Uncertainty in Recurrent Decision Tree Classifiers

Stefan Wezel

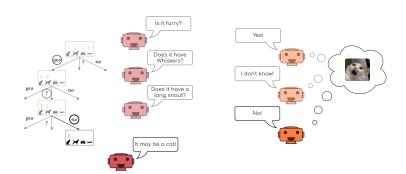
Explainable Machine Learning

October 17, 2020

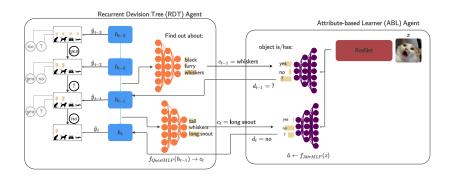
- There are a lot of architectures that perform great on image classification tasks
- o Maybe, most prominently: ResNet
- o However, they only yield a classification
- In many settings a classification is not worth much without the reasoning behind it



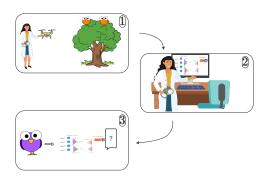
- o Two agents
- o One is asking questions and one is answering them
- o The unfolding decision process is an interpretable tree



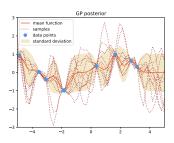
- o Two agents
- o One is asking questions and one is answering them
- o The unfolding decision process is an interpretable tree



Why do we need uncertainty?

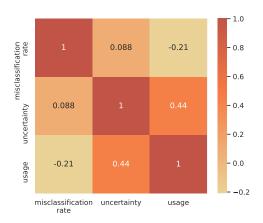


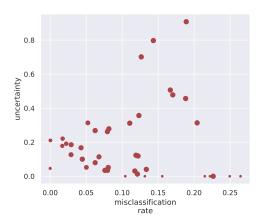
- The ornithologist is tasked to survey bird species, which she automates using a drone and computer vision software
- She uses our model to go through the vast amount of collected data
- Some bird species unknown to the model appear in the data.
 The model yields high uncertainty and the ornithologist can classify them manually

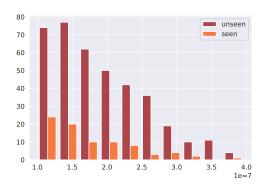


- o Data points can be described by (infinitely) many functions
- o A GP is a PDF over these functions
- $\circ\,$ Parameterized by mean function and covariance function
- The variance resembles the model uncertainty where no data is given





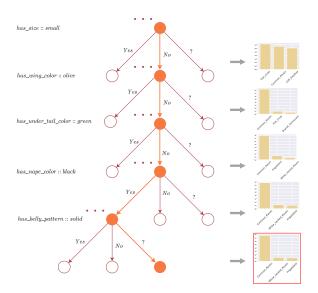




| | AWA2 | aPY | CUB | |
|-----------------|-----------|-----------|-----------|--|
| ResNet [HZRS16] | 98.2± 0.0 | 85.1± 0.6 | 79.0± 0.2 | |
| DT | 78.0± 0.4 | 64.3± 0.6 | 19.3± 0.3 | |
| dNDF[KFCRB15] | 97.6± 0.2 | 85.0± 0.6 | 73.8± 0.3 | |
| RDTC[AA19] | 98.0± 0.1 | 85.7± 0.7 | 78.1± 0.2 | |
| XDT | 73.9± 0.9 | 59.9± 1.5 | 4.9± 1.3 | |
| aRDTC[AA19] | 98.6 | 86.1 | 77.9± 0.6 | |
| remRDTC(ours) | 98.7 | 86.4 | 77.7 | |
| extRDTC(ours) | 98.7 | 85.4 | 77.8 | |

| | aRDTC [AA19] | Random Baseline | remRDTC | extRDTC |
|-----------|--------------|-----------------|---------|---------|
| AWA2 | | | | |
| Class | 98.6 | 98.5 | 98.7 | 98.7 |
| Attribute | e 80.4 | 84.6 | 87.5 | 82.31 |
| aPY | | | | |
| Class | 86.1 | 86.5 | 86.4 | 85.4 |
| Attribute | e 86.4 | 86.2 | 87.6 | 87.12 |
| CUB | | | | |
| Class | 77.9 | 76.8 | 77.7 | 77.8 |
| Attribute | e 68.6 | 70.0 | 77.4 | 82.6 |

Conclusions A qualitative Example



- [AA19] Stephan Alaniz and Zeynep Akata. Explainable observer-classifier for explainable binary decisions. arXiv preprint arXiv:1902.01780, 2019.
- [HZRS16] Kaiming He, Xiangyu Zhang, Shaoqing Ren, and Jian Sun. Deep residual learning for image recognition. In Proceedings of the IEEE conference on computer vision and pattern recognition, pages 770–778, 2016.
- [KFCRB15] Peter Kontschieder, Madalina Fiterau, Antonio Criminisi, and Samuel Rota Bulo. Deep neural decision forests. In Proceedings of the IEEE international conference on computer vision, pages 1467–1475, 2015.