Quantum Statistics

Recall that we derived the equilibrium probability distribution p(p) of a momentum component equal to p in the micro canonical ensemble.

We found that the probability of the momentum component having energy $E = \frac{e^2}{2m}$ is proportional to $e^{\frac{E}{\log T}}$: the Boltzmann Disdribution.

What were the assumptions that lead us to this?

- 1) Particles do not interact
- 2) Particles are like billiard balls (i.e classical)
- 3 Particles are in thermal equilibrium

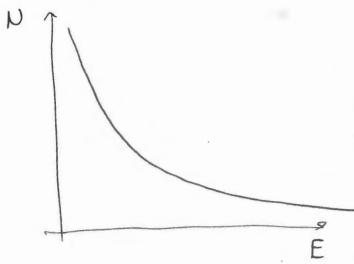
The second assumption is important, as it implies that each particles states state can be determined independently from the other particle states

Quantum Statistics relaxes this assumption.

Before we proceed, let's wish down the Boltzmann Dutabution

The denominator is a normalization factor so that Ni/N sum to 1.
This Factor is called the PARTITION FUNCTION

At sufficiently high temps, the Boltzmann Distribution looks exponential at decays at high energies



It's useful for shidying gasses at high temperatures, but not so useful for low energy/low Temp behavior where interactions quantum effects be one important.

In QM, we are often interested in the ground state Energy, Eand the ground state occupation (No)

Recall from QM that we could find the energy of the harmonic oscillator:

$$E_n = (\frac{1}{z} + n) \hbar \omega$$

At zero temp, the particle will occupy the ground state n=0 w/ Eo = & two.

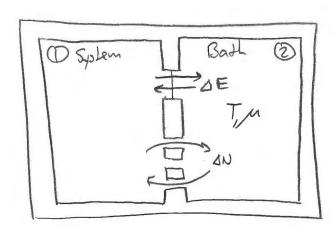
We could gress that with a gas (collection of particles) at zero temp, all particles will live in low energy states. But surprisingly, as we will see, exactly what levels are populated depends on the nature of the particles and their interactions

In a QM statistical system, this is the question that drives us: What is the gound state and Excited state (T>0) occupation of a large number al Quantum particles?

First, lets introduce the GRAND CANONICAL ENSEMBLE

Grand Canonical Ensemble

Consider an equilibrium system which can exchange energy and particles with a heat bath (A second subsystem)



The probability density that the System will be ma state s is

Since $E = E_{both} + E_{s} \Rightarrow E_{Rul} = E - E_{s}$ N=NBash + Ns => NBash : E-Ns

This is completely analogous to the 2 subsystem model he used proviously.