



$$(1) \quad P_x = l_1 \cos \theta_1 + l_2 \cos(\theta_1 + \theta_2)$$

$$(2) \quad P_y = l_1 \sin \theta_1 + l_2 \sin(\theta_1 + \theta_2)$$

SQUARING THE EQUATIONS GIVES:

$$P_x^2 = l_1^2 \cos^2 \theta_1 + l_2^2 \cos^2(\theta_1 + \theta_2) + 2l_1 l_2 \cos \theta_1 \cos(\theta_1 + \theta_2)$$

$$P_y^2 = l_1^2 \sin^2 \theta_1 + l_2^2 \sin^2(\theta_1 + \theta_2) + 2l_1 l_2 \sin \theta_1 \sin(\theta_1 + \theta_2)$$

ADDING THEM TOGETHER GIVES:

$$P_x^2 + P_y^2 = l_1^2 (\cos^2 \theta_1 + \sin^2 \theta_1) + l_2^2 (\cos^2(\theta_1 + \theta_2) + \sin^2(\theta_1 + \theta_2)) + 2l_1 l_2 (\cos \theta_1 \cos(\theta_1 + \theta_2) + \sin \theta_1 \sin(\theta_1 + \theta_2)) \rightarrow \cos(\theta_1 + \theta_2) = \cos \theta_1 \cos \theta_2 - \sin \theta_1 \sin \theta_2$$

$$P_x^2 + P_y^2 = l_1^2 + l_2^2 + 2l_1 l_2 (\cos \theta_1 (\cos \theta_2 - \sin \theta_1 \sin \theta_2) + \sin \theta_1 (\sin \theta_2 \cos \theta_1 + \cos \theta_2 \sin \theta_1)) \rightarrow \sin(\theta_1 + \theta_2) = \sin \theta_1 \cos \theta_2 + \cos \theta_1 \sin \theta_2$$

$$P_x^2 + P_y^2 = l_1^2 + l_2^2 + 2l_1 l_2 (\cos^2 \theta_1 \cos \theta_2 - \cancel{\cos \theta_1 \sin \theta_1 \sin \theta_2} + \sin^2 \theta_1 \cos \theta_2 + \cancel{\cos \theta_1 \sin \theta_1 \sin \theta_2})$$

$$P_x^2 + P_y^2 = l_1^2 + l_2^2 + 2l_1 l_2 (\cos \theta_2 (\cos^2 \theta_1 + \sin^2 \theta_1))$$

$$P_x^2 + P_y^2 = l_1^2 + l_2^2 + 2l_1 l_2 \cos \theta_2$$

$$\cos \theta_2 = \frac{P_x^2 + P_y^2 - l_1^2 - l_2^2}{2l_1 l_2} = D$$

$$\theta_2 = \arccos \left( \pm \sqrt{1 - D^2}, D \right)$$

For  $\theta_2$ :

MULTIPLYING (1) WITH  $\cos \theta_2$  AND (2) WITH  $\sin \theta_2$ :

$$P_x = l_1 \cos \theta_1 + l_2 \cos(\theta_1 + \theta_2)$$

$$P_x = l_1 \cos \theta_1 + l_2 (\cos \theta_1 \cos \theta_2 - \sin \theta_1 \sin \theta_2)$$

$$P_x = l_1 \cos \theta_1 + l_2 \cos \theta_1 \cos \theta_2 - l_2 \sin \theta_1 \sin \theta_2 \quad | \cdot \cos \theta_2$$

$$\cos \theta_2 P_x = l_1 \cos^2 \theta_1 + l_2 \cos^2 \theta_1 \cos \theta_2 - l_2 \cos \theta_1 \sin \theta_1 \sin \theta_2$$

$$\sin \theta_2 P_y = l_1 \sin \theta_1 \cos \theta_2 + l_2 \sin \theta_1 \cos \theta_2 \cos \theta_2 + l_2 \cos \theta_1 \sin \theta_1 \sin \theta_2$$

$$P_y = l_1 \sin \theta_1 + l_2 (\sin \theta_1 \cos \theta_2 + \cos \theta_1 \sin \theta_2)$$

$$| \cdot s\theta_2$$

ADDING THEM TOGETHER GIVES:

$$c\theta_1 P_x + s\theta_1 P_y = l_2(\cancel{c^2\theta_2 + s^2\theta_2}) + l_3 c\theta_2(\cancel{c^2\theta_2 + s^2\theta_2})$$

$$(3) \quad c\theta_2 P_x + s\theta_2 P_y = l_2 + l_3 c\theta_3$$

MULTIPLYING (1) WITH  $-s\theta_2$  AND (2) WITH  $c\theta_2$

$$\begin{aligned} P_x &= l_1 c\theta_1 + l_3 c\theta_3 \\ P_x &= l_2 c\theta_2 + l_3 (c\theta_2 c\theta_3 - s\theta_2 s\theta_3) \\ P_x &= l_2 c\theta_2 + l_3 c\theta_2 c\theta_3 - l_3 s\theta_2 s\theta_3 \quad | \cdot -s\theta_2 \\ -s\theta_1 P_x &= -l_2 c\theta_1 s\theta_2 - l_3 s\theta_1 c\theta_2 c\theta_3 + l_3 s^2\theta_1 s\theta_3 \end{aligned}$$

$$\begin{aligned} P_y &= l_1 s\theta_1 + l_3 s\theta_3 \\ P_y &= l_2 s\theta_2 + l_3 (s\theta_2 c\theta_3 + c\theta_2 s\theta_3) \quad | \cdot c\theta_2 \\ c\theta_1 P_y &= l_2 s\theta_1 c\theta_2 + l_3 s\theta_1 c\theta_2 c\theta_3 + l_3 c^2\theta_1 s\theta_3 \end{aligned}$$

ADDING THEM TOGETHER GIVES:

$$-s\theta_1 P_x + c\theta_1 P_y = l_3 s\theta_3(\cancel{c^2\theta_2 + s^2\theta_2})$$

$$(4) \quad -s\theta_1 P_x + c\theta_1 P_y = l_3 s\theta_3$$

MULTIPLYING (3) BY  $P_x$  AND (4) BY  $P_y$ :

$$c\theta_2 P_x^2 + s\theta_2 P_y P_x = l_2 P_x + l_3 c\theta_3 P_x$$

$$-s\theta_2 P_x P_y + c\theta_2 P_y^2 = l_3 s\theta_3 P_y$$

ADDING THEM TOGETHER GIVES:

$$c\theta_2 (P_x^2 + P_y^2) = P_x (l_2 + l_3 c\theta_3) + P_y l_3 s\theta_3$$

$$c\theta_2 = \frac{P_x (l_2 + l_3 c\theta_3) + P_y l_3 s\theta_3}{P_x^2 + P_y^2} = D2$$



$$s\theta_2 = \pm \sqrt{1 - D_2^2}$$

$$\theta_2 = \text{atan2}\left(\pm \sqrt{1 - D_2^2}, D_2\right)$$