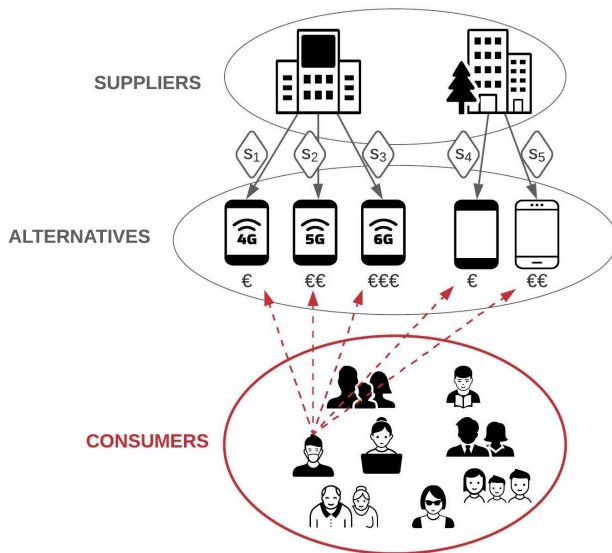
Chapter 4

Part of the work is included in the conference paper

Bortolomiol, S., Lurkin, V., Bierlaire, M., Bongiovanni, C. (2021). Benders decomposition for choice-based optimization problems with discrete upper-level variables. In *Proceedings of the 21st Swiss Transport Research Conference, Ascona, Switzerland*.

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Oligopolistic competition



Oligopolies in transportation



The modeling framework: disaggregate demand



- Random utility models:

$$U_{in} = V_{in} + \varepsilon_{in}$$

$$P_{in} = \Pr[U_{in} + \varepsilon_{in} = \max_{j \in I} (U_{jn} + \varepsilon_{jn})]$$

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¹Pacheco Paneque et al., "Integrating advanced discrete choice models in mixed integer linear optimization" (2021).

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- Simulation can be used to linearize the choice probabilities¹.
- In each simulation scenario, the alternative with the highest utility is chosen.
- Choice probabilities are obtained by sample average approximation.

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The modeling framework: supply

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- Firms make decisions accounting for the expected behavior of customers.
- Decisions can be related to pricing, level of service, capacity, availability, etc.

Market interactions

- Oligopolistic market: firms interact strategically.

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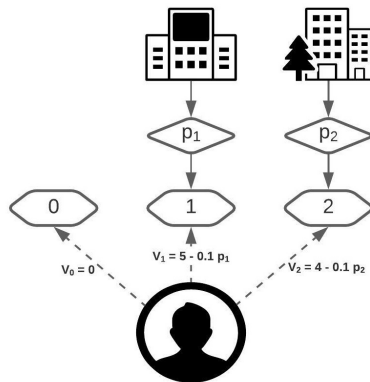
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Market interactions

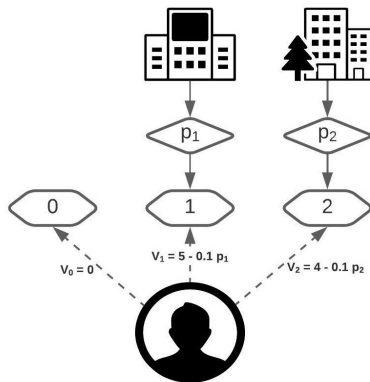
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- A simulation-based heuristic to find **approximate equilibria**.

Small example: logit with unique Nash equilibrium²



²Lin and Sibdari, "Dynamic price competition with discrete customer choices" (2009).

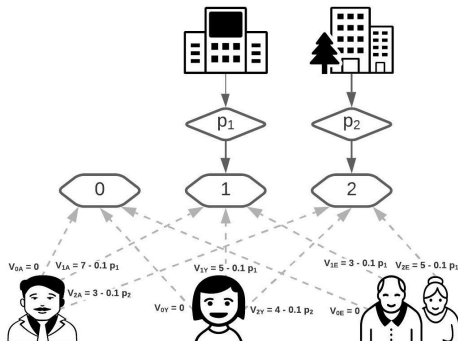
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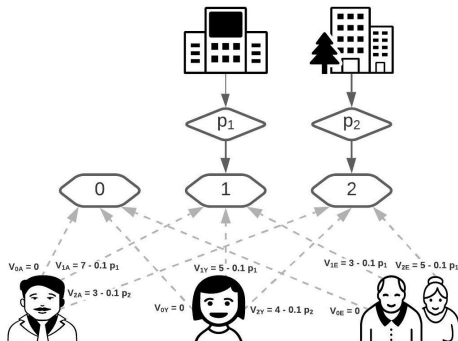
Equilibrium		Prices		Profits		Market shares		
#	ϵ	1	2	1	2	1	2	3
Heuristic	0.9%	21.77	17.63	12.89	6.54	0.037	0.592	0.371
Analytical	0	23.02	16.57	13.02	6.57	0.038	0.566	0.396

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Numerical experiments: accounting for observed heterogeneity

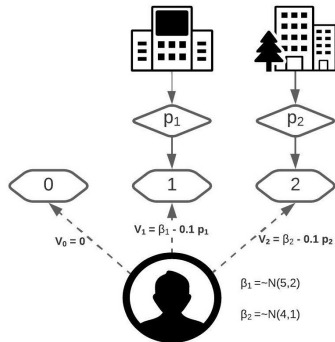


Numerical experiments: accounting for observed heterogeneity

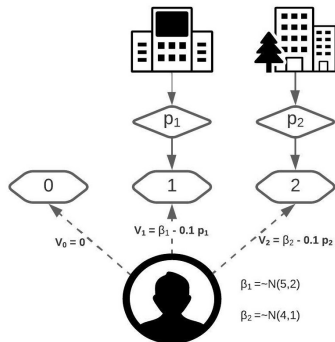


Equilibrium		Prices		Profits		Market shares		
#	ϵ	1	2	1	2	1	2	3
Heuristic	0.8%	33.85	26.04	16.92	11.02	0.077	0.500	0.423
(Analytical)	0	23.02	16.57	13.02	6.57	0.038	0.566	0.396

Numerical experiments: accounting for unobserved heterogeneity

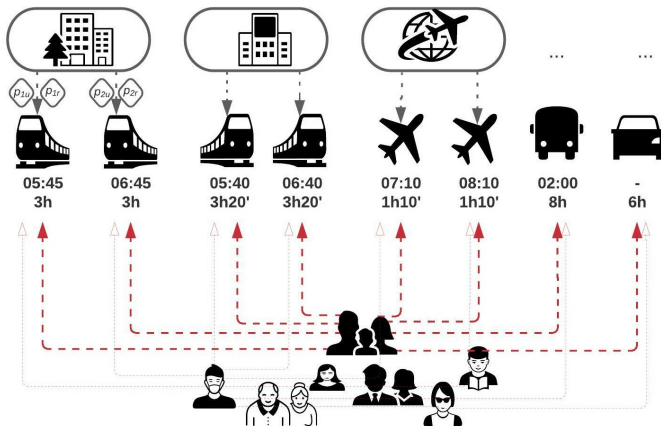


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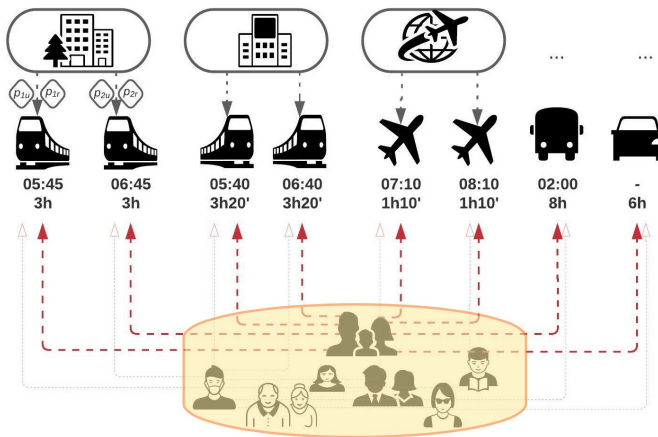


Equilibrium		Prices		Profits		Market shares		
#	ε	1	2	1	2			
Heuristic (Analytical)	0.9%	33.69	25.68	17.55	9.86	0.095	0.521	0.384
	0	23.02	16.57	13.02	6.57	0.038	0.566	0.396

Case study: schedule-based high-speed rail competition

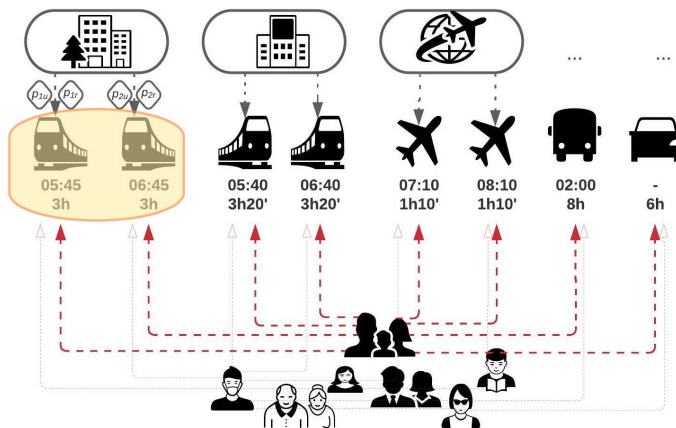


Case study: schedule-based high-speed rail competition



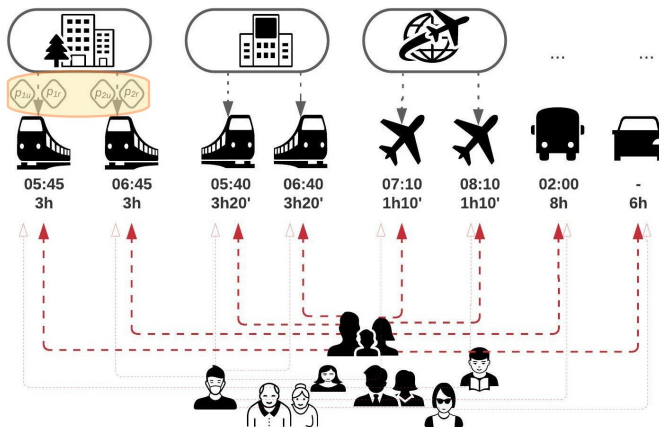
- Heterogeneous demand

Case study: schedule-based high-speed rail competition



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- Multi-product offer by suppliers

Case study: schedule-based high-speed rail competition



- Heterogeneous demand
- Multi-product offer by suppliers
- Price differentiation

Conclusion of the section

Summary

- Integration of discrete choice models into choice-based equilibrium problems.

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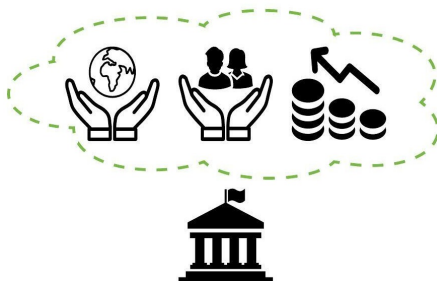
Directions for future work

- Non-linear congestion effects
- Capacity constraints → simulation of arrival of customers

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Regulated competitive markets in transportation

- Imperfect competition, barriers to entry, externalities
- Government as welfare maximizer



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- Regulation according to competition and antitrust laws
- Economic instruments: subsidies and taxes

Price-based regulation

- *Deregulated competition:*

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- *Regulated competition:*

$$p_{in} = r_{in} + t_{in},$$

where t_{in} is a tax (> 0) or subsidy (< 0) set by the regulator.

Optimization problem of the regulator

Objective function

Maximize a **social welfare function** that can include utilities of the customers, profits of the suppliers, environmental externalities and public budget.

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Constraints

Market equilibrium

Profit maximization

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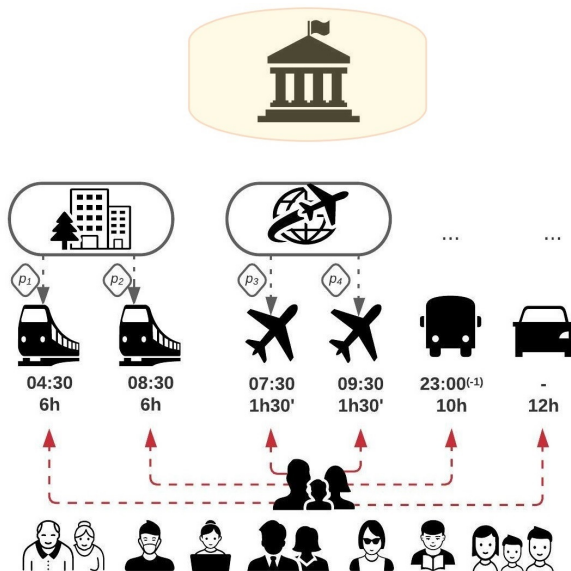
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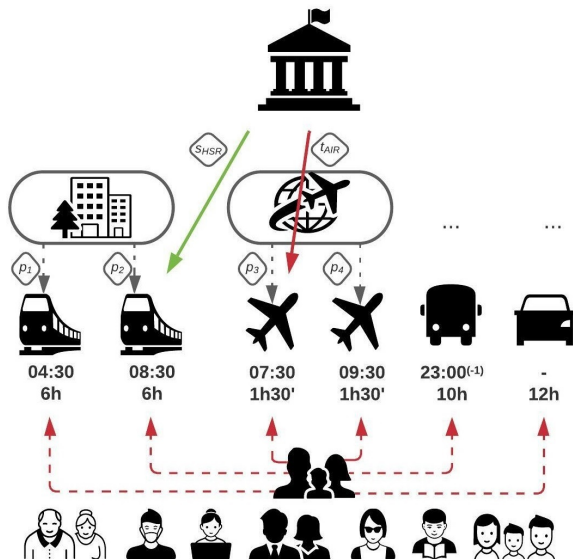
Problem-specific constraints

- Budget
- Policy fairness
- Capacities
- ...

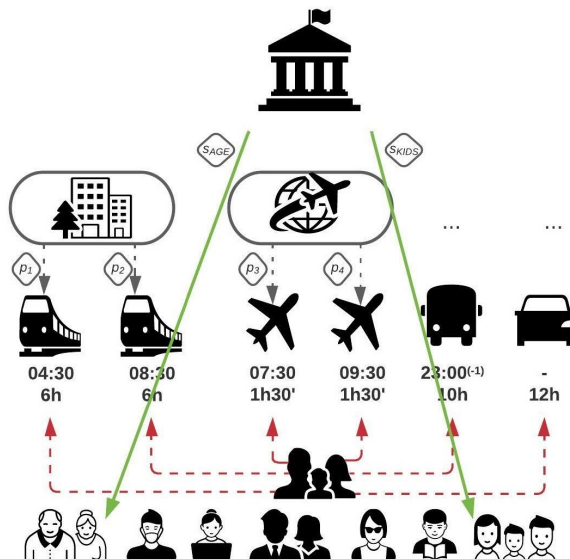
Case study: disaggregate policies



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		r_2	r_3	r_4	r_5	t_{TRAIN}	t_{AIR}
100	150.05	128.82	124.27	93.80	80.95	-0.03	0.00
200	132.69	97.12	99.48	84.90	83.71	-22.34	14.35
300	124.17	79.02	80.25	85.75	79.55	-30.00	30.00

Table: Social welfare maximization problem with marginal cost of public funds.

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100	151.37	113.83	116.45	81.16	81.16	30.00	-29.96	30.00	-8.93
200	141.63	95.88	103.98	87.11	84.47	28.42	-30.00	30.00	-0.28
300	120.05	84.72	107.15	88.24	82.70	3.33	-30.00	30.00	28.95

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Directions for future work

- Investigating the role of value judgements when optimizing social welfare: distributional preferences, policy acceptability, perceived fairness, etc.

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- We investigate tradeoffs related to the decision variables and their domains.
- Assortment and pricing are two common supply problems.

Continuous (CPP) vs Discrete (DPP) Pricing Problem

Prices p are the only set of decision variables for supplier k .
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$$U_{inr} = \beta_{p,inr} p_i + \hat{q}_{inr} + \xi_{inr} \quad \forall i \in I_k, \forall n \in N, \forall r \in R.$$

- The linearization of the product $p_i \cdot x_{inr}$ (continuous and binary) can be done using big-M constraints.

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Discrete formulation:

- Prices p_i of each alternative $i \in I_k$ are chosen from a finite set.
- Utilities are parameters of the optimization model: $\hat{U}_{inr} = \beta_{p,inr} \hat{p}_i + \hat{q}_{inr} + \xi_{inr}$.
- Binary variables y capture the choice of the price level by the supplier.

Numerical experiments

$ R $	CPP		DPP			Gap
	Time	Opt	$ I_i^{exp} $	Time	Opt	
100	101.64	66452.18	21	34.48	66118.40	0.50%
			51	161.03	66255.90	0.30%
			101	395.86	66341.32	0.17%
200	288.89	70788.17	21	139.17	69859.60	1.31%
			51	415.90	70489.95	0.42%
			101	1829.24	70571.67	0.31%

Table: High-speed rail pricing: solving CPP and DPP to optimality with CPLEX.

Assortment and Pricing Problem

- We include the binary decision variables y about offering or not any product to customers.

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$ R $	ACPP		ADPP			Gap
	Time	Opt	$ I_i^{exp} $	Time	Opt	
10	11706	907.8	16	132	864.0	4.82%
			31	800	876.0	3.50%
20	129600*	877.0*	16	429	842.0	3.99%
			31	2778	862.5	1.65%

Table: Parking assortment and pricing: solving ACPP and ADPP to optimality with CPLEX.

Structure of the ADPP

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$$\begin{aligned}
 \max_{\mathbf{x}} \quad & U = \sum_{i \in I} \hat{U}_i x_i, \\
 \text{s.t.} \quad & \sum_{i \in I} x_i = 1, \\
 & x_i \leq y_i^* \quad \forall i \in I, \\
 & x_i \geq 0 \quad \forall i \in I.
 \end{aligned}$$

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- Continuous knapsack problem:
 - knapsack's capacity = 1;
 - weight of each item i (alternative) = 1;
 - value of each item i (alternative) = \hat{U}_i .

Structure of the ADPP

- The discrete upper-level variables \mathbf{y} of the supplier represent a joint decision on assortment and discrete price.
- If we fix these variables to \mathbf{y}^* , the lower-level utility maximization problem for a single customer n and scenario r is as follows:

$$\begin{aligned}
 \max_{\mathbf{x}} \quad & U = \sum_{i \in I} \hat{U}_i x_i, \\
 \text{s.t.} \quad & \sum_{i \in I} x_i = 1, \\
 & x_i \leq y_i^* \quad \forall i \in I, \\
 & x_i \geq 0 \quad \forall i \in I.
 \end{aligned}$$

- Continuous knapsack problem:
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- Benders decomposition to exploit duality.

Benders decomposition Branch-and-Benders-cut implementation

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- Benders cuts can be inserted while processing the branch-and-bound tree of the master problem.³
- Efficient cut generation is key to the success of this approach.
- Some attempts:
 - Pareto-optimal cuts;⁴
 - minimal infeasible subset cuts;
 - partial Benders decomposition;⁵
 - etc.

³Fischetti, Ljubić, and Sinnl, “Redesigning Benders decomposition for large-scale facility location” (2017).

⁴Magnanti and Wong, “Accelerating Benders decomposition: Algorithmic enhancement and model selection criteria” (1981).

⁵Crainic et al., “Partial Benders decomposition: General methodology and application to stochastic network design” (2021).

Computational performance: facility location and pricing

$ R $	$ I_i^{exp} $	Best	CPLEX (s)	BBC (s)	DualTime (%)
50	3	2625.00	4.92	33.78	0.84
50	6	2814.00	47.69	108.52	0.79
50	12	2892.00	684.46	383.59	0.52
100	3	2567.00	17.85	62.96	0.78
100	6	2857.00	258.60	237.33	0.61
100	12	2865.00	2047.72	1476.88	0.32
200	3	2588.50	39.53	131.01	0.75
200	6	2861.50	215.05	515.43	0.63
200	12	2861.50	4025.04	3268.00	0.25
500	3	2572.20	221.06	369.10	0.68
500	6	2824.30	1753.52	1784.22	0.38
500	12	2835.65	46166.88	20903.66	0.10
1000	3	2580.80	677.68	720.91	0.41
1000	6	2809.45	7913.22	6988.75	0.13
1000	12	2820.25	172000.00*	100862.04	0.03

Table: *N818* instances: running time for the ADPP using CPLEX and the BBC algorithm with disaggregate Benders cuts.

Conclusion of the section

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- Testing simulation and decomposition on problems with complex interactions at the alternative and at the customer level (e.g. network design, scheduling).

- 1 Introduction
- 2 A simulation-based heuristic to find approximate equilibria with disaggregate demand models
- 3 Price-based regulation of oligopolistic markets under discrete choice models of demand
- 4 Benders decomposition for choice-based optimization problems
- 5 Conclusion

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- The **trade-off** between the realism of the demand model and the complexity of the resulting optimization problem must be evaluated case by case.
- The possibility to **personalize offers and differentiate policies** provides a strong case for disaggregate demand models.
- This thesis contributes with **exact and heuristic algorithms** for realistic optimization and equilibrium problems with **disaggregate demand**.

Discussion

