# **I2C Interface**

Git repository at <a href="https://github.com/Wyattjoh/I2C Devices">https://github.com/Wyattjoh/I2C Devices</a>.

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#### Notes on in-class comments

As the definitions of all the source is done in C++ classes, the function descriptions are not located beside the function, rather it is located in the class definition itself.

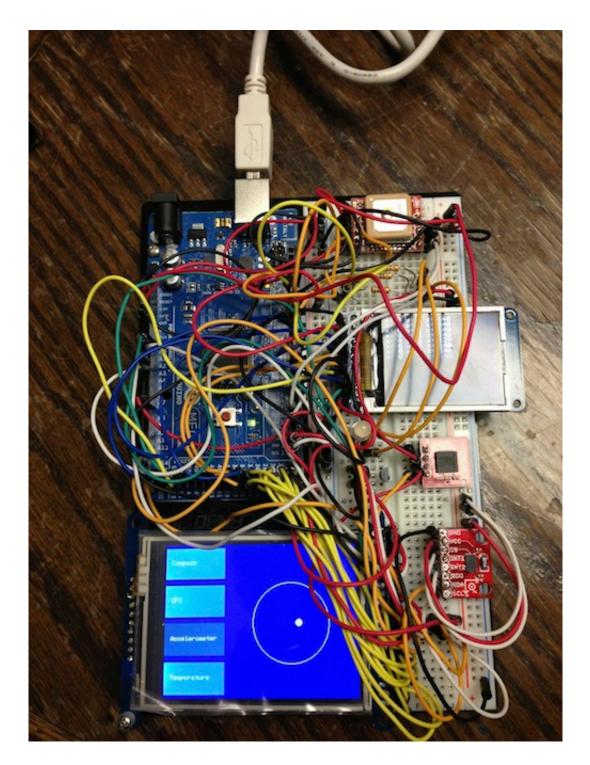
# **Components**

Listed components:

- 1. Arduino MEGA 2560
- 2. GPS GTPA010
- 3. LCD Screen ST7735
- 4. Digital Compass HMC6352
- 5. Accelerometer ADXL345

# **Pictures**

Orientation diagram:



# Wiring

The wiring specifications are specified with the source from the device on the left and the

Arduino on the right, as such:

```
GPS Arduino
------
VCC -> 5V
```

Where - indicates no Arduino pin affiliation.

The following convention will be used when referring to the I2C interfaces:

Where PIN (#) indicates that there is a component that requires a connection with another besides the Arduino, and that these share the same line on the breadboard, connect any devices that have the same PIN (#) definition onto the same line on the breadboard.

#### **GPS - GTPA010**

```
GPS
          Arduino
-----
VCC
          5V
ENABLE ->
          D12
GND
          GND
VBACKUP ->
          3.3V
3D-FIX ->
          D2
          D16
RXD
TXD
          D17
GND
          GND
DMINUS ->
DPLUS ->
```

#### LCD Screen - ST7735

```
LCD Screen Arduino
LITE -> 5V
MISO
        -> D50
SCK
        -> D52
MOSI
MOSI -> D51
TFT_CS -> D34
CARD_CS
        -> D33
        -> D7
D/C
RESET
        -> D32
VCC
        -> 5V
GND
       -> GND
```

### Digital Compass - HMC6352

#### Accelerometer - ADXL345

```
Accelerometer Arduino

GND -> GND

VCC -> 3.3V

CS -> 3.3V

INT1 -> -

INT2 -> -

SDO -> 3.3V

SDA -> PIN(2) -> SDA

SCL -> PIN(1) -> SCL
```

#### **TFTLCD Touch Screen - TFTLCD**

The screen must be oriented such that its left side is at the bottom of the Arduino board as shown in the attached pictures.

| TFTLCD     |    | Arduino |
|------------|----|---------|
| <br>D7     | -> | D29     |
| D6         | -> | D28     |
| D5         | -> | D27     |
| D4         | -> | D26     |
| D3         | -> | D25     |
| D2         | -> | D24     |
| D1         | -> | D23     |
| 00         | -> | D22     |
| <b>/</b> - | -> | A15     |
| (-         | -> | D30     |
| <b>Y</b> + | -> | A14     |
| X+         | -> | D31     |
| Backlight  | -> |         |
| RST        | -> | RESET   |
| RD         | -> | A0      |
| WR         | -> | A1      |
| C/D        | -> | A2      |
| CS         | -> | A3      |
| 3-5V       | -> | 5V      |
| GND        | -> | GND     |

#### Thermistor - T36GZ

The wiring is based on having the flat side facing you.

```
Thermistor Arduino
-----
Left pin -> 5V
Center pin -> A7
Right pin -> GND
```

#### **Tri-color LED**

The wiring is based on having the flat side facing away you, numbered from 0-3 starting with the closest pin.

## Instructions

The I2C Interface project provides a set of data logging methods, sensor communication, and sensor validation classes with the goal of recording said data for any miscellaneous purpose. The project implements a touch screen to provide an interface in-between the hardware and the user to select functions without the need to recompile.

#### Starting the device

- 1. Copy the maps that are located in the maps directory onto the SD card
- 2. Wire the device as described in the wiring section of this document
- 3. Insert a properly formatted SD card with the provided uofa.bmp file on it
- 4. Power the device with a battery pack or USB connection
- 5. The Arduino will start up into mode select mode, choose a function on the touch screen to display data

# Viewing Compass Data

The compass display will show a ring with a small red circle that indicates the direction of magnetic north. The small LCD screen will constantly print out the data as it is read.

If you tilt the device enough, the LED status indicator will turn red, indicating that you have tilted the device too much, and compass measurements are not guaranteed to be accurate, as the measurements are designed to be taken in the plane tangential to the Earth's surface.

- 1. Start the device as described in this section of the document
- 2. Press (Works best with your fingernail) the button titled Compass

## Viewing GPS Data

Once a GPS lock has been acquired, the large TFTLCD screen will display a OpenStreetview map if the available map file uofa.bmp is available and the GPS determines that you are within the maps designed boundaries. Additional maps can be added, although this requires that the source code be recompiled with said map and GPS information to make it available to the GPS.

The map will be centred on the current detected location, and will display the recorded location on the map, leaving a trail of a darker blue where the GPS had been before. The accuracy of the provided *GTPA010* GPS is +/- 5m, so even standing still might result in some drift.

If you venture outside the frame of the screen, but within the bounds of the available map data (North campus), the Arduino will reload the map on the current location (centred), and clear the previous track recorded on the old frame. This is out of design, as it was impractical to have a device which is designed to record information to the SD card also have to constantly re-read said recorded data in the same file for previous tracks. Future designs might incorporate this feature.

- 1. Start the device as described in this section of the document
- 2. Press (Works best with your fingernail) the button titled GPS

#### Viewing Accelerometer Data

The design of the accelerometer pane shows the current position of up would be relative to a ball. To imagine this, picture a ball, where there is a yellow dot on the top, where regardless of how you re-orient the device, the yellow ball will stay on top, this is what the display simulates.

If you tilt the device too far, the yellow dot <u>will</u> go out of the bounds of the white circle; this behaviour is designed. If the Yellow ball was mapped to exist only within the white circle, the visualization would not allow the small yellow ball to move much, hence the mapped magnitude has been expanded to display the movements with increased sensitivity.

- 1. Start the device as described in this section of the document
- 2. Press (Works best with your fingernail) the button titled Accelerometer

# **Viewing Temperature Data**

Due to recored data from the Temperature sensor that I analyzed, as well as the calibration curves that were provided from the manufacturer, I have determined that due to the number of devices that are connected, the electrical interference that is generated is enough to distort the sensitive voltage measurements from the thermistor to the analog pin of the Arduino. Accurate values are generally recorded when the device is stable.

- 1. Start the device as described in this section of the document
- 2. Press (Works best with your fingernail) the button titled Temperature

# **Recording Data**

Data is recorded automatically as soon as a GPS lock is successful. It has been designed this was as to assure that the recorded data has both a location, and a time stamp as provided from the GPS device. The flashing blue LED on the device will indicate that data is currently being written to the onboard SD card.

## **Troubleshooting**

- If the device has started, but is not displaying buttons, and is instead displaying "Failed to initialize SD card!", it indicates that the SD card is either not inserted, or is formatted incorrectly.
  - Solution
    - 1. Unplug the Arduino from power
    - 2. Remove the SD Card from the LCD screen (if attached)
    - 3. Insert the SD Card into a computers SD card slot
    - 4. When the device shows up, eject the device, and reinsert it into the LCD screen on the Arduino

# Code

#### Sensor Classes:

- Sensors
  - o ADXL345
  - o HMC6352
  - T36GZ.h
  - GTPA010

#### Display Classes:

- MapData
- Displays
  - DADXL345
  - o DHMC6352
  - o DT36GZ
  - o DGTPA010

#### Data Classes:

DataLog