Missing Data Imputation

Overview of General Issues and Solutions

Stef van Buuren, University of Utrecht & TNO

December 19, 2019; Building Multi-Source Databases for Comparative Analyses

Overview

- Missing data and harmonization
- Multiple imputation in a nutshell
- Alternatives for recoding
- Imputation of multilevel data

Why this course

- Missing data are everywhere
- ► Harmonization is an attempt to solve a missing data problem
- ► Ad-hoc fixes do not (always) work
- Multiple imputation is broadly applicable, yield correct statistical inferences
- ► Goal of the course: introduce mice as a way to think about data harmonization

Course materials

- ► Slides 1: https://github.com/stefvanbuuren/harmonisation_warsaw_2019/blob/master/Lecture_1/Lecture_1.pdf
- ► Slides 2: https://github.com/stefvanbuuren/harmonisation_warsaw_2019/blob/master/Lecture_2/Lecture_2.pdf
- Materials: https://www.asc.ohio-state.edu/dataharmonization/wp-content/uploads/2019/12/Workshop-Missing-Data-Imputation-Materials-Kotnarowski-2019-FINAL.pdf

Reading materials

- Van Buuren, S. and Groothuis-Oudshoorn, C.G.M. (2011). mice: Multivariate Imputation by Chained Equations in R. Journal of Statistical Software, 45(3), 1–67. https://www.jstatsoft.org/article/view/v045i03
- ▶ Van Buuren, S. (2018). Flexible Imputation of Missing Data. Second Edition. Chapman & Hall/CRC, Boca Raton, FL. https://stefvanbuuren.name/fimd

Chapman & Hall/CRC Interdisciplinary Statistics Series

Flexible Imputation of Missing Data

SECOND EDITION

Stef van Buuren 👩



Today's schedule

Slot	Time	What	Topic
A	10.00-11.30	L	Multiple imputation intro
	11.30-11.45		COFFEE/TEA
В	11.45-13:15	L	Imputation for harmonisation
	13.15-14.30		LUNCH
C	14.30-16.00	Р	Lab session: Kotnarowski, IFiS
	13.15-14.30		COFFEE/TEA
D	16.15-17.30	Р	Lab session: Kotnarowski, IFiS

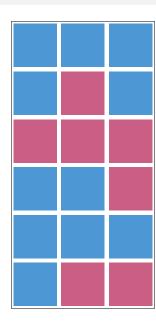
Definition of missing values

- Missing values are those values that are not observed
- Values do exist in theory, but we are unable to see them

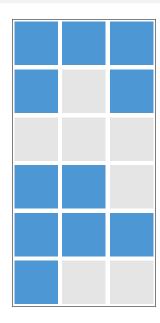
Some confusing terminology

- ▶ Complete data = Observed data + Unobserved data
- ▶ Incomplete data = Observed data
- Missing data = Unobserved data
- ► Complete cases = Subset of rows without missing values
- ► Complete variables = Subset of columns without missing values

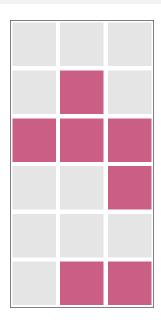
Complete data



${\sf Incomplete\ data} = {\sf observed\ data}$



${\sf Missing\ data} = {\sf unobserved\ data}$



Why values can be missing

Missingness can occur for a lot of reasons. For example

- power failure, bad luck
- death, dropout, refusal
- routing, experimental design
- ▶ join, merge, bind
- different variables per source
- different number of categories per source

Consequences of missing data

- ► Cannot calculate, not even the mean
- Less information than planned
- Enough statistical power?
- ▶ Different analyses, different n's
- Systematic biases in the analysis
- ► Appropriate confidence interval, *P*-values?

Missing data can severely complicate interpretation and analysis

Strategies to deal with missing data

- Prevention impossible for ex-post analyses
- Weighting methods
- ► Likelihood methods, EM-algorithm
- ► Ad-hoc methods, e.g., single imputation, complete cases, recoding
- Multiple imputation

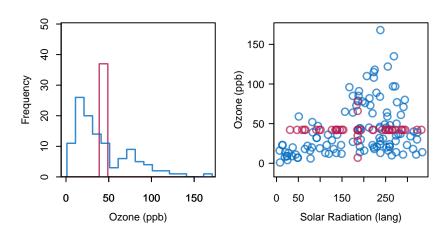
Listwise deletion, complete-case analysis

- Analyze only the complete records
- Advantages
 - Simple (default in most software)
 - Unbiased under MCAR
 - ► Conservative standard errors, significance levels
 - ▶ Two special properties in regression

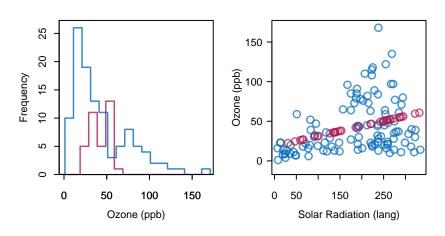
Listwise deletion, complete-case analysis

- Disadvantages
 - Wasteful
 - May not be possible
 - Larger standard errors
 - ▶ Biased under MAR, even for simple statistics like the mean
 - Inconsistencies in reporting

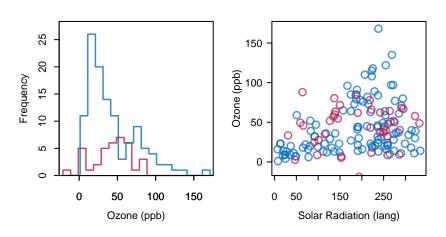
Mean imputation



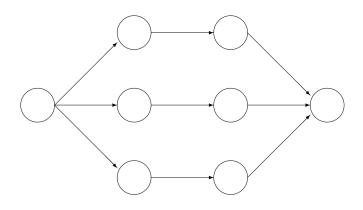
Regression imputation



Stochastic regression imputation



Multiple imputation



Incomplete data Imputed data Analysis results Pooled result

Acceptance of multiple imputation

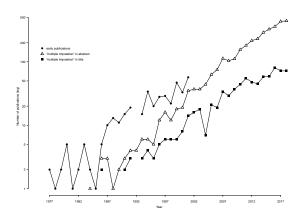


Figure 1: Source: Scopus (April 3, 2019)

Pooled estimate \bar{Q}

 \hat{Q}_ℓ is the estimate of the ℓ -th repeated imputation \hat{Q}_ℓ contains k parameters, represented as a k imes 1 column vector Pooled estimate \bar{Q} is simply the average

$$ar{Q} = rac{1}{m} \sum_{\ell=1}^m \hat{Q}_\ell$$

Within-imputation variance

Average of the complete-data variances as

$$\bar{U} = \frac{1}{m} \sum_{\ell=1}^{m} \bar{U}_{\ell},$$

where $\bar{\it U}_\ell$ is the variance-covariance matrix of $\hat{\it Q}_\ell$ obtained for the $\ell\text{-th}$ imputation

 $ar{U}_\ell$ is the variance is the estimate, *not* the variance in the data Within-imputation variance is large if the sample is small

Between-imputation variance

Variance between the m complete-data estimates is given by

$$B = rac{1}{m-1} \sum_{\ell=1}^{m} (\hat{Q}_{\ell} - \bar{Q})(\hat{Q}_{\ell} - \bar{Q})',$$

where \bar{Q} is the pooled estimate.

The between-imputation variance is large there many missing data

Total variance

The total variance is *not* simply $T = \bar{U} + B$

The correct formula is

$$T = \bar{U} + B + B/m$$
$$= \bar{U} + \left(1 + \frac{1}{m}\right)B \tag{1}$$

for the total variance of $ar Q_m$, and hence of (Q-ar Q) if ar Q is unbiased The term B/m is the simulation error

Three sources of variation

In summary, the total variance T stems from three sources:

- 1. U, the variance caused by the fact that we are taking a sample rather than the entire population. This is the conventional statistical measure of variability;
- 2. *B*, the extra variance caused by the fact that there are missing values in the sample;
- 3. B/m, the extra simulation variance caused by the fact that \bar{Q}_m itself is based on finite m.

Variance ratio's (1)

Proportion of the variation attributable to the missing data

$$\lambda = \frac{B + B/m}{T}$$

Relative increase in variance due to nonresponse

$$r = \frac{B + B/m}{\bar{U}}$$

These are related by $r = \lambda/(1-\lambda)$.

Variance ratio's (2)

Fraction of information about Q missing due to nonresponse

$$\gamma = \frac{r + 2/(\nu + 3)}{1 + r}$$

This measure needs an estimate of the degrees of freedom ν (c.f. section 2.3.6)

Relation between γ and λ

$$\gamma = \frac{\nu+1}{\nu+3}\lambda + \frac{2}{\nu+3}.$$

The literature often confuses γ and λ .

Statistical inference for \bar{Q} (1)

The $100(1-\alpha)\%$ confidence interval of a \bar{Q} is calculated as

$$\bar{Q} \pm t_{(\nu,1-\alpha/2)} \sqrt{T}$$

where $t_{(\nu,1-\alpha/2)}$ is the quantile corresponding to probability $1-\alpha/2$ of t_{ν} .

For example, use t(10,0.975)=2.23 for the 95% confidence interval for $\nu=10$.

Statistical inference for \bar{Q} (2)

Suppose we test the null hypothesis $Q=Q_0$ for some specified value Q_0 . We can find the P-value of the test as the probability

$$P_s = \Pr\left[F_{1,\nu} > rac{(Q_0 - \bar{Q})^2}{T}
ight]$$

where $F_{1,\nu}$ is an F distribution with 1 and ν degrees of freedom.

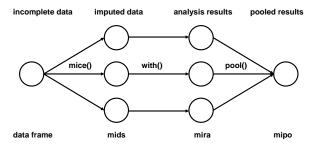
How large should m be?

Classic advice: m = 3, 5, 10. More recently: set m higher: 20–100.

Some advice:

- ▶ Use m=5 or m=10 if the fraction of missing information is low, $\gamma < 0.2$.
- ▶ Develop your model with m = 5. Do final run with m equal to percentage of incomplete cases.

Multiple imputation in mice



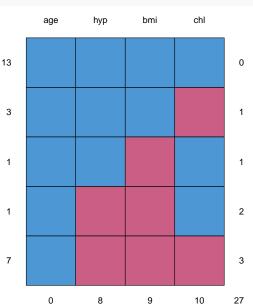
Inspect the data

```
library("mice")
head(nhanes)
```

```
## age bmi hyp chl
## 1 1 NA NA NA
## 2 2 22.7 1 187
## 3 1 NA 1 187
## 4 3 NA NA NA
## 5 1 20.4 1 113
## 6 3 NA NA 184
```

Inspect missing data pattern

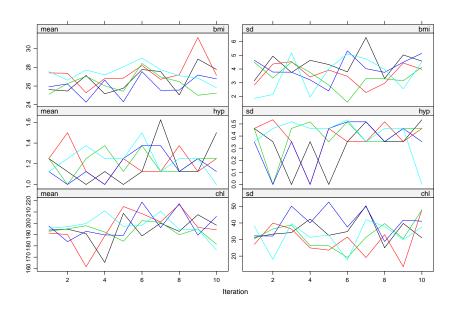
md.pattern(nhanes)



Multiply impute the data

```
imp <- mice(nhanes, print = FALSE, maxit=10, seed = 24415)</pre>
```

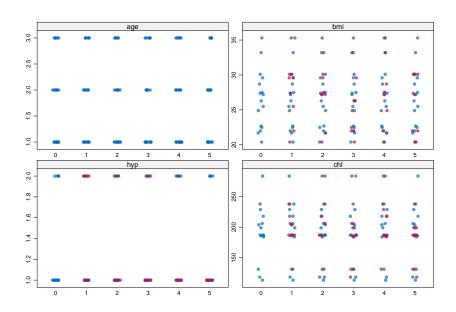
Inspect the trace lines for convergence



Stripplot of observed and imputed data

```
stripplot(imp, pch = 20, cex = 1.2)
```

Stripplot of observed and imputed data

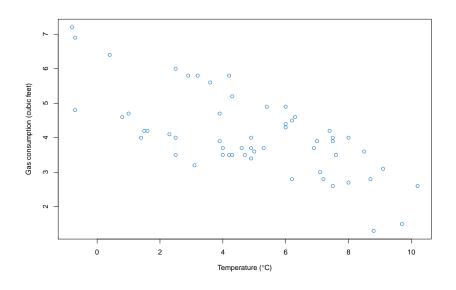


Fit the complete-data model

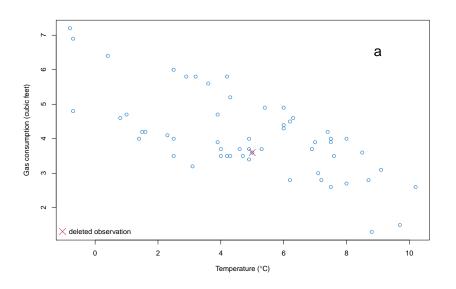
```
fit <- with(imp, lm(bmi ~ age))
est <- pool(fit)
summary(est)</pre>
```

```
## estimate std.error statistic df p.value
## (Intercept) 30.69 2.09 14.70 13.4 1.16e-09
## age -2.35 1.01 -2.33 17.4 3.23e-02
```

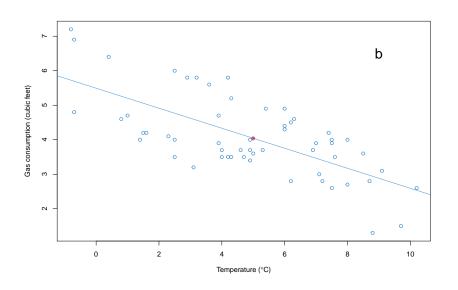
Temperature and gas consumption



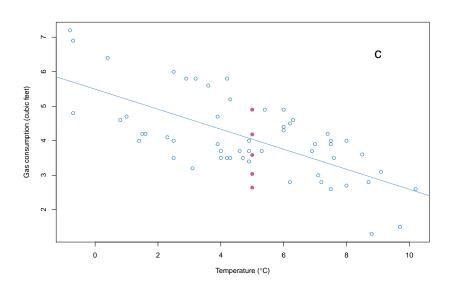
Delete gas consumption of day 47



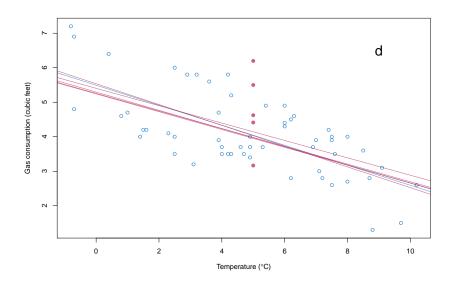
Predict value from regression line



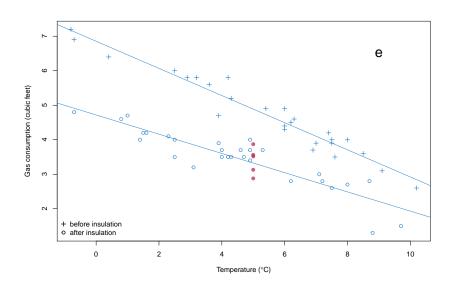
Predict value + add noise



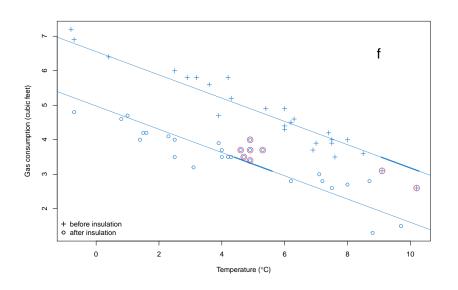
Predict + noise + parameter draw



Two predictors



Drawing from observed data



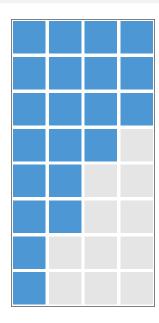


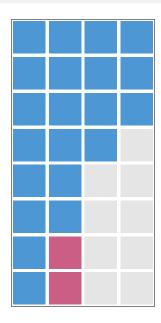
Missing data patterns

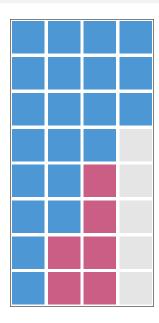


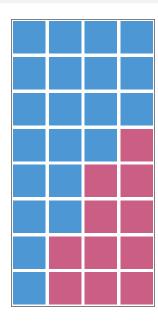
Three general strategies

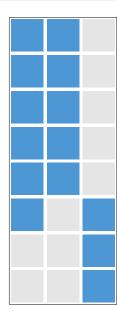
- Monotone data imputation
- Joint modeling
- ► Fully conditional specification (FCS)

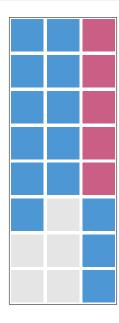


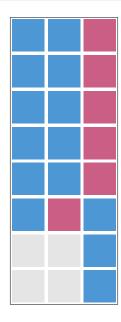


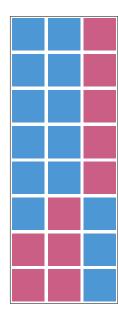




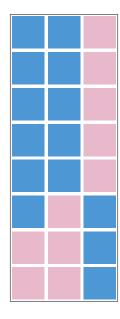




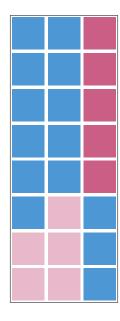


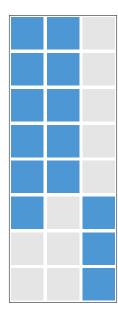


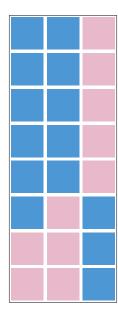
Joint modelling - next iteration

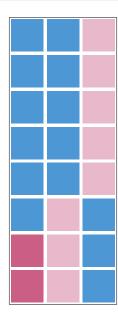


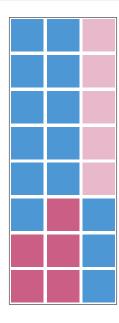
Joint modelling - next iteration

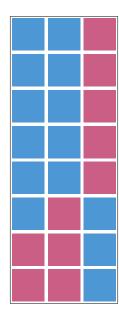




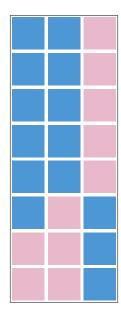




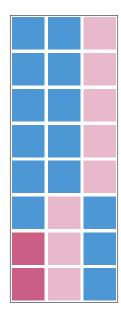




Fully conditional specification - next



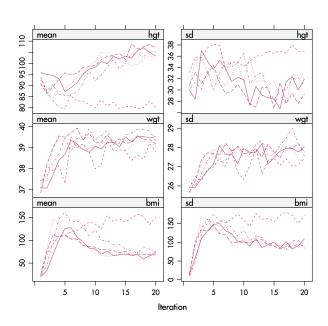
Fully conditional specification - next



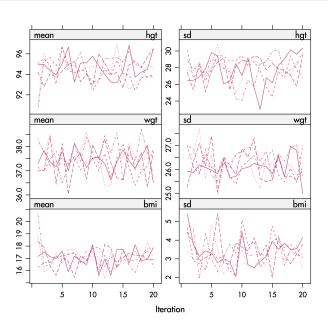
How many iterations?

- Quick convergence
- ▶ 5–10 iterations is adequate for most problems
- More iterations is λ is high
- Inspect the generated imputations
- Monitor convergence to detect anomalies

Non-convergence



Convergence



Conclusion

- ► A general problem, a general solution
- ▶ mice package: >50,000 downloads per month
- Highly useful for data combination