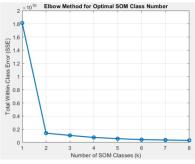
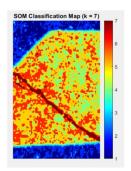
SOM-Based Class Discovery and Feature Attribution for Crack Region Interpretation



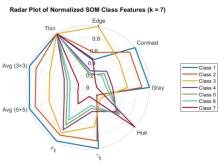
Shadow Crack



Optimal Class Number (Elbow Method) Class number (k) automatically selected by within-cluster error minimization



SOM-Based Crack Region Segmentation Pixel-level clustering based on 9 visualstatistical features, including grayscale, contrast, edge, hue, and structural indicators (e.g., thinness, colNorm, rowNorm, etc.)



Feature Attribution by Class Radar plot showing class-wise feature dominance across 7 cluster types



Input image under shadow occlusion; SOM identifies multi-class structure without supervision.

- SOM auto-selects class number and clusters pixel regions with no labeled data
- Supports unsupervised damage interpretation and label-free classification pipelines
- Radar plot reveals feature attribution across crack, mortar, and background classes

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SOM-Generated Pseudo Labels Enable Efficient CNN Training for Multi-Crack Scenarios												
Experiment	Clean SOM (All Types)		Raw SOM (All Types)		Clean SOM (Concrete Only)		Raw SOM (Concrete Only)		Crack Type	Input	SOM Output	CNN Output
Training Labels	Clean SOM: Concrete, Brick, Shadow		Raw SOM: Concrete, Brick, Shadow		Clean SOM: Concrete; Birck/Shadow as Background		Raw SOM: Concrete; Birck/Shadow as Background		Concrete Crack		\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	
	Label	Output	Label	Output	Label	Output	Label	Output				
Concret Crack	1							1	Brick Crack			
Brick Crack			. , ,	2000								
Shadow Crack		<i>y</i>							Shadow Crack			
Time	42s		42s		30s		36s			CONTROL WAY		

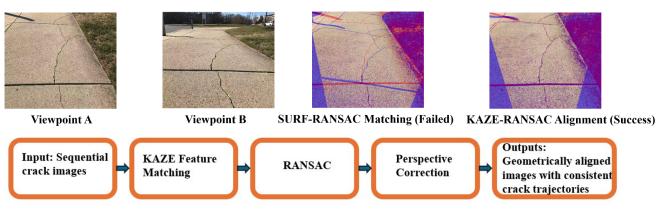
- SOM-generated pseudo-labels used to train CNN models with no manual annotation.
- $\bullet \quad \text{Concrete} + \text{background labels yielded highest segmentation fidelity and training efficiency.} \\$

• CNN trained with Clean SOM cracks + background achieves complete crack structure detection in 30s.

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Unsupervised Alignment for Robust Crack Tracking in Field Conditions



Crack Alignment Pipeline

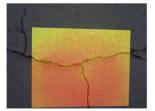
KAZE-RANSAC achieves robust geometric alignment under field-induced distortion, outperforming classical SURF-based matching in consistency and accuracy.

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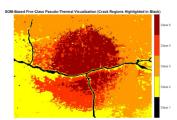
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Crack Image



IR Captured

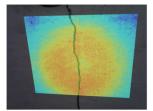


SOM-Based Pseudo-Thermal Field (No IR Sensor)

SOM-Based Five-Class Pseudo-Thermal Visualization (Crack Regions Highlighted in Black)



Crack Image



IR Captured



SOM-Based Pseudo-Thermal Field (No IR Sensor)

SOM-Based Five-Class Pseudo-Thermal Visualization (Crack Regions Highlighted in Black)

- Crack structure detected without thermal input
- Preserves heat-like gradients around defects
- Can support sensor-free damage localization

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