

Automated XCT Simulation, SOM Clustering, and CNN Refinement

Demo for CHIPS Program – Nondestructive Defect Detection
Metrology
Xinxin Sun

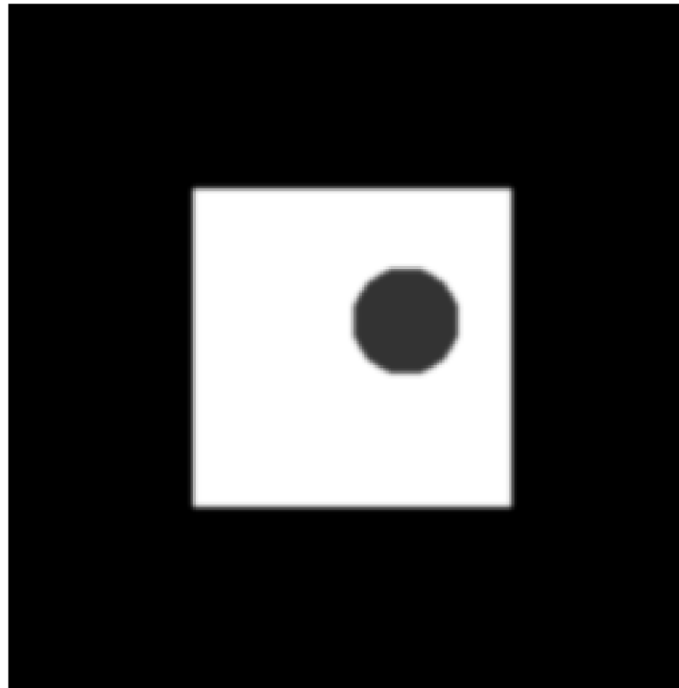
End-to-End XCT Defect Detection Pipeline

- Phantom → Sinogram → FBP Reconstruction → SOM Clustering → Class Extraction → CNN Refinement
 - • Physics-based XCT simulation
 - • 9D feature extraction + PCA + SOM unsupervised clustering
 - • CNN (Mini-UNet) refinement via teacher–student learning

Phantom with Seeded Defect

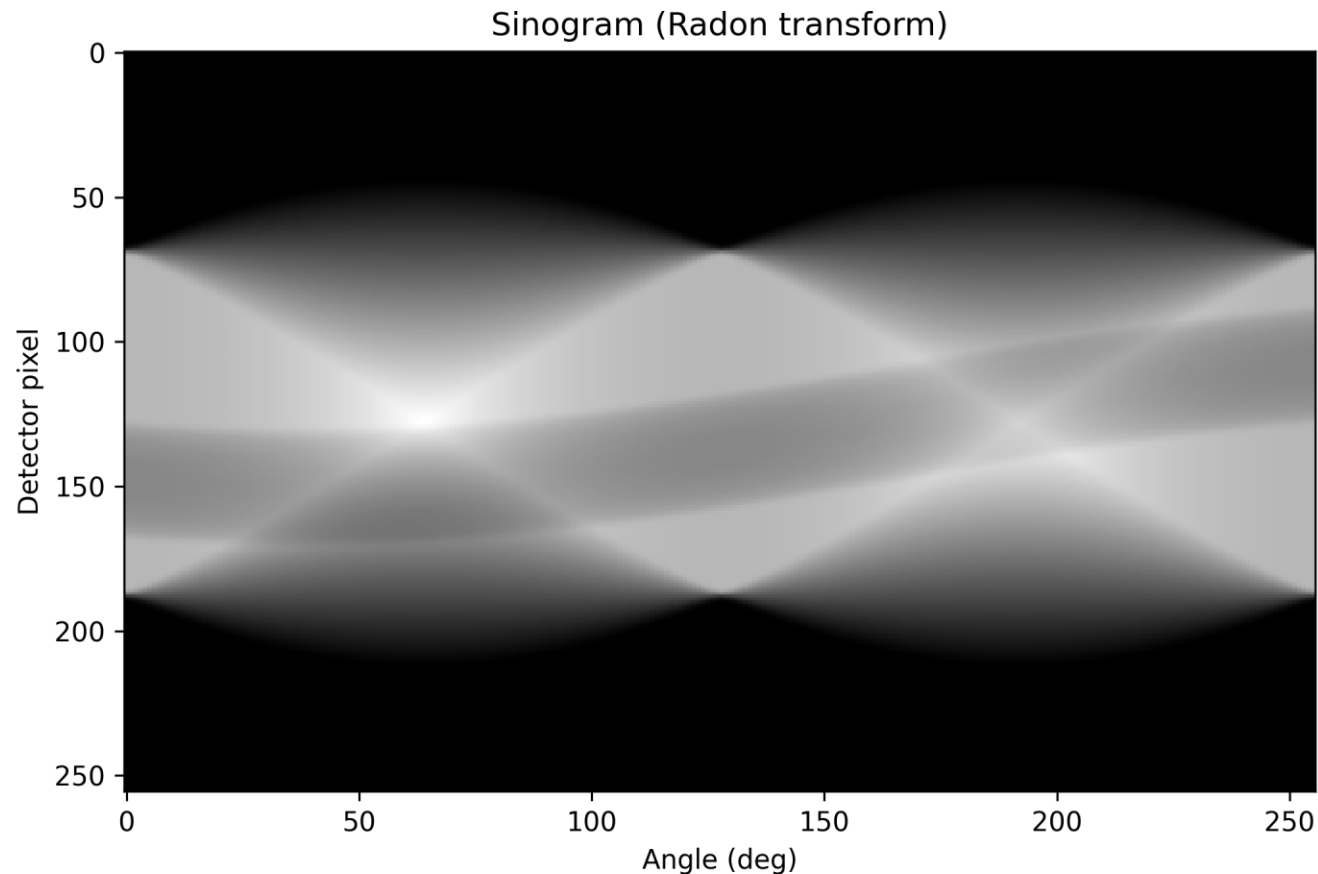
- Synthetic 256×256 reference artifact
- Square package + circular void defect

Phantom with seeded defect



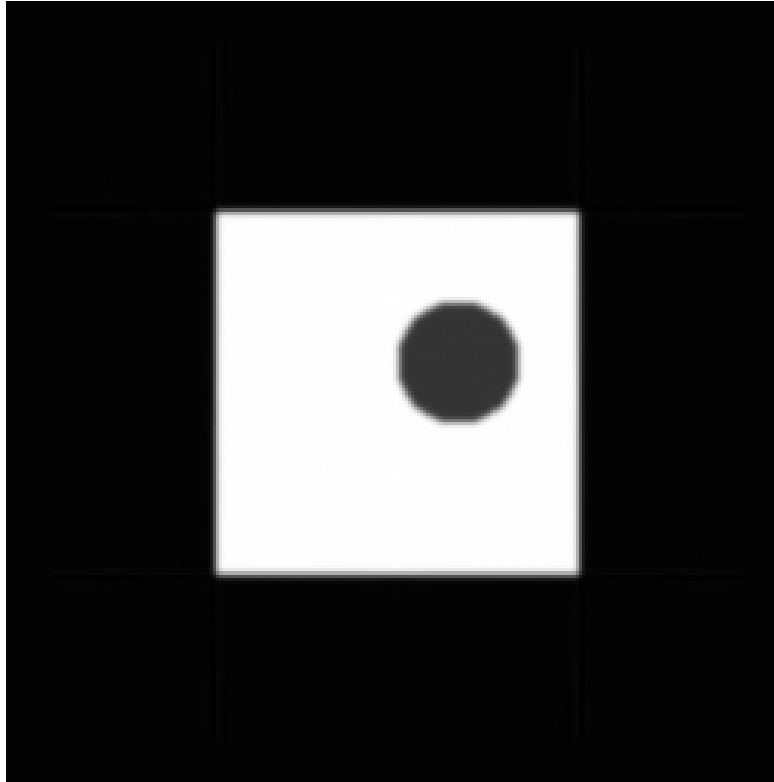
Simulated Sinogram (Radon Transform)

- Generated over 0–250 degrees
- Captures projection of structural and defect geometry



FBP Reconstruction

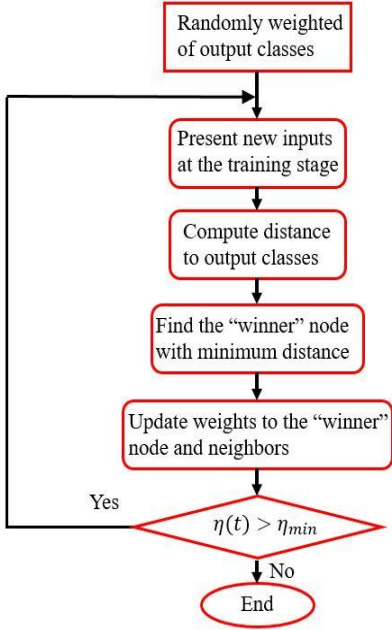
- Typical XCT reconstruction with mild streaking
- Used as input for SOM-based segmentation



Method Overview

Self-Organizing Map (SOM) for Label-Free, Physics-Informed Segmentation (X-ray CT Reconstruction)

Feature	Physical / Statistical Meaning in XCT
Grayscale intensity	Local X-ray attenuation; material density contrast
Edge magnitude	Boundary and interface sharpness; reveals defect edges
Local contrast	Heterogeneity of reconstructed materials; streak-robust
Thinness / filament metric	Captures circular voids and thin structures
Local mean (3×3 / 5×5)	Neighborhood background estimator; denoising
Anisotropy (ρ, γ)	Sensitivity to directional artifacts or coherence
Hue surrogate	Pseudo-channel to improve feature diversity and visualization



Workflow Summary

- 1.Extract 9-dimensional pixel features** from the 256×256 FBP reconstruction.
- 2.PCA reduction (9→6 dimensions)** preserving >95% variance.
- 3.Unsupervised SOM** forms physically interpretable clusters:
 1. Background
 2. Material body
 3. Defect region
 4. Boundary / edge
- 4Automatic selection of cluster count via Elbow method.**
- 5.Produce class-label map + radar plot** to quantify physical differences.

Key Advantages

- **Label-free** — No manual annotation required.
- **Physics-informed** — Features reflect attenuation, structure, and reconstruction artifacts.
- **Interpretable** — Each cluster corresponds to a statistically distinct material regime.
- **Noise-tolerant** — Stable under streaking and low-dose reconstructions.
- **Repeatable & transferable** — Centroids can be reused on new XCT datasets.
- **Efficient** — Runs in seconds on CPU for 256×256 images.

METHOD OVERVIEW (SOM → CNN Refinement)

From Unsupervised SOM Labels to CNN Refinement
A Teacher-Student Framework for Robust XCT Segmentation

Core Idea

- SOM provides **interpretable, noise-robust pseudo-labels** without any ground truth.
- CNN (U-Net) **learns from SOM pseudo-labels**—a teacher→student process.
- The hybrid model leverages physics-driven initialization (SOM) and deep learning refinement (CNN).
- A **self-consistency loop ($\Delta\text{IoU} \rightarrow 0$)** ensures a stable, converged segmentation model.

Workflow

SOM labeling (Teacher)

Produces initial cluster masks: background / material / defect / boundary.

CNN training (Student)

Input: reconstructed image

Label: SOM output

CNN learns a smooth, high-fidelity version of SOM segmentation.

Pseudo-labeling (extension)

CNN can be applied to new or unlabeled XCT frames to generate pseudo-labels.

Self-consistency loop (extension)

Retrain CNN on its own predictions until improvement in IoU falls below a threshold ($\Delta\text{IoU} < 0.005$), ensuring stable and physically consistent masks.

Key Advantages

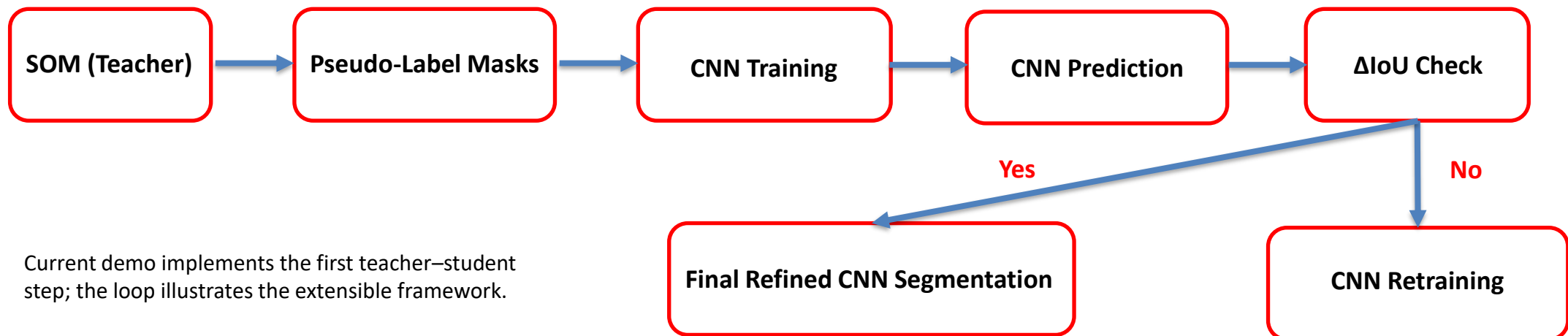
Label-free segmentation pipeline (no ground truth required).

Noise-robust — CNN trained on SOM's stable clusters is resistant to artifacts.

Explainable — SOM provides physics interpretation; CNN provides geometric refinement.

Transferable — Same pipeline applicable to XCT, ghost imaging, quantum imaging, etc.

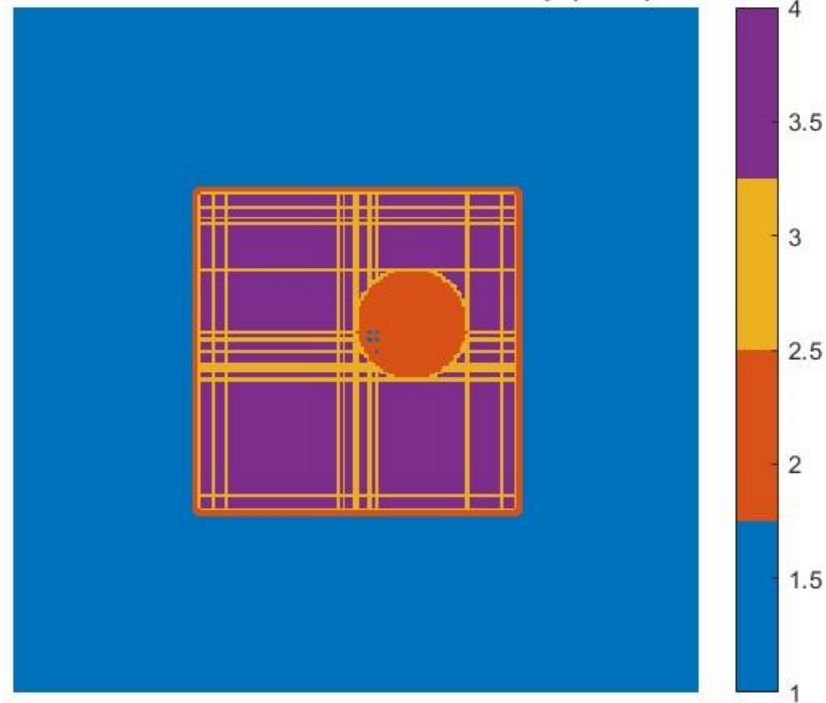
Efficient — Patch-based U-Net converges quickly on 256×256 XCT images.



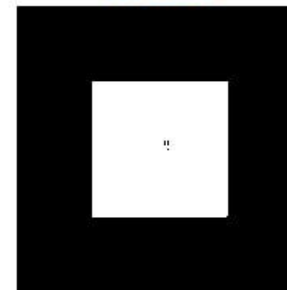
SOM Clustering (k = 4)

- 9D pixel-level physics features + PCA dimensionality reduction
- Automatically determines optimal cluster number via the Elbow criterion
- Class 2 consistently corresponds to the circular defect region

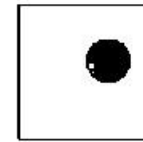
Transferred SOM Classification Map (k = 4)



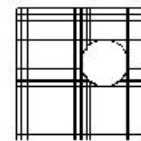
1st class



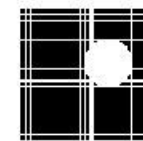
2nd class



3rd class

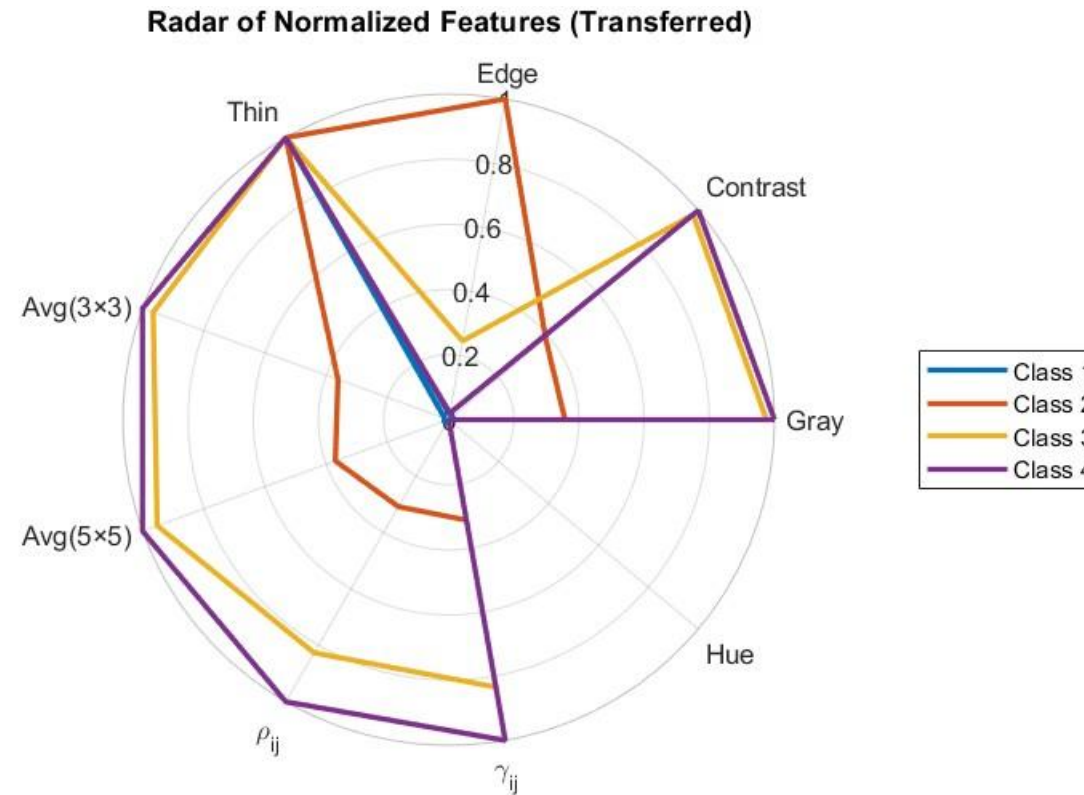


4th class



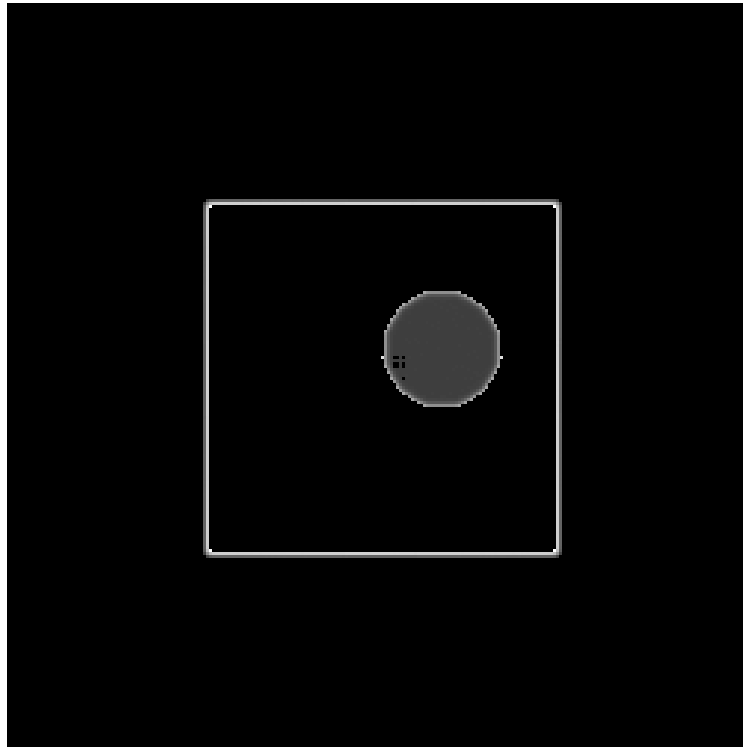
Radar Plot of Normalized 9D Feature Statistics (Transferred SOM Classes)

- Colors consistent with SOM map
- Confirms feature distribution per class



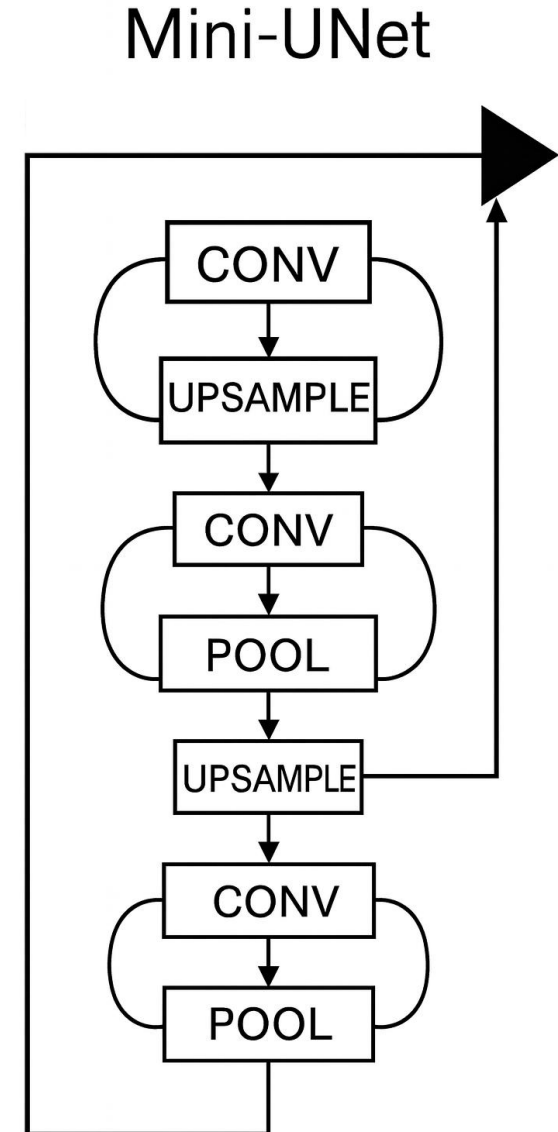
Extracted Class 2 Region

- SOM isolates defect region in grayscale
- Serves as the pseudo-ground-truth (teacher signal) for CNN refinement



Mini-UNet CNN Student Model

- Learns from SOM teacher labels
- 64×64 patch-based training
- BCE loss + ΔIoU convergence



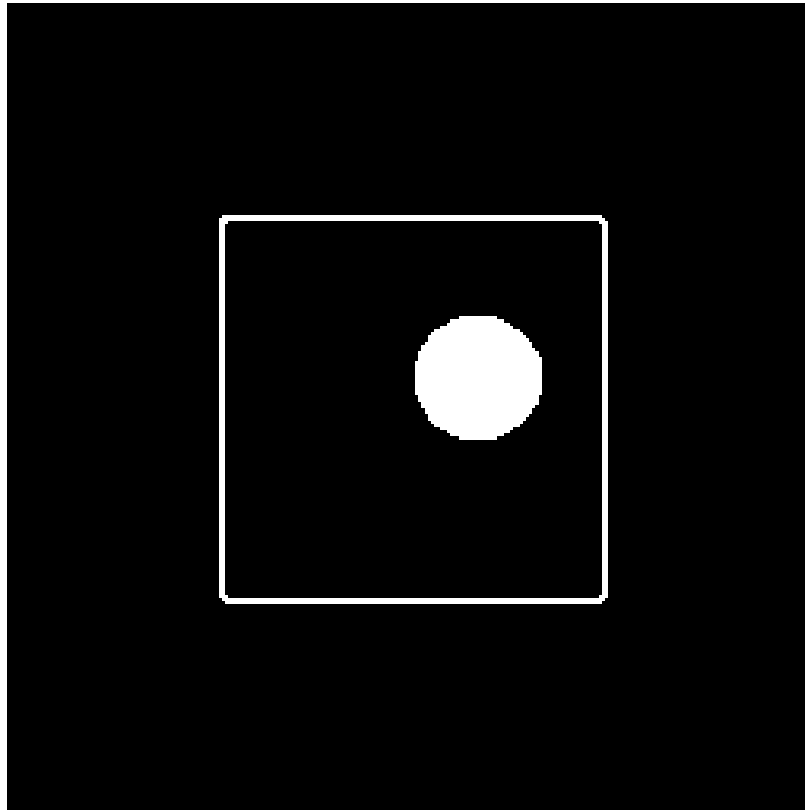
CNN Training Convergence

- IoU ≈ 0.96 from first epoch
- $\Delta\text{IoU} < 0.003 \rightarrow$ Early stopping
- Model saved as cnn_from_som.pth

```
Epoch 0: loss=0.0068, IoU=0.9685  
Epoch 1: loss=0.0048, IoU=0.9658  
Converged at Epoch 1,  $\Delta\text{IoU}=0.0026$   
Model saved.
```

CNN-Refined Segmentation Mask

- Smoother, more geometric defect boundaries
- Higher-quality benchmark mask than raw SOM



Summary and Relevance to CHIPS Program

- Automated XCT simulation + clustering + DL refinement
 - Generates clean benchmark defect datasets
 - Aligns with CHIPS goals in metrology, automation, and AI evaluation