

Physics-Aware Recurrent Convolutions (PARC)

Stephen Baek

Recap of PINN and Neural Operator from a Differential Geometry Point of View

- Physics-informed loss (Raissi et al.)

$$\partial_t u - \mathcal{N}(u) = 0$$

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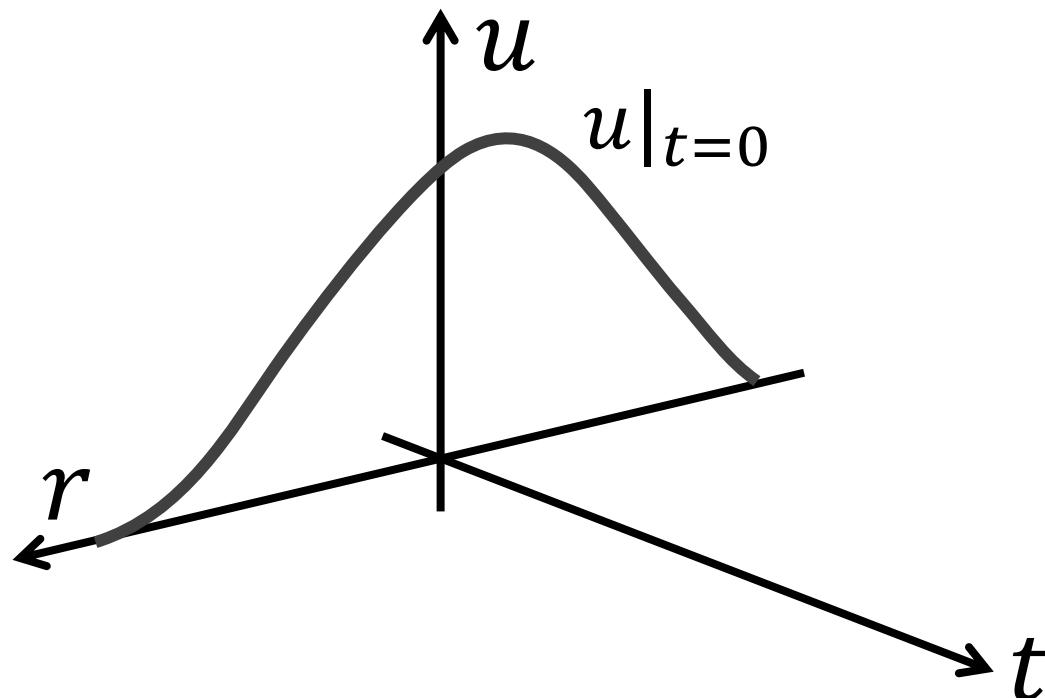
$$\partial_t u - \alpha \nabla^2 u = 0$$

Heat equation

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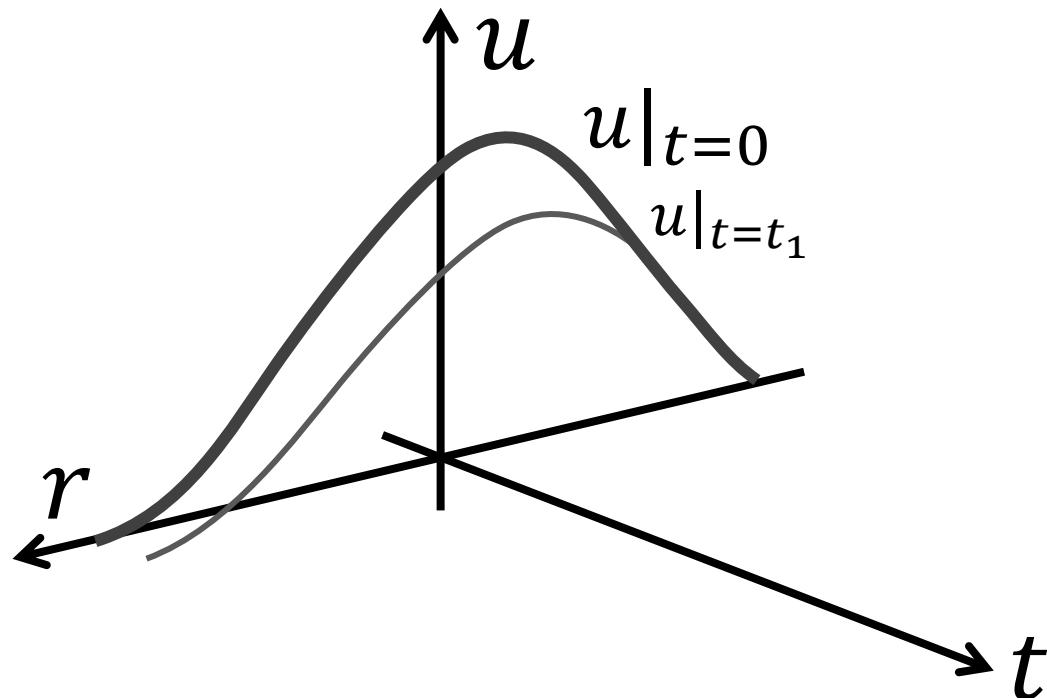
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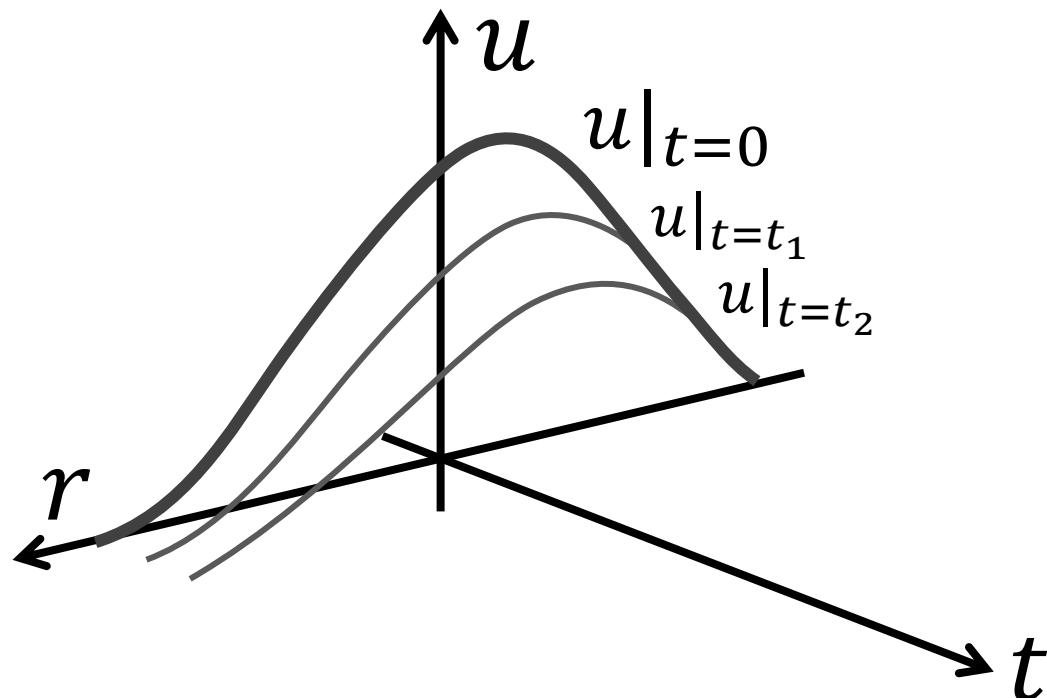
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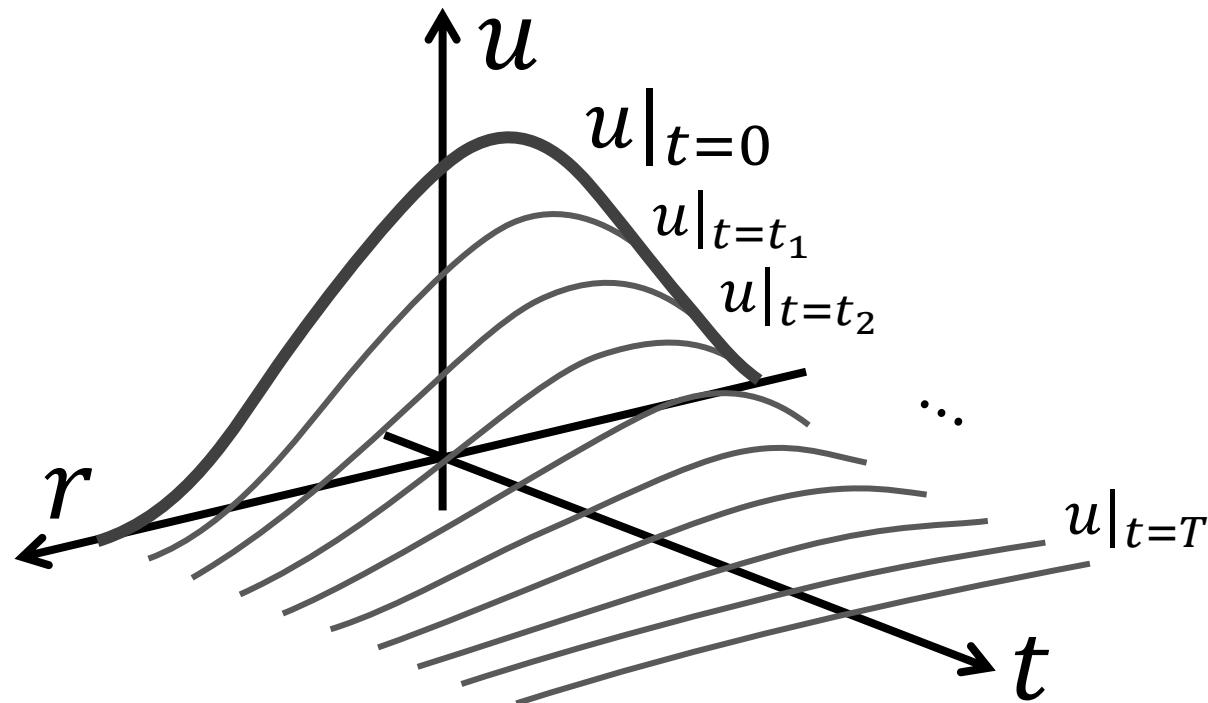
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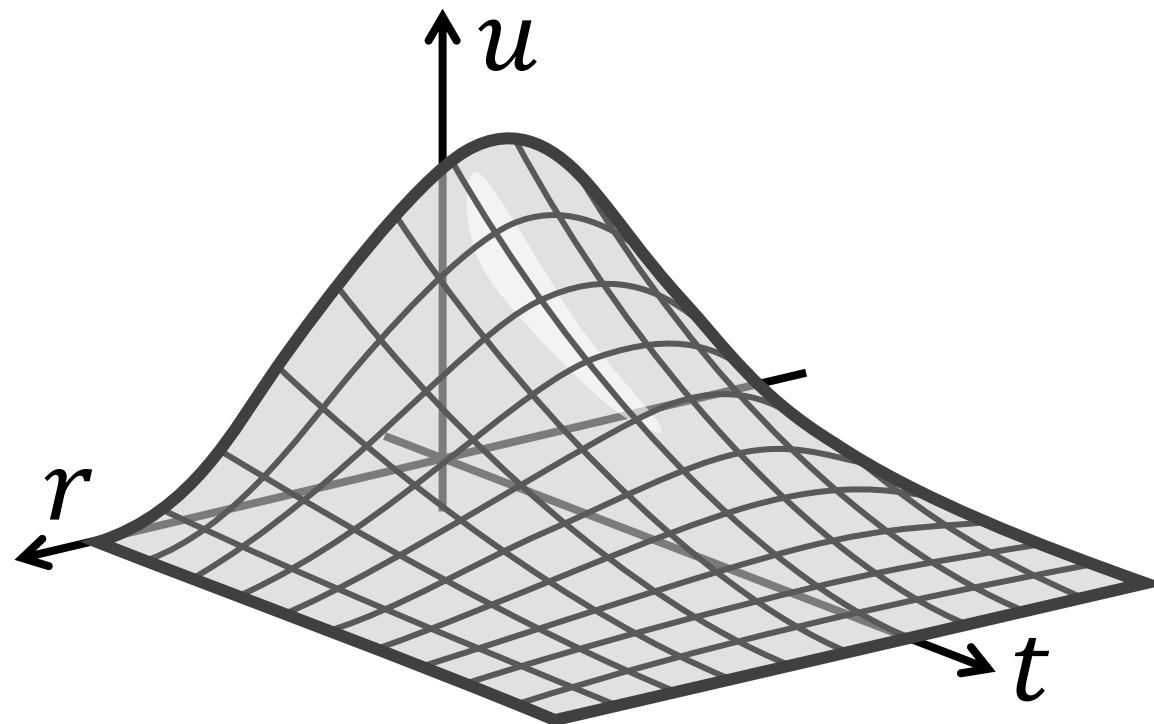
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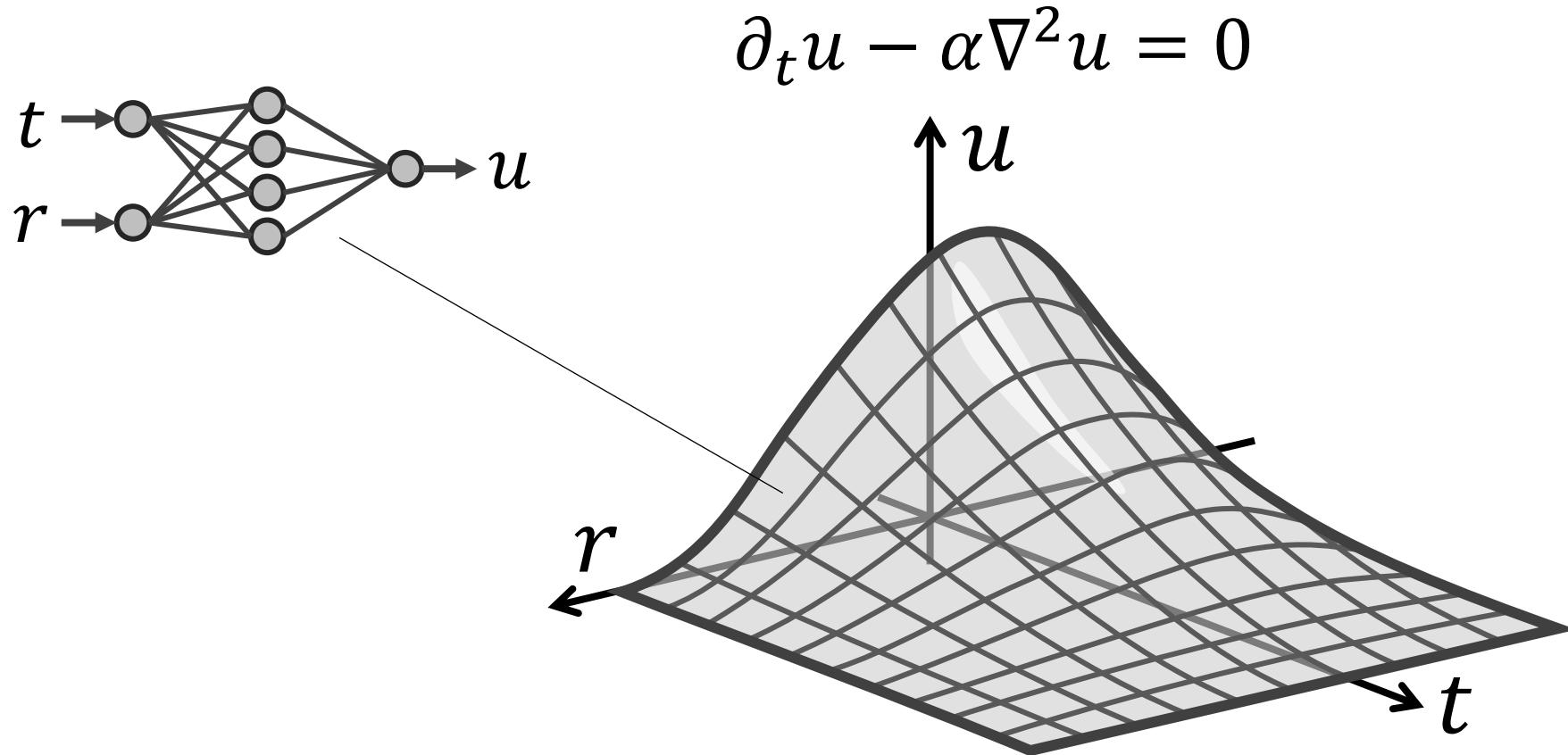
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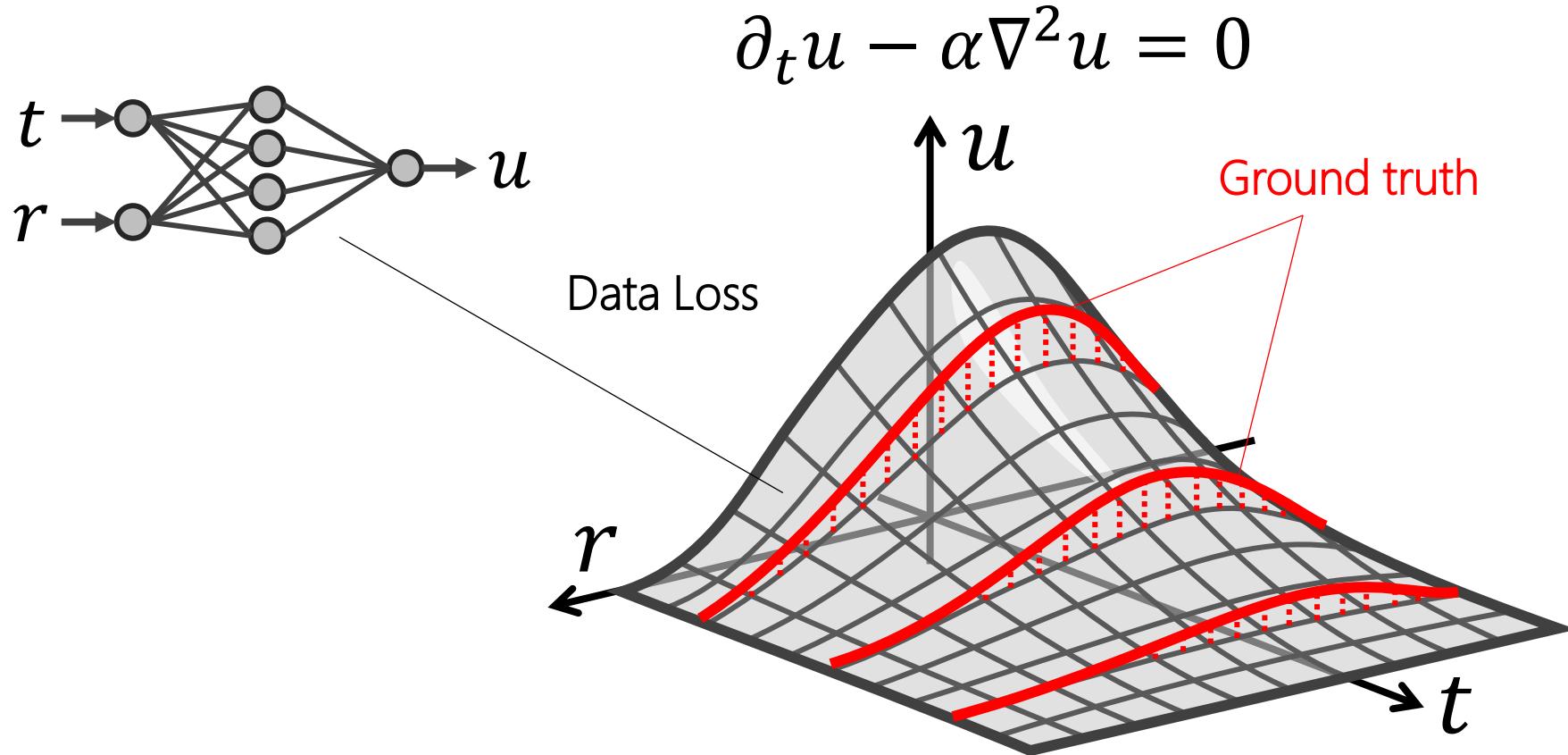
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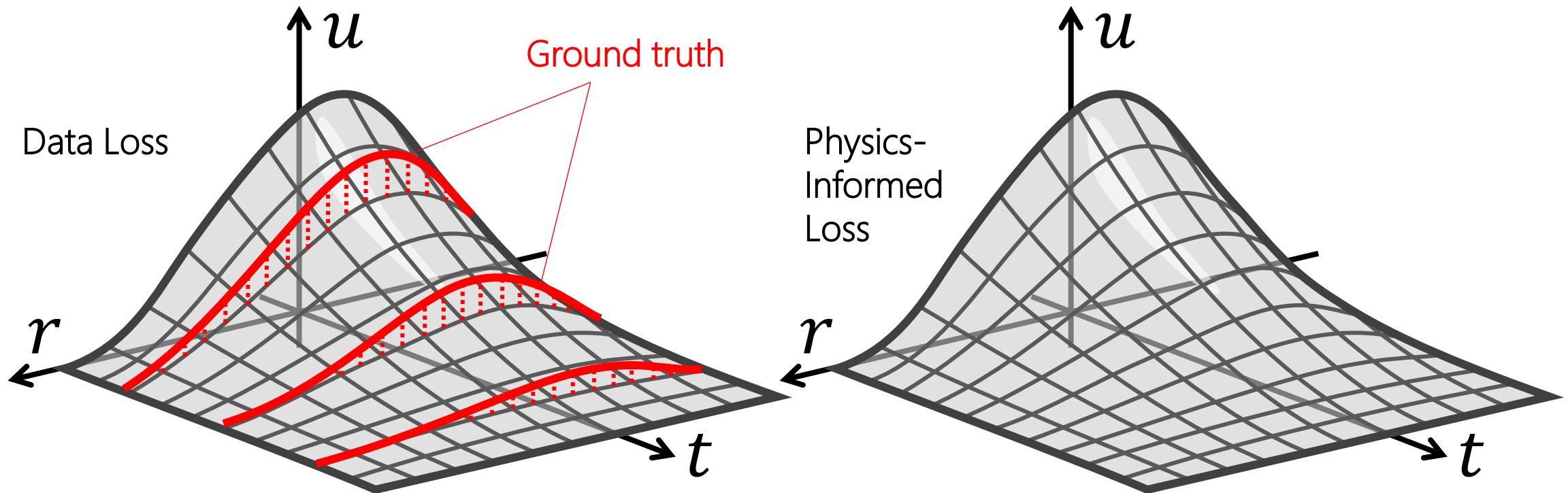
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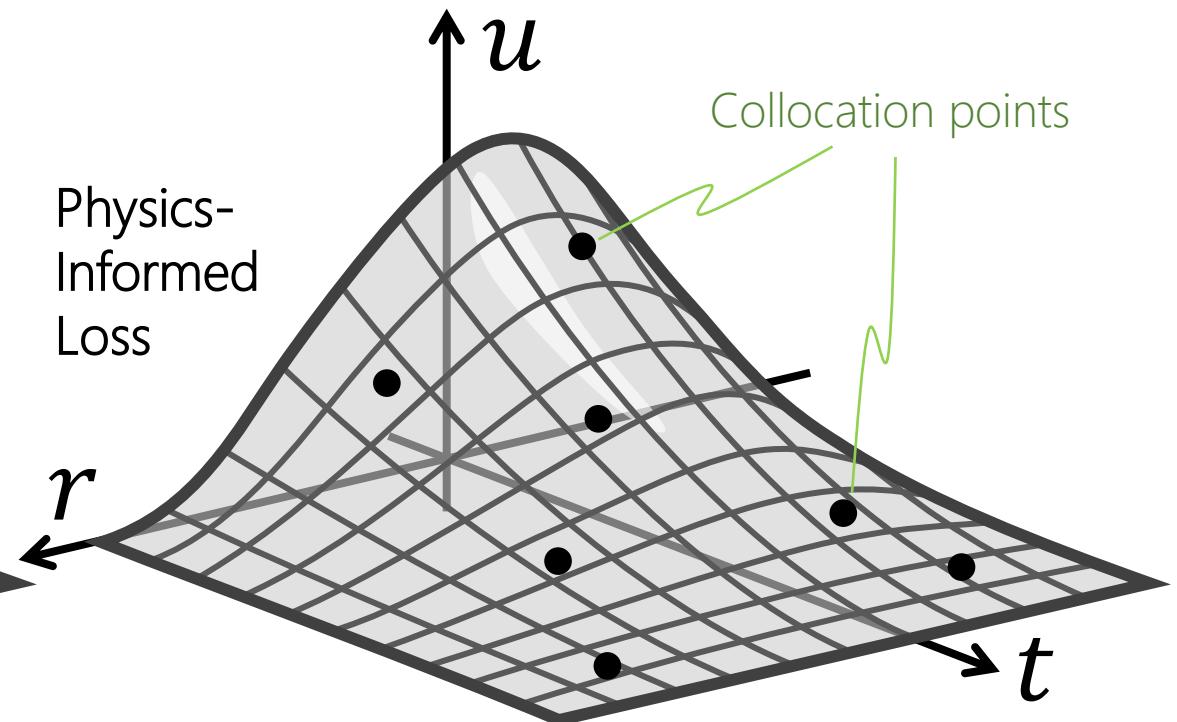
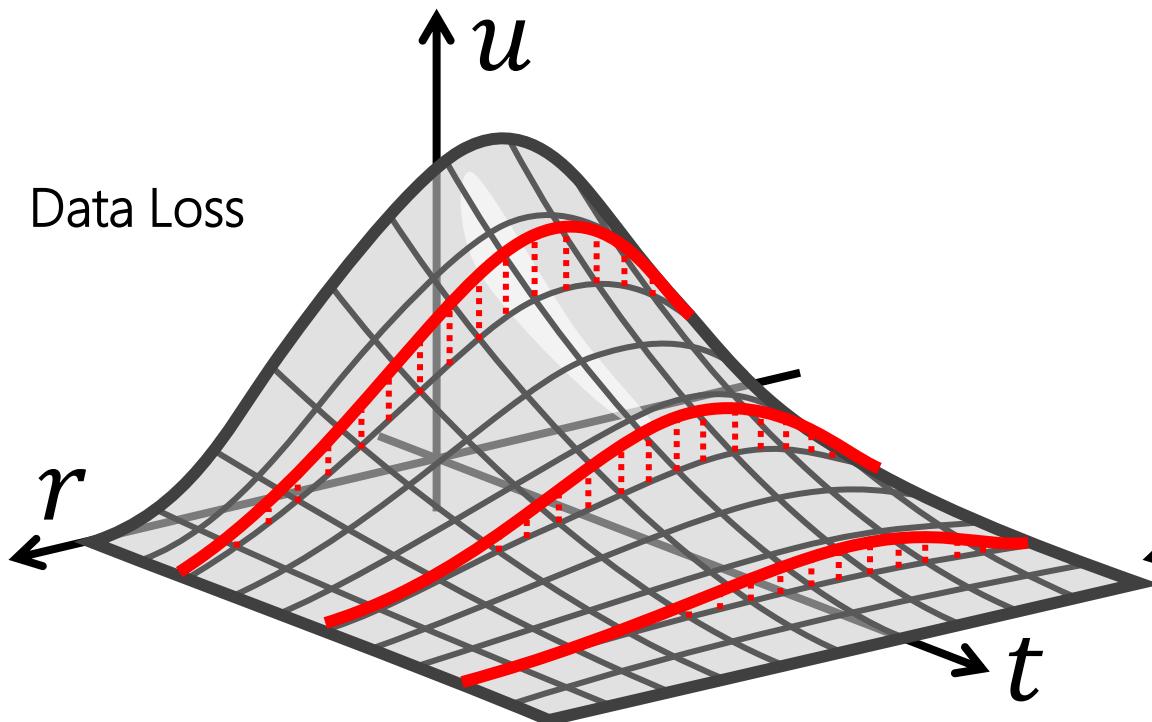
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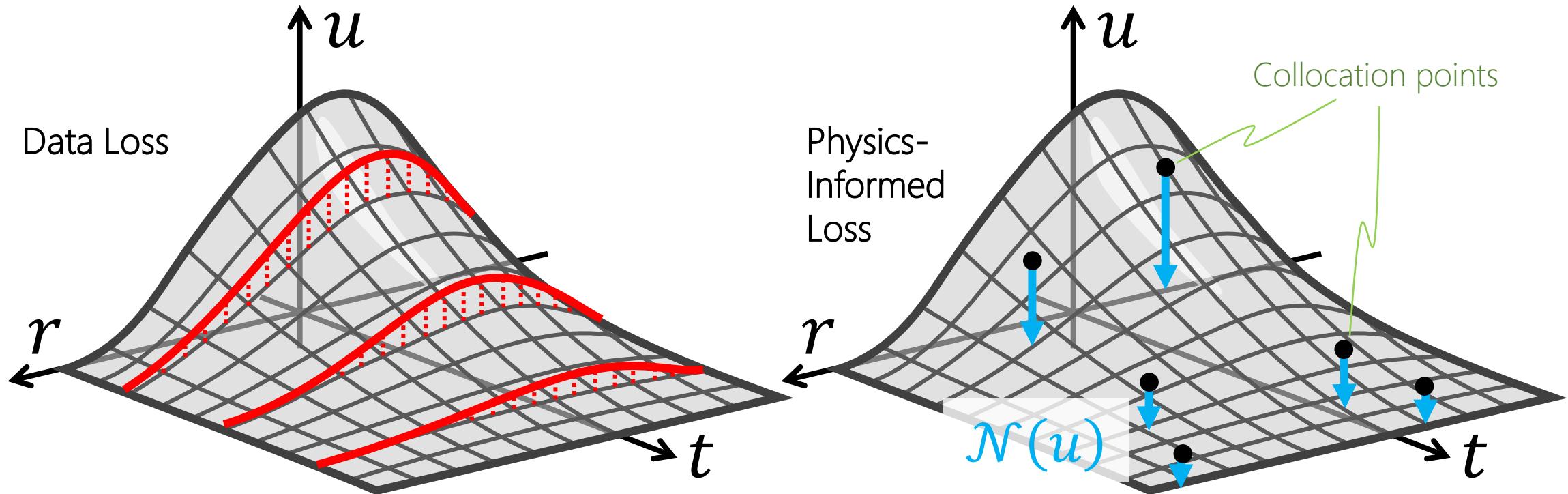
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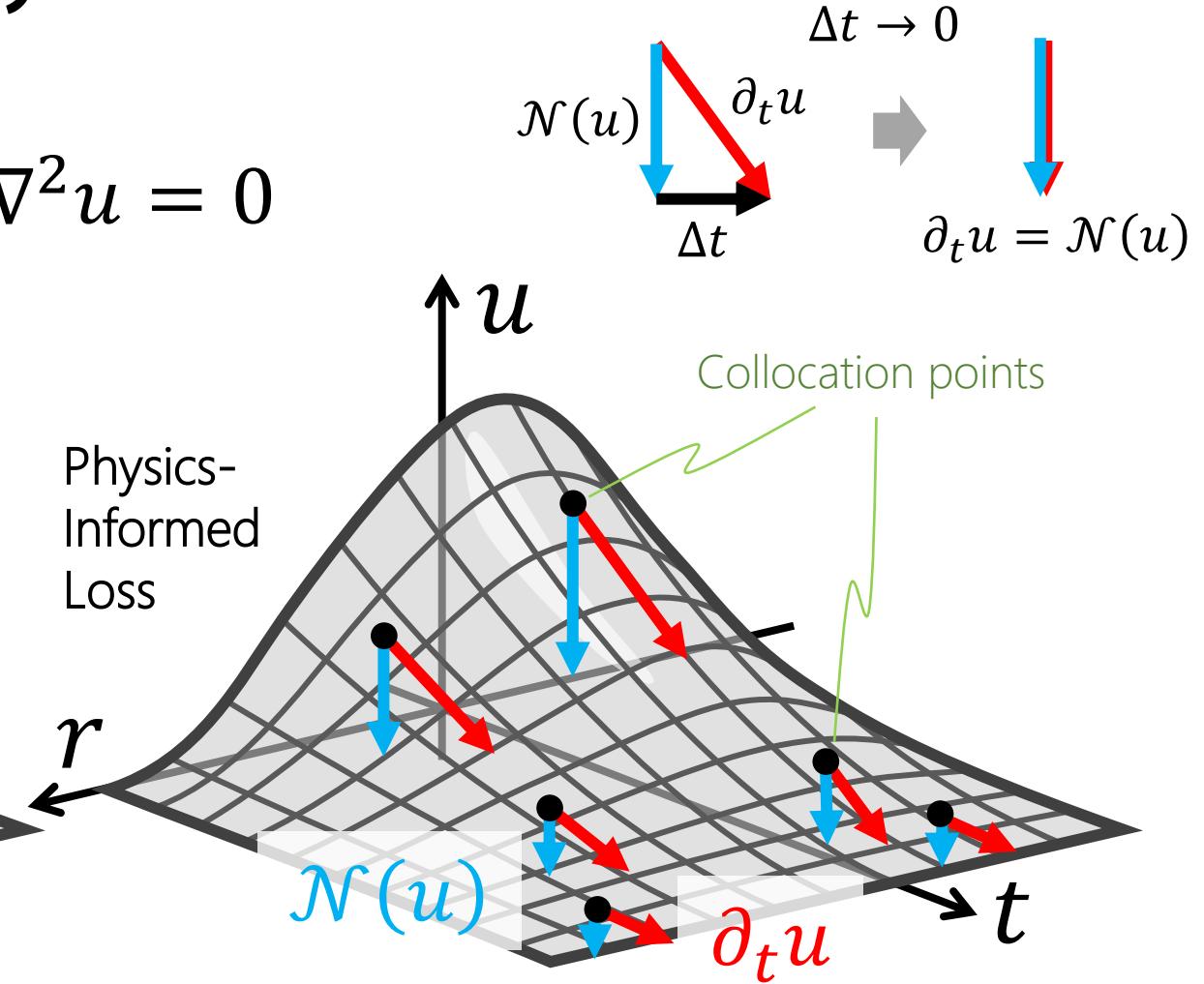
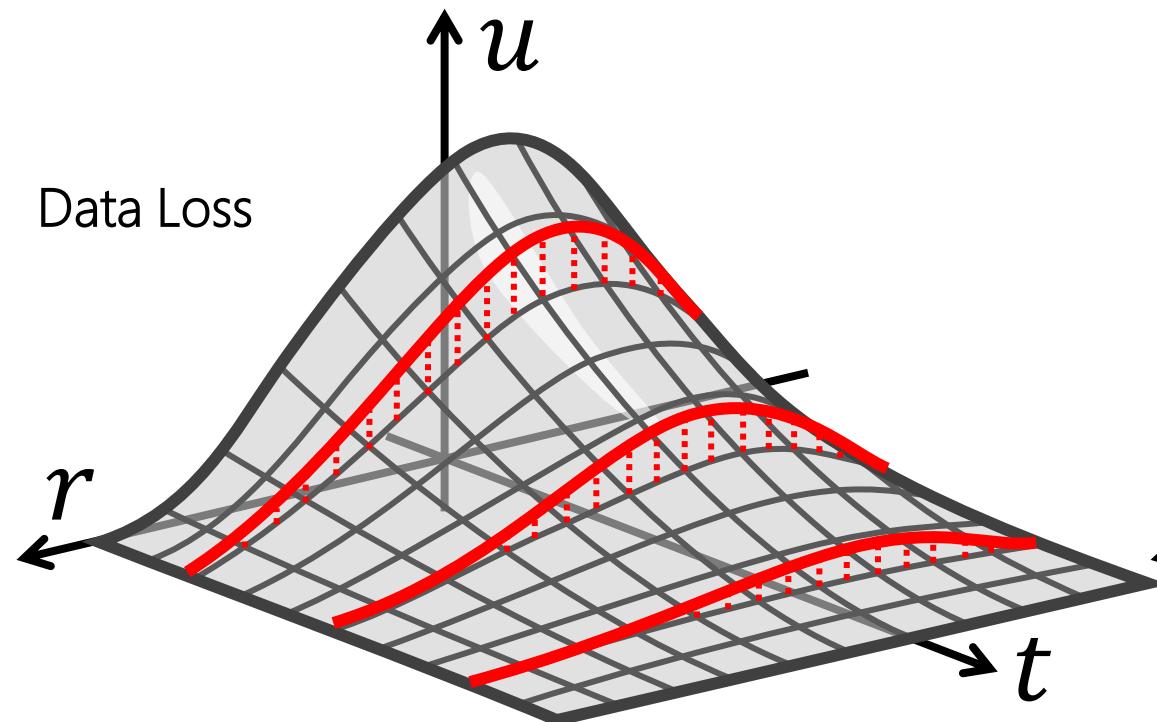
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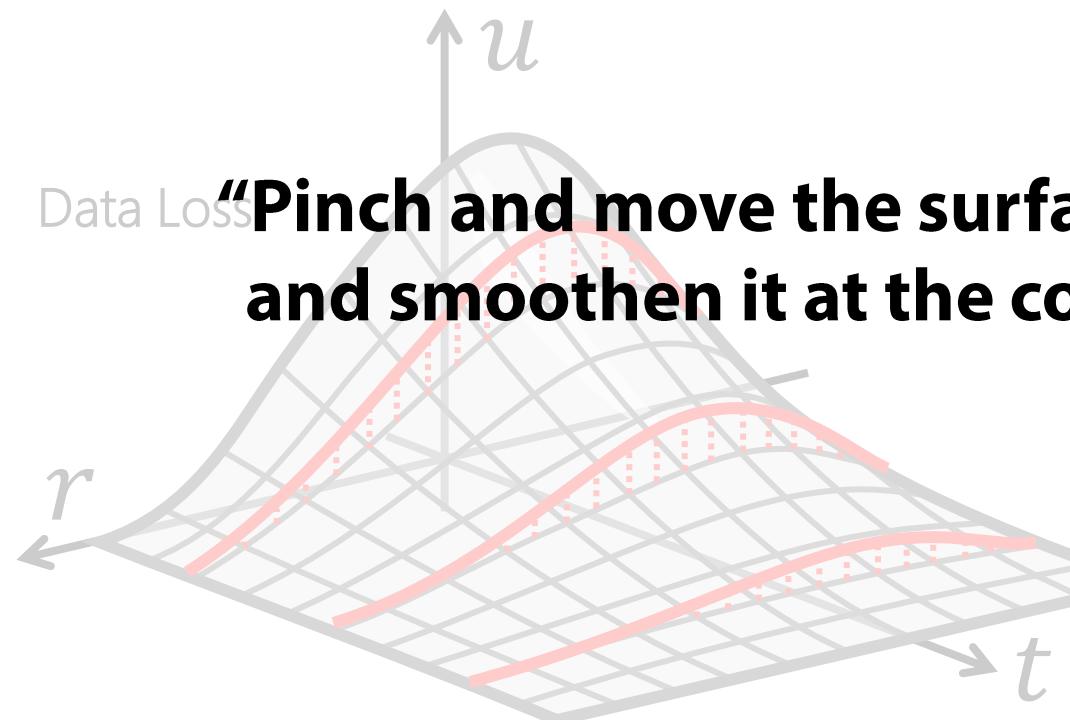
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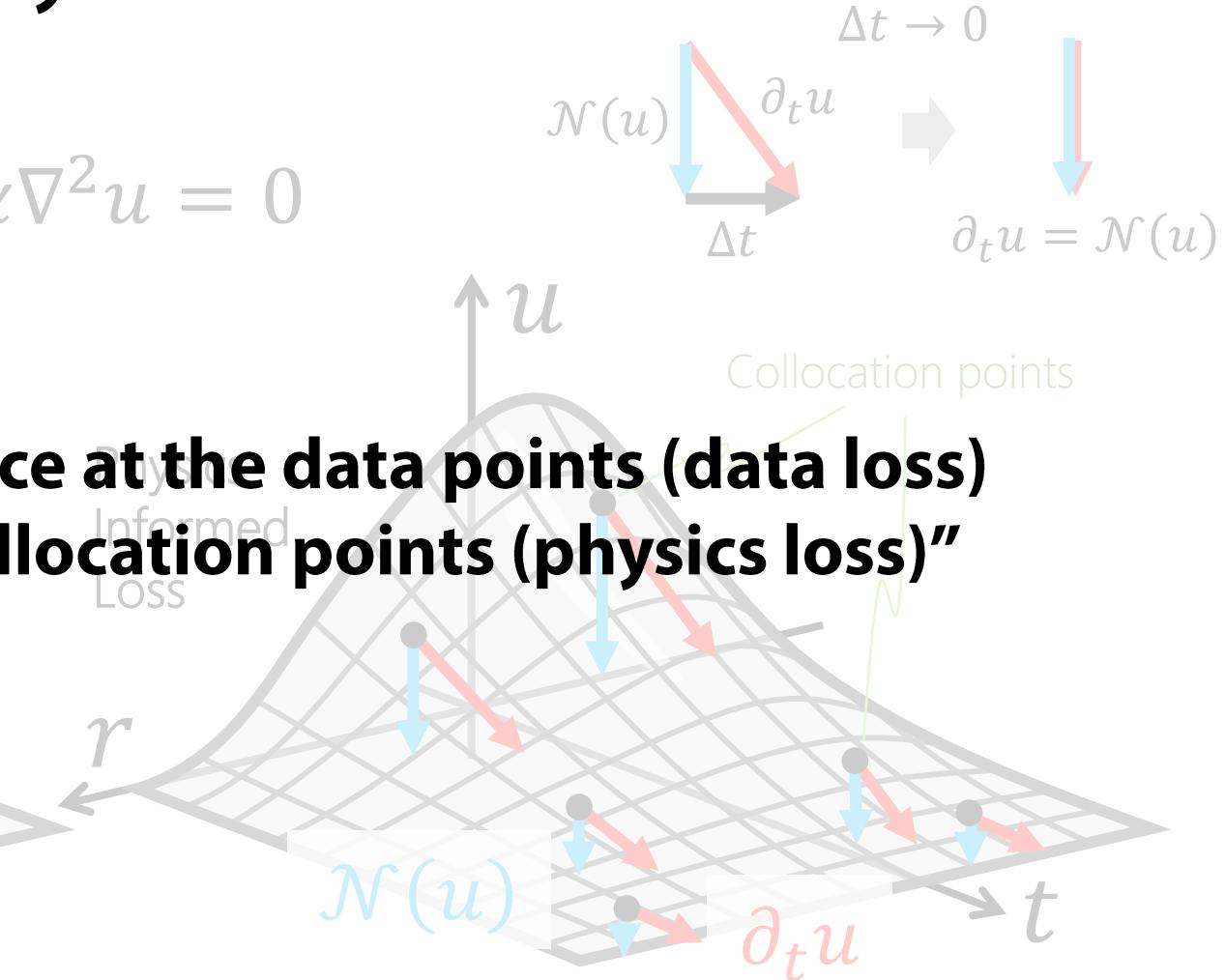
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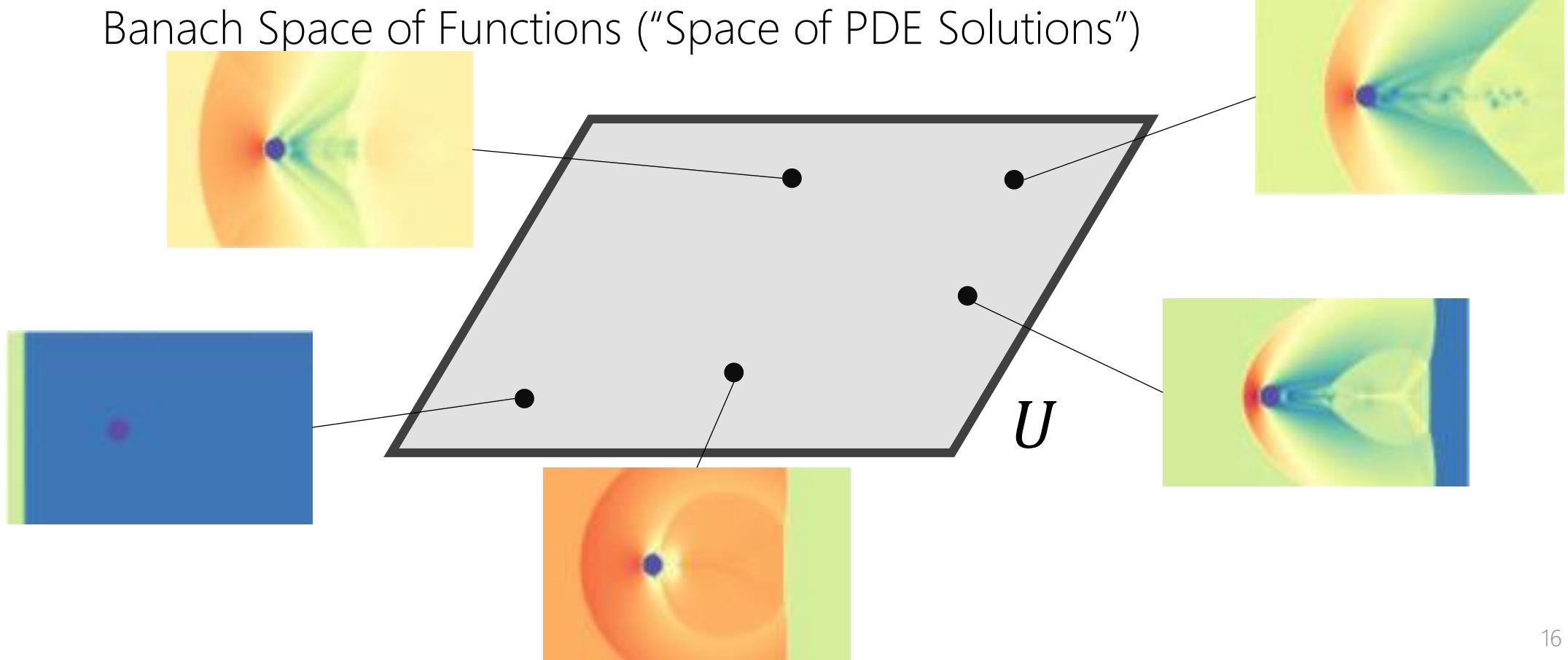
“Pinch and move the surface at the data points (data loss) and smoothen it at the collocation points (physics loss)”



Recap of PINN and Neural Operator from a Differential Geometry Point of View

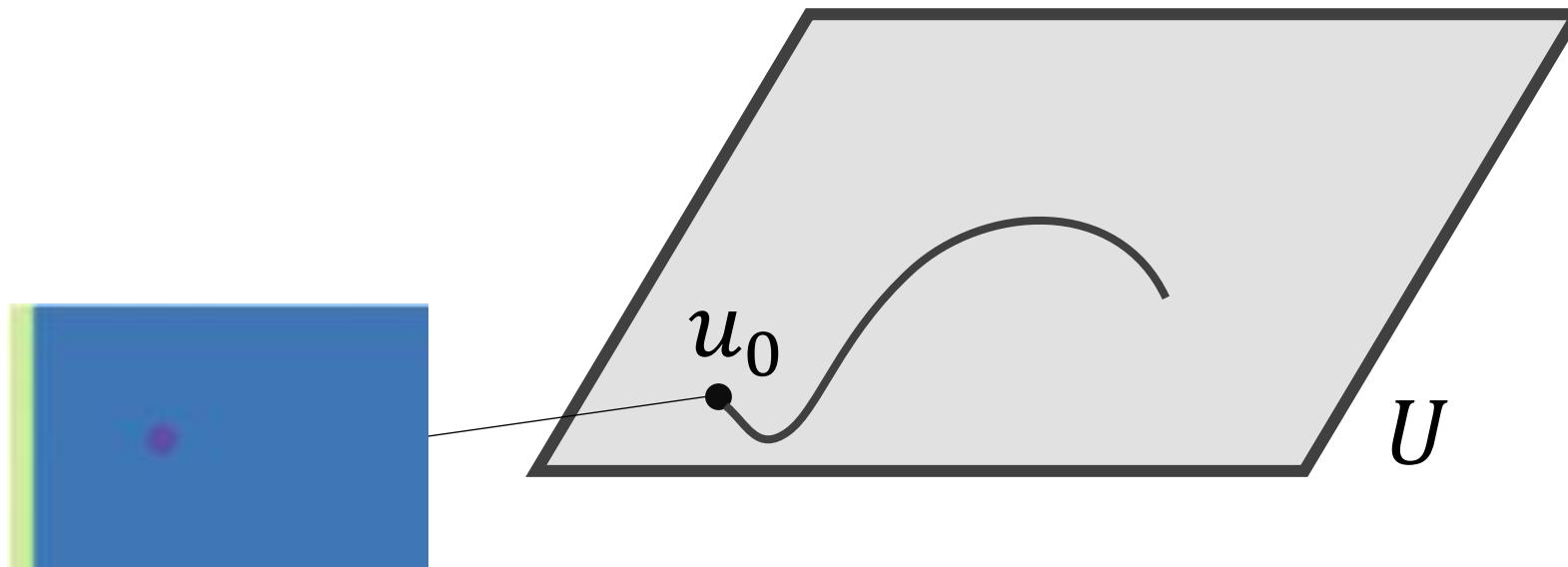
- Neural Operators (Kovachki, Li, et al.)

Banach Space of Functions ("Space of PDE Solutions")



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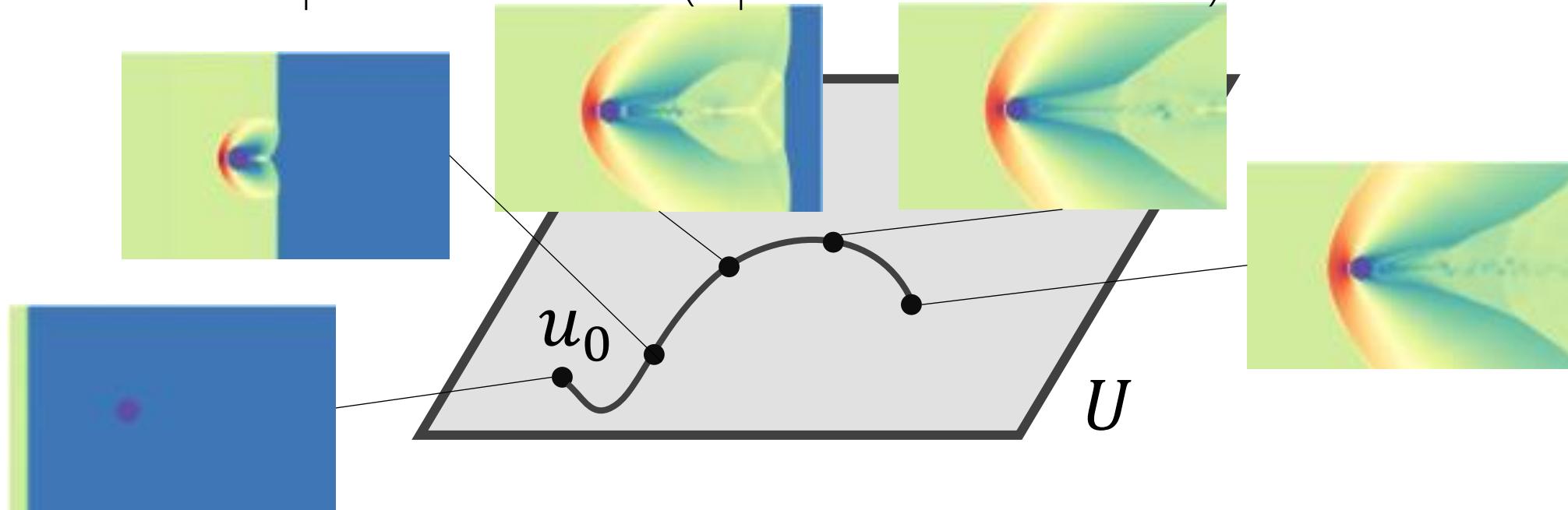
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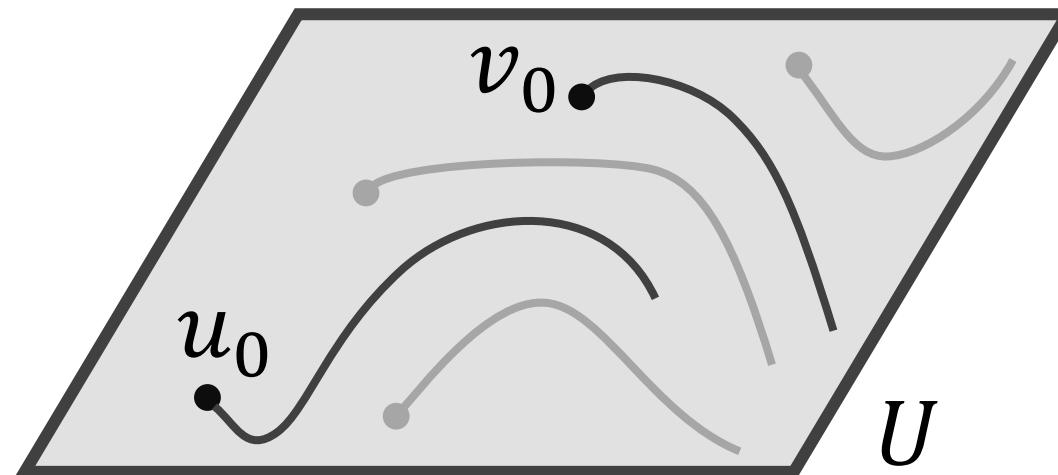
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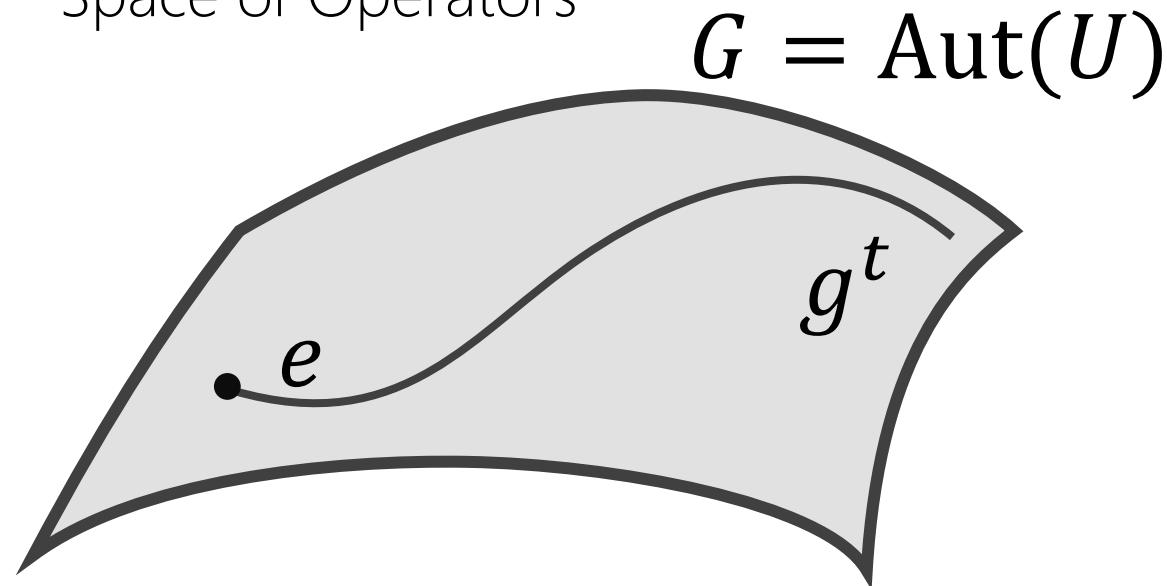
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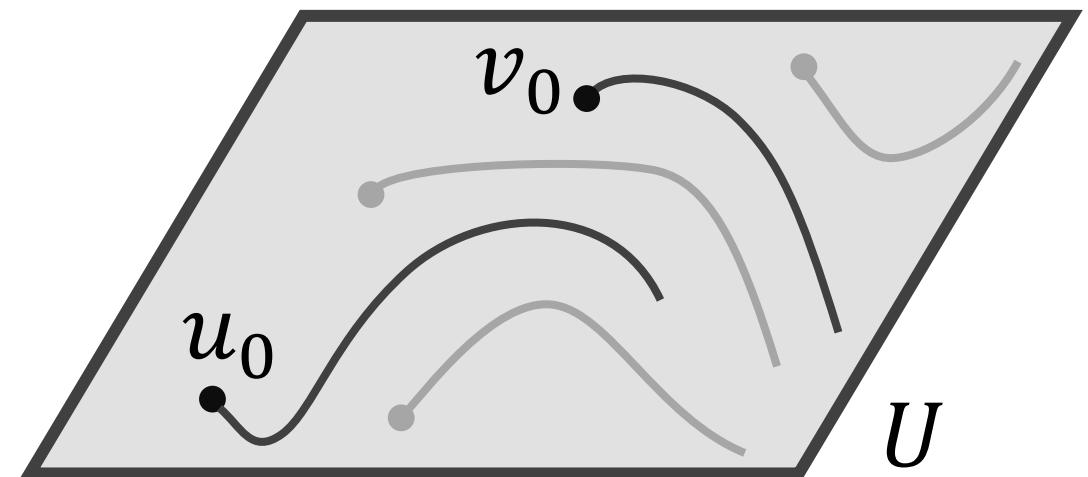
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Space of Operators

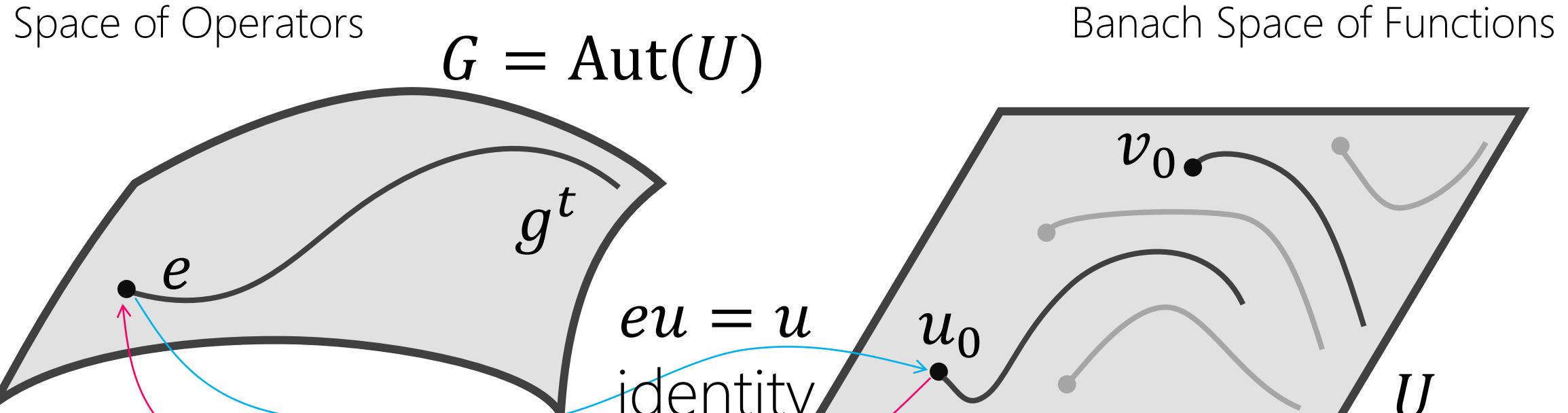


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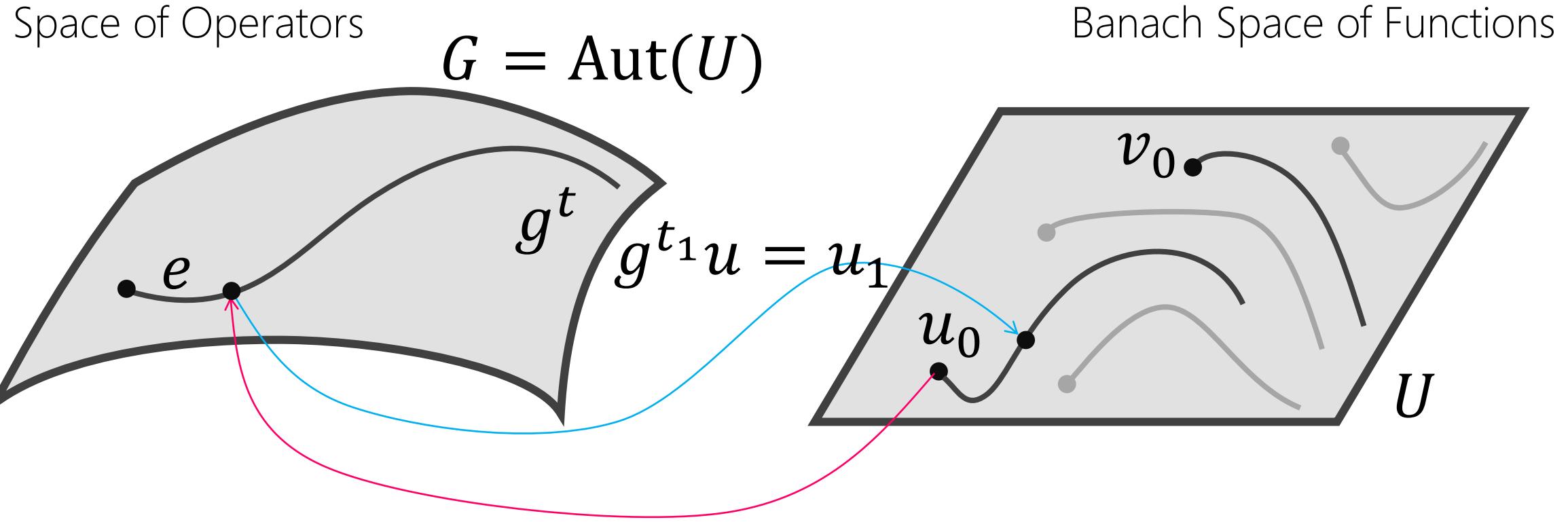
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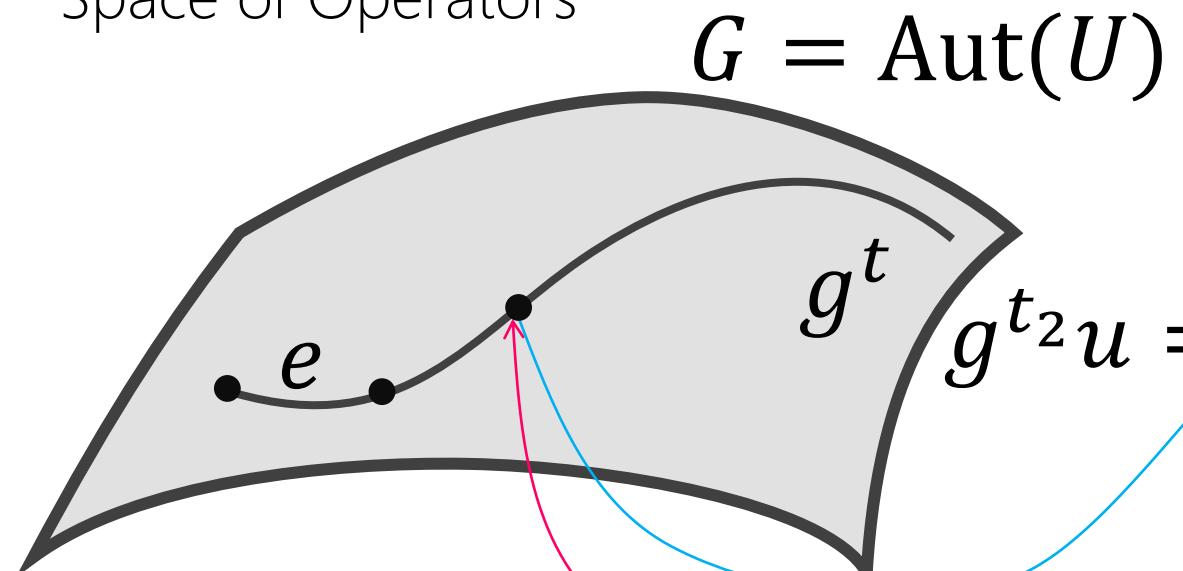
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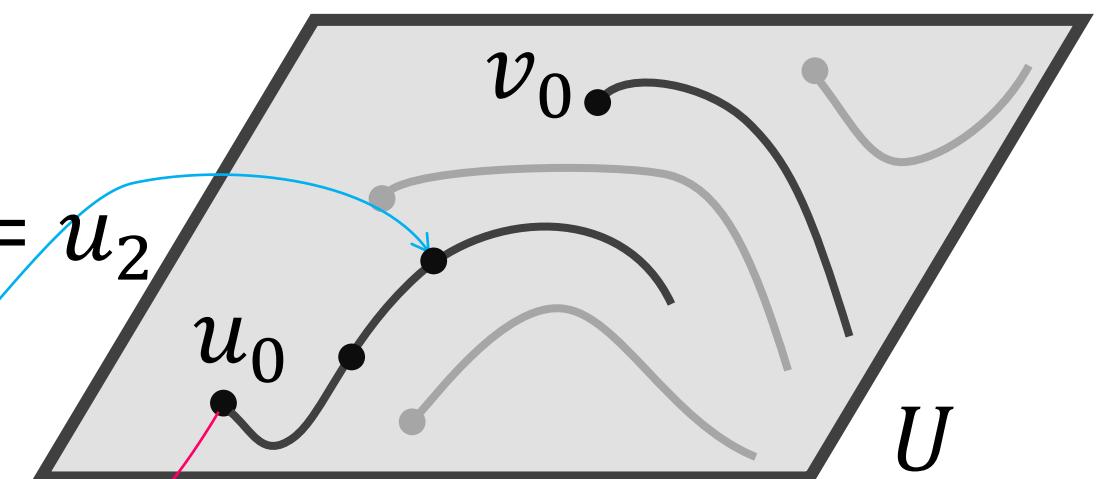
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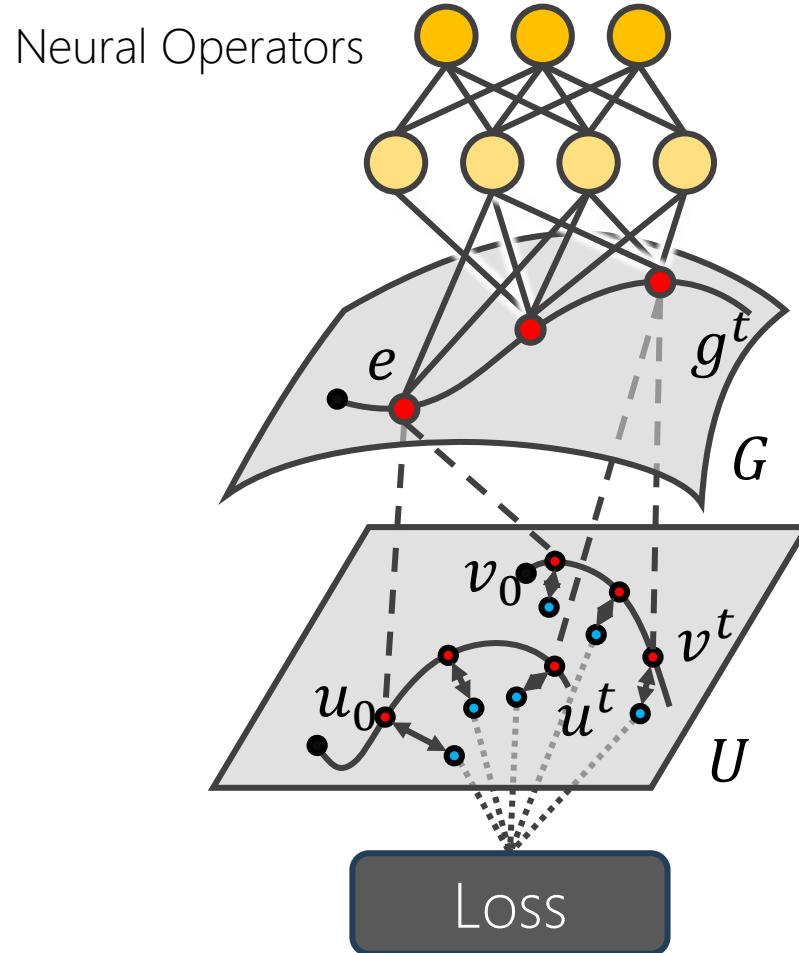
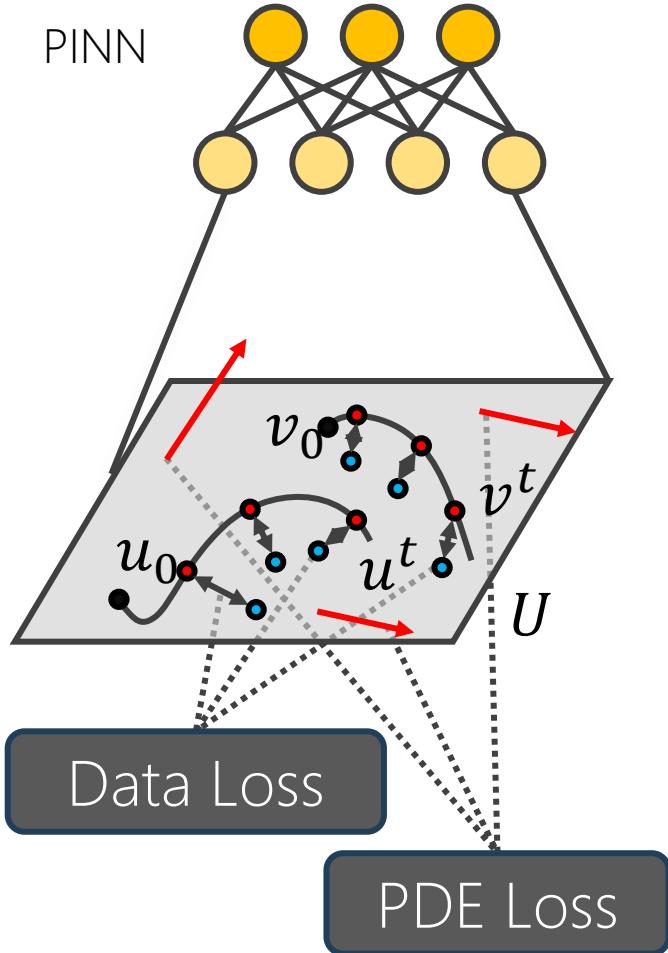
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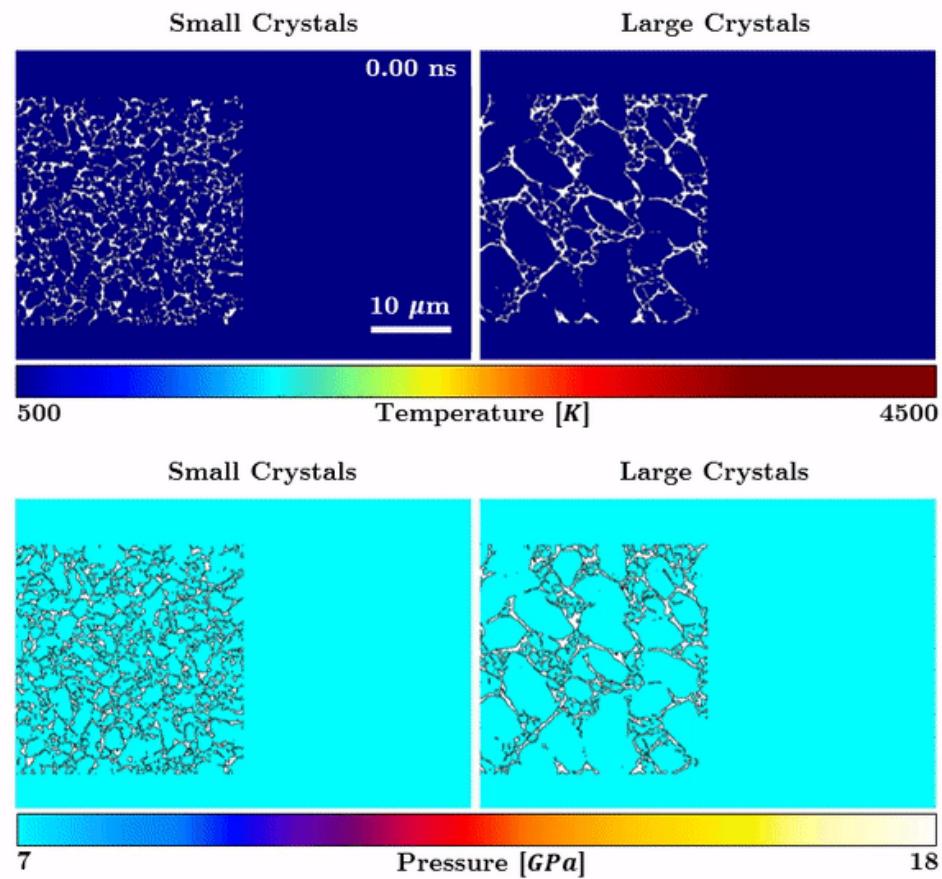
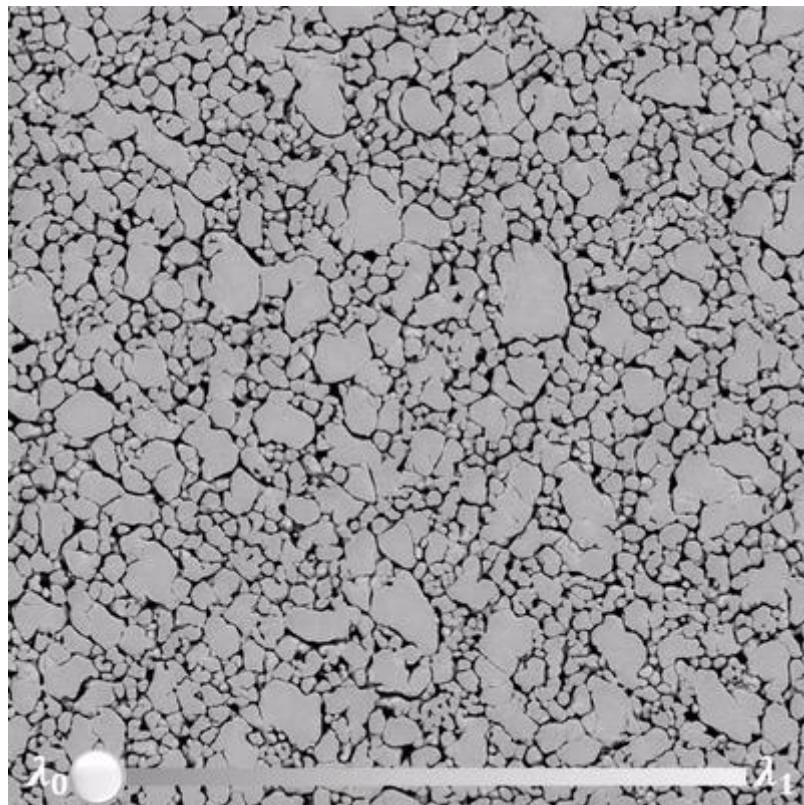


Re-thinking the Physics Learning

- PINN: Learning the solution function
 - Approximate the **solution function** using neural networks
 - Search space: Entire space of functions \mathcal{U}
 - If IC/BC/other physical conditions change, the model needs to be retrained.
 - When the solution function \mathbf{u} is nonlinear, the model is harder to fit with small data
- Neural Operators: Learning the operator
 - Approximate the **solution operator** using neural networks
 - Search space: Space of operators \mathcal{G}
 - Model is still valid for different IC/BC/physical parameters
 - Relatively easier to learn nonlinear dynamics

Physics-Aware Recurrent CNNs (PARC)

- Initial & boundary value problems



$$\frac{\partial X}{\partial t} = f(X, \mu) + \epsilon$$

Morphology

Quantities of interest

(e.g., temperature & pressure)

Deep neural network

$$\frac{\partial X}{\partial t} = f(X, \mu \mid \theta) + \varepsilon$$

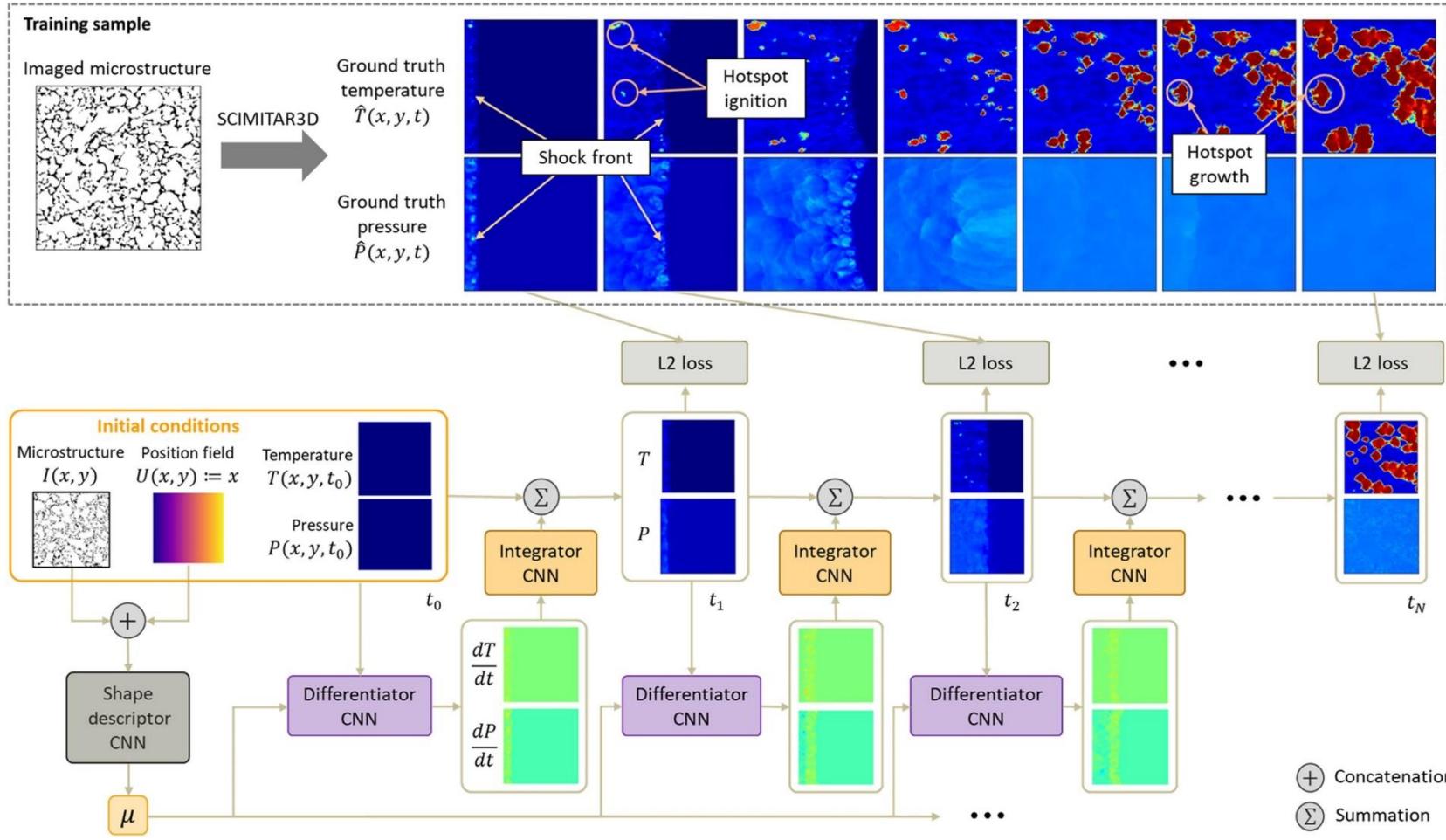
model parameters

stochastic noise + prediction error

$$\frac{\partial X}{\partial t} = f(X, \mu \mid \theta) + \varepsilon$$

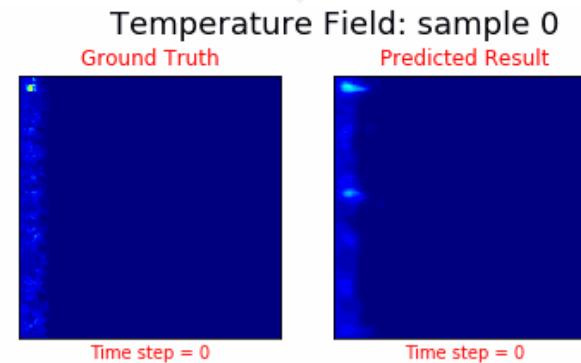
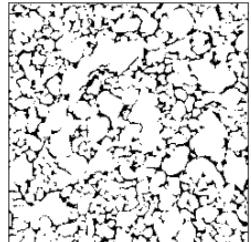
$$X(t + \Delta t) = X(t) + \int_0^{\Delta t} f(X, \mu \mid \theta) dt$$

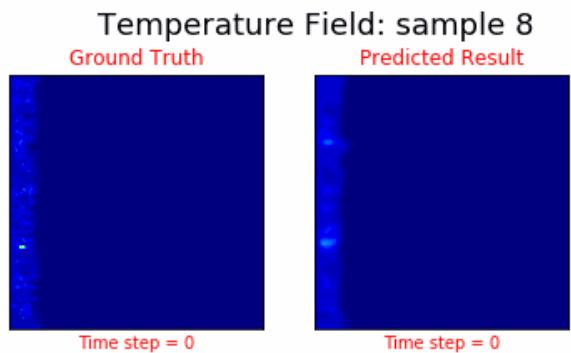
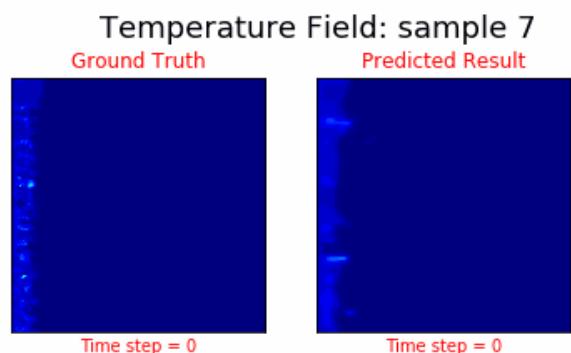
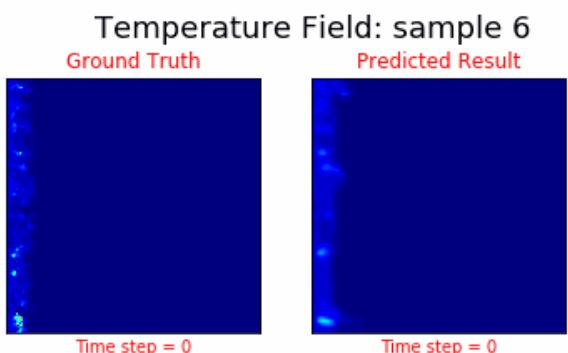
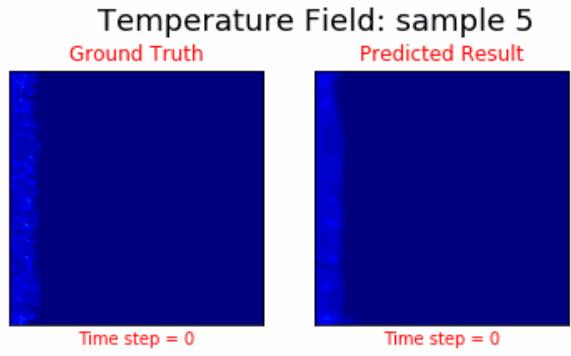
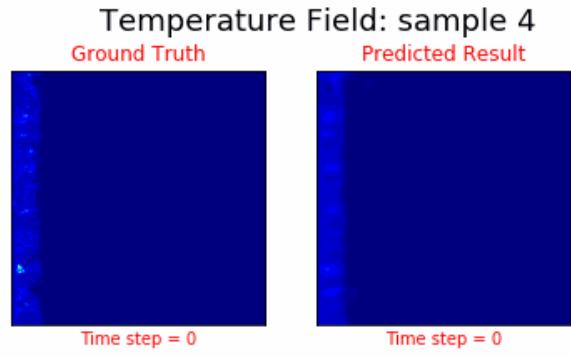
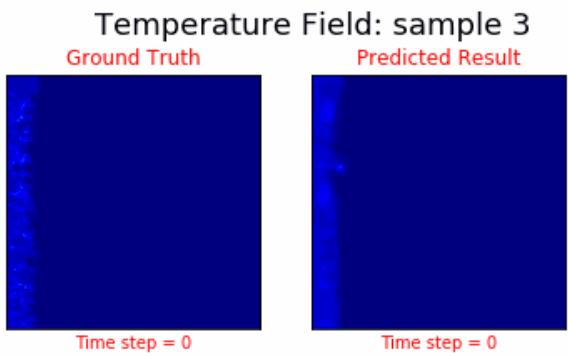
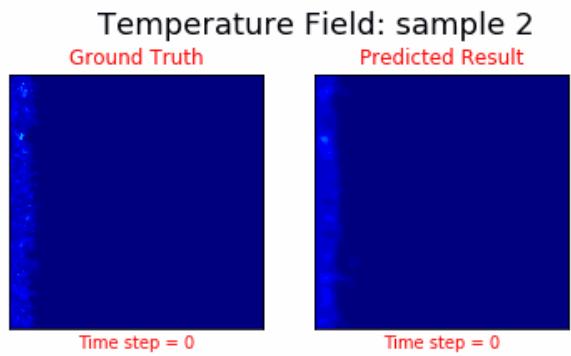
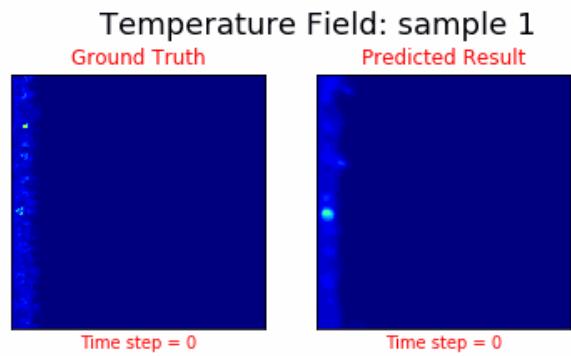
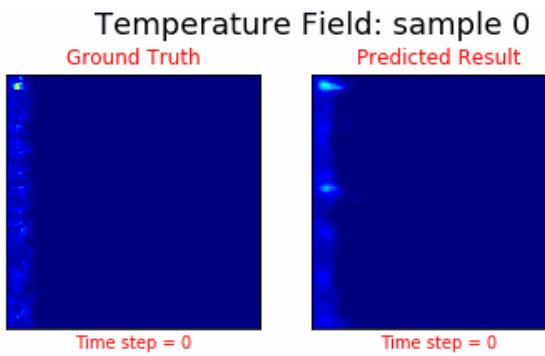
Physics-Aware Recurrent CNNs (PARC)



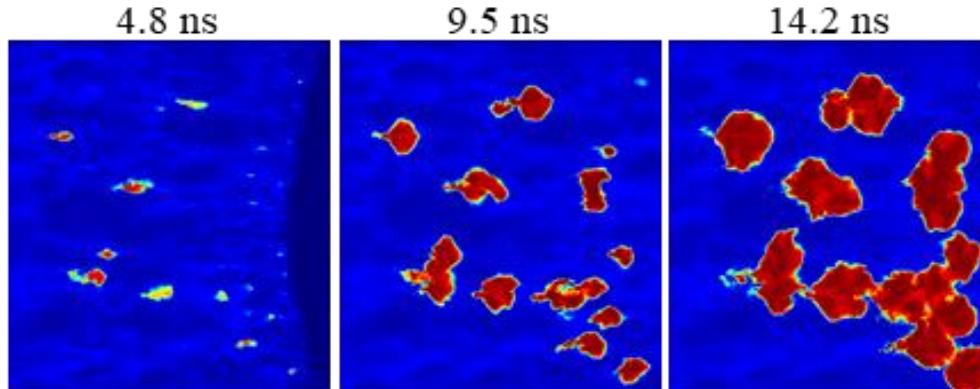
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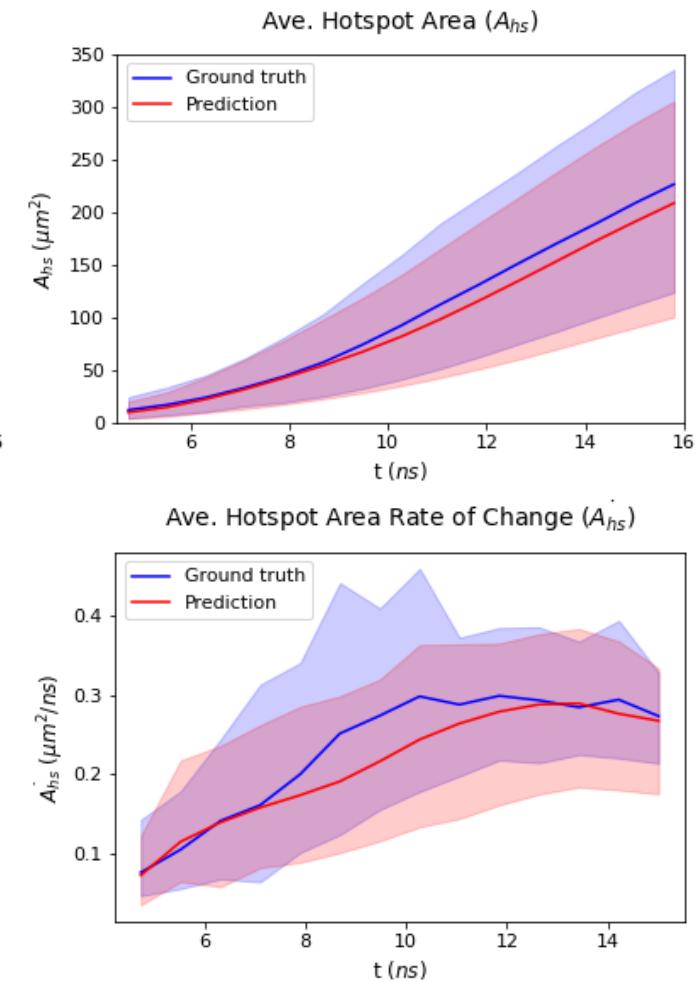
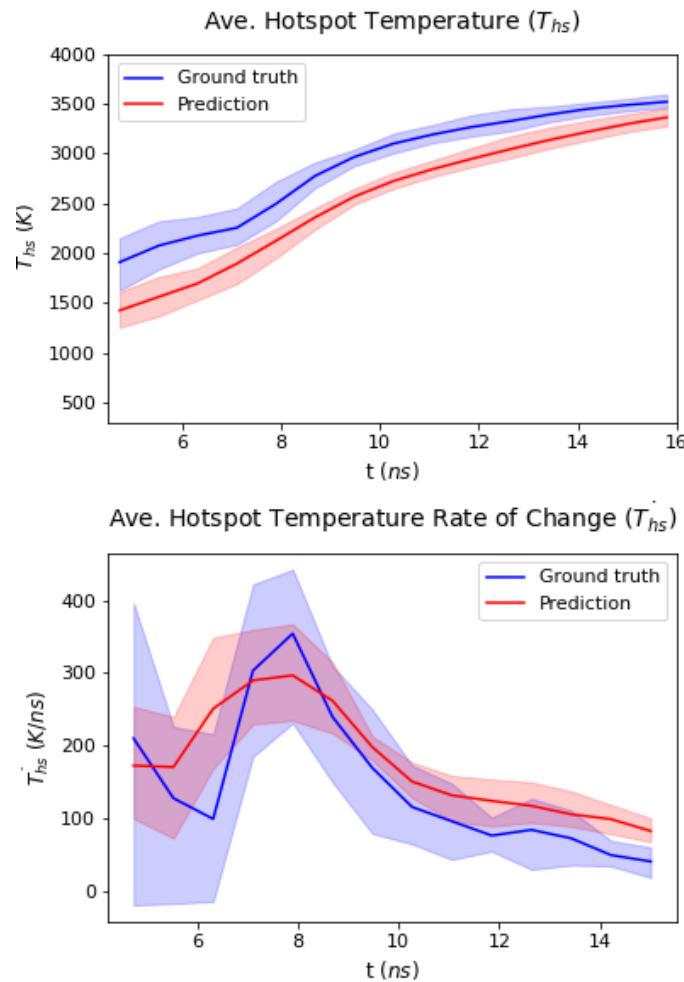
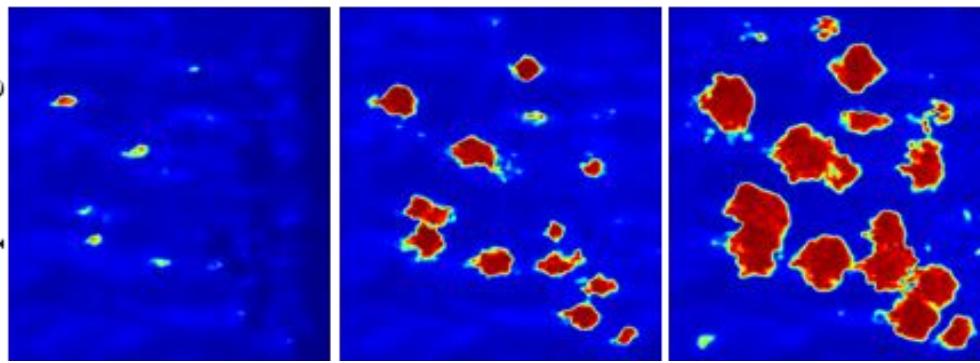




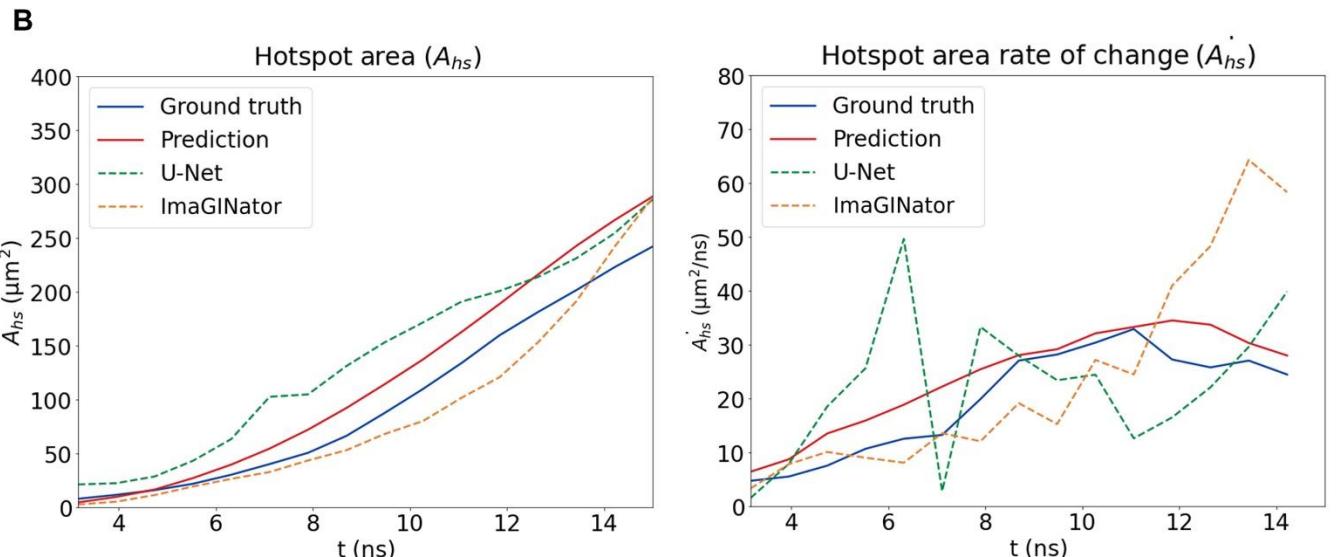
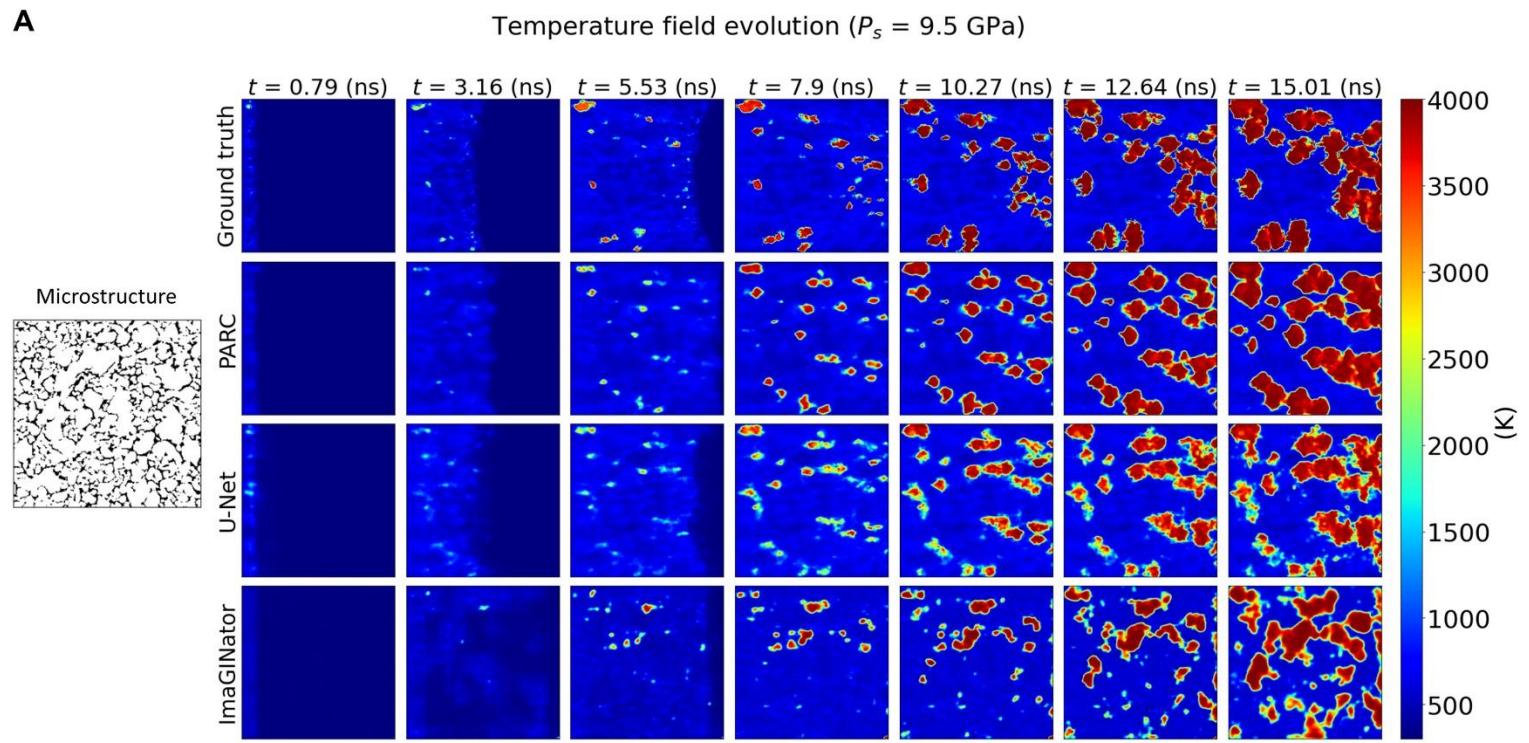
Simulation



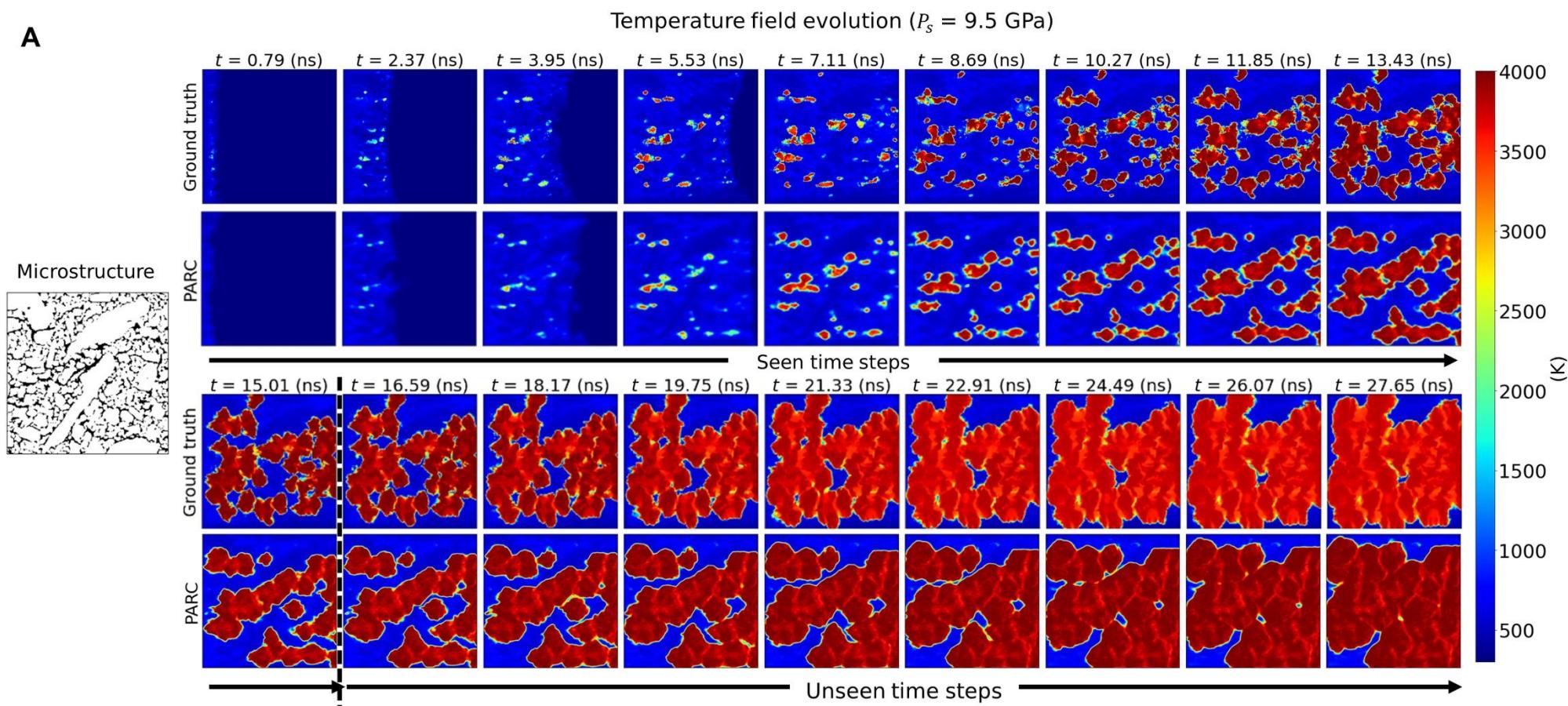
Deep Learning



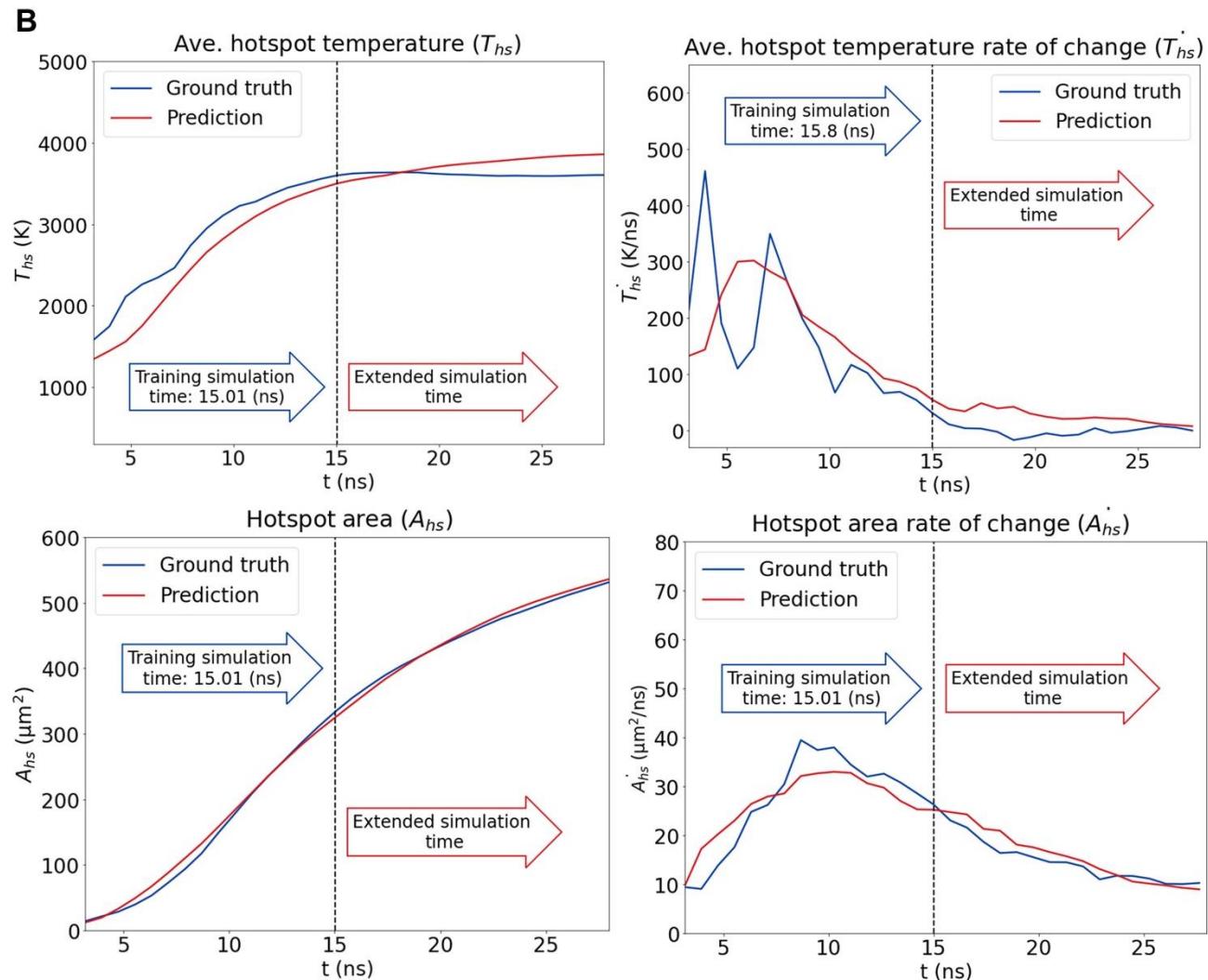
Physics-Aware vs Physics-Naïve



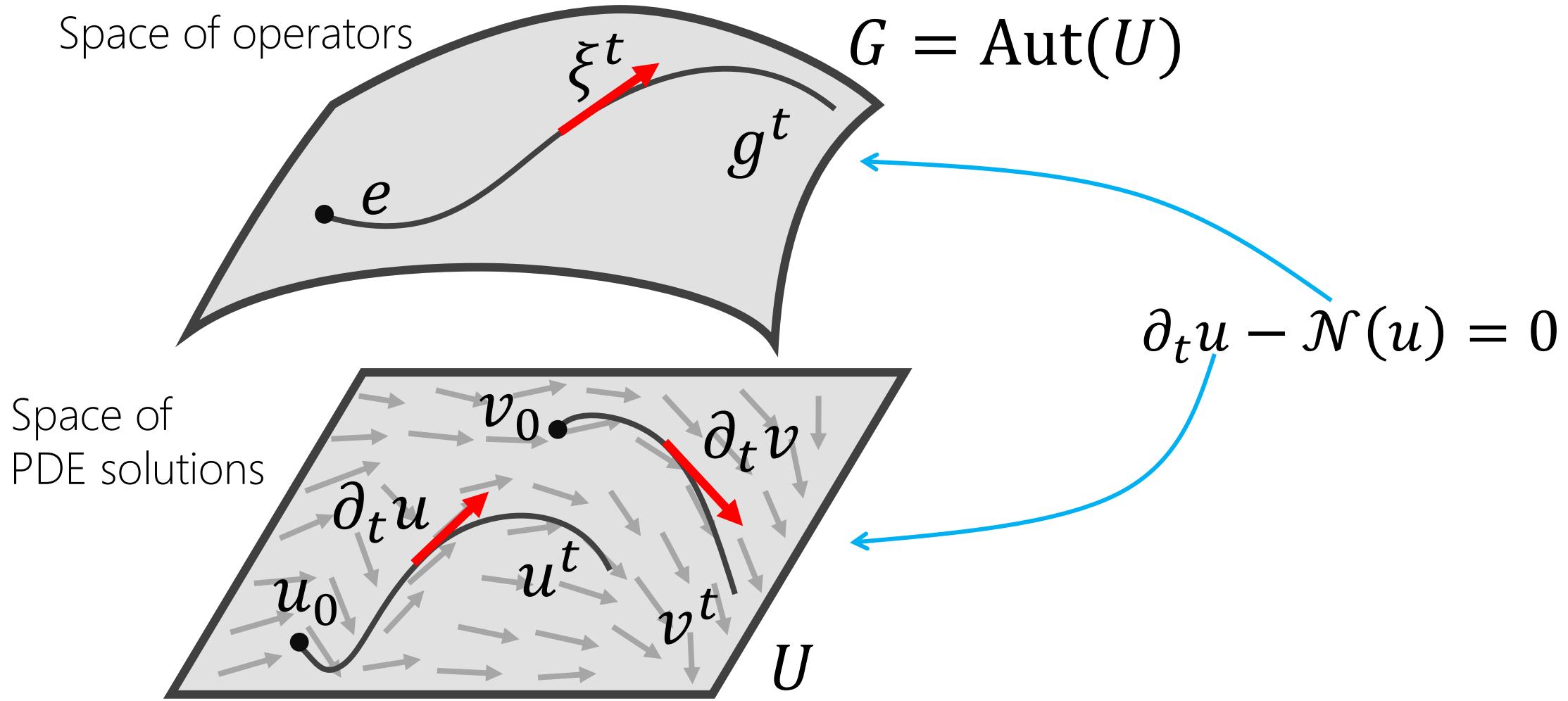
Physics-Awareness



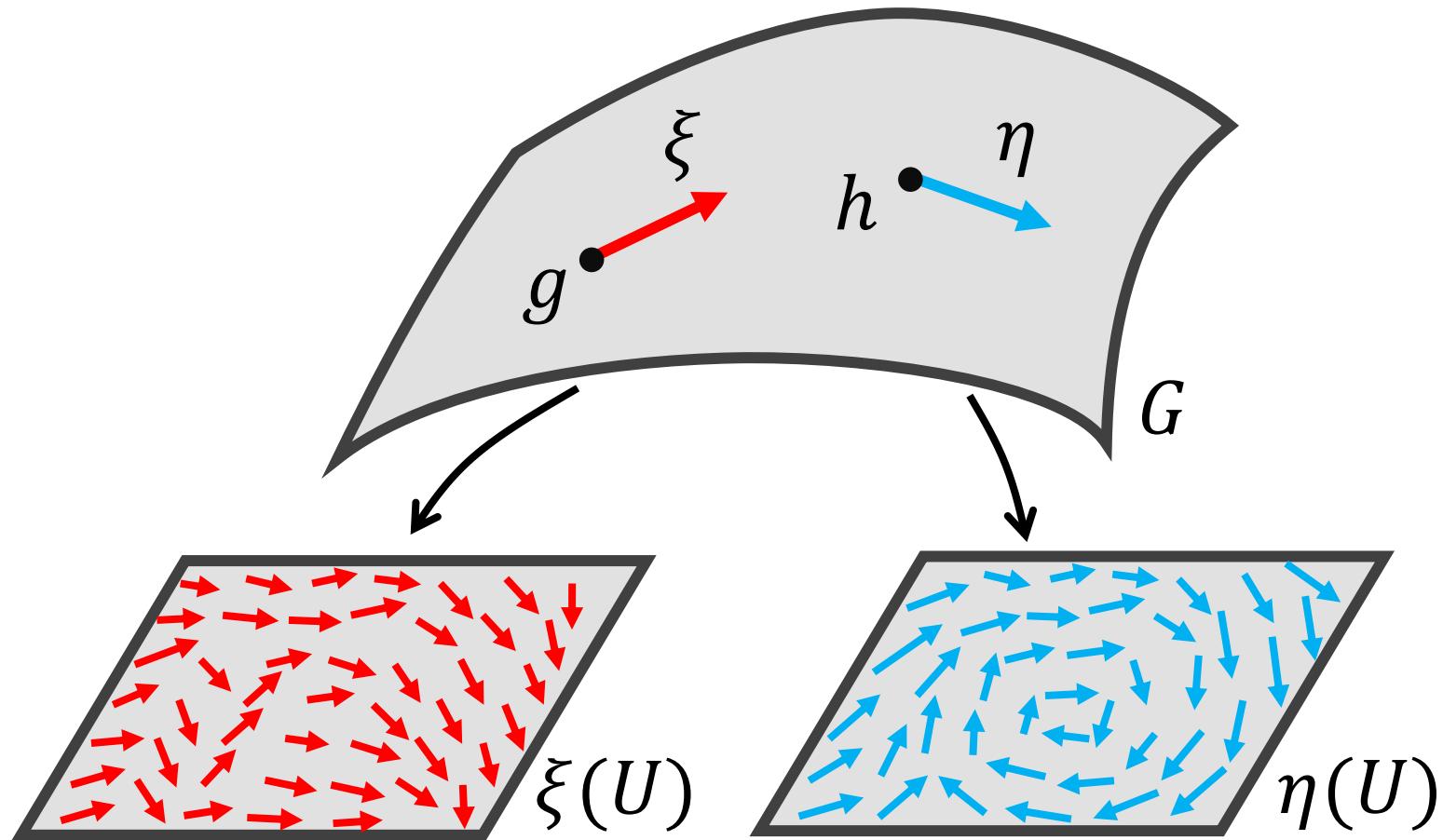
Physics-Awareness



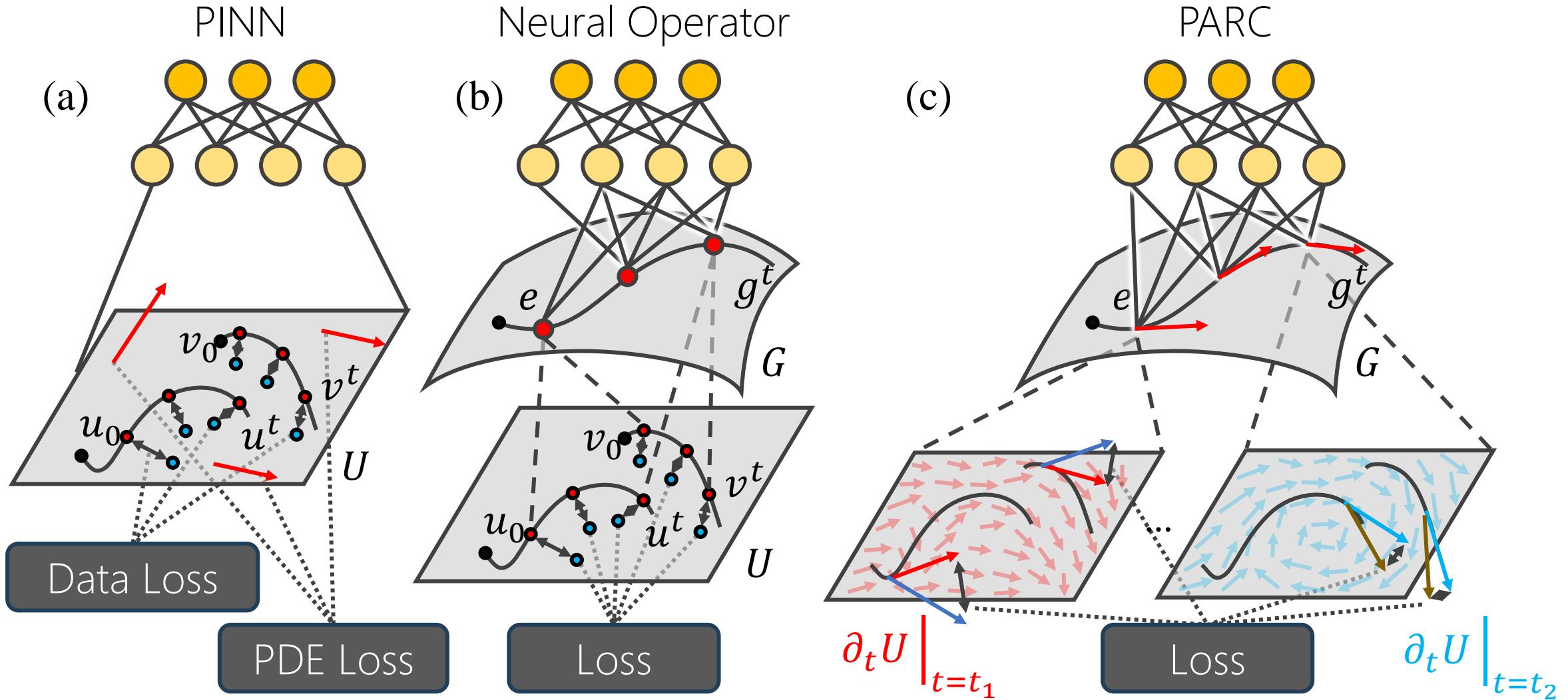
Differential Geometry Perspective



Differential Geometry Perspective

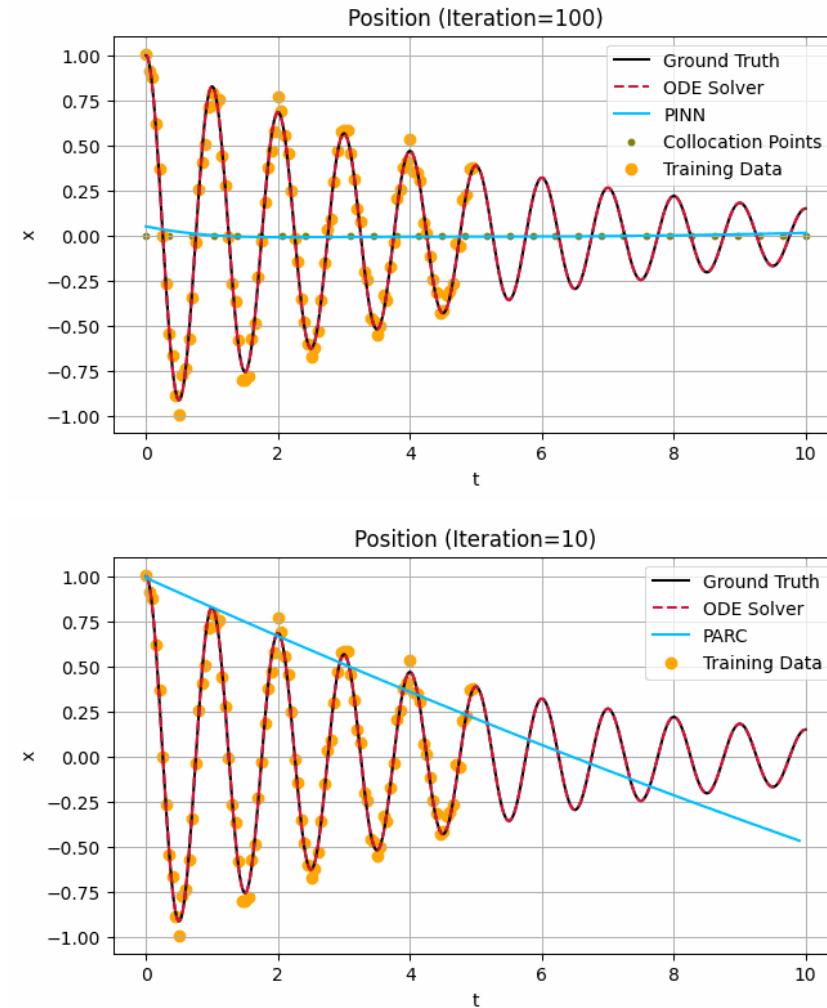


Different Ways to Inform Physics

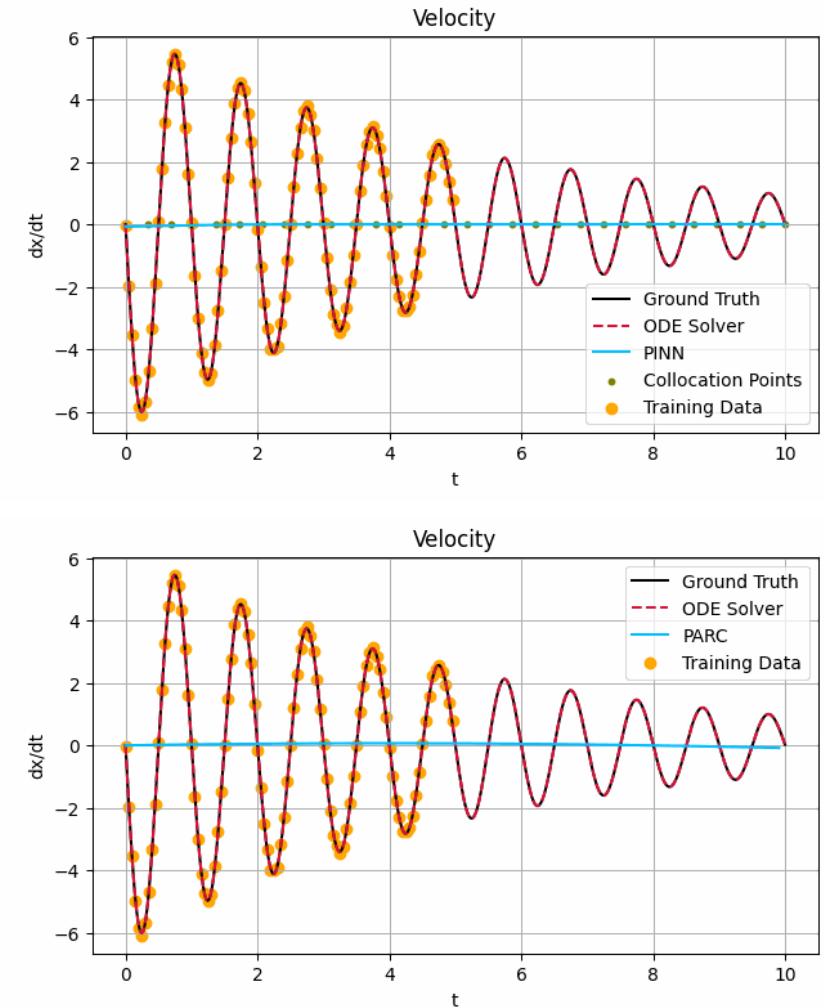


Learning on the Hilbert Space Vs. Learning on the Operator Manifold

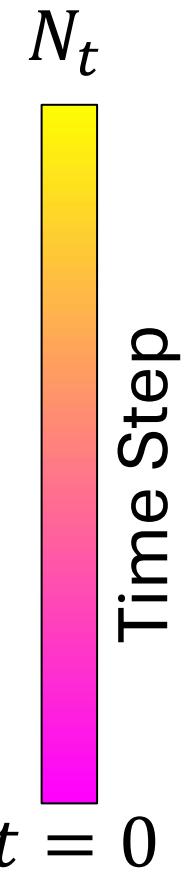
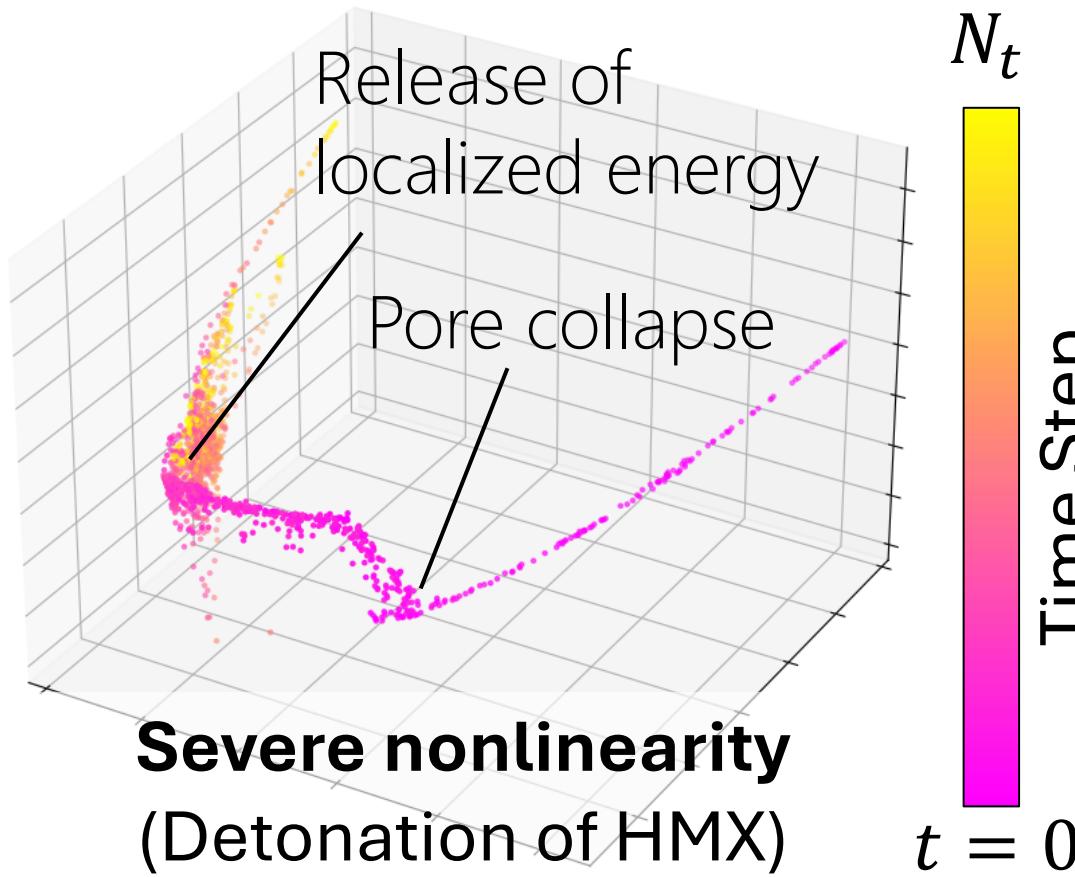
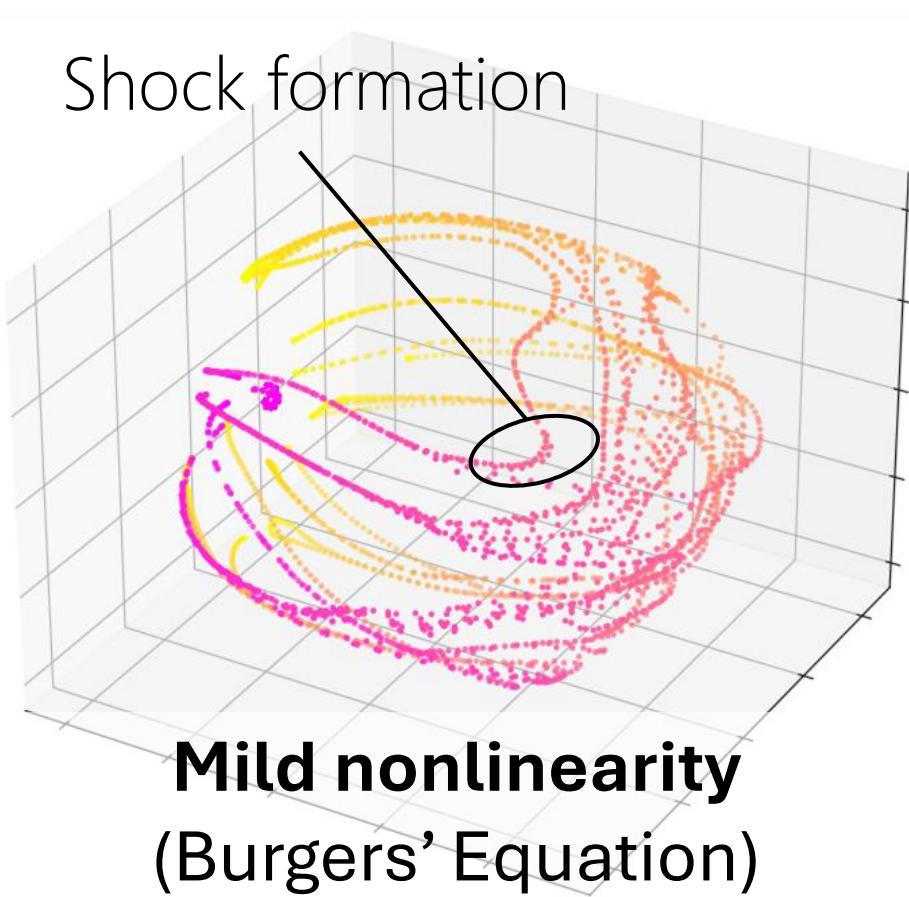
Physics-Informed Neural Network
(3 hidden layers – 256, 256, 256)



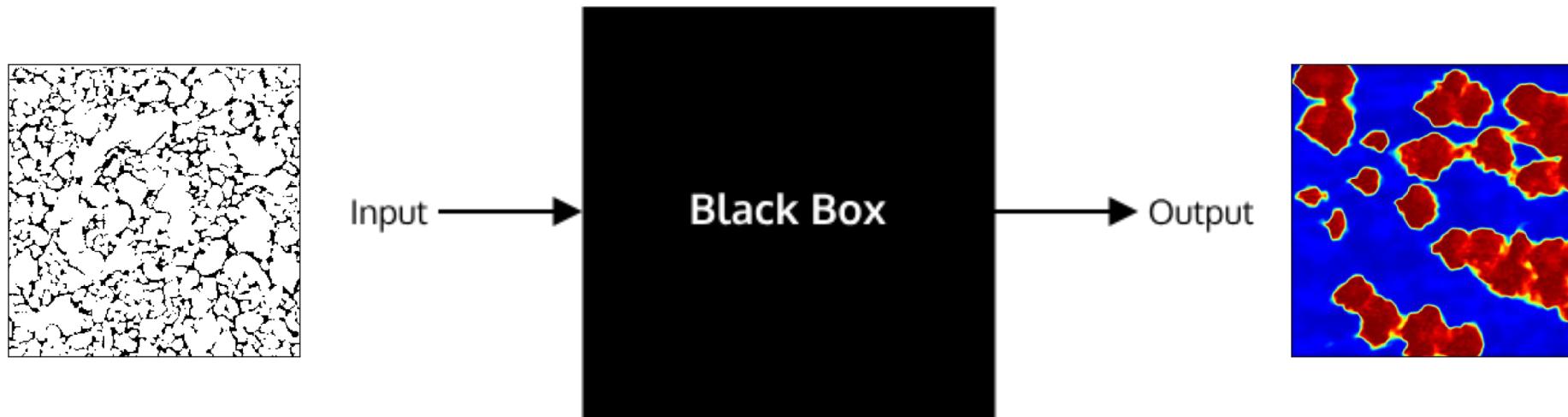
Physics-Aware Recurrent Conv.
(2 hidden layers – 16, 32)



Geometry of Extreme Dynamics



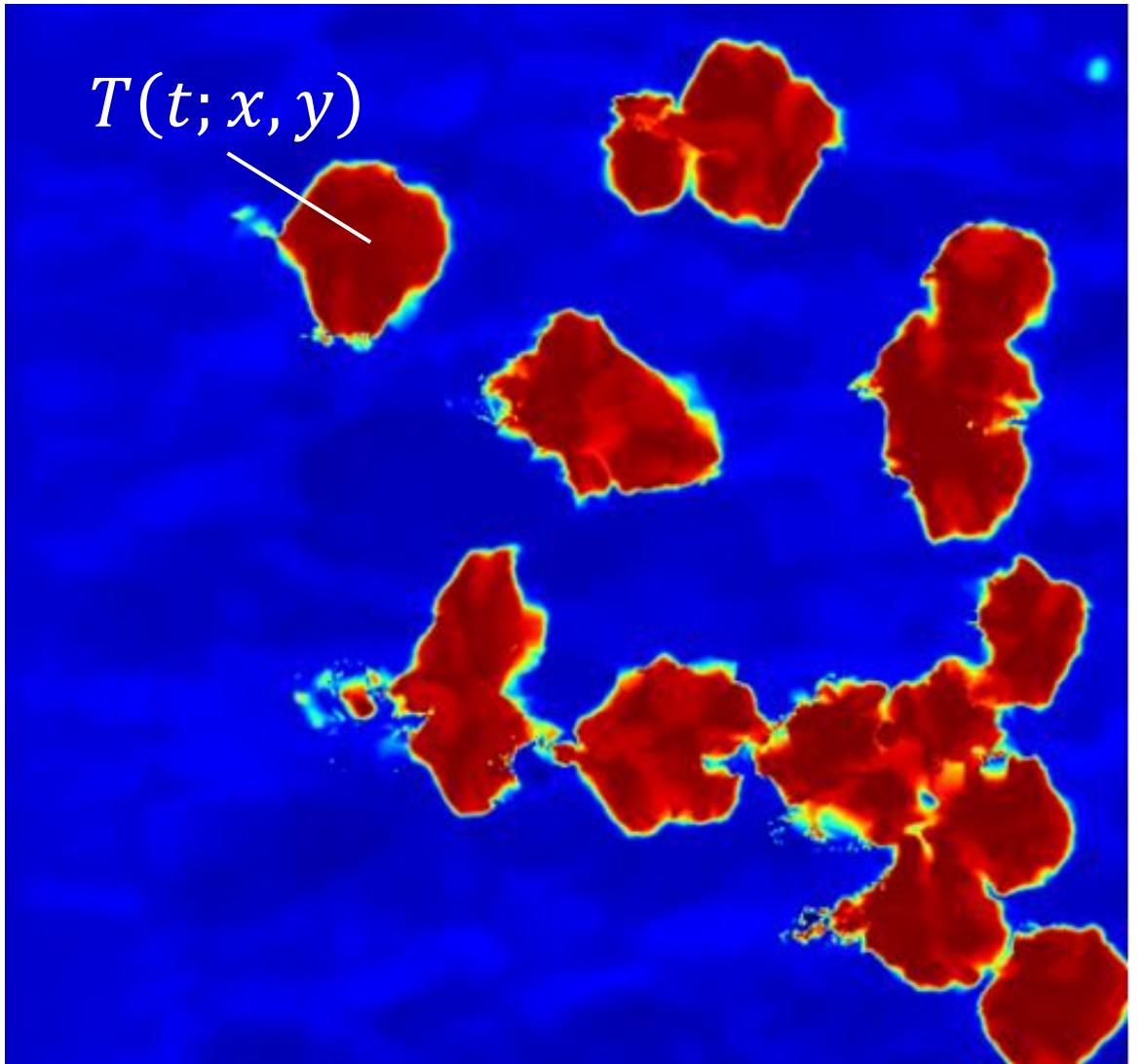
What does PARC see in microstructure images?

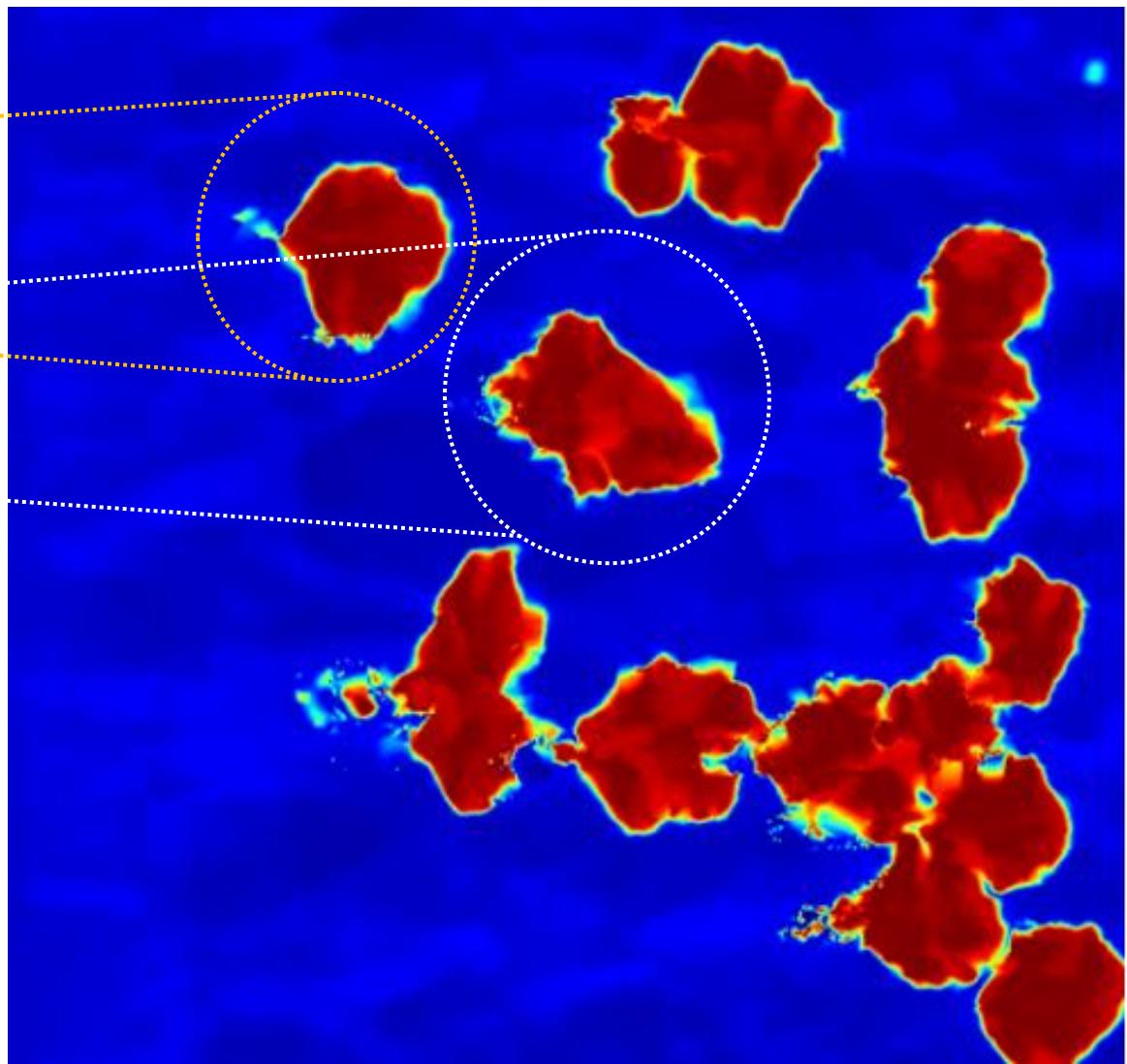
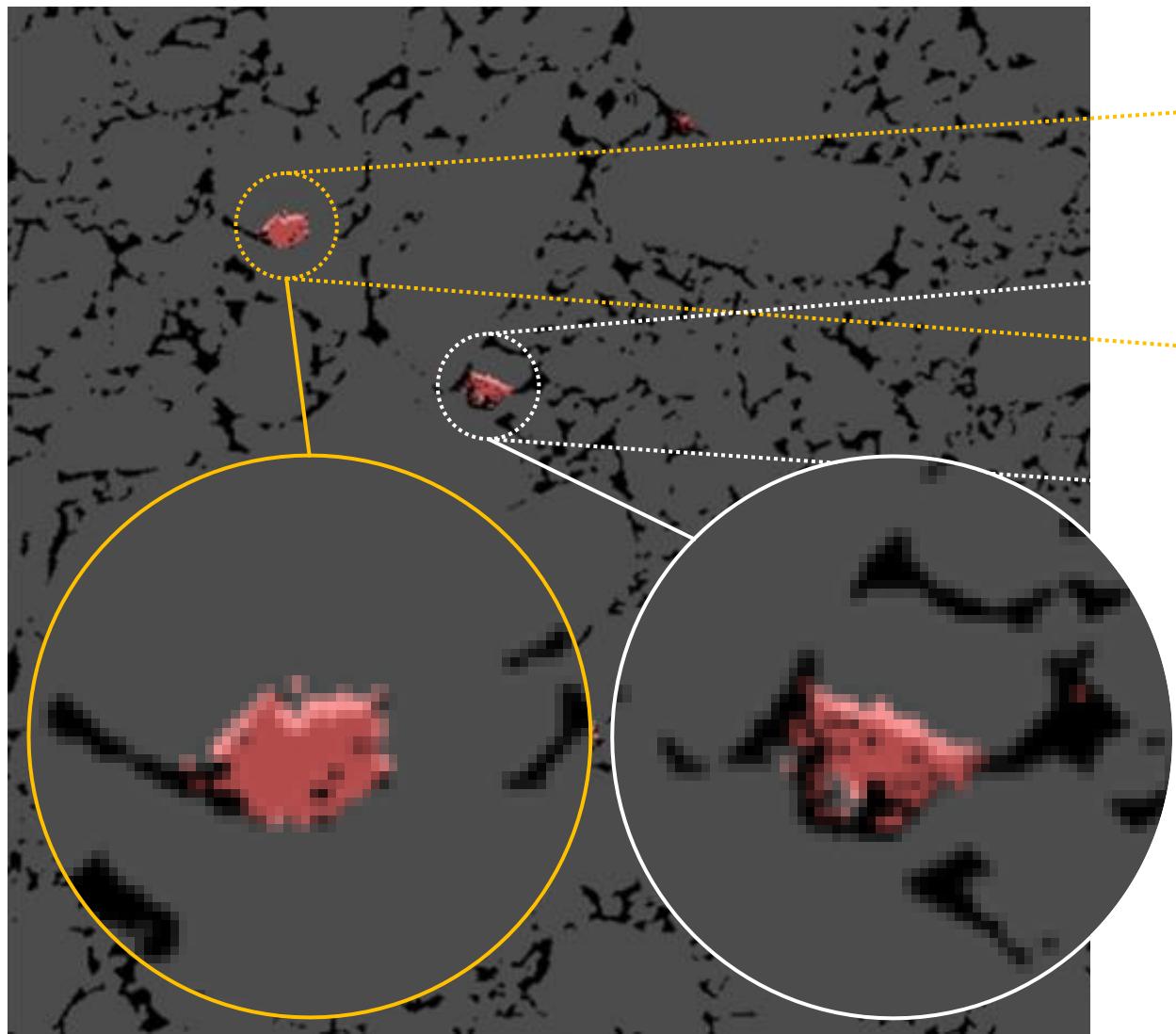


Saliency Map

Which element in the microstructure had the biggest influence on the hotspot formation?

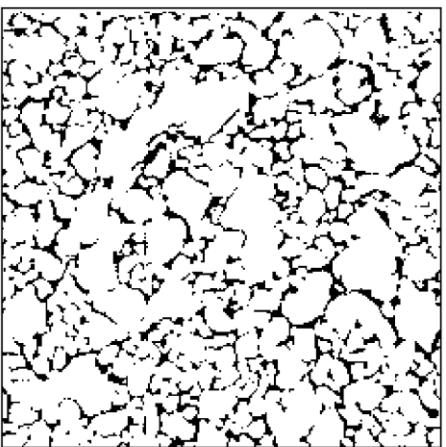
$$\frac{\partial T}{\partial \mu(x, y)}$$



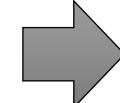
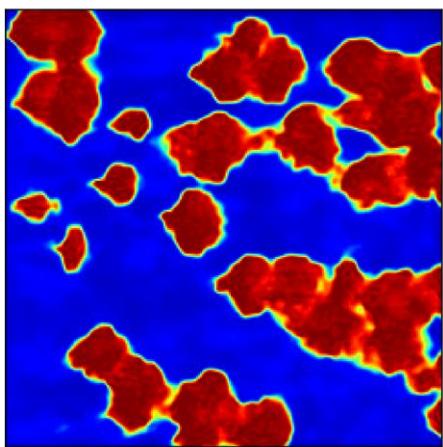


Saliency Map

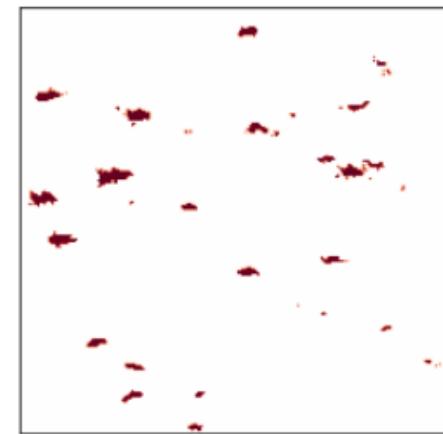
Microstructure $\mu(x, y)$



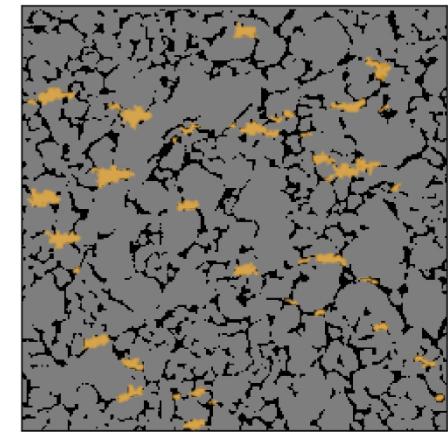
Temperature field $\mathbf{T}(x, y)$



Saliency map $G(x, y)$



Saliency map superimposed
on microstructure



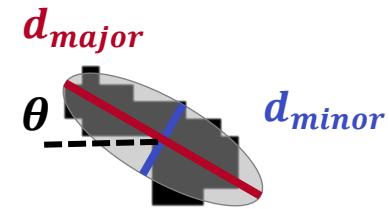


Critical Voids



Non-critical Voids



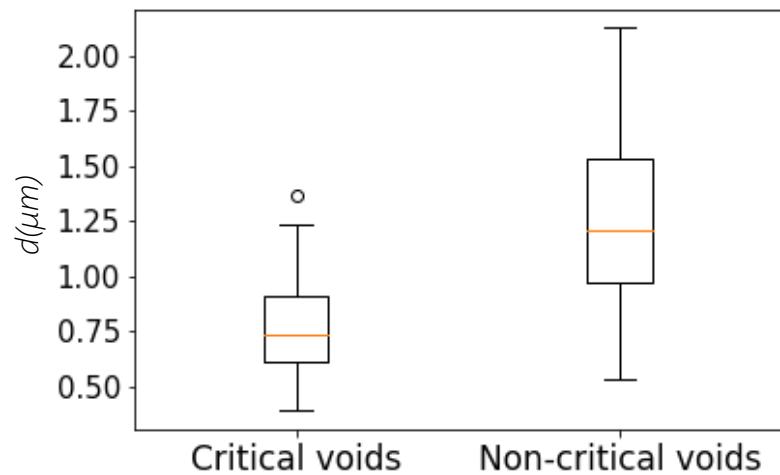


$$d_{void} = \frac{d_{major} + d_{minor}}{2}$$

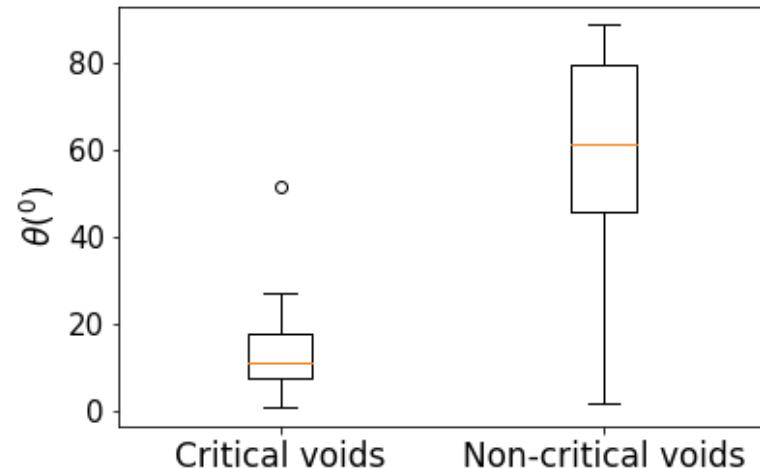
$$AR = \frac{d_{major}}{d_{minor}}$$



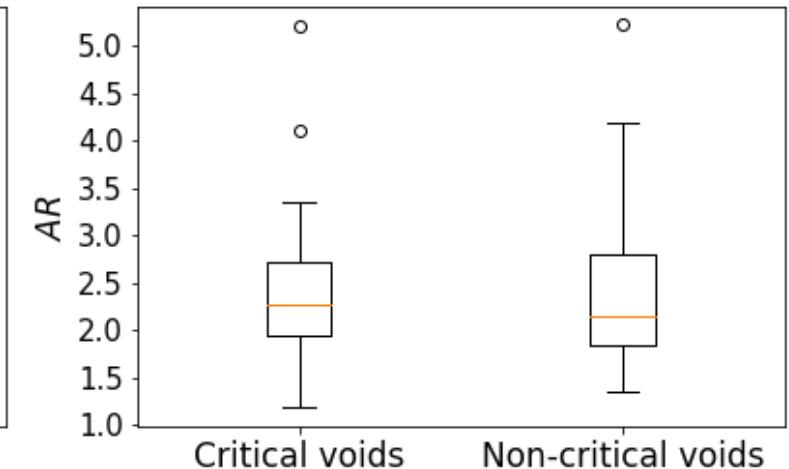
Average void diameter



Void orientation

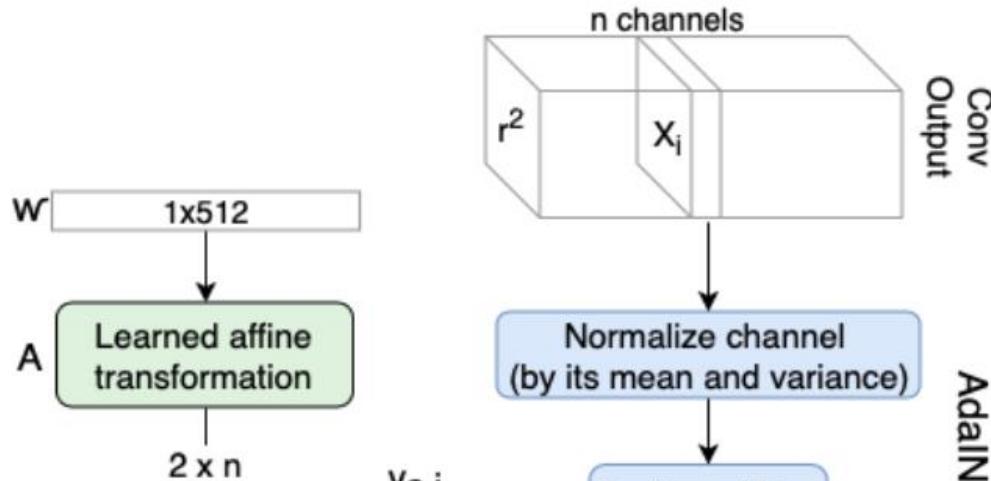


Void aspect ratio



PARCel – Extending PARC to other operating conditions

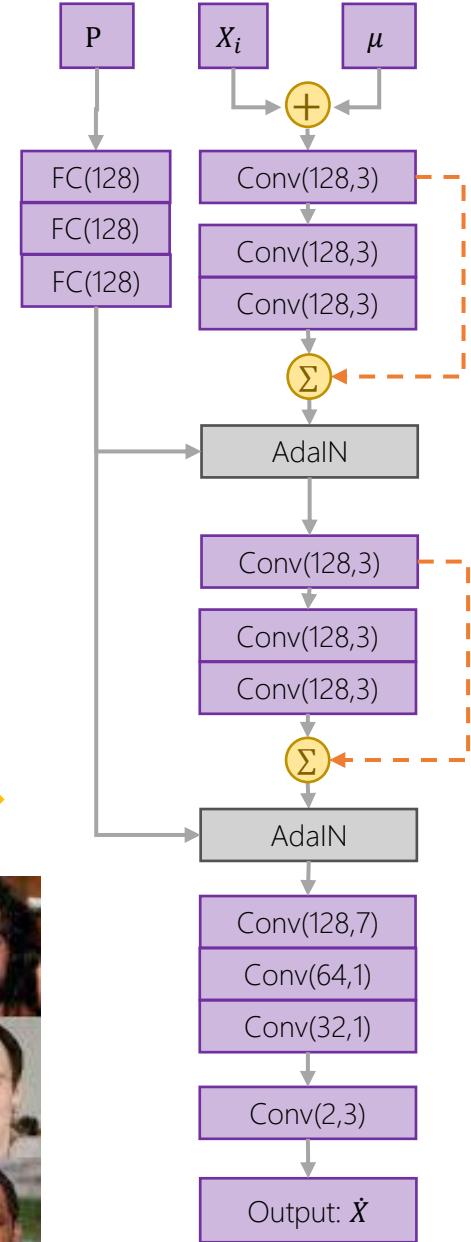
- “Style-vector” in StyleGAN



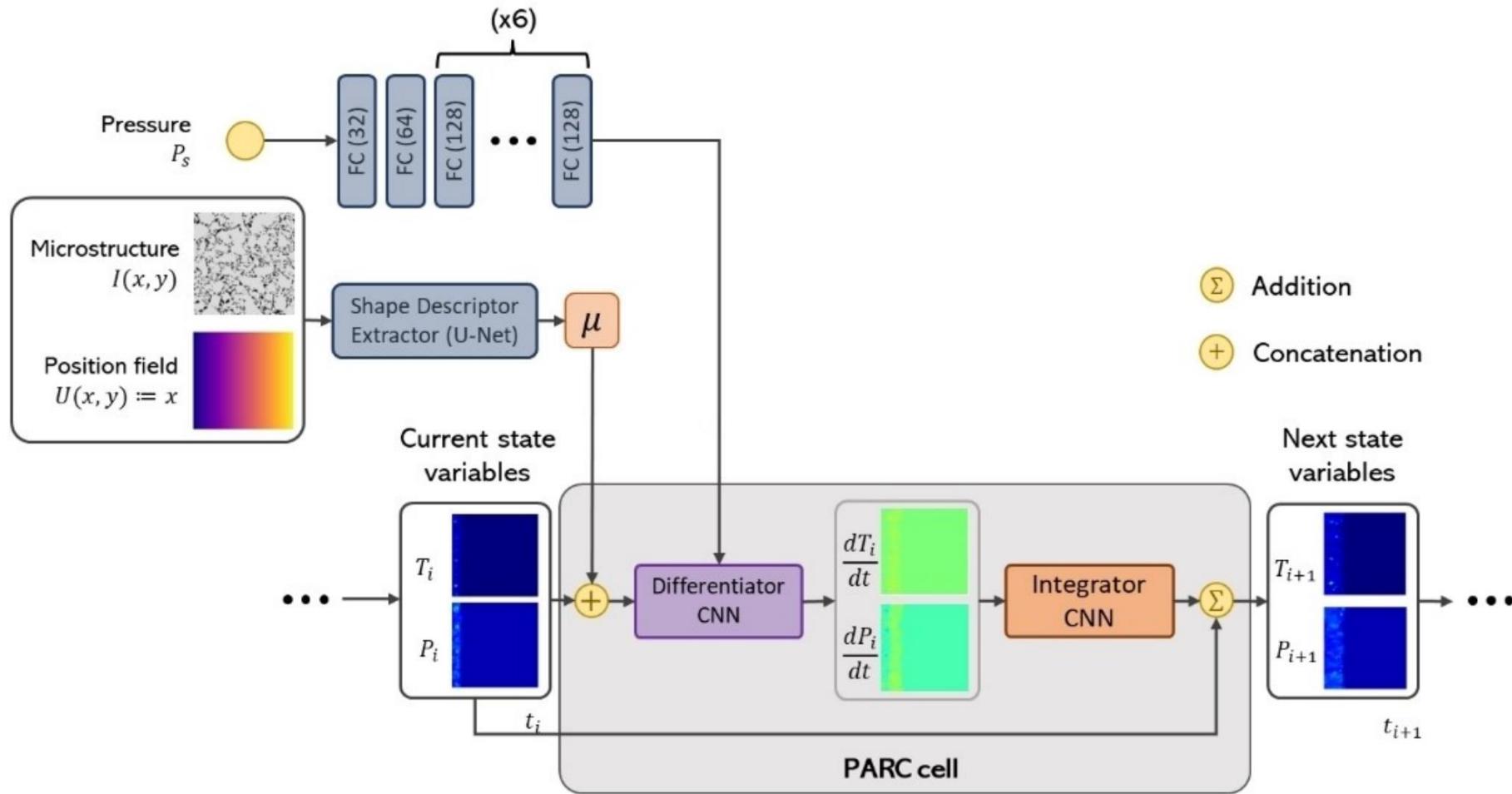
$$\text{AdaIN}(\mathbf{x}_i, \mathbf{y}) = \mathbf{y}_{s,i} \frac{\mathbf{x}_i - \mu(\mathbf{x}_i)}{\sigma(\mathbf{x}_i)} + \mathbf{y}_{b,i},$$

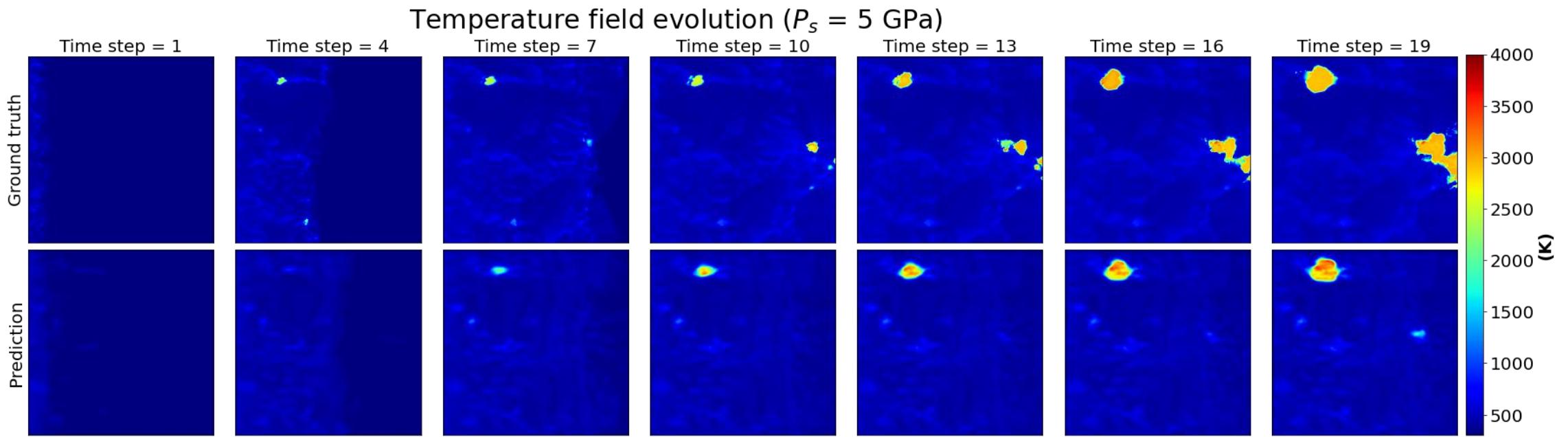
Karras, Laine, & Aila. "A Style-Based Generator Architecture for Generative Adversarial Networks," CVPR 2019

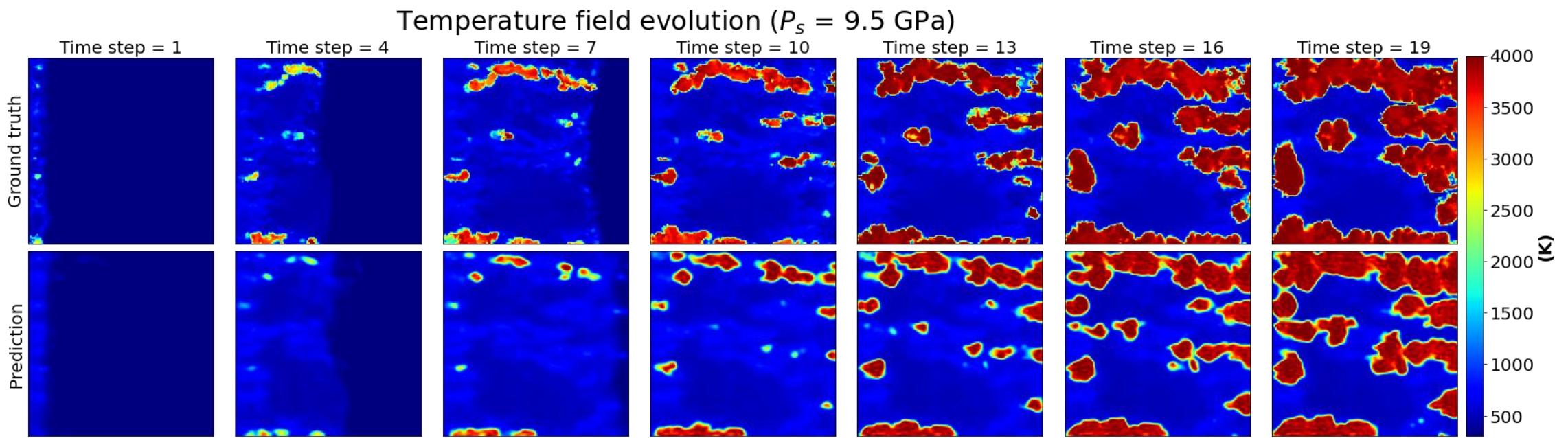
Introducing “Bias” to represent the effects of different shock loadings.

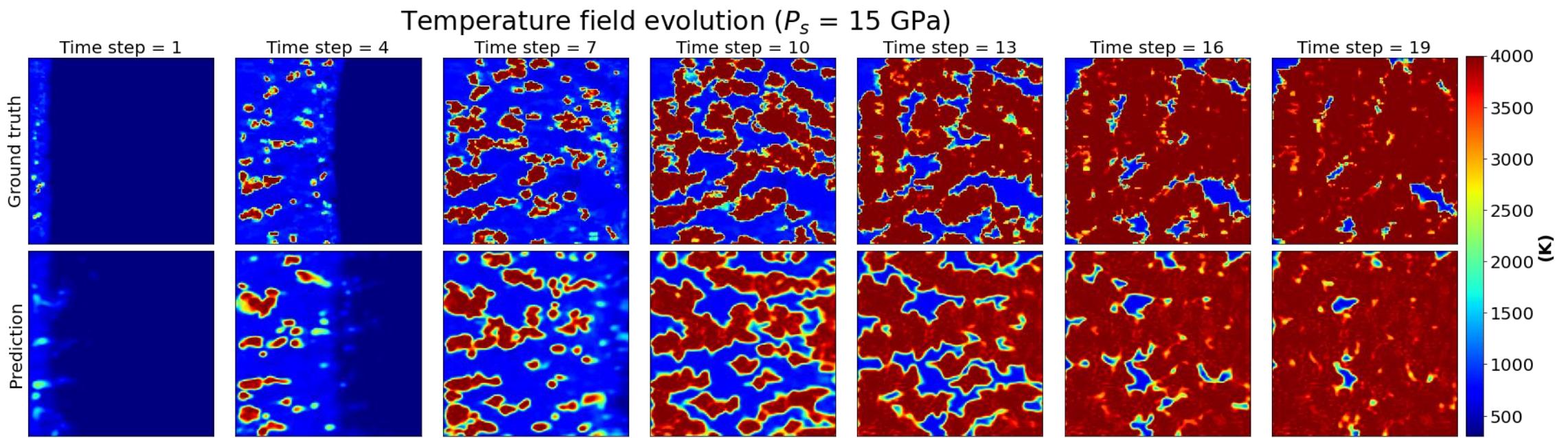


PARCel – Extending PARC to other operating conditions

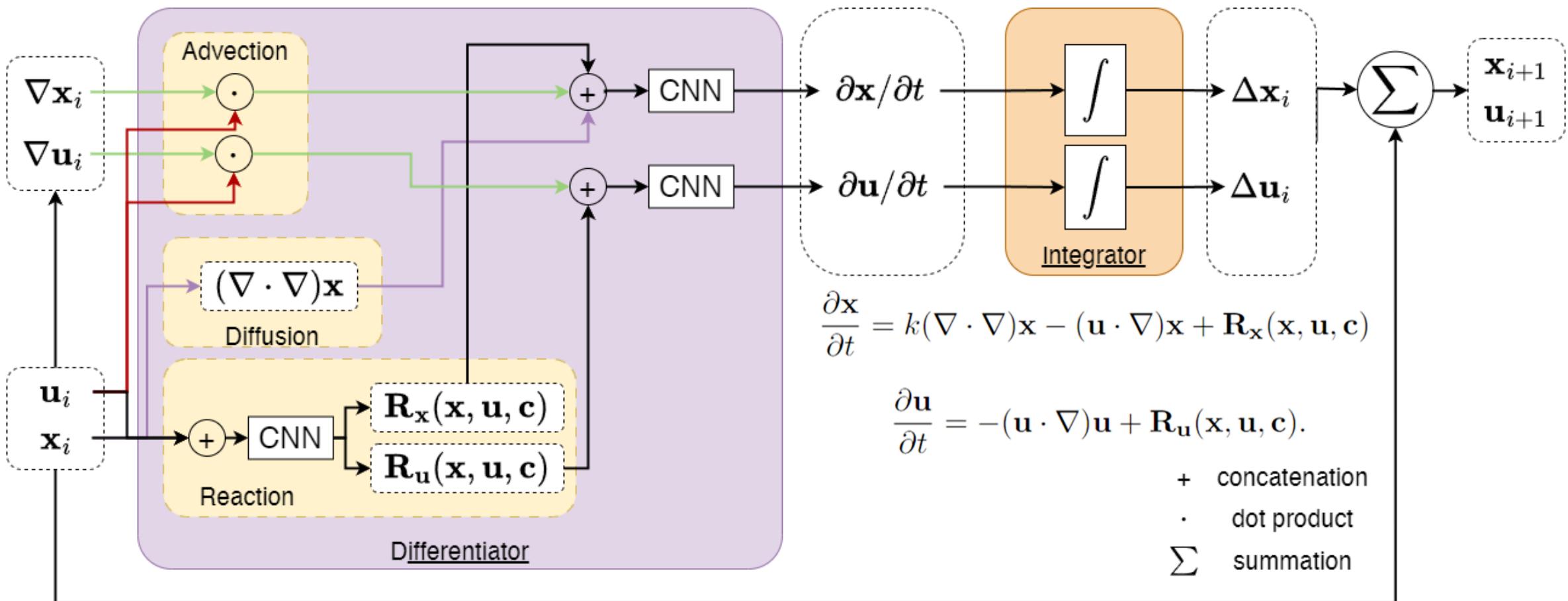




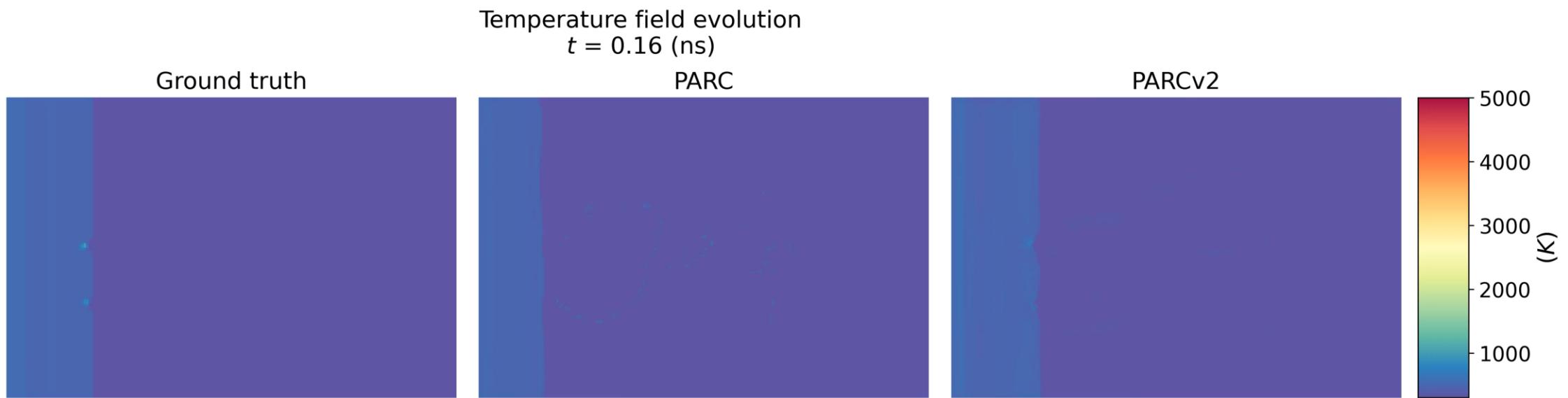




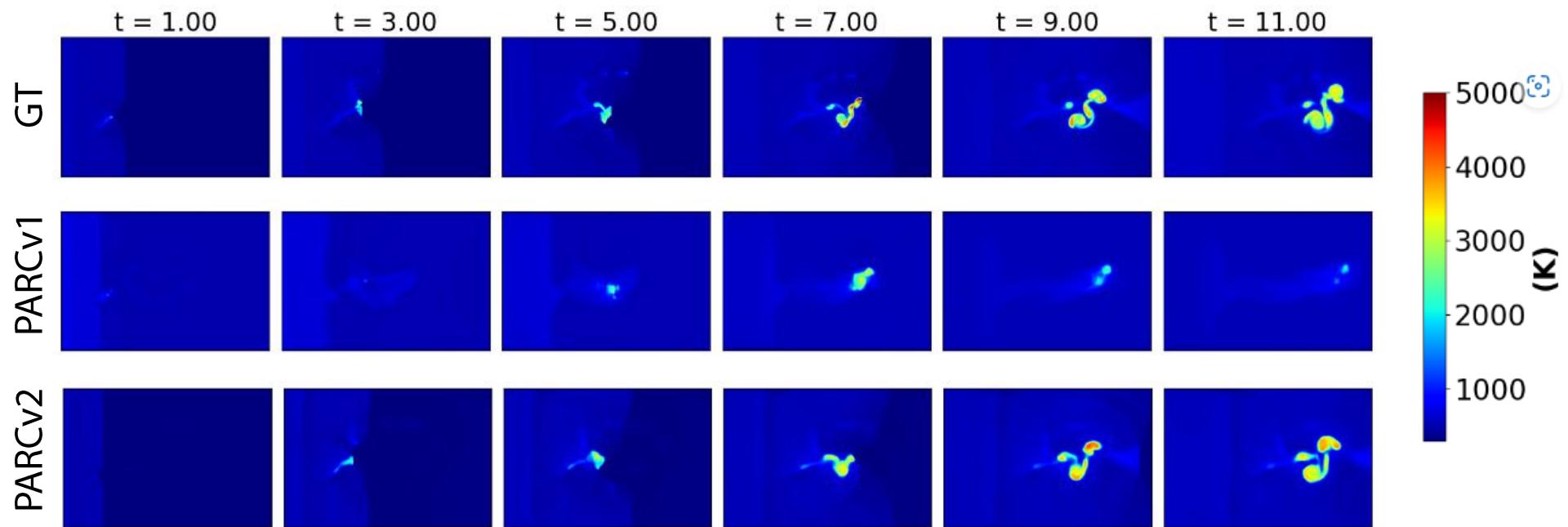
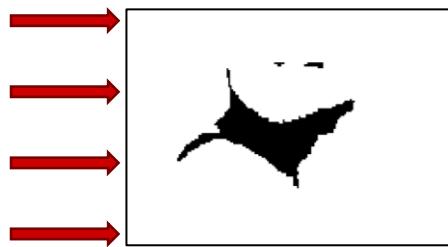
Physics-Aware Recurrent CNNs (PARCv2)



Pore Collapse Simulation



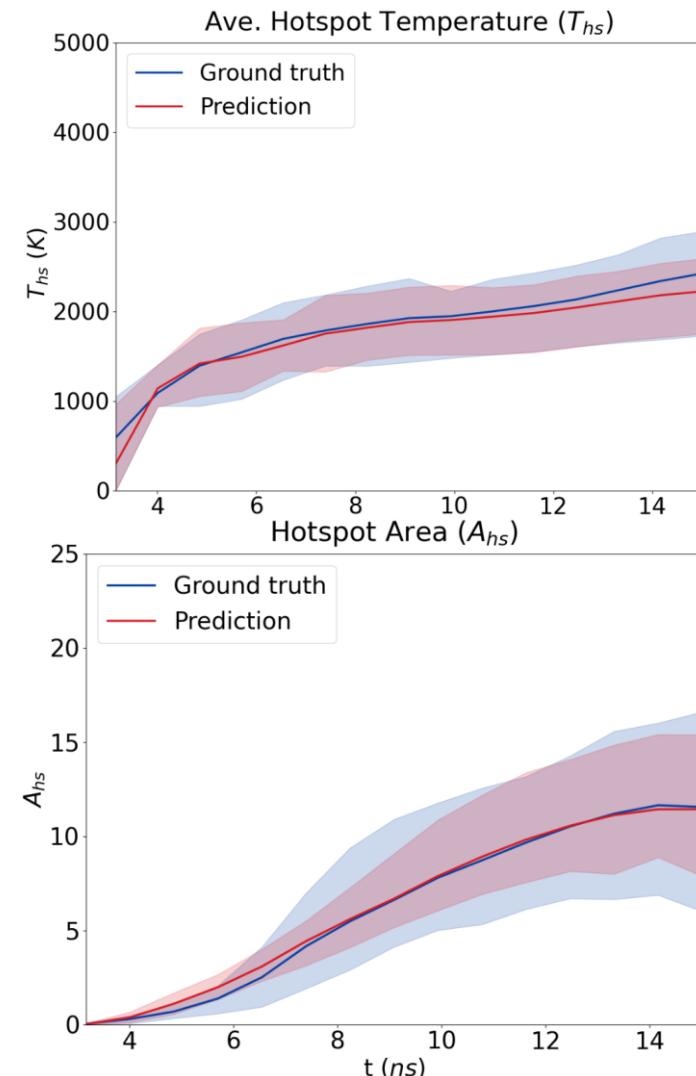
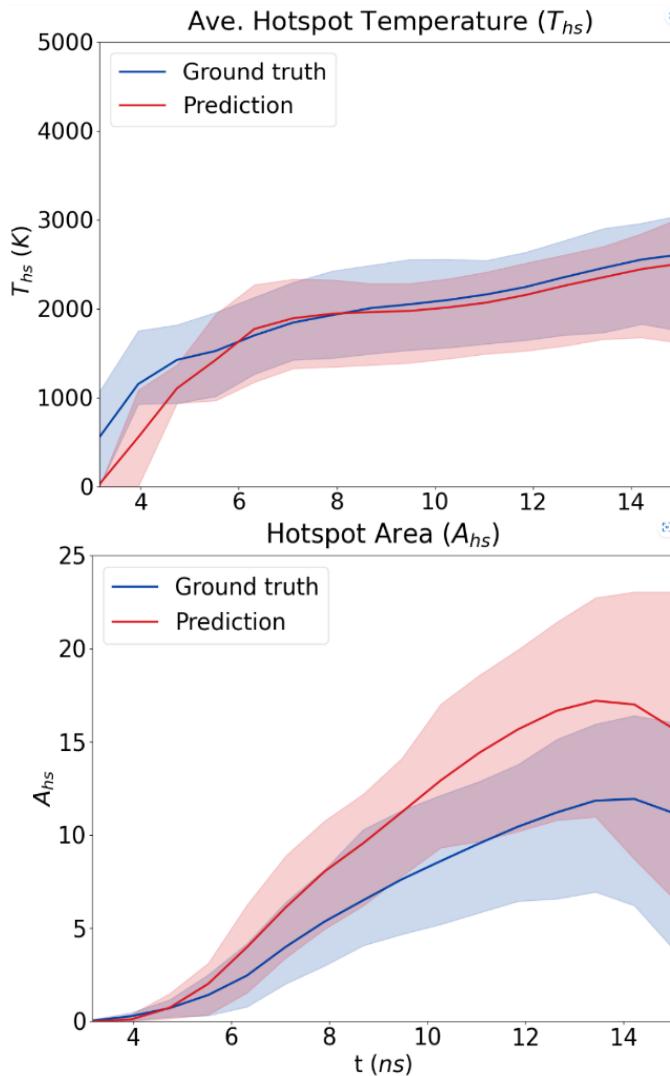
Pore Collapse Simulation



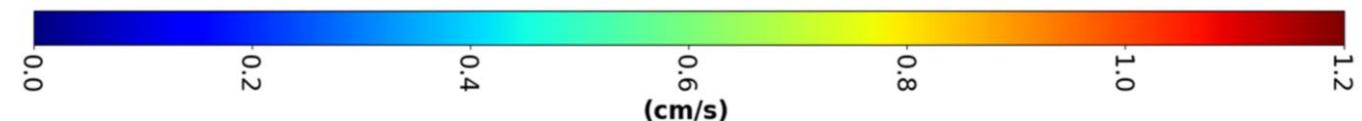
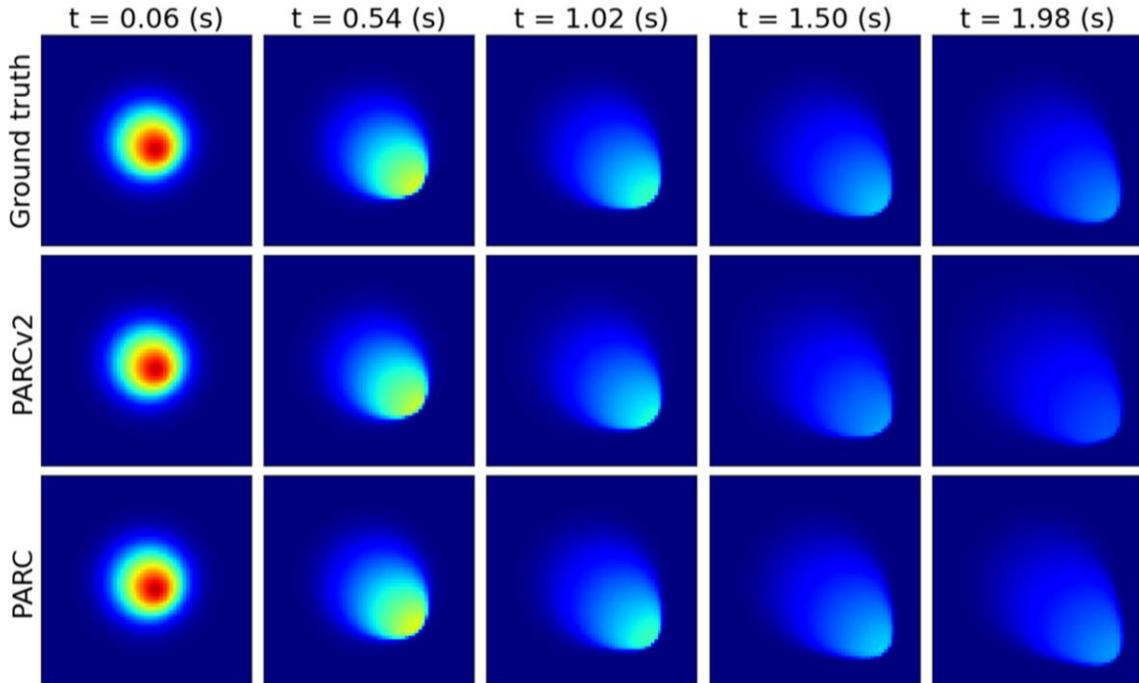
PARCv1

vs.

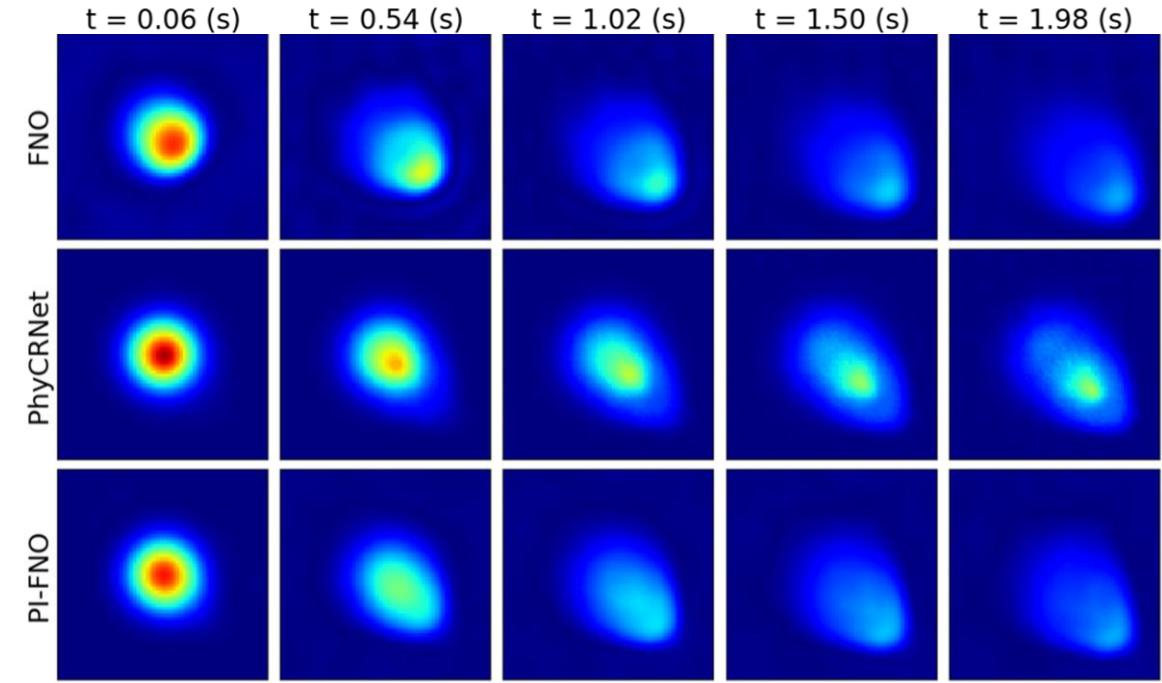
PARCv2



Burgers' Equation

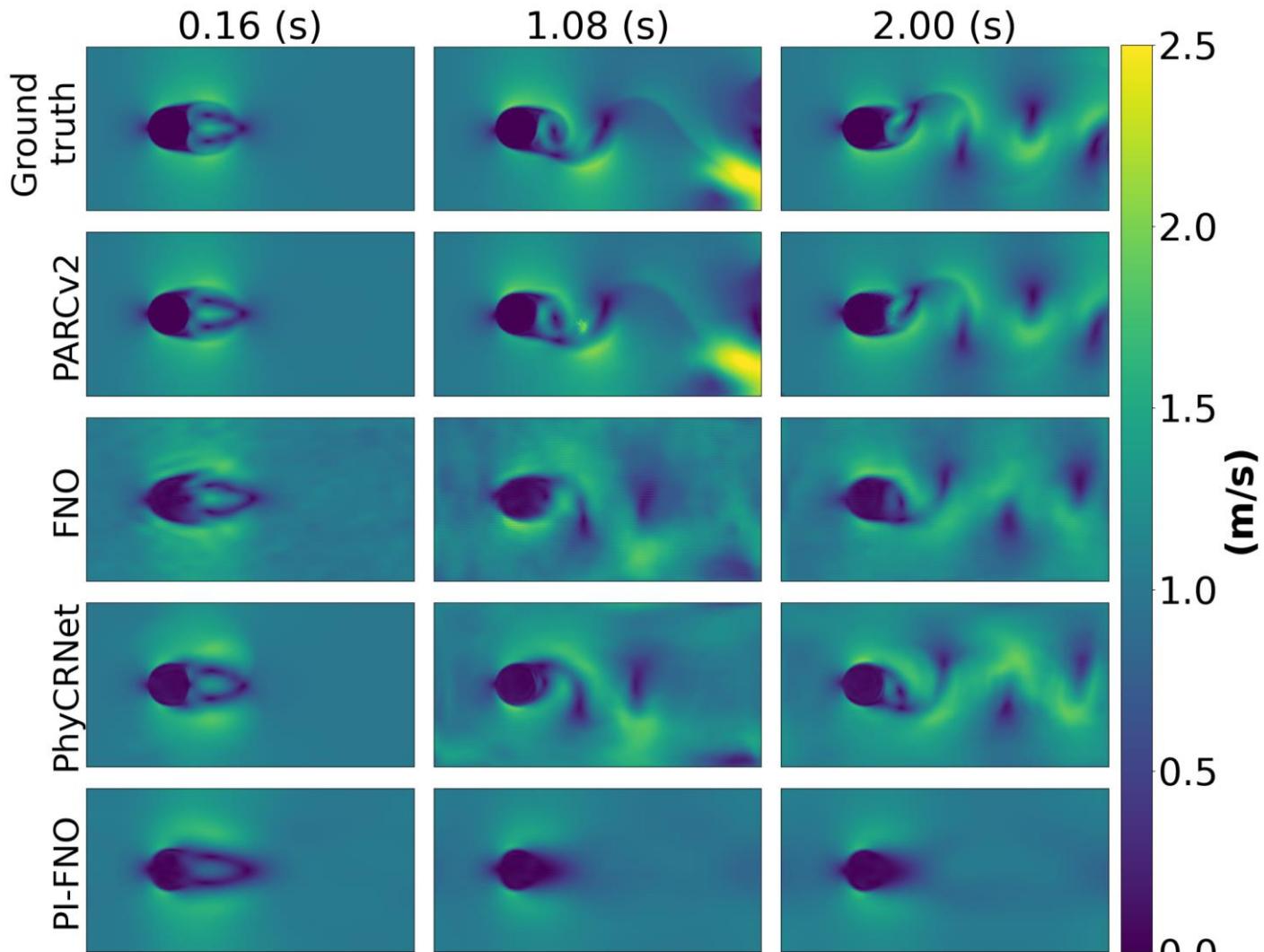


MODEL	$RMSE_u$ (cm/s)	$\ f_u\ $ (cm/s ²)
DNS		0.1241
PARC (NUMERICAL INT.)	0.0074	0.1262
PARC (DATA-DRIVEN INT.)	0.0236	0.1176
FNO	0.0289	0.1537
PHYCRNET	0.0588	0.0560
PIFNO	0.0338	0.1058
PARCv2 (THIS STUDY)	0.0129	0.1292

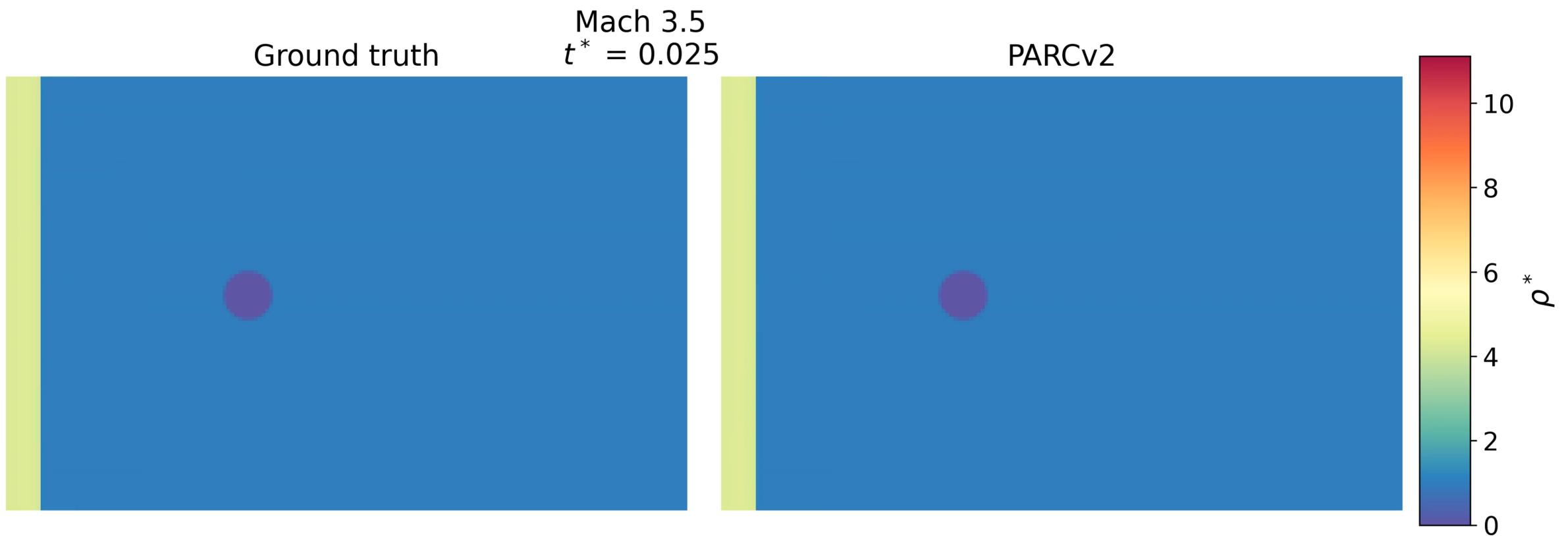


Navier-Stokes Equations

Model	RMSE (cm/s ²)	$\ f_u\ $ (m/s ²)	ε_{div} (1/s)
DNS (Ground truth)	-	2.2339	0.0198
FNO	0.2411	3.2804	1.0471
PhyCRNet	0.2324	2.6994	0.0597
PI-FNO	0.2230	1.4488	0.0307
PARCv2	0.1556	3.0402	0.3655

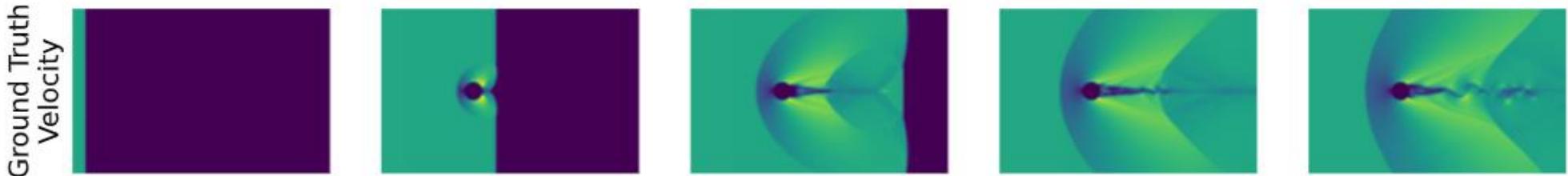


Compressible, Supersonic Flow

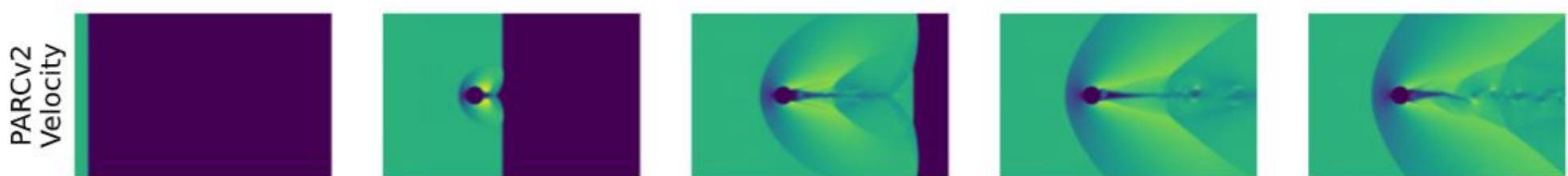
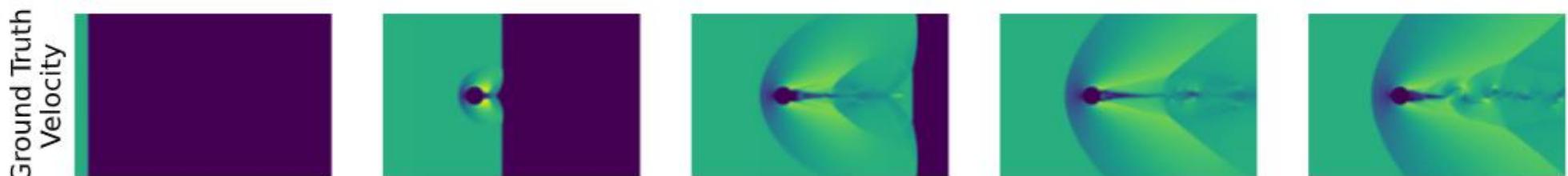
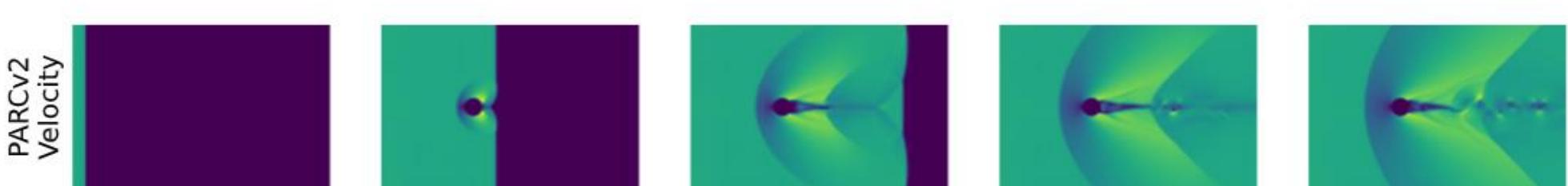


Compressible, Supersonic Flow

Mach 3



Mach 4



Summary

- PARC features its “differentiator-integrator architecture” mimicking how PDEs are solved in physics-based solvers
- Comparable accuracy & fidelity to DNS, but **multiple orders of magnitude faster** (hours on an HPC versus less than a second on a laptop)
- Tends to capture **sharp gradients & fast transients** better, compared to other physics-informed models.