view\_frames Result Recorded at time: 1649196991.223 Broadcaster: /map\_to\_odom Average rate: 45.603 Hz Most recent transform: 1649196991.241 (-0.018 sec old) Buffer length: 4.956 sec odom Broadcaster: /robot\_pose\_ekf Average rate: 5.208 Hz Most recent transform: 1649196991.133 ( 0.090 sec old) Buffer length: 4.800 sec base\_footprint Broadcaster: /base\_link\_broadcaster Average rate: 33.344 Hz Most recent transform: 1649196991.244 ( -0.021 sec old) Buffer length: 4.918 sec base\_link Broadcaster: /zed2i/zed2i\_state\_publisher Broadcaster: /base\_link\_to\_laser Broadcaster: /imu\_broadcaster Average rate: 10000.000 Hz Average rate: 33.322 Hz Average rate: 33.315 Hz Most recent transform: 1649196991.226 ( -0.003 sec old) Most recent transform: 0.000 ( 1649196991.223 sec old) Most recent transform: 1649196991.248 ( -0.025 sec old) Buffer length: 4.922 sec Buffer length: 0.000 sec Buffer length: 4.863 sec imu laser Broadcaster: /zed2i/zed2i\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1649196991.223 sec old) Buffer length: 0.000 sec Broadcaster: /zed2i/zed2i\_state\_publisher Average rate: 10000.000 Hz \Most recent transform: 0.000 ( 1649196991.223 sec old) Most recent transform: 0.000 ( 1649196991.223 sec old) Buffer length: 0.000 sec zed2i\_right\_camera\_frame Broadcaster: /zed2i/zed2i\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1649196991.223 sec old) Most recent transform: 0.000 ( 1649196991.223 sec old) Most recent transform: 0.000 ( 1649196991.223 sec old) Buffer length: 0.000 sec zed2i\_right\_camera\_optical\_frame

zed2i\_base\_link

zed2i\_camera\_center

Broadcaster: /zed2i/zed2i\_state\_publisher

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

Broadcaster: /zed2i/zed2i\_state\_publisher

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

zed2i\_left\_camera\_frame

zed2i\_left\_camera\_optical\_frame

Broadcaster: /zed2i/zed\_node

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

zed2i\_imu\_link