ANNA+ Reference Guide (Version 3.0)

by Stephen Riley

Seattle University

**Table of Contents**

[Acknowledgments 2](#_Toc29908)

[1. ANNA Architecture 3](#_Toc29909)

[1.1 Memory Organization 3](#_Toc29910)

[1.2 Register Set 3](#_Toc29911)

[1.3 Execution of Programs 3](#_Toc29912)

[1.4 Instruction Formats 4](#_Toc29913)

[2. ANNA Instruction Set 5](#_Toc29914)

[3. ANNA Assembly Convention 9](#_Toc29915)

[3.1 ANNA Calling Convention 9](#_Toc29916)

[3.2 ANNA Heap Management 9](#_Toc29917)

[4. ANNA Assembler Reference 10](#_Toc29918)

[4.1 Assembly Language Files 10](#_Toc29919)

[4.2 Assembly Language Format Rules 10](#_Toc29920)

[4.3 Error Checking 12](#_Toc29921)

[5. ANNA Simulator Reference 13](#_Toc29922)

[5.1 Running the Assembler 13](#_Toc29923)

[5.2 Running the Simulator 13](#_Toc29924)

[5.3 Displaying Data 14](#_Toc29925)

[5.4 Setting Breakpoints 14](#_Toc29926)

[6. Style Guide 15](#_Toc29927)

[6.1 Commenting Convention 15](#_Toc29928)

[6.2 Other Style Guidelines 15](#_Toc29929)

*This document refers to version 3.0 of ANNA, called ANNA+. Version 3.0 was created in September 2022.*

# ANNA+ Acknowledgments

ANNA+ is an enhancement of the ANNA 2.0 specification and simulator (see *ANNA 2.0 Acknowledgment*, below.) The additional instructions, directives, and pseudo-ops were defined by [Stephen Riley](mailto:sriley@seattleu.edu?subject=ANNA+), Adjunct Instructor at Seattle University.

The intent of ANNA+ was to develop command-line utilities for ANNA to expose Computer Science Fundamentals Certificate students to low-level development tools, including:

* command line assembler
* minimal debugger in the style of gdb
* VT100 terminal debugger
* TinyC compiler

The utilities take the form of a dotnet tool that can be found at [github.com/stephen-riley/AnnaSim](https://github.com/stephen-riley/AnnaSim).

# ANNA 2.0 Acknowledgments

This document is based on the documentation provided for the ANT assembly language developed at Harvard University, created by the ANT development team consisting of Daniel Ellard, Margo Seltzer, and others. Many elements in presenting their assembly language are used in this document. For more information on ANT, see [http://ant.eecs.harvard.edu/index.shtml.](http://ant.eecs.harvard.edu/index.shtml)

The ANNA assembly language borrows ideas from many different assembly languages. In particular:

* The ANT assembly language from Harvard University. In addition, several of the simulator commands were ideas from the ANT tool suite.

* The LC2K assembly language used in EECS 370 at the University of Michigan.

* The simple MIPS-like assembly language suggested by Bo Hatfield (Salem State

College), Mike Rieker (Salem State College), and Lan Jin (California State

University, Fresno) in their paper *Incorporating Simulation and Implementation into Teaching Computer Organization and Architecture*. Their paper appeared at the 35th ASEE/IEEE Frontiers in Education Conference in October 2005.

The name ANNA comes from Eric Larson’s daughter Anna, who was 6 months at the time when the original document was created.

Eric Larson would like to acknowledge to former Seattle University students Seung Chang Lee and Moon Ok Kim who helped create the ANNA assembler and simulator tools.

# ANNA Architecture

This section describes the architecture of the 16-bit ANNA (A New Noncomplex Architecture) processor. ANNA is a very small and simple processor. It contains 8 user-visible registers, and an instruction set containing 22 instructions.

## Memory Organization

* Memory is word-addressable where a word in memory is 16 bits or 2 bytes.
* The memory of the ANNA processor consists of 216 or 64 K words.
* Memory is shared by instructions and data. No error occurs if instruction memory is overwritten by the program (though your programs should avoid doing this).
* ANNA is a load/store architecture; the only instructions that can access memory are the load and store instructions. All other operations access only registers.

## Register Set

* The ANNA processor has 8 registers that can be accessed directly by the programmer. In assembly language, they are named r0 through r7. In machine language, they are the 3-bit numbers 0 through 7.
* Registers r1 through r7 are general purpose registers. These registers can be used as both the source and destination registers in any of the instructions that use source and destination registers; they are read/write registers.
* The register r0 always contains the constant zero; if an instruction attempts to write a value to r0 the instruction executes in the normal manner, but no changes are made to the register.
* The program counter, PC, is a special 8-bit register that contains the offset (or index) into memory of the next instruction to execute. Each instruction is one word (2 bytes) long. Note that the offset is interpreted as an unsigned number and therefore ranges from 0 to 216 - 1. The PC is not directly accessible to the program.

## Execution of Programs

Programs are executed in the following manner:

### Initialization

1. Each location in memory is filled with zero.
2. All the registers are set to zero.
3. The program counter (PC) is set to zero.
4. The program is loaded into memory from a file. See section 6 for information about the program file format.
5. The fetch and execute loop (described in Section 4.2) is executed until the program terminates via the .halt directive.

### The Fetch and Execute Loop

1. Fetch the instruction at the offset in memory indicated by the PC.
2. Set PC  PC + 1.
3. Execute the instruction.
   1. Get the value of the source registers (if any).
   2. Perform the specified operation.
   3. Place the result, if any, into the destination register.
   4. Update the PC if necessary (only for branching or jumping instructions).

## Instruction Formats

Instructions adhere to one of the following three instruction formats:

R-type (add, sub, and, or, not, jalr, in, out, outns, outs)

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| 15 | 12 | 11 | 9 | 8 |  | 6 | 5 3 | 2 0 |
| Opcode |  | *Rd* |  | *Rs1* |  |  | *Rs2* | Function code |
| I6-type (addi, shf, lw, sw) | | | | | | | | |
| 15 12 | | 11 | 9 | 8 |  | 6 | 5 | 0 |
| Opcode | | *Rd* |  | *Rs1* |  |  | *Imm4* |  |
| I8-type (lli, lui, beq, bne, bgt, bge, blt, ble) | | | | | | | | |
| 15 12 | | 11 9 | | 8 | 7 |  |  | 0 |
| Opcode | | *Rd* | | Unused | *Imm8* | |  |  |

Some notes about the instruction formats:

* The *Opcode* refers to the instruction type and is always in bits 15-12.
* The Function Code is used by the following instructions, all share the same opcode of 0000: add (000), sub (001), and (010), or (011), not (100)
* The fields *Rd*, *Rs1*, *Rs2* refer to any general-purpose registers. The three bits refer to the register number. For instance, 0x5 (0b101) will represent register r5.
* The immediate fields represent an unsigned value. The immediate field for lui is specified using a signed value but the sign is irrelevant as the eight bits are copied directly into the upper eight bits of the destination register.
* Some instructions do not need all the fields specified in the format. The values of the unused fields are ignored and can be any bit pattern.
* The same register can serve as both a source and destination in one command. For instance, you can double the contents of a register by adding that register to itself and putting the result back in that register, all in one command.

# ANNA Instruction Set

In the descriptions below, R(3) refers to the content of register r3 and M(0x45) refers to the content of memory location 0x45. The descriptions do not account for the fact that writes to register r0 are ignored – this is implicit in all instructions that store a value into a general-purpose register.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| 0 0 0 0 | Rd | Rs1 | Rs2 | 0 0 0 |

**add** Add

Two's complement addition. Overflow is not detected.

R(*Rd*)  R(*Rs1*) + R(*Rs2*)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| 0 0 0 0 | Rd | Rs1 | Rs2 | 0 0 1 |

**sub** Subtract

Two's complement subtraction. Overflow is not detected.

R(*Rd*)  R(*Rs1*) - R(*Rs2*)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| 0 0 0 0 | Rd | Rs1 | Rs2 | 0 1 0 |
|  |  |  |  |  |
| 0 0 0 0 | Rd | Rs1 | Rs2 | 0 1 1 |
|  |  |  |  |  |
| 0 0 0 0 | Rd | Rs1 | unused | 1 0 0 |

|  |
| --- |
| **or** |

**and** Bitwise and

Bitwise and operation.

R(*Rd*)  R(*Rs1*) & R(*Rs2*)

Bitwise or

Bitwise or operation.

R(*Rd*)  R(*Rs1*) | R(*Rs2*)

**not** Bitwise not

Bitwise not operation.

R(*Rd*)  ~R(*Rs1*)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| 0 0 0 1 | Rd | Rs1 | unused | unused |

**jalr** Jump and link register

Jumps to the address stored in register *Rd* and stores PC + 1 in register *Rs1*. It is used for subroutine calls. It can also be used for normal jumps by using register r0 as *Rs1*.

R(*Rs1*)  PC + 1

PC  R(*Rd*)

|  |
| --- |
| **in** |

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| 0 0 1 0 | Rd | unused | unused | unused |
|  |  |  |  |  |
| 0 0 1 1 | Rd | unused | unused | unused |

Get word from input

Get a word from user input.

R(*Rd*)  input

**out** Send word to output

Send a word to output. If *Rd* is r0, then the processor is halted.

output  R(*Rd*)

|  |  |  |  |
| --- | --- | --- | --- |
| 0 1 0 0 | Rd | Rs1 | Imm6 |

**addi** Add immediate

Two's complement addition with a signed immediate. Overflow is not detected.

R(*Rd*)  R(*Rs1*) + *Imm6*

|  |  |  |  |
| --- | --- | --- | --- |
| 0 1 0 1 | Rd | Rs1 | Imm6 |

**shf** Bit shift

Bit shift. It is either left if *Imm6* is positive or right if the contents are negative. The right shift is a logical shift with zero extension.

if (*Imm6* > 0)

R(*Rd*)  R(*Rs1*) << *Imm6* else

R(*Rd*)  R(*Rs1*) >> *Imm6*

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **lw** | Load word from memory | 0 1 1 0 | Rd | Rs1 | Imm6 |

Loads word from memory using the effective address computed by adding *Rs1* with the signed immediate.

R(*Rd*)  M[R(*Rs1*) + *Imm6*]

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **sw** | Store word to memory | 0 1 1 1 | Rd | Rs1 | Imm6 |

Stores word into memory using the effective address computed by adding Rs1 with the signed immediate.

M[R(*Rs1*) + *Imm6*]  R(*Rd*)

|  |  |  |  |
| --- | --- | --- | --- |
| 1 0 0 0 | Rd |  | Imm8 |

**lli** Load lower immediate

The lower bits (7-0) of *Rd* are copied from the immediate. The upper bits (15- 8) of *Rd* are set to bit 7 of the immediate to produce a sign-extended result.

R(*Rd*[15..8])  *Imm8*[7]

R(*Rd*[7..0])  *Imm8*

|  |  |  |  |
| --- | --- | --- | --- |
| 1 0 0 1 | Rd |  | Imm8 |

**lui** Load upper immediate

The upper bits (15- 8) of *Rd* are copied from the immediate. The lower bits (7-0) of *Rd* are unchanged. The sign of the immediate does not matter – the eight bits are copied directly.

R(*Rd*[15..8])  *Imm8*

|  |  |  |  |
| --- | --- | --- | --- |
| 1 0 1 0 | Rd |  | Imm8 |

**beq** Branch if equal to zero

Conditional branch – compares *Rd* to zero. If R(*Rd*) = 0, then branch is taken with indirect target of PC + 1 + *Imm8* as next PC. Immediate is a signed value.

if (R(*Rd*) == 0) PC  PC + 1 + *Imm8*

|  |  |  |  |
| --- | --- | --- | --- |
| 1 0 1 0 | Rd |  | Imm8 |

**bne** Branch if not equal to zero

Conditional branch – compares *Rd* to zero. If R(*Rd*) ≠ 0, then branch is taken with indirect target of PC + 1 + *Imm8* as next PC. Immediate is a signed value.

if (R(*Rd*) ≠ 0) PC  PC + 1 + *Imm8*

|  |  |  |  |
| --- | --- | --- | --- |
| 1 1 0 0 | Rd |  | Imm8 |

**bgt** Branch if greater than zero

Conditional branch – compares *Rd* to zero. If R(*Rd*) > 0, then branch is taken with indirect target of PC + 1 + *Imm8* as next PC. Immediate is a signed value.

if (R(*Rd*) > 0) PC  PC + 1 + *Imm8*

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **bge** | Branch if greater than or equal to zero | 1 1 0 1 | Rd |  | Imm8 |

Conditional branch – compares *Rd* to zero. If R(*Rd*) ≥ 0, then branch is taken with indirect target of PC + 1 + *Imm8* as next PC. Immediate is a signed value.

if (R(*Rd*) ≥ 0) PC  PC + 1 + *Imm8*

|  |  |  |  |
| --- | --- | --- | --- |
| 1 1 1 0 | Rd |  | Imm8 |

**blt** Branch if less than to zero

Conditional branch – compares *Rd* to zero. If R(*Rd*) < 0, then branch is taken with indirect target of PC + 1 + *Imm8* as next PC. Immediate is a signed value.

if (R(*Rd*) < 0) PC  PC + 1 + *Imm8*

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **ble** | Branch if less than or equal to zero | 1 1 1 1 | Rd |  | Imm8 |

Conditional branch – compares *Rd* to zero. If R(*Rd*) ≤ 0, then branch is taken with indirect target of PC + 1 + *Imm8* as next PC. Immediate is a signed value.

if (R(*Rd*) ≤ 0) PC  PC + 1 + *Imm8*

# ANNA Assembly Convention

## ANNA Calling Convention

* The start of the stack is at address 0x8000. The program is responsible for initializing the stack and frame pointers at the beginning of the program.
* Register usage:
  + r4: return value after a function call.
  + r5: return address at the beginning of the function call.
  + r6: frame pointer throughout the program
  + r7: stack pointer throughout the program

* All parameters must be stored on the stack (registers are not used).
* The return value is stored in r4 (stack is not used).
* Caller must save values in r1-r5 they want retained after a function (caller save registers).
  + The return address in r5 is treated like any other caller save register.

* All activation records have the same ordering.
  + Function parameters are pushed onto the stack, accessed via FP+*n*.
  + First entry (offset 0) is for the previous frame pointer
  + Next entry (offset -1) is for return address
  + Remaining entries are used for local variables and temporary values (order left up to programmer).
* Activation record for “main” only has local variables and temporary values.
  + No previous frame
  + No parameters
* Alternatively, global variables may be stored in regular memory as labels on .fill directives.

## ANNA Heap Management

* Dynamic memory in ANNA is simplified – only allocations (no deallocations)
* Heap management table is implemented using a single pointer called heapPtr, it points to the next free word in memory.
* Heap is placed at the very end of the program:

# heap section heapPtr: .fill &heap

heap: .fill 0

# ANNA Assembler Reference

# 

## Assembly Language Files

Assembly language files are text files and by convention have the suffix .asm. Any editor (such as Notepad) can be used to edit assembly language files.

## Assembly Language Format Rules

When writing assembly language programs, each line of the file must be one of…

* blank line (only white space)
* comment line (comment optionally preceded by white space)
* instruction line

An instruction line must contain exactly one instruction. Instructions cannot span multiple lines nor can multiple instructions appear on the same line. An instruction is specified by the opcode and the fields required by the instruction. The order of the fields is the same as the order of the fields in machine code (from left to right). For example, the order of the fields for subtract are sub *Rd* *Rs1* *Rs2*. The opcode and fields are separated by white space. Only fields that are necessary for the instruction can be specified. For instance, the in instruction only requires *Rd* to be specified so it is incorrect to specify any other fields.

Additional rules:

* Opcodes are specified in completely lower case letters.
* A register can be any value from: r0, r1, r2, r3, r4, r5, r6, r7.
* Register r0 is always zero. Writes to register r0 are ignored.

### Comments

Comments are specified by using '#'. Anything after the '#' sign on that line is treated as a comment. Comments can either be placed on the same line after an instruction or as a standalone line.

### Assembler directives

In addition to instructions, an assembly-language program may contain directions for the assembler. There are two directives in ANNA assembly:

.halt: The assembler will emit an out instruction with *Rd* equal to r0 (0xF000) that halts the processor. It has no fields.

.fill: Tells the assembler to put numbers into memory starting at the current location. For example, the directive ".fill 32 0x41" puts the values 32 and 65 into memory.

.cstr: Tells the assembler to put a NUL-terminated string into memory starting at the current location.

.def: Assigns a value to a label, such

### Labels

Each instruction may be preceded by an optional label. The label can consist of letters, numbers, and underscore characters and is immediately followed by a colon (the colon is not part of the label name). No whitespace is permitted between the first character of a label and the colon. A label must appear on the same line as an instruction. Only one label can appear before an instruction.

### Immediates

Many instructions and the .fill directive contains an immediate field. An immediate can be specified using decimal values, hexadecimal values, or labels.

* Decimal values are signed. The value of the immediate must not exceeds the range of the immediate (see chart below).
* Hexadecimal values must begin with "0x" and may only contain as many digits (or fewer) as permitted by the size of the immediate. For instance, if an immediate is 8 bits, only two hex digits are permitted. Immediates with fewer than the number of digits will be padded with zeros on the left.
* Binary values must begin with "0b" and may only contain as many digits (or fewer) as permitted by the size of the immediate.
* Labels used as immediates must be preceded by an '&' sign. The address of the label instruction is used to compute the immediate. The precise usage varies by instruction:
* .fill directive: The entire 16-bit address is used as the 16-bit value.
* lui and lli: A 16-bit immediate can be specified. The appropriate 8 bits of the address (upper 8 bits for lui, lower 8 bits for lli) are used as an immediate.
* branches: The appropriate indirect address is computed by determining the difference between PC+1 and the address represented by the label. If the difference is larger than the range of an 8-bit immediate, the assembler will report an error.
* addi, shf, lw, sw: Labels are not permitted for 6-bit immediates.

This table summarizes the legal values possible for immediate values:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| *Opcode* | *Decimal Min* | *Decimal Max* | *Hex Min* | *Hex Max* | *Label Usage* |
| .fill | -32,768 | 32,767 | 0x8000 | 0x7fff | address |
| lui, lli | -32,768 | 32,767 | 0x80 | 0x7f | address |
| branches | -128 | 127 | 0x80 | 0x7f | PC-relative |
| addi, shf, lw, sw | -32 | 31 | 0x00 | 0x3f | not allowed |

## Error Checking

Here is a list of the more common errors you may encounter:

* improperly formed command line
* use of undefined labels
* duplicate labels
* immediates that exceed the allowed range
* invalid opcode
* invalid register
* invalid immediate value
* illegally formed instructions (not enough or too many fields)

# ANNA Simulator Reference

The ANNA+ simulator may be found at [github.com/stephen-riley/AnnaSim](https://github.com/stephen-riley/AnnaSim). See the README there for build and installation instructions.

When fully installed, run anna to see brief command line instructions.

## Running the Assembler

To write an assembly file, use any text editor (such as Notepad).

Then simply run:

anna your\_filename.asm

The output will be an assembled memory file on the terminal screen (STDOUT), which by itself is not that interesting. To write the memory file to your hard drive, use the -m switch:

anna your\_filename.asm -m your\_memfile.mem

If you’d like to see what the assembled bits look like in the context of your assembly file, add the --disam switch:

anna your\_filename.asm --disasm your\_filename.dasm -m your\_memfile.mem

## Running the Simulator

There are three modes for the simulator.

### Runner

The Runner is invoked with the -r switch. To assemble and run a program:

anna your\_filename.asm -r

You can trace execution of your program with the -t switch. This will show you each instruction as it executes, what register changed from the instruction, and what the stack looks like.

anna your\_filename.asm -r -t

### Debugger

The debugger is a very minimal console debugger in the style of gdb. To assemble and invoke the debugger:

anna your\_filename.asm -d

To see all the commands in the debugger, type h and press enter.

Common commands include:

|  |  |
| --- | --- |
| h | Help |
|  |  |

### VT100 advanced debugger

To run the simulator, there are four control buttons:

* *Run / Continue*: Runs the program until a breakpoint or the program halts.

* *Step*: Executes a single instruction.

* *Reset Simulator*: Resets the program back to the initial state.

* *Clear All Breakpoints*: Removes all breakpoints.

The simulator can be in one of five states:

* NOT LOADED: A program has not been successfully assembled and loaded into memory. The simulator is inactive until a program has been loaded.

* READY: A program has been loaded and is in the initial state (PC is at 0, all registers have 0, etc.). The simulator is active.

* RUNNING: A program is in the middle of execution and has stopped due to a breakpoint or by stepping one instruction at a time. The simulator is active.

* HALTED: The program encountered a halt, terminating the program. The simulator is inactive and must be reset to rerun the program.

* ERROR: The simulator encountered an error. This is likely due to a bug in the simulator – contact your instructor. The simulator is inactive and must be reset to rerun the program.

Additional notes:

* When asked to enter a value using the in instruction, you must enter a 16 bit signed decimal value (-32,768 to 32,767) or hexadecimal value (0x8000 to 0x7fff).
* Output values from the out instruction will appear in the output window.
* The simulator will stop every 1000 instructions even if no breakpoints are set. This is used to check if an infinite loop as occurred.

## Displaying Data

The Registers pane displays the current value of all the registers including the PC.

The Memory pane can display the contents of up to four memory addresses. To view the contents of a memory address, simply type the address in one of the four address boxes. The current value will then be displayed in the corresponding value box. The address must be specified in decimal (unsigned value from 0 to 65,535) or hexadecimal (0x0 to 0xffff). The value will be updated appropriately while the program runs.

## Setting Breakpoints

Breakpoints provide a way to stop execution at any point in the program. The typical use is to set a breakpoint at the start of an interesting part of the program, and then to select *Run/Continue* to run the program up to that point. The program will execute until the instruction at the address of the breakpoint is about to be executed, and then stop.

To set a breakpoint, simply click the BP check box by the instruction such that the box is checked. When the PC is equal to any of the enabled breakpoints, the simulator will stop.

To clear a breakpoint, click the BP check box such that box is unchecked. All breakpoints can be cleared by pressing the *Clear All Breakpoints* button. Breakpoints are automatically cleared when a new program is loaded.

# Style Guide

## Commenting Convention

Your program should include the following comments:

* A block comment with your name, name of the program, and a brief description of the program.
* For each function (including the "main" body): indicate what the code does and how each register is used.
* Place a brief comment for each logical segment of code. Since assembly language programs are notoriously difficult to read, good comments are absolutely essential! o You may find it helpful to add comments that paraphrase the steps performed by the assembly instructions in a higher-level language.
* A comment that indicates the start of a new section.
* Place a brief comment for every variable in the data section.

## Other Style Guidelines

This section lists some additional style guidelines:

* Make label names as meaningful as possible. It is expected that some labels for loops and branches may be generic.
* Use labels instead of hard coding addresses. You do not want to change your immediate fields if you add a line.
* Do not assume an address will appear "early" in the program. An lli instruction with a label should always be followed with an lui instruction with the same label.
* Indent all lines so lines with labels are not staggered with the rest of the code.
* Use .halt to halt the program.
* There is no reason to use .fill in the code section. There is no reason to use anything but .fill in the data section.