# hw3 for stat341

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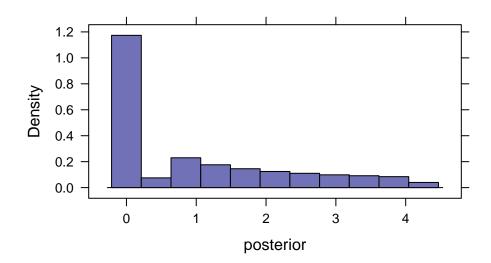
## Q: 2M2-2M3, 3M1-3M3

2M2.Q: Now assume a prior for p that is equal to zero when p < 0.5 and is a positive constant when p >= 0.5. Again compute and plot the grid approximate posterior distribution for each of the sets of observations in the problem just above. **Solution:** 

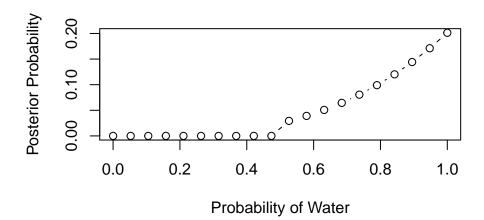
# case(1) WWW

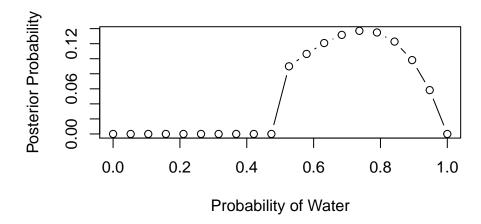
```
##
         p prior likelihood posterior_raw posterior1 posterior
## 1 0.000
                0
                    0.00e+00
                                           0
                                                       0
                                                                  0
                    1.00e-09
                                                                  0
## 2 0.001
                0
                                           0
                                                       0
## 3 0.002
                0
                    8.00e-09
                                           0
                                                       0
                                                                  0
                    2.70e-08
                                                       0
                                                                  0
## 4 0.003
                0
                                           0
## 5 0.004
                    6.40e-08
                                           0
                                                       0
                                                                  0
                0
## 6 0.005
                0
                    1.25e-07
                                           0
                                                                  0
```

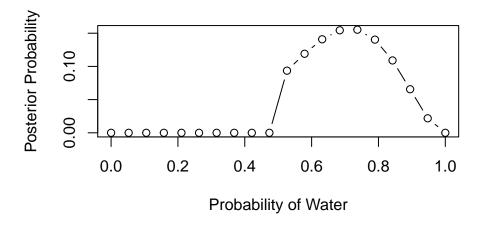
histogram(p~posterior,BinomGrid)



Another way







2M3.Q: Suppose there are two globes, one for Earth and one for Mars. The Earth globe is 70% covered in water. The Mars globe is 100% land. Further suppose that one of these globes—you don't know which—was tossed in the air and produced a "land" observation. Assume that each globe was equally likely to be tossed. Show that the posterior probability that the globe was the Earth, conditional on seeing "land" (Pr(Earth|land)), is 0.23.

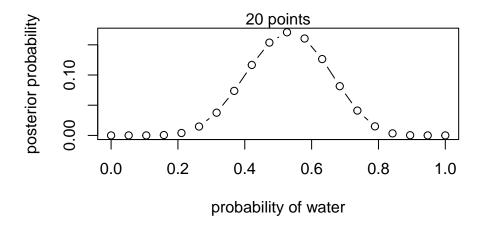
#### Solution:

```
posterior can be identified as prior*likelihood. Also it can be written Pr(Earth|land) = \frac{Pr(Land|Earth)Pr(Earth)}{Pr(Land)} = \frac{Pr(Land|Earth)Pr(Earth)}{Pr(Land|Earth)Pr(Earth)} Since it is equally likely, prior is determined to be 0.5 Then it is \frac{0.3*0.5}{(0.3*0.5)(1.0*0.5)} p<- 0.3*0.5/(0.3*0.5+1*0.5)
```

## [1] 0.2307692

by R, it is 0.2307

3M1. Q: Suppose the globe tossing data had turned out to be 8 water in 15 tosses. Construct the posterior distribution, using grid approximation. Use the same flat prior as before. **Solution:** 



3M2.Q: Draw 10,000 samples from the grid approximation from above. Then use the samples to calculate the 90% HPDI for p. **Solve:** 10000

```
# define grid
p_grid <- seq( from=0 , to=1 , length.out=20 )
# define prior
prior <- rep( 1 , 20 )</pre>
```

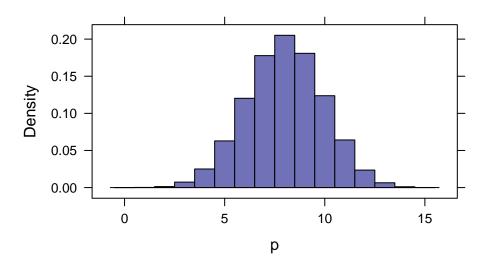
```
## | 0.9 | 0.9 | ## 0.3157895 | 0.6842105
```

3M3.Q: Construct a posterior predictive check for this model and data. This means simulate the distribution of samples, averaging over the posterior uncertainty in p. What is the probability of observing 8 water in 15 tosses?

## Solution:

Based on the R, probability is 0.20547.

```
p<-rbinom(1e5, size = 15, prob = 8/15)
histogram(~p,width=1)</pre>
```



```
tally(~(p==8),format = "prop")
```

```
## (p == 8)
## TRUE FALSE
## 0.20512 0.79488
```