

## Week 1 assignment

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**Task** - in Wokwi, if the distance is less than 100 cms for ultrasonic sensor, glow a LED.

Code –

```
#define ECHO_PIN 2
#define TRIG_PIN 3

void setup() {
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
}

float readDistanceCM() {
    digitalWrite(TRIG_PIN, LOW);
    delayMicroseconds(2);
    digitalWrite(TRIG_PIN, HIGH);
    delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW);
    int duration = pulseIn(ECHO_PIN, HIGH);
    return duration * 0.034 / 2;
}

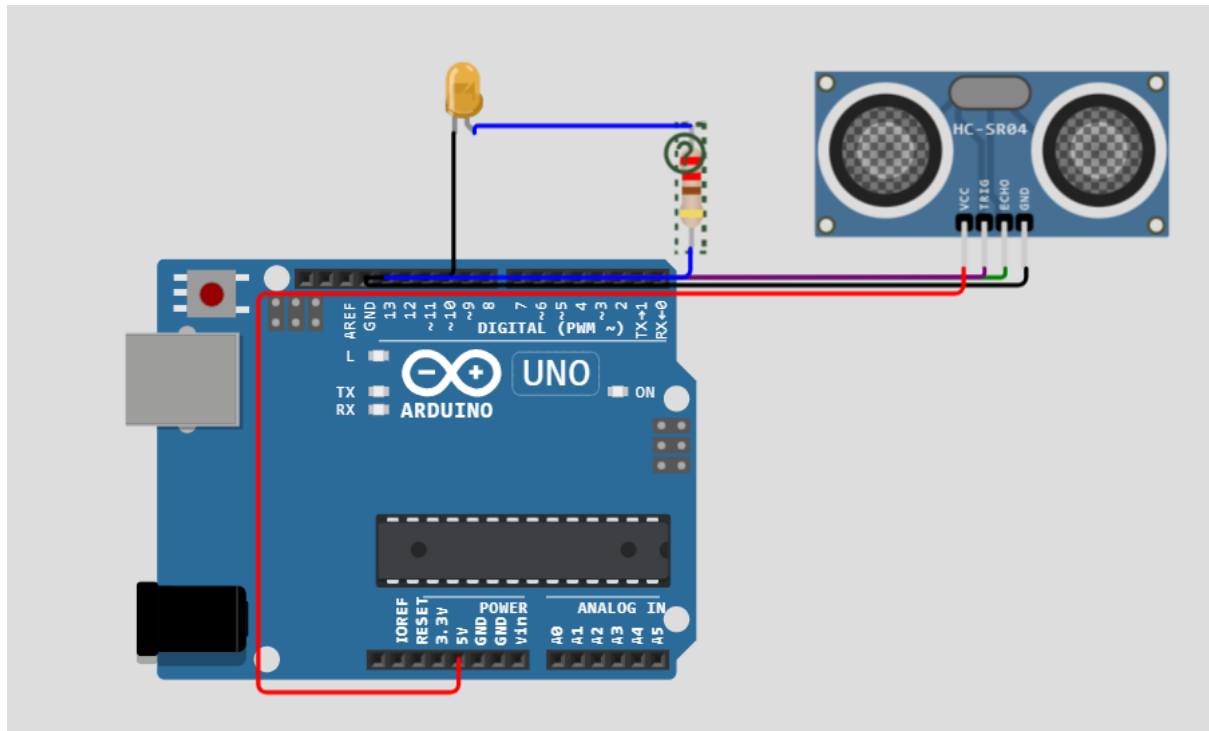
void loop() {
    float distance = readDistanceCM();

    bool isNearby = distance < 100;
    digitalWrite(LED_BUILTIN, isNearby);

    Serial.print("Measured distance: ");
    Serial.println(readDistanceCM());

    delay(100);
}
```

## Schematic



## Output

WOKWIT

SAVE

SHARE

week 1

Docs

R

hc-sr04.ino

diagram.json

Library Manager

```

9  #define ECHO_PIN 2
10 #define TRIG_PIN 3
11
12 void setup() {
13   Serial.begin(115200);
14   pinMode(LED_BUILTIN, OUTPUT);
15   pinMode(TRIG_PIN, OUTPUT);
16   pinMode(ECHO_PIN, INPUT);
17 }
18
19 float readDistanceCM() {
20   digitalWrite(TRIG_PIN, LOW);
21   delayMicroseconds(2);
22   digitalWrite(TRIG_PIN, HIGH);
23   delayMicroseconds(10);
24   digitalWrite(TRIG_PIN, LOW);
25   int duration = pulseIn(ECHO_PIN, HIGH);
26   return duration * 0.034 / 2;
27 }
28
29 void loop() {
30   float distance = readDistanceCM();
31
32   bool isNearby = distance < 100;
33   digitalWrite(LED_BUILTIN, isNearby);
34
35   Serial.print("Measured distance: ");
36   Serial.println(readDistanceCM());
37
38   delay(100);
39 }
40

```

Simulation

00:03.746 102%

Measured distance: 82.77

Measured distance: 82.77

Measured distance: 82.77

Measured distance: 82.77

Measured distance: 82.77

Measured distance: 82.88

Measured distance: 82.77