

Minimizers, intro to convexity

Tuesday, January 19, 2021 5:26 PM

First, go over discussion questions from last time

Solutions

Generic problem: $\min_{x \in C} f(x)$, $C \subseteq \mathbb{R}^n$

- A **feasible point** x means $x \in C$
 - A **solution or minimizer or global minimizer** x^* means
 - 1) $x^* \in C$
 - 2) $\forall y \in C, f(x^*) \leq f(y)$ (NOT $f(x^*) < f(y)$)
- i.e., $x^* \in \arg\min_{x \in C} f(x)$

This is what we usually really want

⚠ Solutions may not exist ... even for convex problems

$$\underline{\text{Ex}} \quad \min_{x \in \mathbb{R}} x$$

$$\underline{\text{Ex}} \quad \min_{x \in (0,1)} x^2$$

} abuse of notation. it's more proper to write $\inf_{x \in (0,1)} x^2$ but optimizers are too lazy

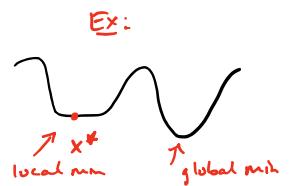
⚠ Solutions need not be unique ... even for convex problems

$$\underline{\text{Ex}} \quad \min_{x \in \mathbb{R}} f(x) \text{ where } f(x) = 0 \quad \forall x$$

- x^* is a **local minimizer** if x^* is feasible and $\exists \varepsilon > 0$ s.t.

$$f(x^*) \leq f(y) \quad \forall y \in C \cap \underline{B_\varepsilon}(x^*) := \{y : \|y - x^*\| < \varepsilon\}$$

open ball of radius ε



- x^* is a **strict local minimizer** if x^* is feasible and $\exists \varepsilon > 0$ s.t.

$$f(x^*) < f(y) \quad \forall y \in B_\varepsilon(x^*) \cap C$$

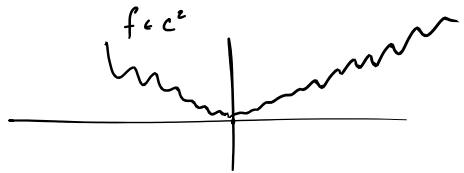


- x^* is an **isolated (and strict) local min** if a local min, and no other local min are nearby

} FAIRLY ESOTERIC

$$\underline{\text{Ex}} \quad f(x) = \begin{cases} x^4 \cos(\frac{1}{x}) + 2x^4 & x \neq 0 \\ 0 & x=0 \end{cases}$$

$x=0$ is a strict but not isolated local min



i.e., \exists sub-optimal local min x_j w/ $x_j \rightarrow 0$

Btw, notation

$f \in C^3$ means f, f', f'', f''' all exist and are continuous

or $f \in C^3(\mathbb{R}^n)$ means $f, \nabla f, \nabla^2 f, \nabla^3 f$ all exist and are continuous

Connections w/ Calc. I

$$\min_{x \in [a,b]} f(x)$$

The procedure: 1) find all points x_i such that $f'(x_i) = 0$
 "critical numbers" or where f is discontinuous or
 not differentiable

generalization

- 2) throw in $\{a, b\}$ boundary
- 3) minimize $\{a, b, x_i\}$

in textbook exercises, $\{x_i\}$ was always finite

Ex:
 Minimize $\{3, -2, 5, 17, -31, 21\}$
 It's easy: it's -31

- A **critical or stationary** point of $f(x)$ is a point where $\nabla f(x) = 0$

... but this isn't enough usually.

- 1) it doesn't take into account constraints

If $x \in \partial C$ then don't expect $\nabla f(x) = 0$ here

boundary, $= \bar{C} \setminus \text{int}(C)$, $\text{int}(C) = \text{largest open set in } C$
 $\bar{C} = \text{closure}(C)$
 $= \text{smallest closed set containing } C$
 $= \{x \in C : \exists \varepsilon > 0 \text{ s.t. } B_\varepsilon(x) \subseteq C\}$

- 2) We can't just check boundary separately

in \mathbb{R} , if $C = [0, 1]$, $\partial C = \{0, 1\}$, so $|\partial C| = 2$

in \mathbb{R}^2 , if $C = [0, 1]^2$, $\partial C = \boxed{}$ so $|\partial C| = \infty$

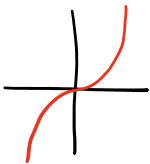
- 3) often there are an ∞ # (or at least a large #) of critical points, so can't check all

- If x^* is a local or global minimizer and $C = \mathbb{R}^n$ (i.e., unconstrained)
 then x^* is a critical point \Rightarrow "necessary" minimizer \Rightarrow crit. pt.

Hw exrc.

but if x^* is a critical point, it need not be a local or global minimizer (so not sufficient) in which case we often call it a **saddle point**

Ex: $f(x) = x^3$



$x^* = 0$ is a saddle point

($f'(0) = 3x^2|_{x=0} = 0$ so it's a crit. pt., but not a local min.)

19th century analysis theorem

Sometimes called "Weierstrass thm":

if f is continuous and C is compact then

f achieves its infimum over C , i.e., $\inf_{x \in C} f(x) = \min_{x \in C} f(x)$

(our first existence of minimizes result)

proof

Q1

on your own, using these ingredients:

1) in \mathbb{R}^n , compact \Leftrightarrow sequentially compact (i.e., every sequence in C has a convergent subseq. whose limit is in C)

2) in \mathbb{R}^n w/ usual topology (i.e., induced by a norm),

a function f is cts \Leftrightarrow sequentially cts (i.e., $x_n \rightarrow x$

shorthand for continuous

$\Rightarrow f(x_n) \rightarrow f(x)$)

One way to prove it:

First, note the set $f(C) := \{f(x), x \in C\}$ is bounded (compact in fact)
since if not bounded, pick $(x_k) \subseteq f(C)$ s.t. $|x_k| \geq k$
but then $\exists x_k$ st. $x_k = f(x_k)$, and \exists convergent subseq. $x_{k_j} \rightarrow x \in C$
so f cts $\Rightarrow \lim_{j \rightarrow \infty} \underbrace{f(x_{k_j})}_{\text{R limit}} = f(x)$
 $= \lim_{j \rightarrow \infty} x_{k_j} \leftarrow \text{unbounded}$

Convergent sequences
are bdd.
Contradiction

So this guarantees $\inf_{x \in C} f(x) =: f^*$ is finite.

So, second step, by "infimum", pick $x_k \in f(C)$ st. $x_k \rightarrow f^*$

again, $\exists x_k$ st. $x_k = f(x_k)$, again pick convergent subseq. x_{k_j} ,
again use continuity of f . \square

So... it's nice when our constraints C are compact

It turns out that's often too much to ask for, but at the
very least, we like our constraint sets to be closed

Ex: $\min_{x \in C} \|x\|^2 \quad (1)$ $\min_{x \in C} \|x\|^2 \quad (2)$

s.t. $\|Ax - b\| < \epsilon$ s.t. $\|Ax - b\| \leq \epsilon$

Very similar, but (1) probably doesn't
have a solution, whereas (2) does.

Other high-level properties of the feasible set C :

- If $C = \emptyset$, the problem is "infeasible".

Not always obvious to spot, ex: $C = \{x : Ax \leq b\}$

may or may not be empty.

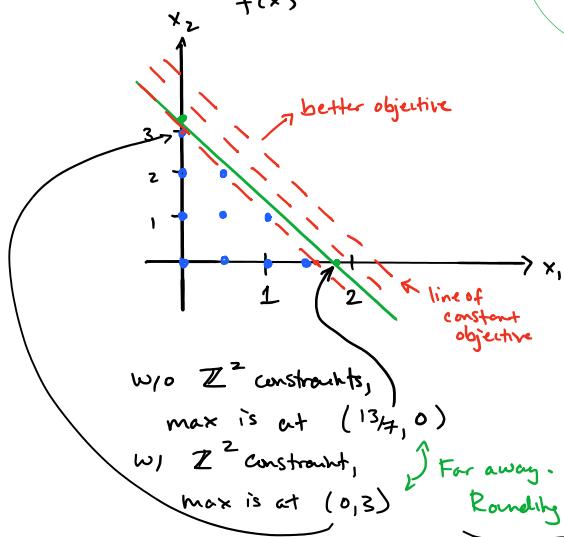
- In this class, C will usually be convex --- in particular, not integral.
 $\underline{\text{makes it hard}}$

ex: $C = \left\{ x \in \mathbb{R}^2, x \geq 0, 7x_1 + 4x_2 \leq 13, x_1, x_2 \in \mathbb{Z} \right\}$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^2$$

$$\max \underbrace{21x_1 + 11x_2}_{f(x)} \text{ s.t. } x \in C$$

"integer linear program"



the line $7x_1 + 4x_2 = 13$ is drawn

in green (intercepts: $x_2 = 0, x_1 = \frac{13}{7} \approx 1.85$
 $x_1 = 0, x_2 = \frac{13}{4} = 3.25$)

C shown in blue

level sets of objective $f(x)$ in red
 e.g. $f(x) = d$

$$d = 7: \quad 21x_1 + 11x_2 = 33 \quad \approx 1.57$$

intercepts $(0, 3)$ and $(\frac{33}{21}, 0)$

Far away.
 Rounding $(\frac{13}{7}, 0)$ to nearest integers is not optimal

Done all the time in practice.

Sometimes it works sorta ok... often it doesn't work well at all.

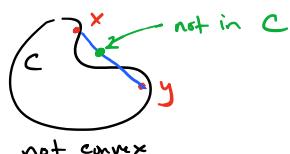
(More on this later in semester)

Convexity from now on, this is always implicitly assumed in this class

Def. A set C inside any vector space is **convex** if $\forall x, y \in C$ and $\forall t \in [0, 1]$,
 then $t \cdot x + (1-t) y \in C$

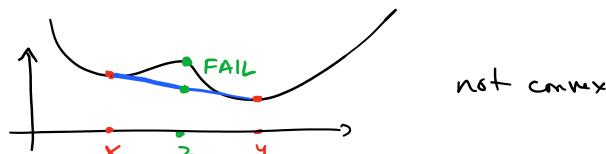
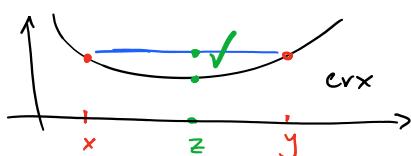
i.e.,

$$\overline{xy} = \{t \cdot x + (1-t) y : t \in [0, 1]\}$$



Def A **function** $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is **convex** if $\forall x, y \in \mathbb{R}^n, \forall t \in [0, 1]$

$$\text{then } f(t \cdot x + (1-t) y) \leq t \cdot f(x) + (1-t) f(y)$$



or, since mathematicians don't like to write/talk more than necessary,

a function f is **convex** iff the set " $\text{epi}(f)$ " is **convex**

where

$$\text{epi}(f) = \text{epigraph}(f) = \{(x, s) : x \in \mathbb{R}^n, s \in \mathbb{R}, s \geq f(x)\}$$

$$\text{graph}(f) = \{(x, s) : \dots, s = f(x)\}$$

Why do we like convexity?

Basic thm #1: If f is convex and C is convex, then any local minimizer of $\min_{x \in C} f(x)$ is in fact global. (Also, $X := \arg\min_{x \in C} f(x)$, the set of global sol'n, is convex, and in particular, connected)

proof

Q2 on your own (scroll down for answer)

Proof: let x be a local sol'n. For contradiction, assume it's not global, so $\exists y \in C$ st. $f(y) < f(x)$.

Since $x \in C$ is a local sol'n, $\exists \varepsilon \text{ st. } f(x) \leq f(z) \forall z \in B_\varepsilon(x) \cap C$

Pick $t \in [0, 1]$ sufficiently close to 1 to guarantee

$z = t x + (1-t)y$ is within ε of x

Since C is convex, $z \in C$, thus by we know $f(x) \leq f(z)$. (*)

But by convexity of f ,

$$f(z) = f(t x + (1-t)y)$$

$$\leq t \cdot f(x) + (1-t)f(y)$$

$$< t \cdot f(x) + (1-t)f(x) \quad \text{since } (1-t) \geq 0 \text{ and } f(y) < f(x)$$

$$= f(x)$$

so $f(z) < f(x)$ which contradicts $(*)$.