

# Ο Αλγόριθμος BACKPROPAGATION ΜΑΘΗΣΗ "ΜΕ ΔΑΣΚΑΛΟ"

Κριτήριο Ελαχιστοποίησης

$$E_p = \frac{1}{2} \sum_j (d_{pj} - y_{pj})^2, j=1$$

$$E = \sum_p E_p$$

$p$  : training samples

$j$  : αριθμός εξόδων

$d$  : επιθυμητή έξοδος

$y$  : πραγματική έξοδος

Άγνωστες Παράμετροι:  $[w_{11}, w_{12}, w_{13}, \theta_1], [w'_{11}, w'_{12}, \theta'_1]$ .

Λειτουργία νευρώσεων εξόδου - παράδοση των "κρυμμένων Επινέδων"

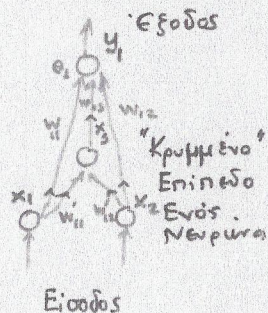
$$y_{pj} = \frac{1}{1 + e^{-(\sum_i w_{ji} x_{pi} + \theta_j)}} \triangleq \frac{1}{1 + e^{-z_{pj}}}$$

Τότε:

$$\Delta_p w_{ji} \approx -\eta \frac{\partial E_p}{\partial w_{ji}}$$

Αλγόριθμος Αναδρομικός από Νευρώσεις Εξόδου → Εισόδου

$$\Delta_p w_{ji} = \begin{cases} \eta \delta_{pj} y_{pi} & (\text{Εξόδου}) \\ \eta \delta'_{pj} x_{pi} & (\text{Κρυφών Επινέδων}) \end{cases}$$



$$\frac{\partial E_p}{\partial w_{ji}} = \frac{\partial E_p}{\partial z_{pj}} \frac{\partial z_{pj}}{\partial w_{ji}} = -\delta_{pj} \cdot x_{pi} \Rightarrow$$

$$-\frac{\partial E_p}{\partial w_{ji}} = \delta_{pj} x_{pi} \Rightarrow \Delta_p w_{ji} = \eta \delta_{pj} x_{pi} \quad (1)$$

$$\delta_{pj} = -\frac{\partial E_p}{\partial z_{pj}} = -\frac{\partial E_p}{\partial y_{pj}} \frac{\partial y_{pj}}{\partial z_{pj}} \quad (2)$$

Όμως:

$$\frac{\partial y_{pj}}{\partial z_{pj}} = \frac{1}{(1 + e^{-z_{pj}})^2} \cdot e^{-z_{pj}} = y_{pj} (1 - y_{pj}) \quad (3)$$

(2) ∧ (3) ⇒

$$\delta_{pj} = -y_{pj} (1 - y_{pj}) \frac{\partial E_p}{\partial y_{pj}} \quad (4)$$

Υπολογισμός του

$$\frac{\partial E_p}{\partial y_{pj}}$$

$\left\{ \begin{array}{l} (a) \text{ Νευρώσεις Εξόδου} \\ (b) \text{ "Κρυφών Επινέδων"} \end{array} \right.$   
 $y_{pj} \equiv x_{pi}$



$$(a) \quad \frac{\partial E_p}{\partial y_{pj}} = - (d_{pj} - y_{pj}) \quad (5)$$

Αρα (1)^(5)^(4)

$$\Delta_p w_{ji} = \eta \delta_{pj} x_{pi} \quad \text{όπου} \quad (A)$$

$$\delta_{pj} = y_{pj} (1 - y_{pj}) (d_{pj} - y_{pj})$$

$$(b) \quad \frac{\partial E_p}{\partial x_{pj}} : \text{Υπολογισμός με κανόνα Μερικών Παραγώγων}$$

$$\frac{\partial E_p}{\partial x_{pj}} = \sum_k \frac{\partial E_p}{\partial z_{pk}} \cdot \frac{\partial z_{pk}}{\partial x_{pj}} = \sum_k \frac{\partial E_p}{\partial z_{pk}} \cdot \frac{\partial z_{pk}}{\partial x_{pj}} = \sum_k \underbrace{\frac{\partial E_p}{\partial z_{pk}}}_{-\delta_{pk}} w_{kj}$$

$$\Rightarrow \quad \frac{\partial E_p}{\partial x_{pj}} = - \sum_k \delta_{pk} w_{kj}$$

Αρα

$$\Delta_p w_{ji} = \eta \delta'_{pj} x_{pi} \quad \text{όπου} \quad (B)$$

$$\delta'_{pj} = x_{pj} (1 - x_{pj}) \sum_k \delta_{pk} w_{kj}$$



# Απόδειξη συχρίσσης Αλγόριθμου Perceptron

Εστω  $\underline{w}^*$  η γραμμένη λύση. Τότε για  $0 < \delta < 1$

$$(\underline{w}^*)^T \underline{x} > +\delta > 0 \quad \text{για patterns } x \text{ κλάσης 1}$$

$$(\underline{w}^*)^T \underline{x} < -\delta < 0 \quad \text{για patterns } x \text{ κλάσης 2}$$

Εστω  $\varphi(w) = \frac{(\underline{w}^*)^T \cdot w}{\|\underline{w}^*\| \|\underline{w}\|} \leq 1$ , για κάποιο  $w$

Είναι όμως:

Updating, όταν  $(\underline{w}^{(k)})^T \underline{x} < 0$  αν  $x \in C_1$   
 ή  $(\underline{w}^{(k)})^T \underline{x} > 0$  αν  $x \in C_2$

$$\underline{w}^{(k+1)} = \underline{w}^{(k)} + \eta x \quad \text{για } x \in C_1$$

$$\underline{w}^{(k+1)} = \underline{w}^{(k)} - \eta x \quad \text{για } x \in C_2$$

$$\Rightarrow (\underline{w}^*)^T \underline{w}^{(k+1)} = \begin{cases} (\underline{w}^*)^T \underline{w}^{(k)} + \eta (\underline{w}^*)^T \underline{x} & \text{αν } x \in C_1 \\ (\underline{w}^*)^T \underline{w}^{(k)} - \eta (\underline{w}^*)^T \underline{x} & \text{αν } x \in C_2 \end{cases} \quad (1)$$

$$\|(\underline{w}^{(k+1)})\|^2 = \begin{cases} (\underline{w}^{(k)} + \eta x)^T (\underline{w}^{(k)} + \eta x) & \text{αν } x \in C_1 \\ (\underline{w}^{(k)} - \eta x)^T (\underline{w}^{(k)} - \eta x) & \text{αν } x \in C_2 \end{cases} \quad (2)$$



$$\left. \begin{aligned} \therefore (w^*)^T w^{(k+1)} &> (w^*)^T w^{(k)} + \eta \cdot \delta \\ \|w^{(k+1)}\|^2 &< \|w^{(k)}\|^2 + \eta^2 \|x\|^2 \end{aligned} \right\} \Rightarrow$$

$$\left. \begin{aligned} (w^*)^T w^{(k_0+1)} &> \eta K_0 \delta \\ \|w^{(k_0+1)}\|^2 &< \eta^2 K_0 \|x\|_{\min}^2 \end{aligned} \right\} \Rightarrow$$

$$\phi(w^{(k_0+1)}) = \frac{(w^*)^T w^{(k_0+1)}}{\|w^*\| \phi \|w^{(k_0+1)}\|} > \frac{K_0 \delta}{\sqrt{K_0} \|x\|_{\min} \|w^*\|} = \frac{\sqrt{K_0} \delta'}{\text{при } < 1}$$

$$\Rightarrow \underline{\underline{K_0 < \infty}}$$