

Computing Kantorovich-Wasserstein Distances on d-dimensional histograms using (d+1)-partite graphs

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Abstract

TASK: To compute the distance between two d-dimensional histograms having n bins. For instance, images are 2-dimensional histograms with n bins (pixels)

PROBLEM: The mathematical tool used to compute this distance requires the solution of an optimization problem with up to n^2 variables

IDEA: To exploit the structure of the cost function in order to reduce the number of variables of the optimization problem

1. Kantorovich-Wasserstein distance

The Kantorovich-Wasserstein distance is a metric between probability distributions or d-dimensional histograms.

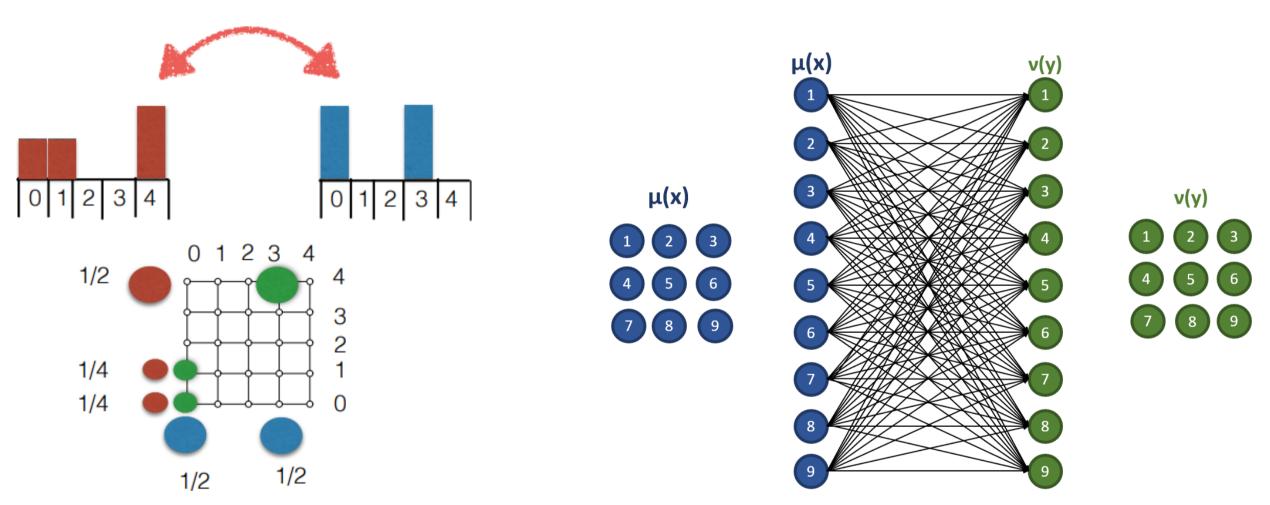


Figure 1: Left: transport map π (green dots) between 1D-histograms (red and blue dots) with n=5 bins. Right: bipartite graph associated to constrained optimization problem used to compute the Kantorovich-Wasserstein distance for 2D-histograms with n=9 bins

The idea of the Kantorovich-Wasserstein distance is to find the optimal way to map a probability μ to a probability ν where moving a unit mass from x to y costs $c_{x,y}$. Figure 1 (left).

Whenever the cost is $c_{x,y} = ||x-y||_2^2$, one gets the Wasserstein distance of order 2

$$W_2(\mu, \nu) := \min \sum \sum c_{x,y} \pi_{x,y}$$

where the minimum is over all the probability measures π with marginals ν and μ , i.e.

$$\sum_x \pi_{x,y} =
u_y, \quad ext{ and } \quad \sum_y \pi_{x,y} = \mu_x.$$

The computation of W_2 distances between histograms with n bins requires the solution of a constrained optimization problem.

Indeed, the standard approach to compute W_2 distances between 2D histograms with n bins is to solve the corresponding uncapacitated min cost flow problem [2] on a bipartite graph, with 2n nodes (2 times the number of bins) and n^2 arcs (one for all the possible costs $c_{x,y}$). See Figure 1 (right).

The solution of this problem requires $O(n^3 \log(n))$ time, which for large n is computationally too heavy.

2. Our contribution

In [1] we propose a novel approach for computing the W_2 distance that exploits the structure of the cost function to reduce the number of arcs.

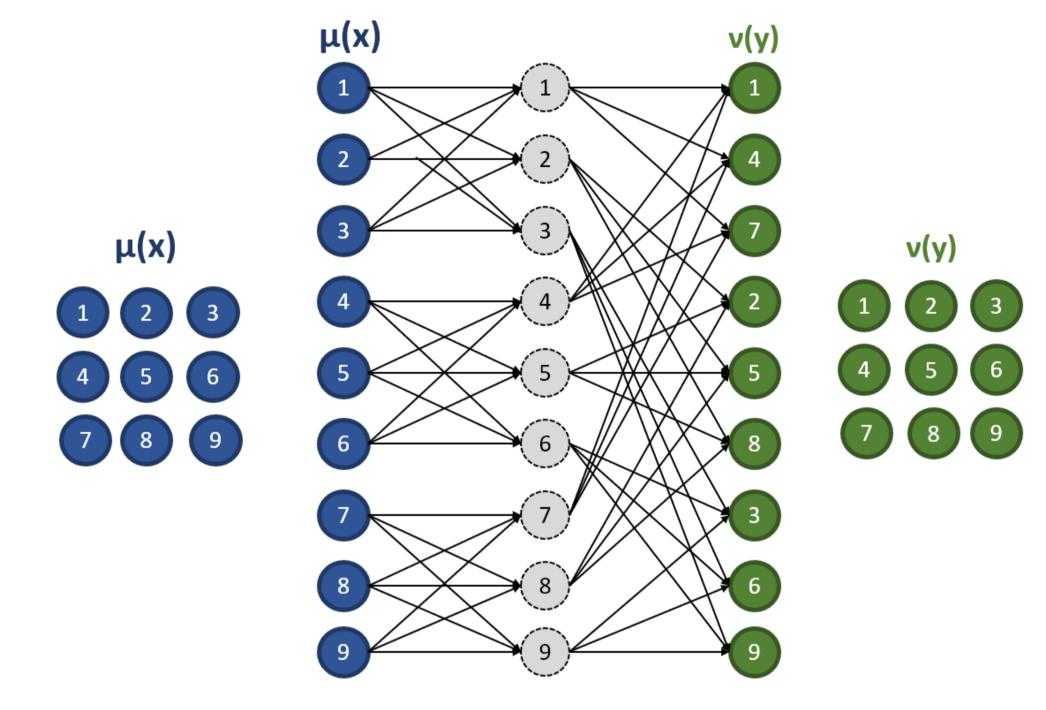


Figure 2: 3–partite graph reformulation for the computation of W_2

Since the cost function is separable, $c_{x,y} = (x_1 - y_1)^2 + (x_2 - y_2)^2$, it can be computed as the concatenation of the costs along the two main directions: $(x_1, x_2) \to (y_1, x_2)$ and $(y_1, x_2) \to (y_1, y_2)$. See Figure 2.

CONTRIBUTION: We prove that the W_2 distance between d-dimensional histograms can be computed as a flow problem on (d+1)-partite graph, with (d+1)n nodes and $dn^{1+\frac{1}{d}}$ arcs.

- Our method requires $dn^{1+\frac{1}{d}}$ arcs while the standard bipartite graph method requires n^2 .
- The method can be adapted to any cost function that is separable, *i.e.* can be written as a sum of independent contributions.
- The method provides an exact solution.

3. Numerical Results

As problem instances, we use the gray scale images proposed by the DOTMark benchmark, and a set of d-dimensional histograms obtained by biomedical data measured by flow cytometry.

Table 1: Comparison on Flow Cytometry data with increasing value of d.

				Bipartite Graph			(d+1)-partite Graph			
N	d	n	V	A	Runtime	V	A	Runtime		
16	2	256	512	65 536	0.024 (0.01)	768	8 192	0.003 (0.00)		
	3	4 096	8 192	16777216	38.2 (14.0)	16384	196 608	0.12 (0.02)		
	4	65 536		out-of-memory		327 680	4 194 304	4.8 (0.84)		
32	2	1 024	2048	1 048 756	0.71 (0.14)	3072	65 536	0.04 (0.01)		
	3	32768		out-of-memory		131 072	3 145 728	5.23 (0.69)		

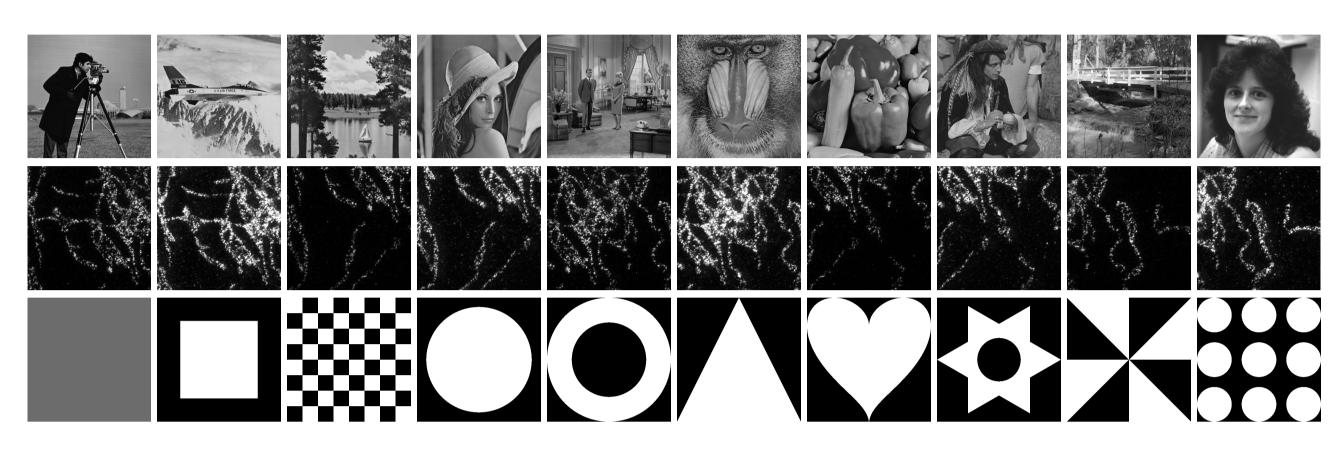


Figure 3: DOTmark benchmark: Classic, Microscopy, and Shapes images.

Table 2: Comparison on 32×32 images. The runtime (in secs) is given as "Mean (StdDev)". The gap to the optimum opt is computed as $\frac{UB-opt}{opt} \cdot 100$, where UB is the upper bound computed by Sinkhorn's algorithm. Each row reports the averages over 45 instances.

	EMD[4]	Sink	horn [3]	Bipartite	3-partite
		$\lambda = 1$	$\lambda = 1.5$		
Image Class	Runtime	Runtime Gap	Runtime Gap	Runtime	Runtime
Classic	24.0 (3.3)	6.0 (0.5) 17.3%	8.9 (0.7) 9.1%	0.54 (0.05)	0.07 (0.01)
Microscopy	35.0 (3.3)	3.5 (1.0) 2.4%	5.3 (1.4) 1.2%	0.55 (0.03)	0.08 (0.01)
Shapes	25.2 (5.3)	1.6 (1.1) 5.6%	2.5 (1.6) 3.0%	0.50 (0.07)	0.05 (0.01)
		3-partite			

	Improved Sinkhorn [5]						3-partite
	$\lambda = 1$		$\lambda = 1.25$		$\lambda = 1.5$		
Image Class	Runtime	Gap	Runtime	Gap	Runtime	Gap	Runtime
CauchyDensity	0.22 (0.15)	2.8%	0.33 (0.23)	2.0%	0.41 (0.28)	1.5%	0.07 (0.01)
Classic	0.20 (0.01)	17.3%	0.31 (0.02)	12.4%	0.39 (0.03)	9.1%	0.07 (0.01)
GRFmoderate	0.19 (0.01)	12.6%	0.29 (0.02)	9.0%	0.37 (0.03)	6.6%	0.07 (0.01)
GRFrough	0.19 (0.01)	58.7%	0.29 (0.01)	42.1%	0.38 (0.02)	31.0%	0.05 (0.01)
GRFsmooth	0.20 (0.02)	4.3%	0.30 (0.04)	3.1%	0.38 (0.04)	2.2%	0.08 (0.01)
LogGRF	0.22 (0.05)	1.3%	0.32 (0.08)	0.9%	0.40 (0.13)	0.7%	0.08 (0.01)
LogitGRF	0.22 (0.02)	4.7%	0.33 (0.03)	3.3%	0.42 (0.04)	2.5%	0.07 (0.02)
Microscopy	0.18 (0.03)	2.4%	0.27 (0.04)	1.7%	0.34 (0.05)	1.2%	0.08 (0.02)
Shapes	0.11 (0.04)	5.6%	0.16 (0.06)	4.0%	0.20 (0.07)	3.0%	0.05 (0.01)
WhiteNoise	0.18 (0.01)	76.3%	0.28 (0.01)	53.8%	0.37 (0.02)	39.2%	0.04 (0.00)

References

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