# EECE6036 - Homework 3

Wayne Stegner

November 1, 2020

## 1 Problem 1

## 1.1 Problem Summary

The goal of this problem is to create a multi-layer feed-forward neural network for classification of the MNIST dataset. The network was trained using gradient descent with back-propagation with momentum, and is trainable for arbitrary amounts and sizes of hidden layers. During training, the loss is calculated using  $J_2$  loss with threshold values. For performance measurement, the loss is calculated as  $1-hit\_rate$  using winner-take-all on the output layer to define the predicted class.

#### 1.2 Results

### 1.2.1 System Description

Table 1 shows the hyper-parameters used in training the classifier. These hyper-parameters were found empirically, considering both minimizing the final loss and training time. More work can to find more optimal hyper-parameters, but this set of hyper-parameters produces pretty good results.

Table 1: Classifier Training Hyper-Parameters

Table 1. Classifier Training Tryper Farameters		
Parameter	Value	Description
$hidden\_layer\_size$	192	Neurons in hidden layer
$\mid \eta \mid$	0.05	Learning rate
$\alpha$	0.8	Momentum
$max\_epochs$	500	Maximum training epochs
$\mid L$	0.25	Lower activation threshold
$\mid H \mid$	0.75	Upper activation threshold
patience	3	Patience before early stopping
$es\_delta$	0.01	Delta value for early stopping

Weight initialization is done randomly on a uniform distribution between (-a, +a) where  $a = \sqrt{\left(\frac{6}{N_{source} + N_{target}}\right)}$ , and  $N_{source}$  and  $N_{target}$  are the numbers of neurons on the source and target layers respectively.

The network utilizes early stopping by monitoring a validation set, which consists of 1000 training points that are set aside before training. If the validation loss does not improve for patience steps (1 step = 10 epochs), training halts. The validation is considered improved if the validation is  $es\_delta$  lower than the previous improved validation loss. The weights used by the final network are the weights from the epoch with the lowest validation loss. To improve the frequency of checking for early stopping, the network only uses 1000 training points per epoch.

#### 1.2.2 Network Results

Throughout the duration of training, the loss of the training and validation sets was tracked every 10 epochs. Figure 1 shows a plot of the loss values while training the classifier. The vertical line designates the point where the validation error is minimized, which occurs at epoch 50. The weights at that epoch are the weights used in the final network, where the test loss is 0.070.

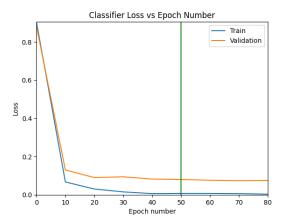


Figure 1: Training and validation loss of the classifier.

Figure 2 shows the confusion matrices for the train and test sets using the weights from the best epoch.

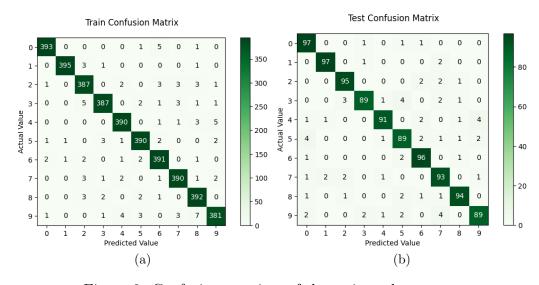


Figure 2: Confusion matrices of the train and test sets.

## 1.3 Discussion and Analysis of Results

Overall, the results look pretty good. The best weights happen pretty early at epoch 50 and get a fairly low loss of 0.070. While testing hyper-parameters, it was observed that when es\_delta is set to 0 and patience is increased to around 5, the test loss would sometimes get as low as 0.05, but that generally occurred after several hundred epochs and is also dependent on weight initialization numbers and dataset shuffling during training. With the early stopping hyper-parameters used by this model, it sacrifices some performance, but it trains significantly faster, making these hyper-parameters ideal for implementing and troubleshooting the network from scratch.

The diagonal of the confusion matrices in Figure 2 is very dark, with hardly any coloring in the incorrect boxes. Many of the incorrect classifications are in two classes which look similar. For example, Figure 2a shows four 9s classified as 4s and five 4s classified as 9s. This mix-up makes a lot of sense, because the shapes of 4s and 9s tend to be similar, especially with some of the sloppy handwriting in MNIST.

#### 1.4 Conclusion

This multi-layer feed-forward neural network classifier is able to effectively classify the MNIST dataset given in this problem. While the results are certainly not state-of-the-art, the trained network classifies over 90% of the test set digits correctly. Further testing in optimizing the hyper-parameters of the network can help to improve the accuracy even further.

## 2 Problem 2

## 2.1 Problem Summary

The goal of this problem is to create a multi-layer feed-forward neural network similar to Problem 1, except in this case it will be trained to be an autoencoder. This network has the same features as the network in Problem 1, except the performance measurement is calculated using  $J_2$  loss instead of  $1 - hit\_rate$ . Additionally, winner-take-all is not used in the output layer, because it does not make sense in the context of an autoencoder.

#### 2.2 Results

## 2.2.1 System Description

Table 2 shows the hyper-parameters used in training the autoencoder. As with the classifier, these hyper-parameters were found empirically with the same consideration for minimizing final loss and training time.

Table 2: Autoencoder Training Hyper-Parameters

Parameter	Value	Description
$hidden\_layer\_size$	192	Neurons in hidden layer
$\eta$	0.005	Learning rate
$\alpha$	0.8	Momentum
$max\_epochs$	500	Maximum training epochs
L	0	Lower activation threshold
H	1	Upper activation threshold
patience	3	Patience before early stopping
$es\_delta$	0.1	Delta value for early stopping

The weight initialization process is the same as in Problem 1, as are the processes for allocating the validation set and applying early stopping.

#### 2.2.2 Network Results

Throughout the duration of training, the loss of the training and validation sets was tracked every 10 epochs. Figure 3 shows a plot of the loss values while training the autoencoder. The vertical line designates the point where the validation error is minimized, which occurs at epoch 160. The weights at that epoch are the weights used in the final network, where the test loss is 2.087.

After training, the loss in each class was measured. Figure 4 shows the loss of each class for the train and test sets using the weights from the best epoch.

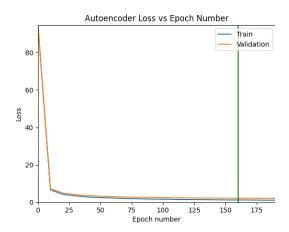


Figure 3: Training and validation loss of the autoencoder.

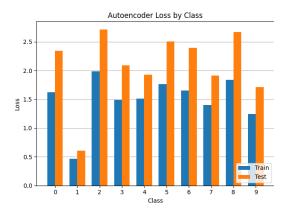


Figure 4: Loss of each class of the train and test sets.

#### 2.2.3 Features

After training, the features learned by 20 arbitrary neurons in the hidden layer of both the classifier and autoencoder were observed by normalizing the weights from 0 to 1 and then displaying them like an image. The images are mapped so 1 is white and 0 is black. Figure 5 shows the features of the classifier, and Figure 6 shows the features of the autoencoder.

#### 2.2.4 Sample Outputs

After training, the outputs of eight random data points from the test set were fed reconstructed the autoencoder, meaning the input data point was presented to the network and the output "prediction" was obtained. Figure 7 shows the original and reconstructed images.

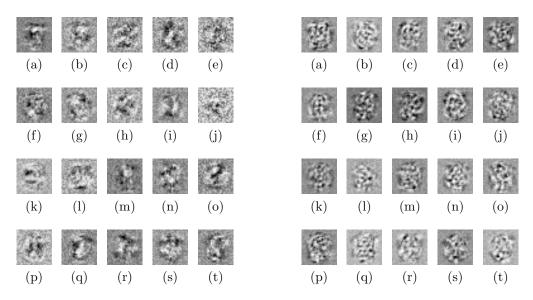


Figure 5: Classifier features.

Figure 6: Autoencoder features.

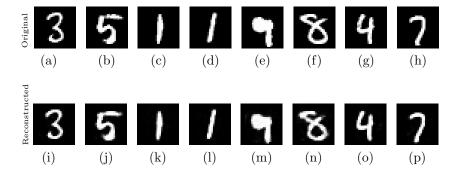


Figure 7: Original (top) and reconstructed (bottom) data points.

# 2.3 Discussion and Analysis of Results

Overall, the results look pretty good. The autoencoder takes longer to train, with its best weights occurring at epoch 160 with a loss of 2.087. In Figure 4, the loss for the 1s is particularly salient because it is drastically lower than the other classes loss values. This makes sense because a 1 is simply a straight line, so it should be quite simple to recognize and then reconstruct. While none of the loss values are as noticeably high as 1's loss is low, classes 2, 8, and 5 all have loss values above 2.5. I do not have any intuition as to why those numbers have the highest loss, but those digits are kind of similar in the sense that a 2 is roughly a backward 5, and stacking a 2 on top of a 5 roughly makes an 8. At first, I was surprised that 6 has a higher loss than

9, because 6 is just an upside-down 9, but it makes sense that 5 and 6 have similar features and ended up having similar loss values.

The features in Figure 5 and Figure 6 are somewhat difficult to interpret. Between the two feature sets, there is a trend where the center of the image appears to have some distinct patterns, while the edge of the image is either somewhat uniform gray or random TV static. This trend makes sense because the digits in the images tended to be mostly centered, so the edge pixels mostly contained 0. When the presented input is 0, the weight delta is 0 according to the back-propagation formula, meaning that the edge of the images did not get updated as much as the center of the image. In Figure 5, the shapes generally seem to be lines or curves, while in Figure 6 the features look like a bunch of dark dots with a few brighter spots.

#### 2.4 Conclusion

This multi-layer feed-forward neural network autoencoder is able to effectively reconstruct digits from the MNIST dataset. Further testing in optimizing the hyper-parameters of the network can help to improve the reconstruction accuracy even further.

# A Code

## A.1 settings.py

```
# Imports
*****
                                import pathlib
import numpy as np
# Constant Values
# Common constants
TRAIN_PORTION = 0.8
SEED = 69420
INPUTS = 784
HIDDEN_LAYER_SIZES = [192]
CLASSES = 10
# Classifier constants
CLASS_POINTS_PER_EPOCH = 1000
CLASS_VALID_POINTS = 1000
CLASS_MAX_EPOCHS = 500
CLASS_HAZ_EPUCHS
CLASS_ETA = 0.05
CLASS_ALPHA = 0.8
CLASS_L = 0.25
CLASS_H = 0.75
CLASS_PATIENCE = 3
CLASS_ES_DELTA = 0.01
# Autoencoder constants
AUTO_POINTS_PER_EPOCH = 1000
AUTO_VALID_POINTS = 1000
AUTO_MAX_EPOCHS = 500
AUTO_ETA = 0.005
 AUTO_ALPHA = 0.8
AUTO_L = 0
AUTO_H = 1
AUTO_PATIENCE = 3
AUTO_ES_DELTA = 0.1
# File locations
# Directory of current file
CODE_DIR = pathlib.Path(__file__).parent.absolute()
# Root directory of the project
ROOT_DIR = CODE_DIR.parent
# Dataset locations
# Dataset locations
DATA_FILE = CODE_DIR.joinpath('data.txt')
LABEL_FILE = CODE_DIR.joinpath('dataset')
DATASET_DIR = CODE_DIR.joinpath('dataset')
DATASET_DIR.mkdir(mode=0o755, exist_ok=True)
TRAIN_DATA_FILE = DATASET_DIR.joinpath('train_data.npy')
TRAIN_LABELS_FILE = DATASET_DIR.joinpath('train_labels.npy')
TEST_DATA_FILE = DATASET_DIR.joinpath('test_data.npy')
TEST_LABELS_FILE = DATASET_DIR.joinpath('test_data.npy')
# Image directory
IMG_DIR = ROOT_DIR.joinpath('images')
IMG_DIR.mkdir(mode=0o775, exist_ok=True)
# Data directory
DATA_DIR = ROOT_DIR.joinpath('data')
DATA_DIR.mkdir(mode=0o775, exist_ok=True)
DATA_DIR.mkdir(mode=0o775, exist_ok=True)

# Classifier locations
CLASS_MODEL_DIR = CODE_DIR.joinpath('class')
CLASS_MODEL_DIR mkdir(mode=0o775, exist_ok=True)
CLASS_MODEL_DIR.mkdir(mode=0o775, exist_ok=True)
CLASS_PLOT = IMC_DIR.joinpath('class_loss.png')
CLASS_PRAM_CSV = DATA_DIR.joinpath('class_parameters.csv')
CLASS_BEST_EPOCH = DATA_DIR.joinpath('class_best_epoch.dat')
CLASS_TRAIN_CONF = IMC_DIR.joinpath('train_conf_mat.png')
CLASS_TEST_LOSS = DATA_DIR.joinpath('test_conf_mat.png')
CLASS_TEST_LOSS = DATA_DIR.joinpath('class_test_loss.dat')
CLASS_FEAT_DIR = IMC_DIR.joinpath('class_feat')
CLASS_FEAT_DIR.mkdir(mode=0o775, exist_ok=True)
# Autoencoder files
   Autoencoder files
# Autoencoder files
AUTO_MODEL_DIR = CODE_DIR.joinpath('auto')
AUTO_MODEL_DIR.mkdir(mode=0o775, exist_ok=True)
AUTO_LOSS_PLOT = IMG_DIR.joinpath('auto_loss.png')
AUTO_PARAM_CSV = DATA_DIR.joinpath('auto_parameters.csv')
AUTO_BEST_EPOCH = DATA_DIR.joinpath('auto_best_epoch.dat')
```

# A.2 dataset.py

```
# Imports
from settings import *
import numpy as np
def shufflePair(data, labels):
    """Shuffle a pair of data and labels in place
   Parameters
   data, labels : np.ndarray
Data and labels to be shuffled
   assert len(data) == len(labels), \
   'Size mismatch between data and labels' indeces = np.random.permutation(len(data))
   data[...] = data[indeces]
labels[...] = labels[indeces]
if __name__ == '__main__':
    # Additional imports
   import pathlib
# Seed for consistency
np.random.seed(SEED)
    # Import dataset
    data = [d.split() for d in data]
labels = list()
with open(LABEL_FILE) as label_f:
    labels = label_f.readlines()
labels = [int(1) for l in labels]
# Sort into bins based on class
   data_points = dict()
classes = list()
for d, l in zip(data, labels):
    if l not in classes:
          classes.append(1)
data_points[1] =
   data_points[1].append(d)
classes.sort()
   # Turn data lists into numpy arrays
for l in classes:
       data_points[1] = np.array(data_points[1], dtype=np.float64)
   # Partition dataset
   train_data = list()
train_labels = list()
   test_data = list()
test_labels = list()
```

# A.3 layer.py

```
import numpy as np
class Layer:
     def __init__(
                self,
                 weight_file = None,
num_neurons = None,
                 inputs = None,
           ):
"""Initialize Layer object either randomly or by a weight file
           File to load pre-existing weights from num_neurons, inputs : int, optional Number of hidden neurons and inputs to the layer
           weight_file : str, optional
           if weight_file:
                 # Load saved weights
                 self.loadWeights(weight_file)
self.num_neurons = self.w.shape[0]
                 self.inputs = self.w.shape[1]
           else:
                 # Randomly initialize weights
self.num_neurons = num_neurons
                 self.inputs = inputs
self.initW()
           # States to save for back-prop
self.x = None # Input for current pass
self.s = None # Net inputs pre-activation function
self.y = None # Final output of the layer
self.delta = None # Delta of this layer
self.w_change = np.zeros(self.w.shape) # Weight changes
              "Initialize weights for the perceptron using Xavier initialization
           0.00
           w_shape = (self.num_neurons, self.inputs + 1)
a = np.sqrt(6 / (self.inputs + self.num_neurons))
self.w = np.random.uniform(-a, a, size=w_shape)
self.w_change = np.zeros(self.w.shape)
```

```
def forwardPass(self, x):
    """Pass the input forward through the layer
           Parameters
           x : np.ndarray of np.float64
Input to the layer
           Returns
           np.array of np.float64

Output of the layer
           # Add bias input
           x = np.concatenate(([1], x))
# Save inputs for back-prop
self.x = x
           # Dot product weights * inputs
self.s = np.matmul(self.w, x)
# Pass through sigmoid activation
self.y = 1.0 / (1 + np.exp(-1 * self.s))
           return self.y
     def setDelta(self):
           """Calculate delta value, different for Output and Hidden layer
Must be implemented per-class
           raise NotImplementedError('Cannot call from Layer class')
     def getWChange(self, eta, alpha):
    """Calculate weight updates for the most recent forward pass
           Requires delta to be calculated (varies between hidden/output layers)
           Learning rate for weight adjustments alpha: float
           Momentum scalar
           # Set delta value
           self.setDelta()
           # Pre-scale weight change for momentum
           self.w_change *= alpha
# Calculate new weight change
           # Calculate new weight change
d = self.delta.reshape(len(self.delta), 1)
x = self.x.reshape(1, len(self.x))
new_change = eta * np.matmul(d, x)
self.w_change += new_change
     def changeW(self):
           """Apply w_change to the weights
           self.w += self.w_change
     {\tt def} \  \  {\tt saveWeights(self, weight\_file):}
           """Save weights to a file Parameters
           weight_file : str
   File name to save weights in
"""
           np.save(str(weight_file), self.w)
     def loadWeights(self, weight_file):
             ""Save weights to a file
           Parameters
           weight_file : str
    File name to save weights in
           self.w = np.load(str(weight_file))
if __name__ == '__main__':
    print('Warning: Tests for this file are deprecated')
```

# A.4 output\_layer.py

# A.5 hidden\_layer.py

# A.6 mlp.py

```
class MLP:
    def __init__(
               self,
                input_size=INPUTS,
           """Initialize Multi-Layer Perceptron object
           Parameters
          input_size : int
   Number of inputs to the network
"""
          # Initialize parameters
self.layers = list()
           self.input_size = input_size
    def addLayer(self, file_name=None, neurons=None, output=False):
           """Add a layer to the network
          if len(self.layers) == 0:
                input_size = self.input_size
           else:
          input_size = self.layers[-1].num_neurons
if file_name:
                if output
                     self.layers.append(OutputLayer(weight_file=file_name))
                     self.layers.append(HiddenLayer(weight_file=file_name))
                     self.layers.append(OutputLayer(num_neurons=neurons,
                          inputs=input_size))
                else:
                      self.layers.append(HiddenLayer(num_neurons=neurons,
                           inputs=input_size))
    def predict(self, data, one_hot):
    """Predict the output given an input
          Parameters
           data : np.ndarray
          Data point to predict on
one_hot : bool
Whether the output should be one-hot or raw
           Returns
          np.ndarray
Array of prediction
           # Forward pass through all the layers
layer_output = data
           for 1 in self.layers:
layer_output = 1.forwardPass(layer_output)
           if one_hot:
    max_idx = np.argmax(layer_output)
    pred = np.eye(10)[max_idx]
          pred = layer_output
return pred
     def trainPoint(self, data, label, eta, alpha, L, H):
    """Update the weights for a single point
    Parameters
          data : np.ndarray
The data point
labels : np.ndarray
           One-hot encoded label eta : float
          Learning rate alpha : float
           Momentum scalar
L, H : float, optional
Low and high thresholds for training
           # Weight change for last layer
          # Weight change for last layer
self.layers[-1].setLabel(label)
self.layers[-1].thresholdOutputs(L, H)
self.layers[-1].getWChange(eta, alpha)
          # Back-prop error
for i in range(len(self.layers)-2, -1, -1):
```

```
down_w = self.layers[i+1].w
                         down_delta = self.layers[i+1].delta
self.layers[i].setDownstreamSum(down_w, down_delta)
self.layers[i].getWChange(eta, alpha)
             # Apply weight changes
for 1 in self.layers:
                       l in self.l
l.changeW()
def logError(self,
                          train_data
                          train labels.
                          valid_data,
                          valid_labels,
                          epoch_num,
               """Log error for train/test data for a given epoch
             Parameters
             train_data : np.ndarray
            Array of data points for the train set
train_labels : np.ndarray
Array of labels for the train set
            Array of lanels for the vicinity valid_data : np.ndarray
Array of data points for the validation set
valid_labels : np.ndarray
Array of labels for the validation set
epoch_num : int
            The current epoch number
             # Evaluate and log train error
train_err = self.eval(train_data, train_labels)
            # Evaluate and log test error
valid_err = self.eval(valid_data, valid_labels)
             self.valid_err.append(valid_err)
             # Record epoch number
self.epoch_num.append(epoch_num)
            # Print out metrics
print(f'Epoch {epoch_num}')
print(f'\tTrain Loss:\t\t{train_err:0.03f}')
print(f'\tValidation Loss:\t{valid_err:0.03f}')
def train(self,
                          data,
                         labels.
                          points_per_epoch,
                            valid_points,
                         max_epochs,
                         alpha,
                         L,
H,
                         patience,
                          es_delta,
                         save_dir,
            ): \label{eq:continuous} \begin{tabular}{lll} \tt """Train & the network & up to the desired number of epochs \\ \tt """Train & the network & up to the desired number of epochs \\ \tt """Train & the network & up to the desired number of epochs \\ \tt """Train & the network & up to the desired number & up to the network & up to the ne
             Parameters:
             data : np.ndarray
             Array of training data points labels : np.ndarray
             Array of training labels
points_per_epoch : int
Number of training points to use in each epoch
             valid_points : int

Number of training points to set aside for validation
These points are set aside before training
             max_epochs : int
Maximum number of epochs to train
             eta, alpha : float
Learning rate and Momentum scalar
            L, H: float
Low and high thresholds for training
patience: int
             Amount of epochs with no improvement before early stopping es_delta : float
                         Required improvement for early stopping
            save_dir : pathlib.Path or str
Directory to save best model parameters in
            # Initialize progress bar
pbar_manager = enlighten.get_manager()
```

```
pbar = pbar_manager.counter(total=max_epochs, desc='Training',
            self.logError(
                          train_data,
                         train_labels, valid_data,
                         valid_labels,
             # Iterate through epochs or until early stopping
             impatience = 0
self.best_weights_epoch = 0
             self.best_weights_epoch = 0
best_loss = np.inf
for e in range(1, max_epochs+1):
    pbar.update()
    shufflePair(train_data, train_labels)
                   epoch_train_data = train_data[:points_per_epoch]
epoch_train_labels = train_labels[:points_per_epoch]
for d, l in zip(epoch_train_data, epoch_train_labels):
    self.trainPoint(d, l, eta, alpha, L, H)
                   # Log data every 10 epochs
if (e % 10) == 0:
                          self.logError(
                                      epoch_train_data
                                       epoch_train_labels,
valid_data,
                                       valid_labels,
                          # Check for early stopping
if ((best_loss - self.valid_err[-1]) >= es_delta):
    impatience = 0
                                impatience = 0
self.best_weights_epoch = e
best_loss = self.valid_err[-1]
for i, 1 in enumerate(self.layers):
                                      layer_name = save_dir.joinpath(f'layer_{i:02d}')
l.saveWeights(layer_name)
                                 impatience += 1
                                # We have become too impatient
if impatience >= patience:
    print(f'* * * Early stopping hit * * *')
    break
             pbar.close()
if __name__ == '__main__':
    print('Warning: This file does not do anything.')
    print('Run either classifier.py or autoencoder.py.')
```

# A.7 classifier.py

```
labels : np.ndarray
Array of labels for the data
                          Returns
                          float
                          Error (1 - Hit Rate)
                         correct = 0
for d, 1 in zip(data, labels):
    # Make prediction
    pred = self.predict(d, one_hot=True)
    # Check equality with label
    if (np.sum(np.abs(pred - 1)) == 0):
        correct += 1
hit_rate = correct / len(data)
return (1 - hit_rate)
if __name__ == '__main__':
    # Additional imports
             from settings import *
             import pathlib
             import csv
# Seed for consistency
np.random.seed(SEED)
             # Delete old model
for f in CLASS_MODEL_DIR.iterdir():
                         f.unlink()
             # Test network
             classifier = Classifier(input_size=INPUTS)
for h in HIDDEN_LAYER_SIZES:
             classifier.addLayer(neurons=h, output=False)
classifier.addLayer(neurons=CLASSES, output=True)
             # Train the network
print('* * * Begin training classifier * * *')
classifier.train(
                          train_data,
                          train labels.
                           points_per_epoch=CLASS_POINTS_PER_EPOCH,
                          valid_points=CLASS_WALID_POINTS,
max_epochs=CLASS_MAX_EPOCHS,
eta=CLASS_ETA,
                           alpha=CLASS_ALPHA,
                          L=CLASS_L,
                         H=CLASS_H,
patience=CLASS_PATIENCE,
es_delta=CLASS_ES_DELTA,
save_dir=CLASS_MODEL_DIR,
            ) # Plot loss over epochs
             plt.figure()
plt.plot(classifier.epoch_num, classifier.train_err)
           plt.plot(classifier.epoch_num, classifier.train_err)
plt.plot(classifier.epoch_num, classifier.valid_err)
plt.axvline(x=classifier.best_weights_epoch, c='g')
plt.legend(['Train', 'Validation'], loc='upper right')
plt.title(f'Classifier Loss vs Epoch Number')
plt.xlabel('Epoch number')
plt.xlim([0, classifier.epoch_num[-1]])
plt.ylabel('Loss')
plt.ylabel('Loss')
plt.ylabel('Ioss')
plt.ylabel('Soss')
plt.ylabel('Loss')
plt.ylabel('Loss')
plt.savefig(str(CLASS_LOSS_PLOT), bbox_inches='tight', pad_inches=0)
plt.close()
# Save parameters to CSV
          plt.close()
# Save parameters to CSV
csv_rows = list()
csv_rows.append(['Parameter', 'Value', 'Description'])
csv_rows.append(['Parameter', 'Value', 'Description'])
csv_rows.append(['Shidden\\_layer\\_size$', str(HIDDEN_LAYER_SIZES[0]),
    'Neurons in hidden layer'])
csv_rows.append(['$\\attraction*\], 'Learning rate'])
csv_rows.append(['$\\attraction*\], 'str(CLASS_ETA), 'Learning rate'])
csv_rows.append(['$\\attraction*\], 'epochs$', str(CLASS_ALPHA), 'Momentum'])
csv_rows.append(['$\\attraction*\], 'str(CLASS_L), 'Lower activation threshold'])
csv_rows.append(['$\\attraction*\], 'typer activation threshold'])
csv_rows.append(['$\\attraction*\], 'typer activation threshold'])
csv_rows.append(['$\\attraction*\], 'typer activation threshold'])
csv_rows.append(['\attraction*\], str(CLASS_PATIENCE),
    'Patience before early stopping'])
csv_rows.append(['\attraction*\], 'delta\attraction*\], 'typer activation threshold'])
with open(str(CLASS_PARAM_CSV), 'w') as csv_file:
    csv_writer = csv.writer(csv_file)
    csv_writer.writerows(csv_rows)
                           csv_writer.writerows(csv_rows)
                    Write best epoch
           with open(str(CLASS_BEST_EPOCH), 'w') as best_epoch_file:
    best_epoch_file.write(str(classifier.best_weights_epoch))
```

## A.8 autoencoder.py

```
# Imports
                                          from mlp import MLP import numpy as np
import matplotlib.pyplot as plt
class Autoencoder(MLP):
      def eval(self, data, labels):

"""Evaluate error on a data set
            Parameters
            data : np.ndarray
Array of data points
            labels : np.ndarray
Array of labels for the data
            Returns
            float
            Error (1 - Hit Rate)
            # Calculate loss
total_loss = 0
for d, 1 in zip(data, labels):
    pred = self.predict(d, one_hot=False)
    loss = np.sum(np.square(1 - pred))
    total_loss += loss / 2
            total_loss /= len(data)
return total_loss
if __name__ == '__main__':
    # Additional imports
     # Additional imports
from settings import *
import pathlib
import csv
# Seed for consistency
      np.random.seed(SEED)
# Delete old model
for f in AUTO_MODEL_DIR.iterdir():
            f.unlink()
      # Training constants
# Test network
autoencoder = Autoencoder(input_size=INPUTS)
      for h in HIDDEN_LAYER_SIZES:
      autoencoder.addLayer(neurons=h, output=False)
autoencoder.addLayer(neurons=INPUTS, output=True)
      # Train the network
print('* * * Begin training autoencoder * * *')
autoencoder.train(
            train_data,
             train_data,
            points_per_epoch=AUTO_POINTS_PER_EPOCH, valid_points=AUTO_VALID_POINTS,
            max_epochs=AUTO_MAX_EPOCHS,
eta=AUTO_ETA,
             alpha=AUTO_ALPHA,
            L=AUTO_L,
H=AUTO_H,
patience=AUTO_PATIENCE,
            es_delta=AUTO_ES_DELTA,
save_dir=AUTO_MODEL_DIR,
      plt.plot(autoencoder.epoch_num, autoencoder.train_err)
plt.plot(autoencoder.epoch_num, autoencoder.valid_err)
plt.laxvline(x=autoencoder.best_weights_epoch, c='g')
plt.legend(['Train', 'Validation'], loc='upper right')
plt.title(f'Autoencoder Loss vs Epoch Number')
plt.xlabel('Epoch number')
```

# A.9 test\_classifier.py

```
# Custom imports
from settings import *
from classifier import Classifier
# External imports
import numpy as np
import pathlib
import matplotlib.pyplot as plt
def makeConfMat(classifier, data, labels, plot_name, title):
    '''Generate and save a confusion matrix
                    classifier : Classifier
                                      Classifier for use in classification
                  Classifier for use in classification
data : np.ndarray
   Array of data values
labels : np.ndarray
   Array of labels as one-hot-vectors
plot_name : pathlib.Path or str
                                       File name to save the matrix as
                   Title of the confusion matrix ,,,, % \left( \frac{1}{2}\right) =\frac{1}{2}\left( \frac{1}{2}\right) \left( \frac{1}{2}
                  conf_mat += 1.reshape((CLASSES,1)) * pred.reshape((1,CLASSES))
                     # Plot confusion matrix and save
                plt.figure()
                    plt.xticks(range(CLASSES))
plt.ylabel('Actual Value')
                    plt.yticks(range(CLASSES))
                    plt.colorbar()
plt.tight_layout()
                   plt.savefig(str(plot_name), bbox_inches='tight', pad_inches=0)
plt.close()
# Seed for consistency
np.random.seed(SEED)
## Load best weights back up and make confusion matrices classifier = Classifier(input_size=INPUTS) weight_files = sorted(CLASS_MODEL_DIR.iterdir()) for weight_file in weight_files[:-1]: classifier.addLayer(file_name=weight_file, output=False) classifier.addLayer(file_name=weight_files[-1], output=True) train_conf_title_name=weight_files[-1], output=True)
```

# A.10 test\_autoencoder.py

```
# Imports
# Custom imports
from autoencoder import Autoencoder
from settings import *
# External imports
# External imports
import numpy as np
import pathlib
import matplotlib
import matplotlib.pyplot as plt
def splitClasses(data, labels):
       ''Split up dataset by class
     Parameters
     data, labels : np.ndarray
         Arrays of data points and labels
     Returns
     Data split up by class
     split_data = list()
for i in range(CLASSES):
     split_data.append(list())
for d, l in zip(data, labels):
   idx = np.argmax(l)
   split_data[idx].append(d)
     return split_data
def getLossByClass(autoencoder, data, labels):
    Parameters
     autoencoder : Autoencoder
    Autoencoder for use in loss calculation data, labels : np.ndarray
Arrays of data points and labels
    Returns
     float
     Loss values by class
     loss = list()
    plus = 11st()
split_data = splitClasses(data, labels)
for i, d in enumerate(split_data):
    print(f'Evaluating class {i}')
    loss.append(autoencoder.eval(d, d))
return loss
def getSamplePoints(data, n):
    '''Get sample points from the given data set
    Parameters
    data : np.ndarray
    Array of data points n : int
          Number of sample points
    Reduced list of data points
    indeces = np.random.choice(np.arange(len(data)), 8, replace=False)
def drawSamples(autoencoder, data, num_samples, dir_name, title):
    \ref{eq:constraints} ''''Draw the output predictions and save them Parameters
```

```
autoencoder : Autoencoder
              Autoencoder for use in inference
       data : np.ndarray
Array of data points
       num_samples : int
   Number of sample points
       dir_name : str

Name of the directory to save the images to
       title : str
       Title of the plot
       sample_points = getSamplePoints(data, num_samples)
       for i, d in enumerate(sample_points):
    d_name = dir_name.joinpath(f'orig_{i}.png')
    matplotlib.image.imsave(str(d_name), d.reshape(28, 28, order='F'), cmap='Greys_r')
              pred = autoencoder.predict(d, one_hot=False)
p_name = dir_name.joinpath(f'pred_{i}.png')
               matplotlib.image.imsave(str(p_name), pred.reshape(28, 28, order='F'), cmap='Greys_r')
# Seed for consistency
np.random.seed(SEED)
# Load best weights back up
autoencoder = Autoencoder(input_size=INPUTS)
weight_files = sorted(AUTO_MODEL_DIR.iterdir())
       weight_file in weight_files[:-1]:
   autoencoder.addLayer(file_name=weight_file, output=False)
autoencoder.auddayer(file_name=weight_files[-1], output=raise)
# Test on all data and draw samples
test_err = autoencoder.eval(test_data, test_data)
print(f'Test loss: {test_err:0.3f}')
sample_title = 'Autoencoder Sample Outputs'
drawSamples(autoencoder, test_data, 8, AUTO_SAMPLE_DIR, sample_title)
# Graph loss by class
print('Testing train set')
train_loss = getLossByClass(autoencoder, train_data, train_labels)
print('Testing test set')
test_loss = getLossByClass(autoencoder, test_data, test_labels)
x = np.arange(len(train_loss))
plt.figure()
pit.figure()
rect_width = 0.35
plt.bar(x-rect_width/2, train_loss, rect_width, label='Train')
plt.bar(x+rect_width/2, test_loss, rect_width, label='Test')
plt.title('Autoencoder Loss by Class')
plt.xlabel('Class')
plt.xticks(x)
plt.ylabel('Loss')
plt.grid(axis='y')
plt.gca().set_axisbelow(True)
plt.legend(loc='lower right')
plt.legend(loc='lower right')
plt.stight_layout()
plt.savefig(str(AUTO_BAR), bbox_inches='tight', pad_inches=0)
with open(str(AUTO_TEST_LOSS), 'w') as loss_f:
    loss_f.write(f'{test_err:0.3f}')
```

## A.11 features.py